

Bootstrap

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OVERVIEW

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Bootstrap methods

Bootstrap methods

Bradley Efron 1979.

“pull oneself up by one’s bootstraps” = “better oneself by one’s own effort.”

- ▶ The bootstrap is a general tool for assessing statistical accuracy.
 - ▶ bias
 - ▶ variance (main application)
- ▶ As with cross-validation, the bootstrap can be used to estimate prediction error.
 - ▶ typically estimates well the expected prediction error Err .
- ▶ The bootstrap can be used to estimate effective d.f.

General ideas

The data are realizations of

$$Z_1, \dots, Z_n \stackrel{i.i.d.}{\sim} \mathbb{P}$$

\mathbb{P} denotes an unknown distribution.

We denote a statistical procedure or estimator by

$$\hat{\theta}_n = S(Z_1, \dots, Z_n)$$

which is a (known) function S of the data Z_1, \dots, Z_n .

One typically would need to find out the

- ▶ sampling distribution of $\hat{\theta}_n$,
- ▶ the expectation $E(\hat{\theta}_n)$ or the variance $\text{Var}(\hat{\theta}_n)$.

If we knew the distribution \mathbb{P} :

- ▶ can simulate to obtain the distribution of any $\hat{\theta}_n$ with arbitrary accuracy.

But we do not know the distribution \mathbb{P} !

Bootstrap:

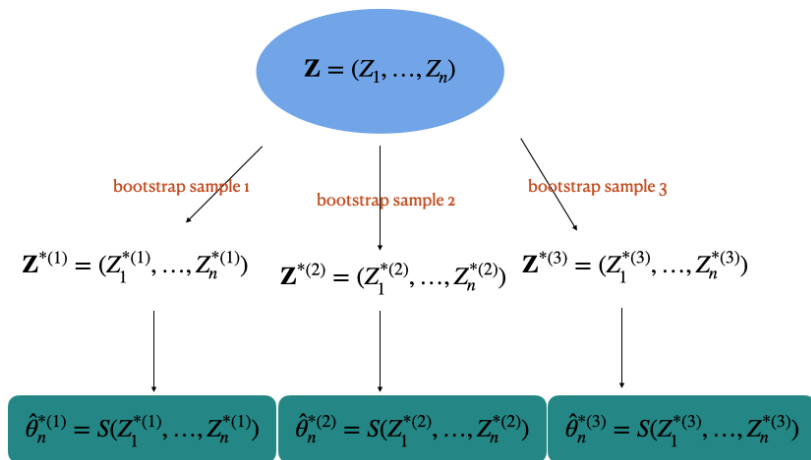
- ▶ use the empirical distribution $\hat{\mathbb{P}}_n$ which places probability mass $1/n$ on every data point $Z_i, i = 1, \dots, n$.
- ▶ simulate from $\hat{\mathbb{P}}_n$: generate simulated data

$$Z_1^*, \dots, Z_n^* \stackrel{i.i.d.}{\sim} \hat{\mathbb{P}}_n$$

i.e., generate n random drawings with **replacement** from the original data set $\{Z_1, \dots, Z_n\}$.

- ▶ such a simulated new data set is called a **bootstrap sample**.
- ▶ compute a bootstrap estimator $\hat{\theta}_n^* = S(Z_1^*, \dots, Z_n^*)$ based on the bootstrap sample.
- ▶ We then repeat this many times (say obtain B bootstrap samples, then B $\hat{\theta}_n^*$ s)
- ▶ Get an approximate distribution for $\hat{\theta}_n$ by the “histogram” of B $\hat{\theta}_n^*$ s.

Bootstrap (an illustration)



$\hat{\theta}_n = S(\mathbf{Z})$ could be any quantity computed from the original data
 $\mathbf{Z} = \{Z_1, \dots, Z_n\}$.

The resampling with replacement is the key feature of bootstrap.

(Nonparametric) bootstrap

The algorithm can be described as:

- ▶ 1. Generate a bootstrap sample

$$Z_1^*, \dots, Z_n^* \stackrel{i.i.d.}{\sim} \hat{\mathbb{P}}_n$$

That is obtain n random draws with replacement from the data set $\{Z_1, \dots, Z_n\}$.

- ▶ 2. Compute the *bootstrapped estimator* based on the bootstrap sample

$$\hat{\theta}_n^* = S(Z_1^*, \dots, Z_n^*)$$

- ▶ 3. Repeat steps 1 and 2 for B times to obtain

$$\hat{\theta}_n^{*(1)}, \dots, \hat{\theta}_n^{*(B)}.$$

Bootstrap distribution

Bootstrap distribution

The **bootstrap distribution** denoted by \mathbb{P}^* ,

- ▶ the conditional probability distribution which is induced by i.i.d. resampling (with replacement) of the data given the original data.

The bootstrap distribution of $\theta_n^* = S(Z_1^*, \dots, Z_n^*)$ is the distribution which arises when resampling with $\hat{\mathbb{P}}_n$ and applying the function S on such a bootstrap sample.

The bootstrap distribution of θ_n^* can be described by Monte Carlo simulation:

$$\text{bootstrap expectation} \quad \mathbb{E}^* \left(\hat{\theta}_n^* \right) \cong \frac{1}{B} \sum_{b=1}^B \hat{\theta}_n^{*(b)}$$

$$\text{bootstrap variance} \quad \text{Var}^* \left(\hat{\theta}_n^* \right) \cong \frac{1}{B-1} \sum_{b=1}^B \left(\hat{\theta}_n^{*(b)} - \frac{1}{B} \sum_{b'=1}^B \hat{\theta}_n^{*(b')} \right)^2$$

α -quantile of the bootstrap distribution of $\hat{\theta}_n^*$:

empirical α -quantile of $\hat{\theta}_n^{*(1)}, \dots, \hat{\theta}_n^{*(B)}$

Bootstrap consistency

The bootstrap is called to be **consistent** for $\hat{\theta}_n$ if, for an increasing sequence a_n , for all x

$$\mathbb{P} \left(a_n \left(\hat{\theta}_n - \theta \right) \leq x \right) - \mathbb{P}^* \left(a_n \left(\hat{\theta}_n^* - \hat{\theta}_n \right) \leq x \right) \xrightarrow{P} 0 \quad (n \rightarrow \infty)$$

In classical situations, $a_n = \sqrt{n}$.

In other words, if $\hat{\theta}_n$ is asymptotically unbiased estimate some parameter θ , the bootstrap consistency says that the sampling distribution of $\hat{\theta}_n - \theta$ in \mathbb{P} and the bootstrap distribution of $\hat{\theta}_n^* - \hat{\theta}_n$ in \mathbb{P}^* are asymptotically identical.

Such approximation may be reasonable when the distribution of $\hat{\theta}_n - \theta$ is *pivotal*, that is the distribution does not depend on θ .

Estimating bias and variance

Under bootstrap consistency, the bias of $\hat{\theta}_n$ may be approximated as

$$E(\hat{\theta}_n) - \theta \approx E^*(\hat{\theta}_n^*) - \hat{\theta}_n \cong \frac{1}{B} \sum_{b=1}^B \hat{\theta}_n^{*(b)} - \hat{\theta}_n$$

And

$$\text{Var}(\hat{\theta}_n) \approx \text{Var}^*(\hat{\theta}_n^*) \cong \frac{1}{B-1} \sum_{b=1}^B \left(\hat{\theta}_n^{*(b)} - \frac{1}{B} \sum_{b'=1}^B \hat{\theta}_n^{*(b')} \right)^2.$$

Estimating confidence intervals

We can also construct the bootstrap confidence interval for θ .

Recall that a $(1 - \alpha)$ confidence interval for θ , computed over z_1, \dots, z_n , is a random interval (L, U) satisfying

$$P(L \leq \theta \leq U) = 1 - \alpha.$$

The bootstrap confidence interval for θ is given by (why?)

$$\left(2\hat{\theta}_n - q_{1-\alpha/2}^*, 2\hat{\theta}_n - q_{\alpha/2}^*\right).$$

Here $q_{\alpha/2}^*$ and $q_{1-\alpha/2}^*$, are the $\alpha/2$ and $1 - \alpha/2$ are the bootstrap quantiles of $\hat{\theta}_n^{*(1)}, \dots, \hat{\theta}_n^{*(B)}$.

Studentized bootstrap confidence intervals

In some cases, the distributions of $(\hat{\theta}_n - \theta)/\widehat{\text{SE}}(\hat{\theta}_n)$ and $(\hat{\theta}_n^* - \hat{\theta}_n)/\widehat{\text{SE}}(\hat{\theta}_n^*)$ could be close, where $\widehat{\text{SE}}(\cdot)$ denote estimated standard errors. The so-called **studentized bootstrap confidence intervals** is obtained:

- ▶ repeat, for $b = 1, \dots, B$:
 - ▶ draw a bootstrap sample $z_1^{*(b)}, \dots, z_n^{*(b)}$ from $\{z_1, \dots, z_n\}$
 - ▶ recompute the statistic $\hat{\theta}_n^{*(b)}$ based on $z_1^{*(b)}, \dots, z_n^{*(b)}$
 - ▶ repeat, for $m = 1, \dots, M$:
 - ▶ draw a bootstrap sample $z_1^{*(b,m)}, \dots, z_n^{*(b,m)}$ from $\{z_1^{*(b)}, \dots, z_n^{*(b)}\}$
 - ▶ recompute the statistic $\hat{\theta}_n^{*(b,m)}$ from $\{z_1^{*(b,m)}, \dots, z_n^{*(b,m)}\}$
 - ▶ compute the sample standard deviation $\hat{s}^{*(b)}$ of $\hat{\theta}_n^{*(b,1)}, \dots, \hat{\theta}_n^{*(b,M)}$
 - ▶ compute $(\hat{\theta}_n^{*(b)} - \hat{\theta}_n)/\hat{s}^{*(b)}$.

From above we have a sample $\{(\hat{\theta}_n^{*(b)} - \hat{\theta}_n)/\hat{s}^{*(b)} : b = 1, \dots, B\}$, from which, we compute the quantiles $q_{\alpha/2}^*$ and $q_{1-\alpha/2}^*$.

The approximate $1 - \alpha$ bootstrap confidence interval for θ is given by

$$(\hat{\theta}_n - \widehat{\text{SE}}(\hat{\theta}_n)q_{1-\alpha/2}^*, \hat{\theta}_n - \widehat{\text{SE}}(\hat{\theta}_n)q_{\alpha/2}^*),$$

- $\widehat{\text{SE}}(\hat{\theta}_n)$ can be approximated with $\text{Var}^*(\hat{\theta}_n^*)$ using bootstrap samples $\{\hat{\theta}_n^{*(1)}, \dots, \hat{\theta}_n^{*(B)}\}$.

Nonparametric bootstrap, (semi)-parametric bootstrap

Parametric bootstrap

Assume that the data are realizations from

$$Z_1, \dots, Z_n \stackrel{i.i.d.}{\sim} \mathbb{P}_\theta$$

where \mathbb{P}_θ is given up to an unknown parameter (vector) θ .

- ▶ estimate the unknown parameter θ by $\hat{\theta}_n$
- ▶ draw

$$Z_1^*, \dots, Z_n^* \stackrel{i.i.d.}{\sim} \mathbb{P}_{\hat{\theta}_n}$$

Example (parametric regression)

- ▶ $y_i = \beta^\top x_i + \varepsilon_i, (i = 1, \dots, n), \varepsilon_1, \dots, \varepsilon_n \stackrel{i.i.d.}{\sim} N(0, \sigma^2), \theta = (\beta, \sigma^2).$
 - ▶ training data $z = \{z_1, z_2, \dots, z_n\}$, with $z_i = (x_i, y_i) \ i = 1, 2, \dots, n.$
 - ▶ $\hat{\beta}, \hat{\sigma}$ denote the MLE estimates based on original data.
1. Simulate $\varepsilon_1^*, \dots, \varepsilon_n^* \stackrel{i.i.d.}{\sim} N(0, \hat{\sigma}^2)$
 2. Construct

$$y_i^* = \hat{\beta}^\top x_i + \varepsilon_i^*, i = 1, \dots, n$$

The parametric bootstrap regression sample is then

$$(x_1, y_1^*), \dots, (x_n, y_n^*)$$

where the predictors x_i are from the original data.

nonparametric regression

Suppose $Y = f(X) + \epsilon$, $E(Y|X = x) = f(x) \approx \sum_{j=1}^M \beta_j h_j(x)$ where $\text{var}(\epsilon) = \sigma^2$.

$$\hat{\beta} = (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{y}$$

$$\widehat{\text{Var}}(\hat{\beta}) = (\mathbf{H}^\top \mathbf{H})^{-1} \hat{\sigma}^2$$

$$\hat{\sigma}^2 = \sum_{i=1}^n \left(y_i - \hat{f}(x_i) \right)^2 / n$$

- ▶ Let $h(x)^\top = (h_1(x), h_2(x), \dots, h_M(x))$.
- ▶ $\hat{f}(x) = h(x)^\top \hat{\beta}$
- ▶ standard error $\widehat{\text{se}}(\hat{f}(x)) = \left(h(x)^\top (\mathbf{H}^\top \mathbf{H})^{-1} h(x) \right)^{\frac{1}{2}} \hat{\sigma}$.
- ▶ The (biased) 95% pointwise confidence interval is $\hat{f}(x) \pm 1.96 \widehat{\text{se}}(\hat{f}(x))$.

example: nonparametric bootstrap

Suppose we have $n = 50$. The nonparametric bootstrap works as follows:

- We draw B datasets each of size $n = 50$ with replacement from our training data, the sampling unit being the pair $z_i = (x_i, y_i)$.

To each bootstrap dataset \mathbf{Z}^* we fit a $\hat{f}^*(x)$. Using $B = 200$ bootstrap samples, we can form a 95% pointwise confidence interval from the percentiles at each x : we find the $2.5\% \times 200 =$ fifth largest and smallest values at each x , i.e., obtain $(q_{2.5\%}^*(x), q_{97.5\%}^*(x))$.

More appropriately, for x , obtain the quantiles $\hat{f}^*(x) - \hat{f}(x)$, say $\tilde{q}_{\alpha/2}^*(x), \tilde{q}_{1-\alpha/2}^*(x)$, then the pointwise confidence interval is given by

$$(\hat{f}(x) - \tilde{q}_{1-\alpha/2}^*(x), \hat{f}(x) - \tilde{q}_{\alpha/2}^*(x)).$$

example: semi-parametric bootstrap

Simulate new responses by adding Gaussian noise to the predicted values:

$$y_i^* = \hat{f}(x_i) + \varepsilon_i^*; \quad \varepsilon_i^* \sim N(0, \hat{\sigma}^2); \quad i = 1, 2, \dots, n$$

This process is repeated B times, where $B = 200$ say. The resulting bootstrap datasets have the form $(x_1, y_1^*), \dots, (x_n, y_n^*)$ and we recompute the splines on each.

The confidence intervals from this method will exactly equal the least squares intervals, as the number of bootstrap samples goes to infinity.

- the estimate based on bootstrap sample is

$$\hat{f}^*(x) = h(x)^\top (\mathbf{H}^\top \mathbf{H})^{-1} \mathbf{H}^\top \mathbf{y}^* \text{ with distribution}$$

$$\hat{f}^*(x) \sim N\left(\hat{f}(x), h(x)^\top (\mathbf{H}^\top \mathbf{H})^{-1} h(x) \hat{\sigma}^2\right)$$

.

Residual bootstrap

Suppose

$$y_i = f(x_i) + \varepsilon_i$$
$$\varepsilon_1, \dots, \varepsilon_n \stackrel{i.i.d.}{\sim} \mathbb{P}_\varepsilon$$

where \mathbb{P}_ε is unknown with expectation 0.

1. Estimate \hat{f} from the original data and compute the residuals $r_i = y_i - \hat{f}(x_i)$.
2. Consider the centered residuals $\tilde{r}_i = r_i - n^{-1} \sum_{i=1}^n r_i$. In case of linear regression with an intercept, the residuals are already centered. Denote the empirical distribution of the centered residuals by $\hat{\mathbb{P}}_{\tilde{r}}$.
3. Generate

$$\varepsilon_1^*, \dots, \varepsilon_n^* \stackrel{i.i.d.}{\sim} \hat{\mathbb{P}}_{n, \tilde{r}}$$

Note that $\hat{\mathbb{P}}_{n, \tilde{r}}$ is an estimate of \mathbb{P}_ε .

4. Construct the bootstrap response variables

$$y_i^* = \hat{f}(x_i) + \varepsilon_i^*, i = 1, \dots, n$$

and the bootstrap sample is $(x_1, y_1^*), \dots, (x_n, y_n^*)$.

Confidence band via bootstrap

Bootstrapping $\sup_x |\hat{f}(x) - E(\hat{f}(x))|$:

More generally, if $\sigma^2 = \sigma^2(x)$ is not constant in x , $\hat{\sigma}^2(x)$ can be estimated as using the regression $e_i^2 := (y_i - \hat{f}(x_i))^2$ v.s. x_i , and taking $\hat{\sigma}^2(x_i) = \hat{e}_i^2$.

One then obtain bootstrap (upper) α quantile R_α from

$$\frac{\sqrt{n} \sup_x |\hat{f}(x) - E(\hat{f}(x))|}{\hat{\sigma}(x)}$$

Then $\hat{f}(x) \pm (R_\alpha \hat{\sigma}(x)/\sqrt{n})$ has a (supposedly) sup-norm coverage.

- ▶ still biased for the true f unless done with undersmoothing
- ▶ Or view this confidence band as for the smoothed version $E(\hat{f}(\cdot))$ instead of f .

Bootstrap is to address the variance estimate, without undersmoothing, the above band is still biased. A even better approach is to use debiased estimator with the bootstrap.

Bootstrap estimate of prediction error

If $\hat{f}^{*(b)}(x_i)$ is the predicted value at x_i , from the model fitted to the b -th bootstrap dataset, our estimate of EPE is

$$\widehat{\text{Err}}_{\text{naive}} = \frac{1}{n} \sum_{i=1}^n \sum_{b=1}^B \frac{1}{B} L\left(y_i, \hat{f}^{*(b)}(x_i)\right)$$

- ▶ Repeat for $b = 1, \dots, B$:
 - ▶ Generate $\left(X_1^{*(b)}, Y_1^{*(b)}\right), \dots, \left(X_n^{*(b)}, Y_n^{*(b)}\right)$ by resampling with replacement from the original data.
 - ▶ Compute the bootstrapped estimator $\hat{f}^{*(b)}(\cdot)$ based on $\left(X_1^{*(b)}, Y_1^{*(b)}\right), \dots, \left(X_n^{*(b)}, Y_n^{*(b)}\right)$
 - ▶ Evaluate $\text{err}^{*(b)} = n^{-1} \sum_{i=1}^n L\left(Y_i, \hat{f}^{*(b)}(X_i)\right)$
- ▶ Approximate the error EPE by

$$B^{-1} \sum_{b=1}^B \text{err}^{*(b)}$$

Leave-one-out bootstrap estimate

Above estimate is not a good estimate in general. Tends to be overfitting.

The **leave-one-out bootstrap estimate** of prediction error is defined by

$$\widehat{\text{Err}}^{(1)} = \frac{1}{n} \sum_{i=1}^n \frac{1}{|C^{-i}|} \sum_{b \in C^{-i}} L\left(y_i, \hat{f}^{*(b)}(x_i)\right)$$

- ▶ $C^{-i} \subset \{1, \dots, B\}$ is the set of indices of the bootstrap samples b that do not contain observation i ,
- ▶ $|C^{-i}|$ is the number of such samples.

The leave-one out bootstrap solves the overfitting problem suffered by $\widehat{\text{Err}}_{\text{naive}}$, but has the training-set-size bias mentioned in the discussion of cross-validation.

- ▶ Typically, the leave-one out bootstrap estimate will be biased upward.

Bias

- ▶ Given a bootstrap sample by $\mathbf{Z}^* = \{Z_1^*, \dots, Z_n^*\}$, the out-of-bootstrap sample

$$\mathbf{Z}_{\text{out}}^* = \{Z_i : Z_i \notin \mathbf{Z}^*\}$$

The out-of-bootstrap estimate above can be written as:

$$\widehat{\text{Err}}^{(1)} = \frac{1}{B} \sum_{b=1}^B \frac{1}{|\mathbf{Z}_{\text{out}}^{*(b)}|} \sum_{i \in \mathbf{Z}_{\text{out}}^{*(b)}} L(y_i, \hat{f}^{*(b)}(x_i))$$

Note that $\hat{f}^{*(b)}(\cdot)$ involves only data from $\mathbf{Z}^{*(b)}$, and $(X_i, Y_i) \in \mathbf{Z}_{\text{out}}^*$.

- ▶ The expected size of the out-of-bootstrap sample:
 $E^*(|\mathbf{Z}_{\text{out}}^*|) \approx 0.368n$.
- ▶ $\widehat{\text{Err}}^{(1)}$ is like a CV estimate that uses about 36.8% data points as test data, or about 63.2% data points as training data
- ▶ Unlike CV estimate, the training data in $\widehat{\text{Err}}^{(1)}$ may have duplicates.

The .632 estimator

The “.632 estimator” is designed to alleviate this bias:

$$\widehat{\text{Err}}^{(.632)} = .368 \cdot \overline{\text{err}} + .632 \cdot \widehat{\text{Err}}^{(1)}$$

The derivation of the .632 estimator is complex; intuitively it pulls the leave-one out bootstrap estimate down toward the training error rate, and hence reduces its upward bias.

Note that $\overline{\text{err}} \leq \widehat{\text{Err}}^{(.632)} \leq \widehat{\text{Err}}^{(1)}$.

- ▶ The .632 estimator works well in “light fitting” situations
- ▶ In the heavily-overfitting situations, one can further improve the .632 estimator: the .632+ estimator

Estimating degrees of freedom

The so-called **effective d.f.** of a fitted model is

$$\text{d.f.}(\hat{f}) = \frac{\sum_{i=1}^n \text{cov}(\hat{y}_i, y_i)}{\sigma^2}, \quad \{x_i\}_i \text{ fixed}$$

We can estimate the covariance terms $\text{cov}(\hat{y}_i, y_i)$ via the bootstrap.

After fitting $\hat{y}_i = \hat{f}(x_i), i = 1, \dots, n$ using the original samples $(x_i, y_i), i = 1, \dots, n$, we record the (empirical) residuals

$$\hat{e}_i = y_i - \hat{y}_i, \quad i = 1, \dots, n$$

Then for $b = 1, \dots, B$, we repeat:

- ▶ obtain a bootstrap sample $(x_i, \tilde{y}_i^{(b)}), i = 1, \dots, n$ according to

$$\tilde{y}_i^{(b)} = \hat{y}_i + \tilde{e}_i^{(b)}, \text{ where } \tilde{e}_i^{(b)} \stackrel{i.i.d.}{\sim} \{\hat{e}_1, \dots, \hat{e}_n\}, \quad i = 1, \dots, n$$

- ▶ estimate the estimator $\hat{f}^{(b)}$ based on the sample $(x_i, \tilde{y}_i^{(b)})_{i=1}^n$
- ▶ store $\tilde{\mathbf{y}}^{(b)} = (\tilde{y}_1^{(b)}, \dots, \tilde{y}_n^{(b)})$, and $\hat{\mathbf{y}}^{(b)} = (\hat{f}^{(b)}(x_1), \dots, \hat{f}^{(b)}(x_n))$.

With $\tilde{\mathbf{y}}^{(b)} = (\tilde{y}_1^{(b)}, \dots, \tilde{y}_n^{(b)})$, and $\hat{\mathbf{y}}^{(b)} = (\hat{f}^{(b)}(x_1), \dots, \hat{f}^{(b)}(x_n))$,

we approximate the covariance of \hat{y}_i and y_i by the empirical covariance between $\hat{y}_i^{(b)}$ and $\tilde{y}_i^{(b)}$ over $b = 1, \dots, B$, i.e.

$$\text{Cov}(\hat{y}_i, y_i) \approx \frac{1}{B} \sum_{b=1}^B \left(\hat{y}_i^{(b)} - \frac{1}{B} \sum_{b'=1}^B \hat{y}_i^{(b')} \right) \left(\tilde{y}_i^{(b)} - \frac{1}{B} \sum_{b'=1}^B \tilde{y}_i^{(b')} \right).$$

Summing this up over $i = 1, \dots, n$ yields the bootstrap estimate for degrees of freedom

$$\widehat{\text{d.f.}}(\hat{f}) \approx \frac{1}{\sigma^2} \sum_{i=1}^n \left(\frac{1}{B} \sum_{b=1}^B \left(\hat{y}_i^{(b)} - \frac{1}{B} \sum_{b'=1}^B \hat{y}_i^{(b')} \right) \left(\tilde{y}_i^{(b)} - \frac{1}{B} \sum_{b'=1}^B \tilde{y}_i^{(b')} \right) \right)$$

Some discussions

Correct way to do bootstrap for inference

The bootstrap procedure should be applied to the entire estimation process to obtain *correct inference*.

Suppose that we adaptively choose by cross-validation the number and position of the knots that define the B -splines, rather than fix them in advance. Denote by λ the collection of knots and their positions. Then the standard errors and confidence bands should account for the adaptive choice of λ .

The catch is with the bootstrap, we compute the B -spline smoother with an adaptive choice of knots for *each* bootstrap sample. Lastly the usual bootstrap estimate for variance, or bootstrap CI can be obtained.

Estimation of prediction error of tuned model

The 0.632 (0.632+) estimators were proposed to assess the *prediction error* of a generic algorithm and can be directly applied to a (adaptively) tuned model:

specifically, for each bootstrap sample, the model can be fit and tuned (say by CV) with this bootstrap sample.

Alternatively, one can use Wang and Zou (2021) Honest leave-one-out cross-validation or nested cross validation to assess the performance of a tuned model.

Bayesian bootstrap

The bootstrap discussed above is a “poor man’s” version of Bayesian bootstrap.

Bayesian bootstrap sample:

- ▶ Draw weights from a uniform Dirichlet distribution with the same dimension as the number of data points
- ▶ Sample from data accordingly to the probability defined by the Dirichlet weights
- ▶ Use the resampled data to calculate the statistics.