

StrategicInfluence2

June 13, 2021

1 Experimentation with Strategic Influence Network Model, Part 2

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```
[1]: import matplotlib.pyplot as plt
import numpy as np
```

This notebook implements modification for analysis of “bots”.

```
[2]: N = 5
M = 1
= 1
Q = 0.2 * np.identity(N)
```

Starting with the baseline infinite-horizon model for comparison:

```
[3]: A = np.array([
    [0.217, 0.2022, 0.2358, 0.1256, 0.1403],
    [0.2497, 0.0107, 0.2334, 0.1282, 0.378],
    [0.1285, 0.0907, 0.3185, 0.2507, 0.2116],
    [0.1975, 0.0629, 0.2863, 0.2396, 0.2137],
    [0.1256, 0.0711, 0.0253, 0.2244, 0.5536],
])
```

```
[4]: B = np.array([
    0.0791,
    0,
    0,
    0,
    0,
    0,
])
```

```
[5]: x = np.array([
    -0.98,
    -4.62,
    2.74,
    4.67,
    2.15,
])
```

```

[6]: K = np.zeros((N, N)) # the initial K is zero

K_t = [K, Q] # now the K_t matrices will be added on-demand
K = Q # start here to avoid division by zero caused by inverse of zero
      →matrix

while True:
    # iteratively construct each K_t using the discrete Riccati difference
    →equation
    K_new = ( * A.T * (K - (K @ B * (1/(B.T @ K @ B)) * B.T @ K)) @ A) + Q
    K_t.append(K_new)
    current_difference = np.max(np.abs(K - K_new))
    K = K_new
    print(current_difference)
    if current_difference == 0:
        break

```

```

0.05735777400000003
0.018849471778646265
0.0067461258790245116
0.0024623325659086093
0.0009042138120677334
0.00033258472349328994
0.0001223868536117667
4.5042563995456586e-05
1.6577808048701126e-05
6.101484085307973e-06
2.2456655787150837e-06
8.265231525306227e-07
3.0420409807829785e-07
1.1196315397032919e-07
4.120834706800025e-08
1.5166845668268536e-08
5.582199369413843e-09
2.0545438683683415e-09
7.56180562611064e-10
2.7831431603786427e-10
1.0243433878898145e-10
3.770123102597722e-11
1.3876066962126288e-11
5.107081424426951e-12
1.8797186029928525e-12
6.918354777951663e-13
2.5462965069777965e-13
9.370282327836321e-14
3.447242491461111e-14
1.2712053631958042e-14

```

```

4.6629367034256575e-15
1.7208456881689926e-15
6.661338147750939e-16
2.220446049250313e-16
1.1102230246251565e-16
2.0816681711721685e-17
2.168404344971009e-18
0.0

```

```

[7]: def L(t):
        return -1 * (1/(B.T @ K_t[t+1] @ B)) * B.T @ K_t[t+1] @ A

K_t.reverse()

x_t = x
payoff = 0
r_ts = []
payoffs = []
for t in range(len(K_t) - 1):
    r_t = L(t) @ x_t
    r_ts.append(r_t)
    x_t = A @ x_t + B * r_t
    payoff += -1 * (x_t.T @ Q @ x_t)
    payoffs.append(payoff)

old_length = len(K_t)

# division by zero is due to K_t[-1] being the zero matrix (last term)

```

```

c:\users\jbrig\appdata\local\programs\python\python37\lib\site-
packages\ipykernel_launcher.py:2: RuntimeWarning: divide by zero encountered in
double_scalars

```

```

c:\users\jbrig\appdata\local\programs\python\python37\lib\site-
packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in
multiply

```

```

c:\users\jbrig\appdata\local\programs\python\python37\lib\site-
packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in
matmul

```

A strategy purely using the steady-state K_t can also be used:

```

[8]: def steady_L(t):
        return -1 * (1/(B.T @ K_t[0] @ B)) * B.T @ K_t[0] @ A

steady_x_t = x

```

```

steady_payoff = 0
steady_r_ts = []
steady_payoffs = []
for t in range(len(K_t) - 1):
    steady_r_t = steady_L(t) @ steady_x_t
    steady_r_ts.append(steady_r_t)
    steady_x_t = A @ steady_x_t + B * steady_r_t
    steady_payoff += -1 * (steady_x_t.T @ Q @ steady_x_t)
    steady_payoffs.append(steady_payoff)

```

```

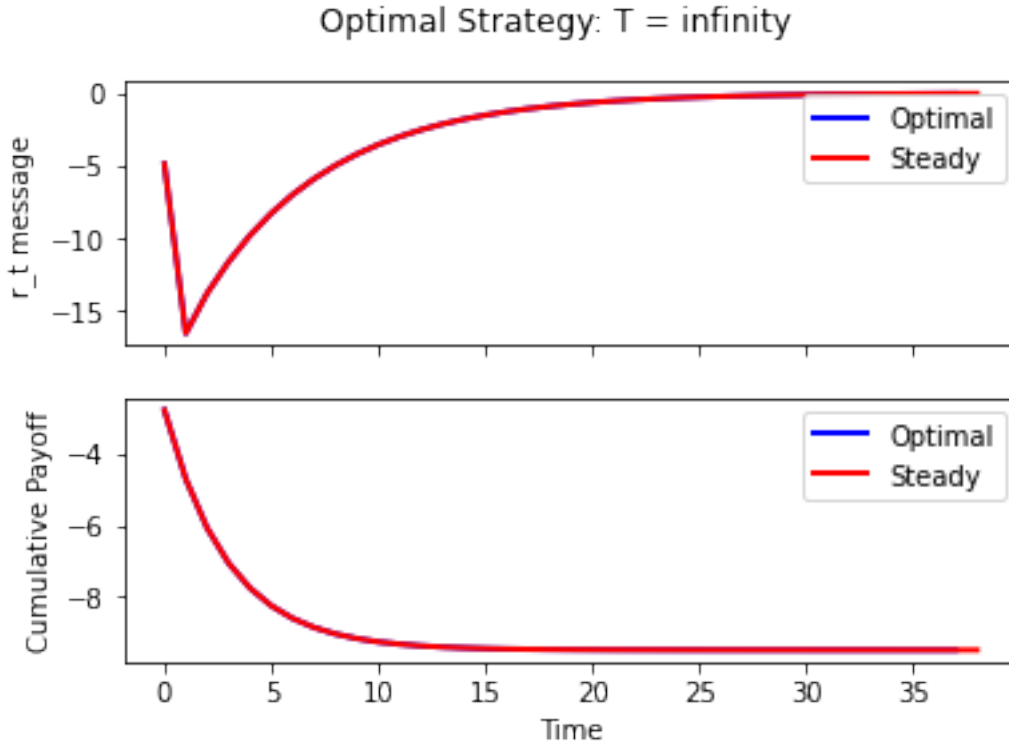
[9]: fig, sub = plt.subplots(2, sharex=True)
fig.suptitle("Optimal Strategy: T = infinity")

sub[0].plot(range(len(K_t) - 1), r_ts, 'b', label = "Optimal", linewidth=2)
sub[0].plot(range(len(K_t) - 1), steady_r_ts, 'r', label = "Steady",
    →linewidth=2)
sub[0].set(ylabel = "r_t message")

sub[1].plot(range(len(K_t) - 1), payoffs, 'b', label = "Optimal", linewidth=2)
sub[1].plot(range(len(K_t) - 1), steady_payoffs, 'r', label = "Steady",
    →linewidth=2)
sub[1].set(xlabel = "Time", ylabel = "Cumulative Payoff")

sub[0].legend()
sub[1].legend()
plt.show()

```



First change: to maintain parity with our five-agent network, A would be modified to have a sixth row/column as follows:

```
[10]: A = np.array([
    [1,      0,      0,      0,      0,      0      ],
    [0,      0.217,   0.2022,  0.2358,  0.1256,  0.1403],
    # proportionate shifting of agent 2's influence profile to the bot
    [0.1012,  0.8988*0.2497,  0.8988*0.0107,  0.8988*0.2334,  0.8988*0.1282,  0.8988*0.378 ],
    [0,      0.1285,   0.0907,  0.3185,  0.2507,  0.2116],
    [0,      0.1975,   0.0629,  0.2863,  0.2396,  0.2137],
    [0,      0.1256,   0.0711,  0.0253,  0.2244,  0.5536],
])
```

Likewise, B becomes:

```
[11]: B = np.array([
    0, # the robot does not care about the strategic agent
    0.0791,
    0,
    0,
    0,
    0,
])
```

The x initial opinion vector similarly has an extra entry for the (fixed) opinions of the bot:

```
[12]: x = np.array([
    2, # the robot, which is against the strategic agent
    -0.98,
    -4.62,
    2.74,
    4.67,
    2.15,
])
```

Additionally, Q needs to be modified. If the strategic agent's payoff was dependent on the bot, the fact that the bot's opinion never changes would result in infinite cost (i.e. a downward-sloping payoff function with no optimal solution - see the original notebook PDF file).

```
[13]: N = 6
Q = 0.2 * np.identity(N)
Q[0, :] = 0 # strategic agent does not care about the bot
Q
```

```
[13]: array([[0. , 0. , 0. , 0. , 0. , 0. ],
           [0. , 0.2, 0. , 0. , 0. , 0. ],
           [0. , 0. , 0.2, 0. , 0. , 0. ],
           [0. , 0. , 0. , 0.2, 0. , 0. ],
           [0. , 0. , 0. , 0. , 0.2, 0. ],
           [0. , 0. , 0. , 0. , 0. , 0.2]])
```

```
[14]: K = np.zeros((N, N)) # initial K

K_t = [K, Q] # saved K
K = Q
i = 0
while True:
    K_new = ( * A.T * (K - (K @ B * (1/(B.T @ K @ B)) * B.T @ K)) @ A) + Q
    K_t.append(K_new)
    current_difference = np.max(np.abs(K - K_new))
    K = K_new
    i += 1
    if i % 300 == 0:
        print(i, current_difference)
        break
    if abs(current_difference) == 0:
        break
```

300 1.2484611557303776e-20

```
[15]: K_t.reverse()

x_t = x
x_ts = [x]
payoff = 0
```

```

r_ts2 = []
payoffs2 = []
for t in range(len(K_t) - 1):
    r_t = L(t) @ x_t
    r_ts2.append(r_t)
    x_t = A @ x_t + B * r_t
    x_ts.append(x_t)
    payoff += -1 * (x_t.T @ Q @ x_t)
    payoffs2.append(payoff)

```

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: divide by zero encountered in double_scalars

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in multiply

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in matmul

[16]: `print("\n".join(str(x) for x in x_ts))` *# it converges sometime prior to 300*

```

[ 2.   -0.98 -4.62  2.74  4.67  2.15]
[2.         0.         1.78138488 1.953435  1.878701  1.85594   ]
[ 2.00000000e+00 -2.22044605e-16  1.47634774e+00  1.64744790e+00
  1.51806869e+00  1.62510726e+00]
[ 2.00000000e+00 -2.22044605e-16  1.28924533e+00  1.38306941e+00
  1.27554129e+00  1.38696275e+00]
[ 2.00000000e+00 -1.11022302e-16  1.12313039e+00  1.17070168e+00
  1.07907993e+00  1.18071104e+00]
[2.         0.         0.98427159 0.99510021 0.91668229 1.00526049]
[2.         0.         0.86777735 0.84873822 0.78126912 0.85737346]
[2.         0.         0.77010598 0.72631492 0.66798974 0.73313078]
[ 2.00000000e+00 -1.11022302e-16  6.88220956e-01  6.23775415e-01
  5.73104017e-01  6.28888402e-01]
[ 2.00000000e+00 -5.55111512e-17  6.19573434e-01  5.37844073e-01
  4.93585174e-01  5.41471189e-01]
[2.00000000e+00 5.55111512e-17 5.62024235e-01 4.65815754e-01
 4.26931328e-01 4.68178089e-01]
[2.         0.         0.51377935 0.40543608 0.37105678 0.40673184]
[2.         0.         0.47333457 0.35481957 0.32421687 0.35521913]
[ 2.00000000e+00 -5.55111512e-17  4.39428842e-01  3.12387017e-01
  2.84950279e-01  3.12034601e-01]
[ 2.00000000e+00 -5.55111512e-17  4.11004940e-01  2.76815018e-01

```

2.52032358e-01 2.75831980e-01]
 [2. 0. 0.38717658 0.24699429 0.2244366 0.24548252]
 [2.00000000e+00 -2.77555756e-17 3.67200750e-01 2.21994952e-01
 2.01302494e-01 2.20039904e-01]
 [2. 0. 0.35045459 0.20103748 0.18190869 0.19871082]
 [2. 0. 0.33641593 0.18346839 0.16565045 0.18083019]
 [2.00000000e+00 -2.77555756e-17 3.24647019e-01 1.68739840e-01
 1.52020819e-01 1.65840474e-01]
 [2.00000000e+00 -2.77555756e-17 3.14780892e-01 1.56392587e-01
 1.40594811e-01 1.53274279e-01]
 [2.00000000e+00 2.77555756e-17 3.06509907e-01 1.46041623e-01
 1.31016146e-01 1.42739770e-01]
 [2.00000000e+00 -2.77555756e-17 2.99576165e-01 1.37364189e-01
 1.22986147e-01 1.33908468e-01]
 [2. 0. 0.29376346 0.13008971 0.11625443 0.126505]
 [2.00000000e+00 -1.38777878e-17 2.88890549e-01 1.23991362e-01
 1.10611085e-01 1.20298513e-01]
 [2.00000000e+00 -1.38777878e-17 2.84805482e-01 1.18878986e-01
 1.05880151e-01 1.15095484e-01]
 [2.00000000e+00 -4.16333634e-17 2.81380883e-01 1.14593172e-01
 1.01914107e-01 1.10733674e-01]
 [2.00000000e+00 -1.38777878e-17 2.78509970e-01 1.11000284e-01
 9.85892890e-02 1.07077075e-01]
 [2.00000000e+00 -1.38777878e-17 2.76103222e-01 1.07988288e-01
 9.58020229e-02 1.04011671e-01]
 [2.00000000e+00 -1.38777878e-17 2.74085594e-01 1.05463269e-01
 9.34653985e-02 1.01441878e-01]
 [2.00000000e+00 -1.38777878e-17 2.72394173e-01 1.03346491e-01
 9.15065565e-02 9.92875655e-02]
 [2.00000000e+00 -1.38777878e-17 2.70976219e-01 1.01571952e-01
 8.98644176e-02 9.74815595e-02]
 [2. 0. 0.26978752 0.10008432 0.08848778 0.09596755]
 [2. 0. 0.268791 0.0988372 0.08733371 0.09469832]
 [2.00000000e+00 -1.38777878e-17 2.67955607e-01 9.77917180e-02
 8.63662324e-02 9.36342945e-02]
 [2.00000000e+00 -2.77555756e-17 2.67255275e-01 9.69152669e-02
 8.55551745e-02 9.27423021e-02]
 [2. 0. 0.26666817 0.09618052 0.08487525 0.09199453]
 [2.00000000e+00 -2.77555756e-17 2.66175990e-01 9.55645647e-02
 8.43052501e-02 9.13676492e-02]
 [2.00000000e+00 -1.38777878e-17 2.65763384e-01 9.50481969e-02
 8.38274092e-02 9.08421251e-02]
 [2.00000000e+00 -1.38777878e-17 2.65417488e-01 9.46153148e-02
 8.34268250e-02 9.04015670e-02]
 [2.00000000e+00 -1.38777878e-17 2.65127515e-01 9.42524205e-02
 8.30910067e-02 9.00322379e-02]
 [2. 0. 0.26488443 0.0939482 0.08280948 0.08972262]
 [2.00000000e+00 -1.38777878e-17 2.64680638e-01 9.36931627e-02

8.25734759e-02 8.94630633e-02]
 [2.00000000e+00 -1.38777878e-17 2.64509798e-01 9.34793608e-02
 8.23756261e-02 8.92454702e-02]
 [2. 0. 0.26436658 0.09330013 0.08220976 0.08906306]
 [2. 0. 0.26424652 0.09314987 0.08207072 0.08891014]
 [2. 0. 0.26414587 0.09302391 0.08195415 0.08878194]
 [2.00000000e+00 -1.38777878e-17 2.64061488e-01 9.29183093e-02
 8.18564354e-02 8.86744701e-02]
 [2.00000000e+00 -1.38777878e-17 2.63990752e-01 9.28297847e-02
 8.17745157e-02 8.85843758e-02]
 [2. 0. 0.26393145 0.09275557 0.08170584 0.08850885]
 [2. 0. 0.26388174 0.09269336 0.08164827 0.08844553]
 [2. 0. 0.26384007 0.0926412 0.08160001 0.08839245]
 [2.00000000e+00 -1.38777878e-17 2.63805129e-01 9.25974815e-02
 8.15595450e-02 8.83479533e-02]
 [2. 0. 0.26377584 0.09256083 0.08152563 0.08831065]
 [2. 0. 0.26375129 0.0925301 0.08149719 0.08827938]
 [2. 0. 0.2637307 0.09250434 0.08147335 0.08825316]
 [2.00000000e+00 -2.77555756e-17 2.63713449e-01 9.24827462e-02
 8.14533702e-02 8.82311835e-02]
 [2.00000000e+00 1.38777878e-17 2.63698984e-01 9.24646428e-02
 8.14366176e-02 8.82127592e-02]
 [2. 0. 0.26368686 0.09244947 0.08142257 0.08819731]
 [2.00000000e+00 -1.38777878e-17 2.63676691e-01 9.24367437e-02
 8.14108001e-02 8.81843654e-02]
 [2.00000000e+00 -2.77555756e-17 2.63668168e-01 9.24260780e-02
 8.14009301e-02 8.81735105e-02]
 [2.00000000e+00 -1.38777878e-17 2.63661024e-01 9.24171367e-02
 8.13926560e-02 8.81644107e-02]
 [2. 0. 0.26365503 0.09240964 0.08138572 0.08815678]
 [2. 0. 0.26365001 0.09240336 0.0813799 0.08815039]
 [2. 0. 0.2636458 0.09239809 0.08137503 0.08814503]
 [2. 0. 0.26364228 0.09239367 0.08137094 0.08814053]
 [2.00000000e+00 -1.38777878e-17 2.63639317e-01 9.23899711e-02
 8.13675173e-02 8.81367634e-02]
 [2.00000000e+00 -2.77555756e-17 2.63636837e-01 9.23868676e-02
 8.13646452e-02 8.81336048e-02]
 [2.00000000e+00 -1.38777878e-17 2.63634758e-01 9.23842658e-02
 8.13622376e-02 8.81309569e-02]
 [2.00000000e+00 -1.38777878e-17 2.63633015e-01 9.23820846e-02
 8.13602192e-02 8.81287370e-02]
 [2. 0. 0.26363155 0.09238026 0.08135853 0.08812688]
 [2.00000000e+00 1.38777878e-17 2.63630329e-01 9.23787232e-02
 8.13571086e-02 8.81253161e-02]
 [2.00000000e+00 -2.77555756e-17 2.63629302e-01 9.23774382e-02
 8.13559194e-02 8.81240082e-02]
 [2. 0. 0.26362844 0.09237636 0.08135492 0.08812291]
 [2.00000000e+00 -1.38777878e-17 2.63627720e-01 9.23754578e-02

8.13540868e-02 8.81219927e-02]
 [2. 0. 0.26362711 0.0923747 0.08135339 0.08812122]
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 [2. 0. 0.26362553 0.09237271 0.08135155 0.0881192]
 [2. 0. 0.26362528 0.0923724 0.08135126 0.08811888]
 [2.00000000e+00 -2.77555756e-17 2.63625067e-01 9.23721378e-02
 8.13510144e-02 8.81186138e-02]
 [2.00000000e+00 -1.38777878e-17 2.63624891e-01 9.23719174e-02
 8.13508106e-02 8.81183896e-02]
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 8.13506397e-02 8.81182016e-02]
 [2. 0. 0.26362462 0.09237158 0.0813505 0.08811804]
 [2. 0. 0.26362452 0.09237145 0.08135038 0.08811791]
 [2.00000000e+00 -1.38777878e-17 2.63624429e-01 9.23713393e-02
 8.13502756e-02 8.81178012e-02]
 [2.00000000e+00 -1.38777878e-17 2.63624356e-01 9.23712481e-02
 8.13501912e-02 8.81177084e-02]
 [2.00000000e+00 -2.77555756e-17 2.63624295e-01 9.23711717e-02
 8.13501204e-02 8.81176306e-02]
 [2. 0. 0.26362424 0.09237111 0.08135006 0.08811757]
 [2.00000000e+00 -1.38777878e-17 2.63624201e-01 9.23710538e-02
 8.13500114e-02 8.81175106e-02]
 [2.00000000e+00 -1.38777878e-17 2.63624165e-01 9.23710088e-02
 8.13499697e-02 8.81174648e-02]
 [2. 0. 0.26362413 0.09237097 0.08134993 0.08811743]
 [2.00000000e+00 -1.38777878e-17 2.63624109e-01 9.23709393e-02
 8.13499054e-02 8.81173941e-02]
 [2. 0. 0.26362409 0.09237091 0.08134988 0.08811737]
 [2.00000000e+00 -1.38777878e-17 2.63624070e-01 9.23708905e-02
 8.13498603e-02 8.81173445e-02]
 [2.00000000e+00 -1.38777878e-17 2.63624055e-01 9.23708719e-02
 8.13498430e-02 8.81173255e-02]
 [2.00000000e+00 -1.38777878e-17 2.63624043e-01 9.23708562e-02
 8.13498285e-02 8.81173096e-02]
 [2. 0. 0.26362403 0.09237084 0.08134982 0.0881173]
 [2.00000000e+00 -1.38777878e-17 2.63624024e-01 9.23708321e-02
 8.13498062e-02 8.81172850e-02]
 [2.00000000e+00 -1.38777878e-17 2.63624016e-01 9.23708229e-02
 8.13497977e-02 8.81172757e-02]
 [2. 0. 0.26362401 0.09237082 0.08134979 0.08811727]
 [2.00000000e+00 -1.38777878e-17 2.63624005e-01 9.23708087e-02
 8.13497846e-02 8.81172612e-02]
 [2. 0. 0.263624 0.0923708 0.08134978 0.08811726]
 [2.00000000e+00 -2.77555756e-17 2.63623997e-01 9.23707987e-02

8.13497753e-02 8.81172510e-02]
 [2.00000000e+00 -1.38777878e-17 2.63623994e-01 9.23707949e-02
 8.13497718e-02 8.81172472e-02]
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[2.00000000e+00	-2.77555756e-17	2.63623978e-01	9.23707752e-02		

[illegible]

[illegible]

[illegible]

```
[17]: fig, sub = plt.subplots(2, sharex=True)
fig.suptitle("Optimal Strategy: T = infinity")

sub[0].plot(range(old_length - 1), r_ts, 'b', label = "Optimal-Original",
             linewidth=2)
sub[0].plot(range(len(K_t) - 1), r_ts2, 'r', label = "Optimal-New", linewidth=2)
sub[0].set(ylabel = "r t message")
```



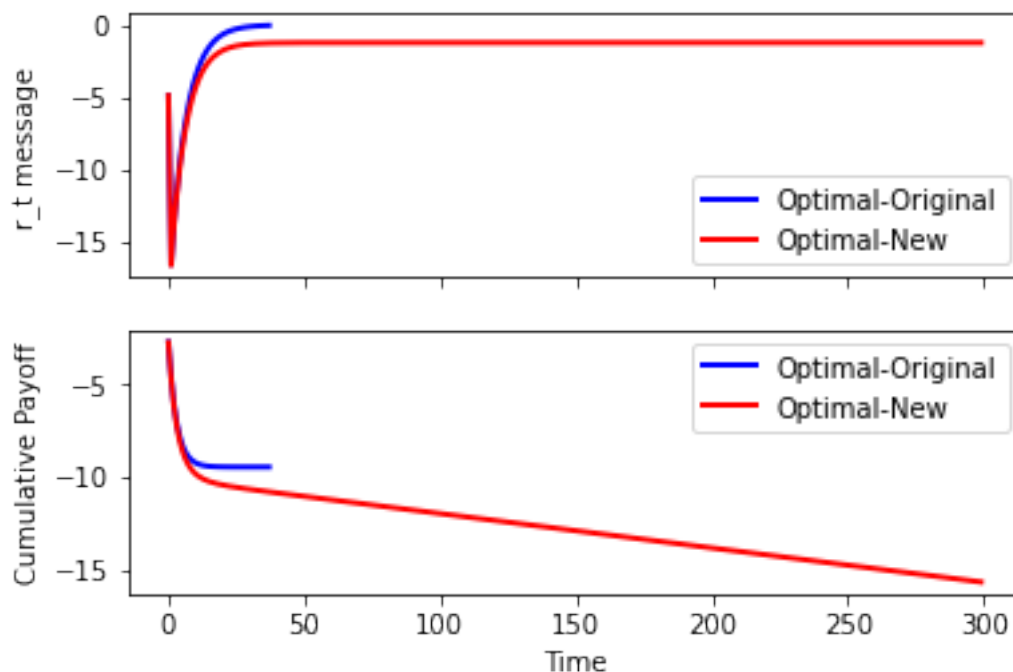
```

sub[1].plot(range(old_length - 1), payoffs, 'b', label = "Optimal-Original",
            linewidth=2)
sub[1].plot(range(len(K_t) - 1), payoffs2, 'r', label = "Optimal-New",
            linewidth=2)
sub[1].set(xlabel = "Time", ylabel = "Cumulative Payoff")

sub[0].legend()
sub[1].legend()
plt.show()

```

Optimal Strategy: $T = \text{infinity}$



We still see eternally decreasing cumulative payoff.

```

[18]: fig, sub = plt.subplots(2, sharex=True)
fig.suptitle("Optimal Strategy: T = infinity")

sub[0].plot(range(old_length - 1), r_ts, 'b', label = "Optimal-Original",
            linewidth=2)
sub[0].plot(range(old_length - 1), r_ts2[:old_length - 1], 'r', label =
            "Optimal-New", linewidth=2)
sub[0].set(ylabel = "r_t message")

sub[1].plot(range(old_length - 1), payoffs, 'b', label = "Optimal-Original",
            linewidth=2)

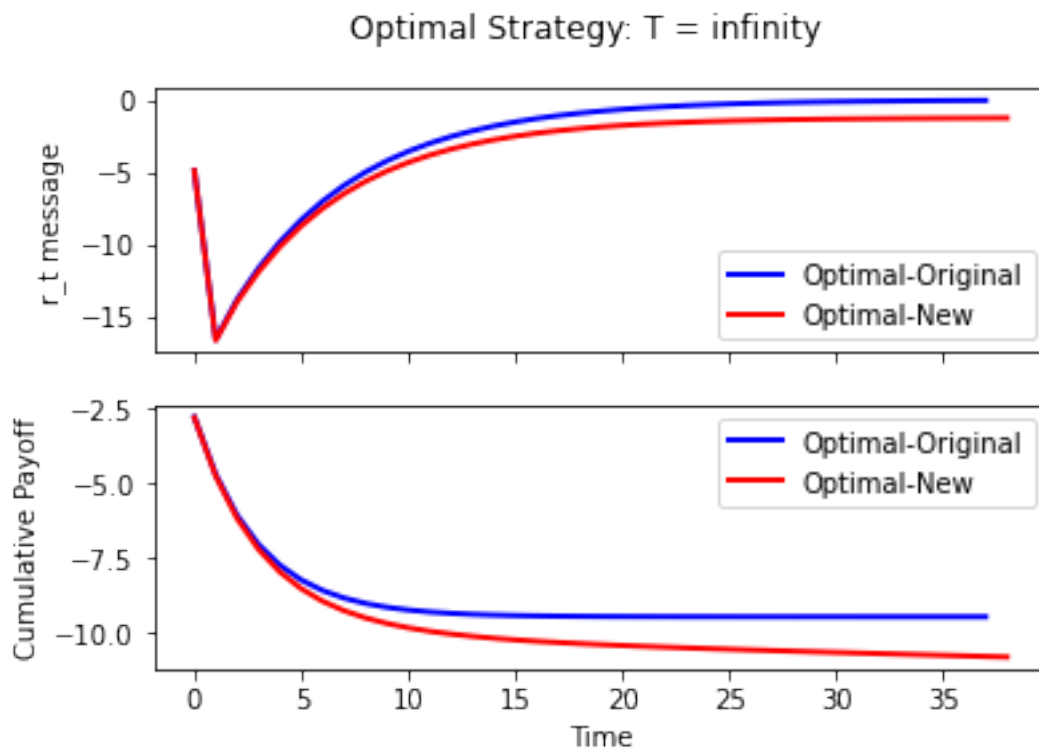
```

```

sub[1].plot(range(old_length - 1), payoffs2[:old_length - 1], 'r', label = "Optimal-New", linewidth=2)
sub[1].set(xlabel = "Time", ylabel = "Cumulative Payoff")

sub[0].legend()
sub[1].legend()
plt.show()

```



Locally the two trajectories are extremely similar, but the solution does not converge to exactly zero; rather it stops short and payoff is continuously decreasing (albeit at a very slow rate). A possible explanation is that, due to the bot essentially having a “proxy” through the agent that listens to it, the fact that this “proxy” agent is in fact part of the Q payoff matrix results in this infinitely decreasing payoff.

Next: what happens if the bot has a lesser agenda? This becomes:

```

[19]: x = np.array([
    0.5, # the robot, which is against the strategic agent
    -0.98,
    -4.62,
    2.74,
    4.67,
    2.15,
    ])

```

```
[20]: K = np.zeros((N, N)) # initial K

K_t = [K, Q] # saved K
K = Q
i = 0
while True:
    K_new = ( * A.T * (K - (K @ B * (1/(B.T @ K @ B)) * B.T @ K)) @ A) + Q
    K_t.append(K_new)
    current_difference = np.max(np.abs(K - K_new))
    K = K_new
    i += 1
    if i % 300 == 0:
        print(i, current_difference)
        break
    if abs(current_difference) == 0:
        break
```

300 1.2484611557303776e-20

```
[21]: K_t.reverse()

x_t = x
x_ts = [x]
payoff = 0
r_ts2 = []
payoffs2 = []
for t in range(len(K_t) - 1):
    r_t = L(t) @ x_t
    r_ts2.append(r_t)
    x_t = A @ x_t + B * r_t
    x_ts.append(x_t)
    payoff += -1 * (x_t.T @ Q @ x_t)
    payoffs2.append(payoff)
```

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: divide by zero encountered in double_scalars

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in multiply

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in matmul

```
[22]: print("\n".join(str(x) for x in x_ts))
```

```
[ 0.5 -0.98 -4.62  2.74  4.67  2.15]
[0.5      0.      1.62958488 1.953435  1.878701  1.85594  ]
[ 5.00000000e-01 -2.22044605e-16  1.32308785e+00  1.63367964e+00
  1.50852047e+00  1.61431428e+00]
[ 5.00000000e-01 -2.22044605e-16  1.12831602e+00  1.36010602e+00
  1.25736517e+00  1.36760002e+00]
[ 5.00000000e-01 -1.11022302e-16  9.56292670e-01  1.14013764e+00
  1.05389025e+00  1.15389007e+00]
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[0.5      0.      0.6917617  0.8066279  0.74539715 0.81892063]
[0.5      0.      0.59058171 0.67980844 0.62804988 0.69021352]
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 2.03380835e-02 2.20300163e-02]

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```


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[illegible]

[illegible]

[illegible]

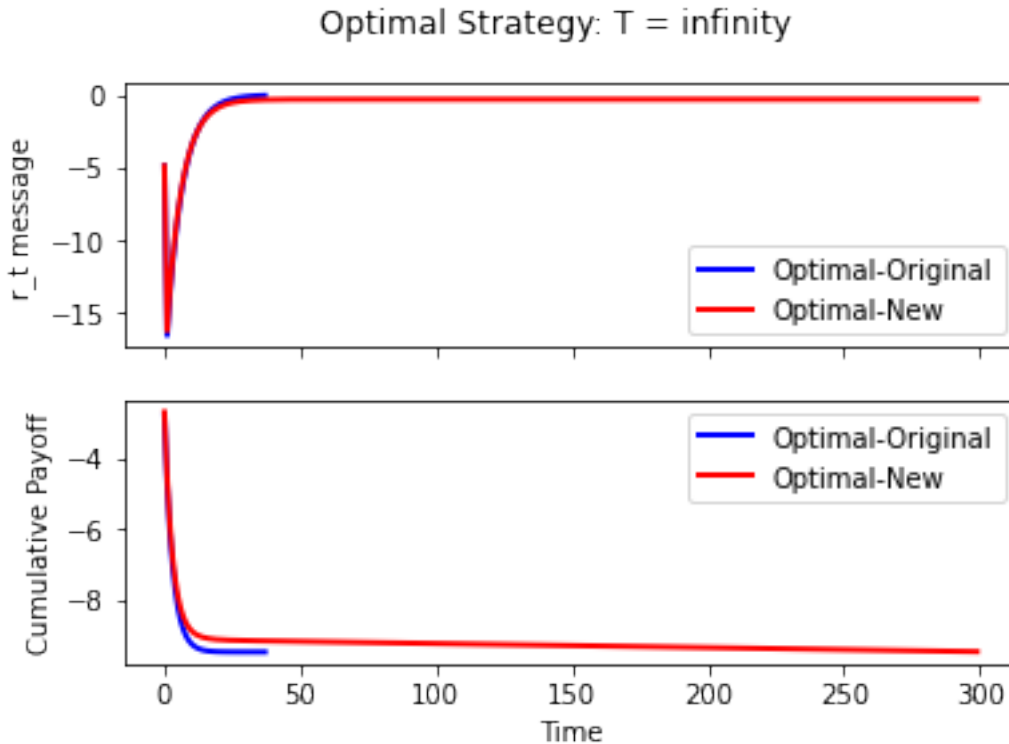
[illegible]

```
[23]: fig, sub = plt.subplots(2, sharex=True)
fig.suptitle("Optimal Strategy: T = infinity")

sub[0].plot(range(old_length - 1), r_ts, 'b', label = "Optimal-Original",
            linewidth=2)
sub[0].plot(range(len(K_t) - 1), r_ts2, 'r', label = "Optimal-New", linewidth=2)
sub[0].set(ylabel = "r_t message")

sub[1].plot(range(old_length - 1), payoffs, 'b', label = "Optimal-Original",
            linewidth=2)
sub[1].plot(range(len(K_t) - 1), payoffs2, 'r', label = "Optimal-New",
            linewidth=2)
sub[1].set(xlabel = "Time", ylabel = "Cumulative Payoff")

sub[0].legend()
sub[1].legend()
plt.show()
```



```
[24]: r_ts[-2]
```

```
[24]: -0.03727761846790481
```

As expected the cost is still decreasing, but is much closer to the original problem. Just for fun, this is what happens if the superbots are too much in favour:

```
[25]: x = np.array([
    -0.5, # the robot, which is now ahead of the strategic agent
    -0.98,
    -4.62,
    2.74,
    4.67,
    2.15,
])
```

```
[26]: K = np.zeros((N, N)) # initial K

K_t = [K, Q] # saved K
K = Q
i = 0
while True:
    K_new = ( * A.T * (K - (K @ B * (1/(B.T @ K @ B)) * B.T @ K)) @ A) + Q
    K_t.append(K_new)
    current_difference = np.max(np.abs(K - K_new))
```

```

K = K_new
i += 1
if i % 300 == 0:
    print(i, current_difference)
    break
if abs(current_difference) == 0:
    break

K_t.reverse()

x_t = x
x_ts = [x]
payoff = 0
r_ts2 = []
payoffs2 = []
for t in range(len(K_t) - 1):
    r_t = L(t) @ x_t
    r_ts2.append(r_t)
    x_t = A @ x_t + B * r_t
    x_ts.append(x_t)
    payoff += -1 * (x_t.T @ Q @ x_t)
    payoffs2.append(payoff)

print("\n".join(str(x) for x in x_ts))

fig, sub = plt.subplots(2, sharex=True)
fig.suptitle("Optimal Strategy: T = infinity")

sub[0].plot(range(old_length - 1), r_ts, 'b', label = "Optimal-Original",
    →linewidth=2)
sub[0].plot(range(len(K_t) - 1), r_ts2, 'r', label = "Optimal-New", linewidth=2)
sub[0].set(ylabel = "r_t message")

sub[1].plot(range(old_length - 1), payoffs, 'b', label = "Optimal-Original",
    →linewidth=2)
sub[1].plot(range(len(K_t) - 1), payoffs2, 'r', label = "Optimal-New",
    →linewidth=2)
sub[1].set(xlabel = "Time", ylabel = "Cumulative Payoff")

sub[0].legend()
sub[1].legend()
plt.show()

```

```

300 1.2484611557303776e-20
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[-5.00000000e-01 -2.22044605e-16  1.22091460e+00  1.62450080e+00

```

1.50215499e+00 1.60711896e+00]
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[-0.5 0. -0.06579288 -0.02295113 -0.02020644 -0.02188523]
[-5.00000000e-01 3.46944695e-18 -6.58111670e-02 -2.29740191e-02
-2.02276182e-02 -2.19085278e-02]
[-5.00000000e-01 -3.46944695e-18 -6.58264986e-02 -2.29932063e-02
-2.02453738e-02 -2.19280551e-02]
[-5.00000000e-01 6.93889390e-18 -6.58393514e-02 -2.30092913e-02
-2.02602587e-02 -2.19444254e-02]
[-0.5 0. -0.06585013 -0.02302278 -0.02027274 -0.02195815]

```

```

[-5.00000000e-01  3.46944695e-18 -6.58591589e-02 -2.30340800e-02
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-2.03242069e-02 -2.20147549e-02]
[-5.00000000e-01  6.93889390e-18 -6.58964166e-02 -2.30807072e-02
-2.03263462e-02 -2.20171077e-02]
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[-5.00000000e-01  3.46944695e-18 -6.59003516e-02 -2.30856318e-02
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[-0.5          0.          -0.06590126 -0.02308677 -0.02033196 -0.02202328]
[-5.00000000e-01  3.46944695e-18 -6.59020288e-02 -2.30877308e-02
-2.03328456e-02 -2.20242557e-02]
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[-0.5          0.          -0.06590321 -0.02308921 -0.02033421 -0.02202576]
[-5.00000000e-01  3.46944695e-18 -6.59036581e-02 -2.30897698e-02
-2.03347325e-02 -2.20263309e-02]
[-5.00000000e-01  6.93889390e-18 -6.59040359e-02 -2.30902425e-02
-2.03351700e-02 -2.20268120e-02]
[-5.00000000e-01  6.93889390e-18 -6.59043525e-02 -2.30906388e-02
-2.03355368e-02 -2.20272154e-02]
[-5.00000000e-01  3.46944695e-18 -6.59046180e-02 -2.30909711e-02
-2.03358442e-02 -2.20275535e-02]
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-2.03363180e-02 -2.20280746e-02]
[-5.00000000e-01  3.46944695e-18 -6.59051836e-02 -2.30916788e-02
-2.03364992e-02 -2.20282738e-02]
[-0.5          0.          -0.06590531 -0.02309184 -0.02033665 -0.02202844]
[-0.5          0.          -0.06590542 -0.02309198 -0.02033678 -0.02202858]
[-0.5          0.          -0.06590552 -0.0230921  -0.02033689 -0.0220287 ]
[-0.5          0.          -0.06590559 -0.02309219 -0.02033697 -0.0220288 ]
[-5.00000000e-01  3.46944695e-18 -6.59056588e-02 -2.30922736e-02
-2.03370495e-02 -2.20288791e-02]
[-5.00000000e-01  3.46944695e-18 -6.59057130e-02 -2.30923415e-02
-2.03371124e-02 -2.20289482e-02]
[-5.00000000e-01  3.46944695e-18 -6.59057586e-02 -2.30923985e-02
-2.03371651e-02 -2.20290062e-02]

```

```

[-0.5      0.      -0.0659058 -0.02309245 -0.02033721 -0.02202905]
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[-0.5      0.      -0.06590598 -0.02309268 -0.02033742 -0.02202929]
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-2.03374269e-02 -2.20292942e-02]
[-0.5      0.      -0.06590599 -0.02309268 -0.02033743 -0.0220293 ]
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-2.03374303e-02 -2.20292979e-02]
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-2.03374316e-02 -2.20292994e-02]
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-2.03374327e-02 -2.20293006e-02]
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[-0.5      0.      -0.06590599 -0.02309269 -0.02033744 -0.0220293 ]
[-0.5      0.      -0.06590599 -0.02309269 -0.02033744 -0.0220293 ]
[-5.00000000e-01  3.46944695e-18 -6.59059931e-02 -2.30926920e-02
-2.03374367e-02 -2.20293050e-02]

```

```

[-5.00000000e-01  3.46944695e-18 -6.59059934e-02 -2.30926923e-02
-2.03374370e-02 -2.20293052e-02]
[-5.00000000e-01  6.93889390e-18 -6.59059935e-02 -2.30926925e-02
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[-5.00000000e-01  3.46944695e-18 -6.59059937e-02 -2.30926927e-02
-2.03374374e-02 -2.20293057e-02]
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-2.03374381e-02 -2.20293065e-02]
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-2.03374382e-02 -2.20293066e-02]
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-2.03374382e-02 -2.20293066e-02]
[-5.00000000e-01  1.04083409e-17 -6.59059944e-02 -2.30926937e-02
-2.03374383e-02 -2.20293066e-02]
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-2.03374383e-02 -2.20293067e-02]
[-0.5          0.          -0.06590599 -0.02309269 -0.02033744 -0.02202931]
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-2.03374383e-02 -2.20293067e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
-2.03374383e-02 -2.20293067e-02]
[-5.00000000e-01 -3.46944695e-18 -6.59059945e-02 -2.30926938e-02
-2.03374383e-02 -2.20293067e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
-2.03374384e-02 -2.20293067e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
-2.03374384e-02 -2.20293067e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
-2.03374384e-02 -2.20293067e-02]

```

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

```

[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
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[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[-5.00000000e-01  3.46944695e-18 -6.59059945e-02 -2.30926938e-02
 -2.03374384e-02 -2.20293068e-02]
[nan nan nan nan nan nan]

```

```

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-
packages\ipykernel_launcher.py:2: RuntimeWarning: divide by zero encountered in
double_scalars

```

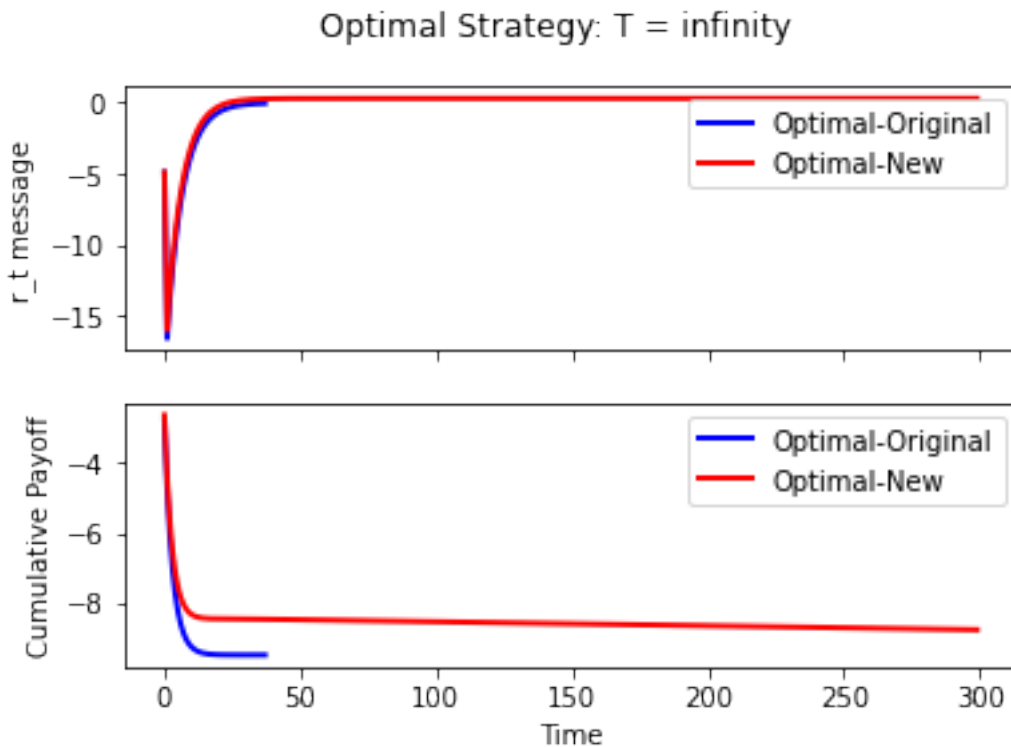
```

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-
packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in

```

multiply

```
c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-  
packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in  
matmul
```



Also as expected, a bot pushing an agenda in the opposite direction will push all the metrics in the opposite direction - it should be noted that because this push is not exactly at zero, the long-term cumulative payoff will still dip below the original cumulative payoff, even though the local payoff is much higher.

Finally: applying the modification to Q for the superbots case (no adjustment to A as this is an entirely new network):

```
[27]: A = np.array([  
    [1,      0,      0,      0,      0],  
    [0.8,    0,      0,      0,      0],  
    [0.8,    0,      0,      0,      0],  
    [0.2,    0,      0,      0,      0],  
    [0.2,    0,      0,      0,      0],  
])
```

```
[28]: B = np.array([  
    0,  
    0.2,
```

```

    0.2,
    0.8,
    0.8,
])

```

```

[29]: x = np.array([
    10,
    1,
    1,
    -1,
    -1,
])

```

```

[30]: N = 5
Q = 0.2 * np.identity(N)
Q[0, :] = 0 # strategic agent does not care about the bot
Q

```

```

[30]: array([[0. , 0. , 0. , 0. , 0. ],
            [0. , 0.2, 0. , 0. , 0. ],
            [0. , 0. , 0.2, 0. , 0. ],
            [0. , 0. , 0. , 0.2, 0. ],
            [0. , 0. , 0. , 0. , 0.2]])

```

```

[31]: K = np.zeros((N, N)) # initial K

K_t = [K, Q] # saved K
K = Q

i = 0
while True:
    K_new = ( * A.T * (K - (K @ B * (1/(B.T @ K @ B)) * B.T @ K)) @ A) + Q
    K_t.append(K_new)
    current_difference = np.max(np.abs(K - K_new))
    K = K_new
    i += 1
    if i % 1000000 == 0:
        print(i, current_difference)
        break
    if current_difference == 0:
        break

```

```

1000000 0.015058823526487686

```

```

[32]: K_t.reverse()

x_t = x
payoff = 0
r_ts2 = []

```

```

payoffs2 = []
x_ts = []
for t in range(len(K_t) - 1):
    r_t = L(t) @ x_t
    r_ts2.append(r_t)
    x_t = A @ x_t + B * r_t
    x_ts.append(x_t)
    payoff += -1 * (x_t.T @ Q @ x_t)
    payoffs2.append(payoff)

```

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: divide by zero encountered in double_scalars

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in multiply

c:\users\jbrigg\appdata\local\programs\python\python37\lib\site-packages\ipykernel_launcher.py:2: RuntimeWarning: invalid value encountered in matmul

```

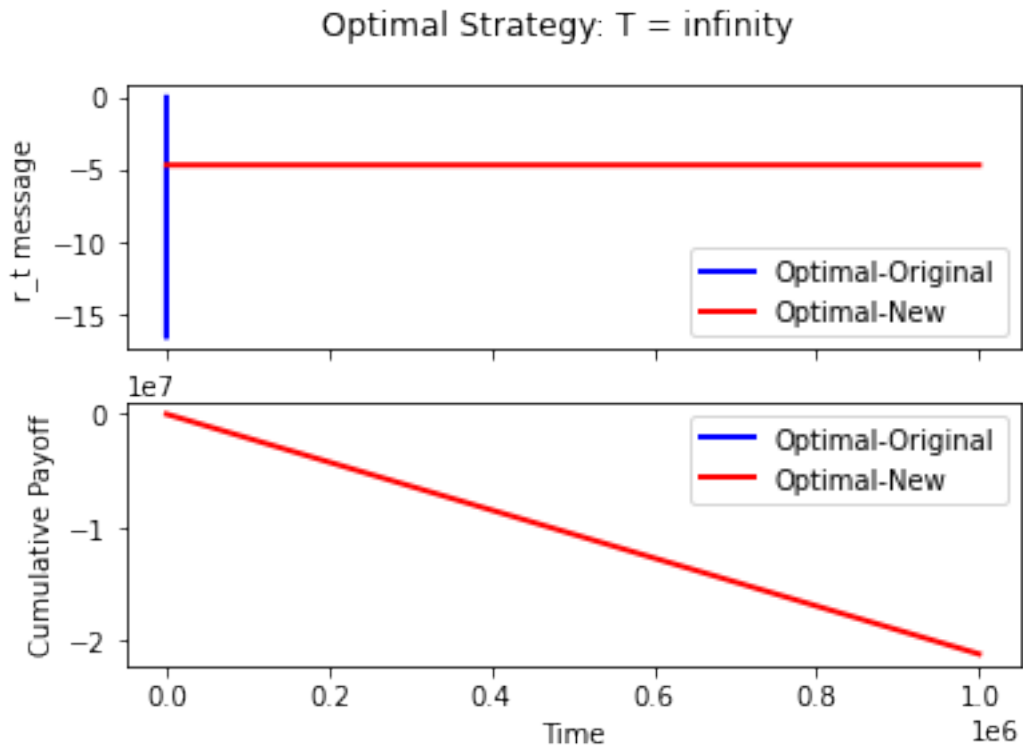
[33]: fig, sub = plt.subplots(2, sharex=True)
fig.suptitle("Optimal Strategy: T = infinity")

sub[0].plot(range(old_length - 1), r_ts, 'b', label = "Optimal-Original",
            linewidth=2)
sub[0].plot(range(len(K_t) - 1), r_ts2, 'r', label = "Optimal-New", linewidth=2)
sub[0].set(ylabel = "r_t message")

sub[1].plot(range(old_length - 1), payoffs, 'b', label = "Optimal-Original",
            linewidth=2)
sub[1].plot(range(len(K_t) - 1), payoffs2, 'r', label = "Optimal-New",
            linewidth=2)
sub[1].set(xlabel = "Time", ylabel = "Cumulative Payoff")

sub[0].legend()
sub[1].legend()
plt.show()

```



This continues to be an extreme case of the anomaly found earlier.

```
[34]: for i in range(0, 1000000, 100000):
      print(x_ts[i])
```

```
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
[10.      7.05882353  7.05882353 -1.76470588 -1.76470588]
```