## Bagging and Model Averaging

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### Introduction

#### Introduction

Bootstrap aggregating (bagging) and boosting are useful techniques to improve the predictive performance of models.

- ▶ Boosting may also be useful in connection with many other models, e.g. for additive models with high-dimensional predictors
- bagging is most prominent for improving tree algorithms.

## Bagging in Regression problems

### Bagging in Regression problems

Let training data be  $z = \{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$ , from z, obtain the prediction  $\hat{f}(x)$  at input x.

Bagging works as follows:

1. Generate a bootstrap sample

$$(X_1^*, Y_1^*), \dots, (X_n^*, Y_n^*)$$

and compute the bootstrapped estimator  $\hat{f}^*(\cdot)$ .

2. Repeat step B times, yielding

$$\hat{f}^{*(1)}(\cdot),\ldots,\hat{f}^{*(B)}(\cdot)$$

3. Aggregate the bootstrap estimates

$$\hat{f}_{bag}(\cdot) = B^{-1} \sum_{b=1}^{B} \hat{f}^{*(b)}(\cdot)$$

The bagging estimator is essentially (with  $B = \infty$ )

$$\hat{f}_{bag}(\cdot) \cong \mathrm{E}^* \left( \hat{f}^*(\cdot) \right)$$

here, E\* is with respect to the bootstrap distribution

The bagged estimate will differ from the original estimate  $\hat{f}(x)$  only when the latter is a nonlinear or adaptive function of the data.

An identity indicates properties of bagging: with  $B = \infty$ 

$$\begin{split} \hat{f}_{bag}(\cdot) &\cong \hat{f}(\cdot) + \left( \mathbf{E}^* \big( \hat{f}^* (\cdot) \big) - \hat{f}(\cdot) \right) \\ &\cong \hat{f}(\cdot) + \text{ bootstrap bias estimate.} \end{split}$$

▶ Adding the bootstrap bias estimate

What we can hope for is a variance reduction at the price of a higher bias. How?

- ▶ An ideal aggregate estimator  $f_{ag}(\cdot) := \mathbb{E}_{\mathbb{P}} \hat{f}(\cdot)$  never increases MSE.
- ▶ By the bootstrap principle

$$f_{\mathrm{ag}}(x) := \mathcal{E}_{\mathbb{P}}(\hat{f}(x)) \approx \mathcal{E}^*(\hat{f}^*(x)) =: \hat{f}_{bag}(x)$$

we hope that using  $\hat{f}_{bag}(x)$  can decrease MSE

▶ the decrease in MSE is possible when  $\hat{f}(\cdot)$  has high variance (e.g., trees)

## Bagging in Classification

#### Hard classification

Hard classification: If  $\hat{f}^{*(b)}(x)$  is indicator-vector, with one 1 and K-1 0's (hard classification), equivalently, for some  $\hat{h}^{*(b)}(x) \in \{1, \ldots, K\}$ .

"Consensus vote" (majority vote): selects the most "votes" from the B classifiers.

$$\hat{p}_{bag,k}(x) = \frac{1}{B} \sum_{b=1}^{B} 1\{\hat{h}^{*(b)}(x) = k\}$$

so the classifier is

$$\hat{p}_{bag}(x) = \arg\max_{k} \hat{p}_{bag,k}(x)$$

### Soft classification

If 
$$\hat{f}^{*(b)}(x) = (\hat{p}_1^{*(b)}, \dots, \hat{p}_K^{*(b)})$$
, the estimates of class probabilities  $\hat{p}_k^{*(b)} := \hat{P}^{(b)}(Y = k \mid X = x), k = 1, \dots, K$ .

"averaging probabilities": the bagged estimates are the average prediction at x from B classifiers

$$\hat{p}_{\text{bag},k}(x) = B^{-1} \sum_{b=1}^{B} \hat{p}_k^{*(b)}(x), \quad k = 1, \dots, K$$

If a predicted label is desired,

$$\hat{p}_{bag}(x) = \arg\max_{k} \hat{p}_{bag,k}(x)$$

### Effects of bagging

In the classification under 0-1 loss, bagging a good classifier can make it better, but bagging a bad classifier can make it worse.

The **Wisdom of Crowds** asserts that the collective knowledge of a diverse and independent body of people typically exceeds the knowledge of any single individual and can be harnessed by voting.

#### The Wisdom of Crowds

Consider an example: optimal decision at x be  $h^*(x) = 1$  in a two-class example.

- Suppose each of the weak learners  $h^{*(b)}$  have an error-rate  $e_b = e$ , say slightly less than 0.5
- let  $S_1(x) = \sum_{b=1}^{B} 1 \left( h^{*(b)}(x) = 1 \right)$  be the consensus vote for class-1.
- ▶ the weak learners are assumed to be **independent**

$$S_1(x) \sim \text{Bin}(B, 1-e),$$
 
$$\Pr(S_1/B > 1/2) \to 1, \text{ as } B \text{ gets large}.$$

## Model Averaging

### Bayesian model averaging

- ▶ J models, denoted by  $M_j$ , j = 1, 2, ..., J.
- ightharpoonup Consider the prediction f(x) at some x as a parameter

The posterior distribution of f(x) is

$$\Pr(f(x) \mid Z) = \sum_{m=1}^{M} \Pr(f(x) \mid M_m, Z) \Pr(M_m \mid Z)$$

with posterior mean

$$E(f(x) \mid Z) = \sum_{m=1}^{M} E(f(x) \mid M_m, Z) \Pr(M_m \mid Z)$$

- ▶  $\Pr(M_m \mid Z)$  are the weights proportional to posterior probability of each model.
- ► The **committee method** uses a simple unweighted average (equal probability).
- ▶ Bagging estimate can be viewed as some approximate to the posterior mean.

# $\Pr(M_m|Z)$

To obtain  $Pr(M_m|Z)$ , there are two methods

▶ Use BIC

$$\Pr(M_m \mid Z) \approx \frac{\exp\left(-\frac{1}{2}BIC_m\right)}{\sum_{l=1}^{J} \exp\left(-\frac{1}{2}BIC_l\right)}$$

▶ a full Bayesian procedure: suppose each model  $M_m$  has parameters  $\theta_m$ 

$$\Pr(M_m|Z) \propto \Pr(M_m) \Pr(Z|M_m)$$
  
  $\propto \Pr(M_m) \int p(Z|M_k, \theta_k) p(\theta_k|M_k) d\theta_k$ 

### Frequentist model averaging

Given predictions  $\hat{f}_1(x), \hat{f}_2(x), \dots, \hat{f}_M(x)$ , under squared-error loss, we can seek the weights  $w = (w_1, w_2, \dots, w_M)$  such that

$$\hat{w} = \underset{w}{\operatorname{argmin}} \quad \operatorname{E}\left(Y - \sum_{m=1}^{M} w_m \hat{f}_m(x)\right)^2$$

The solution is the population LS of Y on

$$\hat{F}(x)^{\top} \equiv \left(\hat{f}_1(x), \hat{f}_2(x), \dots, \hat{f}_M(x)\right):$$

$$\hat{w} = \mathrm{E}\left(\hat{F}(x)\hat{F}(x)^{\top}\right)^{-1}\mathrm{E}(\hat{F}(x)Y)$$

It holds that

$$\operatorname{E}\left(Y - \sum_{m=1}^{M} \hat{w}_{m} \hat{f}_{m}(x)\right)^{2} \leq \operatorname{E}\left(Y - \hat{f}_{m}(x)\right)^{2}, \quad \forall m$$

so combining models never makes things worse at the population level.

### Stacking (emsemble)

However, the in-sample analog of the loss won't work:

$$\hat{w}^{\text{st}} = \arg\min_{w} \sum_{i=1}^{n} \left( y_i - \sum_{m=1}^{M} w_m \hat{f}_m(x_i) \right)^2$$

Instead, the stacking weights are solved by

$$\hat{w}^{\text{st}} = \arg\min_{w} \sum_{i=1}^{n} \left( y_i - \sum_{m=1}^{M} w_m \hat{f}_m^{-(i)}(x_i) \right)^2$$

- ▶  $\hat{f}_m^{-(i)}(x)$  is the **LOO prediction** at x, i.e., estimated leaving out i-th training example.
- $\triangleright$  The final prediction at point x is

$$\sum_{m} \hat{w}_{m}^{\rm st} \hat{f}_{m}(x)$$

The weights may be restriced to be sum up to 1.

$$\hat{w}^{\text{st}} = \arg\min_{w} \sum_{i=1}^{n} \left( y_i - \sum_{m=1}^{M} w_m \hat{f}_m^{-(i)}(x_i) \right)^2$$

The objective function in the stacking weights problem is related to leave-one-out cross-validation error estimate

LOOCV
$$(\hat{f}) = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{f}^{-(i)}(x_i))^2$$

- ▶ If the weight vectors w are restricted so that have one unit weight and the rest zero, this leads to a model choice with smallest leave-one-out cross-validation error.
- ▶ Stacking combines them with estimated optimal weights.
  - better prediction, but less interpretability

### Estimate weights (K-fold CV)

Suppose there are M methods to predict f. We choose  $w = (w_1, \ldots, w_M) \in \mathcal{W}$  (a grid of weights) by minimizing the K-fold cross validation loss. Suppose the data is divided into K folds, say  $C_1, \ldots, C_k$ .

- 1. For k = 1, ..., K:
  - (1) For m = 1, ..., M:
    - (i) Estimate  $\hat{f}_m^{(-k)}$  based on the  $\{i \in C_k^c\}$
    - (ii) Obtain the out-of-sample estimate  $\hat{f}_m^{(-k)}(x_i)$  for all  $i \in C_k$
  - (2) For each  $\tilde{w} \in \mathcal{W}$ : Obtain the out-of-sample loss  $MSE_k(\tilde{w}) = \sum_{i \in C_k} (Y_i \sum_{m=1}^M \tilde{w} \hat{f}_m^{(-k)}(x_i))^2$
- 2. Obtain the overall out-of-sample loss  $MSE(\tilde{w}) = \sum_{k=1}^{K} MSE_k(\tilde{w})$  for each  $\tilde{w} \in \mathcal{W}$ .
- 3. Choose  $w^* = \arg\min_{\tilde{w} \in \mathcal{W}} MSE(\tilde{w})$

## Bumping

### Bumping

To maintain original interpretation of the model, "Bumping" uses bootstrap sampling to estimate potential models, aiming to stochastically identify the optimal *single* (fitted) model.

- ▶ Draw bootstrap samples  $\mathbf{Z}^{*(1)}, \dots, \mathbf{Z}^{*(B)}$ , for  $b = 1, \dots, B$ 
  - By convention, the original training sample is included in the set of bootstrap samples.
- ▶ Fit the model to  $\mathbf{Z}^{*(b)}$  giving  $\hat{f}^{*(b)}(x)$ .
- ► Choose the model

$$\hat{b} = \arg\min_{b} \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{f}^{*(b)}(x_i))^2$$

▶ The prediction is

$$\hat{f}^{*(\hat{b})}(x)$$

- ▶ Bumping introduces variations in the data to navigate the model fitting process.
  - if certain data points lead to suboptimal solutions, any bootstrap sample that exclude these point should result in improved outcomes.
- ▶ When employing bumping to compare models based on the training data, it's crucial to match the complexity across the models.
  - ▶ For each bootstrap sample, the resulting model may vary but should maintain comparable complexity levels.
  - ▶ Models from the same family may be used as well.
    - E.g., in the context of decision trees, this could involve adjusting trees to have the same number of terminal nodes for each bootstrap sample.
- ▶ It's a standard practice to include the original training sample within the pool of bootstrap samples during the bumping process.