Colby Community College

Let us extend Variation of Parameters to solve

$$y'' + p(t)y' + q(t)y = f(t)$$

Let us extend Variation of Parameters to solve

$$y'' + p(t)y' + q(t)y = f(t)$$

We first need to find two linearly independent solutions to the associated homogeneous equation

$$y'' + p(t)y' + q(t)y = 0$$

Let us extend Variation of Parameters to solve

$$y'' + p(t)y' + q(t)y = f(t)$$

We first need to find two linearly independent solutions to the associated homogeneous equation

$$y'' + p(t)y' + q(t)y = 0$$

Which gives the general solution

$$y_h = c_1 y_1(t) + c_2 y_2(t)$$

where c_1 and c_2 are arbitrary constants.

Let us extend Variation of Parameters to solve

$$y'' + p(t)y' + q(t)y = f(t)$$

We first need to find two linearly independent solutions to the associated homogeneous equation

$$y'' + p(t)y' + q(t)y = 0$$

Which gives the general solution

$$y_h = c_1 y_1(t) + c_2 y_2(t)$$

where c_1 and c_2 are arbitrary constants.

Just like with single order equations, we want to perturb the homogeneous solution into a particular solution to the nonhomogeneous DE.

We do so by replacing the constants c_1 and c_2 with unknown functions.

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

We do so by replacing the constants c_1 and c_2 with unknown functions.

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

To find $v_1(t)$ and $v_2(t)$ we substitute y_p into the nonhomogeneous DE.

We do so by replacing the constants c_1 and c_2 with unknown functions.

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

To find $v_1(t)$ and $v_2(t)$ we substitute y_p into the nonhomogeneous DE.

But, we need two equations and we only have L(y) = f. Thus, we must choose an auxiliary condition.

We do so by replacing the constants c_1 and c_2 with unknown functions.

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

To find $v_1(t)$ and $v_2(t)$ we substitute y_p into the nonhomogeneous DE.

But, we need two equations and we only have L(y) = f. Thus, we must choose an auxiliary condition.

Let us calculate

$$y_p' = v_1 y_1' + v_2 y_2' + v_1' y_1 + v_2' y_2$$

We do so by replacing the constants c_1 and c_2 with unknown functions.

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

To find $v_1(t)$ and $v_2(t)$ we substitute y_p into the nonhomogeneous DE.

But, we need two equations and we only have L(y) = f. Thus, we must choose an auxiliary condition.

Let us calculate

$$y_p' = v_1 y_1' + v_2 y_2' + v_1' y_1 + v_2' y_2$$

So, we can choose $v_1y_1' + v_2y_2' = 0$ as our auxiliary condition, which reduces y_p' to:

$$y_p' = v_1' y_1 + v_2' y_2$$

We can then obtain

$$y_p'' = v_1 y_1'' + v_2 y_2'' + v_1' y_1' + v_2' y_2'$$

We can then obtain

$$y_p'' = v_1 y_1'' + v_2 y_2'' + v_1' y_1' + v_2' y_2'$$

$$(v_1y_1'' + v_2y_2'' + v_1'y_1' + v_2'y_2') + p \cdot (v_1'y_1 + v_2'y_2) + q \cdot (v_1y_1 + v_2y_2) = f$$

We can then obtain

$$y_p'' = v_1 y_1'' + v_2 y_2'' + v_1' y_1' + v_2' y_2'$$

$$(v_1y_1'' + v_2y_2'' + v_1'y_1' + v_2'y_2') + p \cdot (v_1'y_1 + v_2'y_2) + q \cdot (v_1y_1 + v_2y_2) = f$$

$$v_1(y_1'' + py_1' + qy_1) + v_2(y_2'' + py_2' + qy_2) + (v_1'y_1' + v_2'y_2') = f$$

We can then obtain

$$y_p'' = v_1 y_1'' + v_2 y_2'' + v_1' y_1' + v_2' y_2'$$

$$(v_1y_1'' + v_2y_2'' + v_1'y_1' + v_2'y_2') + p \cdot (v_1'y_1 + v_2'y_2) + q \cdot (v_1y_1 + v_2y_2) = f$$

$$v_1(y_1'' + py_1' + qy_1) + v_2(y_2'' + py_2' + qy_2) + (v_1'y_1' + v_2'y_2') = f$$

$$v_1 \cdot 0 + v_2 \cdot 0 + v_1'y_1' + v_2'y_2' = f$$

We can then obtain

$$y_p'' = v_1 y_1'' + v_2 y_2'' + v_1' y_1' + v_2' y_2'$$

$$(v_1y_1'' + v_2y_2'' + v_1'y_1' + v_2'y_2') + p \cdot (v_1'y_1 + v_2'y_2) + q \cdot (v_1y_1 + v_2y_2) = f$$

$$v_1(y_1'' + py_1' + qy_1) + v_2(y_2'' + py_2' + qy_2) + (v_1'y_1' + v_2'y_2') = f$$

$$v_1 \cdot 0 + v_2 \cdot 0 + v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1' + v_2'y_2' = f$$

We can then obtain

$$y_p'' = v_1 y_1'' + v_2 y_2'' + v_1' y_1' + v_2' y_2'$$

We then substitute y_p , y'_p , and y''_p into L(y) = f.

$$(v_1y_1'' + v_2y_2'' + v_1'y_1' + v_2'y_2') + p \cdot (v_1'y_1 + v_2'y_2) + q \cdot (v_1y_1 + v_2y_2) = f$$

$$v_1(y_1'' + py_1' + qy_1) + v_2(y_2'' + py_2' + qy_2) + (v_1'y_1' + v_2'y_2') = f$$

$$v_1 \cdot 0 + v_2 \cdot 0 + v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1' + v_2'y_2' = f$$

So, we have the system

$$v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1 + v_2'y_2 = 0$$

Using Cramer's Rule, the system

$$v'_1y'_1 + v'_2y'_2 = f$$

 $v'_1y_1 + v'_2y_2 = 0$

has solution

$$v_1' = \frac{\begin{vmatrix} 0 & y_2 \\ f & y_2' \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} \quad \text{and} \quad v_2' = \frac{\begin{vmatrix} y_1 & 0 \\ y_1' & f \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

Using Cramer's Rule, the system

$$v'_1y'_1 + v'_2y'_2 = f$$

 $v'_1y_1 + v'_2y_2 = 0$

has solution

$$v_1' = \frac{\begin{vmatrix} 0 & y_2 \\ f & y_2' \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} \quad \text{and} \quad v_2' = \frac{\begin{vmatrix} y_1 & 0 \\ y_1' & f \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

The denominator is just the Wronskian $W(y_1, y_2) = y_1y_2' - y_2y_1' \neq 0$, because y_1 and y_2 are linearly independent.

Using Cramer's Rule, the system

$$v'_1y'_1 + v'_2y'_2 = f$$

 $v'_1y_1 + v'_2y_2 = 0$

has solution

$$v_1' = \frac{\begin{vmatrix} 0 & y_2 \\ f & y_2' \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} \quad \text{and} \quad v_2' = \frac{\begin{vmatrix} y_1 & 0 \\ y_1' & f \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

The denominator is just the Wronskian $W(y_1, y_2) = y_1 y_2' - y_2 y_1' \neq 0$, because y_1 and y_2 are linearly independent.

Thus, we can integrate to find v_1 and v_2 .

Using Cramer's Rule, the system

$$v'_1y'_1 + v'_2y'_2 = f$$

 $v'_1y_1 + v'_2y_2 = 0$

has solution

$$v_1' = \frac{\begin{vmatrix} 0 & y_2 \\ f & y_2' \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} \quad \text{and} \quad v_2' = \frac{\begin{vmatrix} y_1 & 0 \\ y_1' & f \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

The denominator is just the Wronskian $W(y_1, y_2) = y_1y_2' - y_2y_1' \neq 0$, because y_1 and y_2 are linearly independent.

Thus, we can integrate to find v_1 and v_2 .

$$v_1 = -\int rac{y_2 f}{W(y_1, y_2)}$$
 and $v_2 = \int rac{y_1 f}{W(y_1, y_2)}$

Consider

$$y'' + y = \sec(t) \quad |t| < \frac{\pi}{2}$$

Consider

$$y'' + y = \sec(t) \quad |t| < \frac{\pi}{2}$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

Consider

$$y'' + y = \sec(t) \quad |t| < \frac{\pi}{2}$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is

$$W(y_1, y_2) = \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = \cos^2(t) + \sin^2(t) = 1$$

Consider

$$y'' + y = \sec(t) \quad |t| < \frac{\pi}{2}$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is

$$W(y_1, y_2) = \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = \cos^2(t) + \sin^2(t) = 1$$

So,

$$v_1' = -\frac{y_2 f}{1} = -\sin(t)\sec(t) = -\frac{\sin(t)}{\cos(t)}$$

$$v_2' = \frac{y_1 f}{1} = \cos(t) \sec(t) = 1$$

Consider

$$y'' + y = \sec(t) \quad |t| < \frac{\pi}{2}$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is

$$W(y_1, y_2) = \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = \cos^2(t) + \sin^2(t) = 1$$

So,

$$v_1' = -\frac{y_2 f}{1} = -\sin(t)\sec(t) = -\frac{\sin(t)}{\cos(t)}$$
 $v_2' = \frac{y_1 f}{1} = \cos(t)\sec(t) = 1$

Integrating gives $v_1 = \ln(\cos(t))$ and $v_2 = t$.

Consider

$$y'' + y = \sec(t) \quad |t| < \frac{\pi}{2}$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is

$$W(y_1, y_2) = \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = \cos^2(t) + \sin^2(t) = 1$$

So,

$$v'_1 = -\frac{y_2 f}{1} = -\sin(t)\sec(t) = -\frac{\sin(t)}{\cos(t)}$$
 $v'_2 = \frac{y_1 f}{1} = \cos(t)\sec(t) = 1$

Integrating gives $v_1 = \ln(\cos(t))$ and $v_2 = t$.

Thus, the general solution is

$$y = c_1 \cos(t) + c_2 \sin(t) + \ln(\cos(t)) \cos(t) + t \sin(t)$$

Consider

$$y'' + y = 4\sin(t)$$

Consider

$$y'' + y = 4\sin(t)$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

Consider

$$y'' + y = 4\sin(t)$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is $W(y_1, y_2) = 1$.

Consider

$$y'' + y = 4\sin(t)$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is $W(y_1, y_2) = 1$.

So,

$$v_1' = -\frac{y_2 f}{1} = -2(1 - \cos(2t))$$
 and $v_2' = \frac{y_1 f}{1} = 2\sin(2t)$

Consider

$$y'' + y = 4\sin(t)$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is $W(y_1, y_2) = 1$.

So,

$$v_1' = -\frac{y_2 f}{1} = -2(1 - \cos(2t))$$
 and $v_2' = \frac{y_1 f}{1} = 2\sin(2t)$

Integrating gives $v_1 = -2t + 2\sin(t)\cos(t)$ and $v_2 = 1 - 2\cos^2(t)$.

Consider

$$y'' + y = 4\sin(t)$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is $W(y_1, y_2) = 1$.

So,

$$v_1' = -\frac{y_2 f}{1} = -2(1 - \cos(2t))$$
 and $v_2' = \frac{y_1 f}{1} = 2\sin(2t)$

Integrating gives $v_1 = -2t + 2\sin(t)\cos(t)$ and $v_2 = 1 - 2\cos^2(t)$.

Thus, the particular solution is

$$y_p = (-2t + 2\sin(t)\cos(t))(\cos(t)) + (1 - 2\cos^2(t))(\sin(t))$$

Consider

$$y'' + y = 4\sin(t)$$

The characteristic equation is $r^2 + 1 = 0$, so the characteristic roots are $r = \pm i$. Which means $y_1 = \cos(t)$ and $y_2 = \sin(t)$.

The Wronskian is $W(y_1, y_2) = 1$.

So,

$$v_1' = -\frac{y_2 f}{1} = -2(1 - \cos(2t))$$
 and $v_2' = \frac{y_1 f}{1} = 2\sin(2t)$

Integrating gives $v_1 = -2t + 2\sin(t)\cos(t)$ and $v_2 = 1 - 2\cos^2(t)$.

Thus, the particular solution is

$$y_p = (-2t + 2\sin(t)\cos(t))(\cos(t)) + (1 - 2\cos^2(t))(\sin(t))$$

= -2t \cos(t) + \sin(t)

Method for Determining a General Solution of L(y) = f(t)

1 Determine two linearly independent solutions, y_1 and y_2 , of L(y) = 0.

Method for Determining a General Solution of L(y) = f(t)

- **1** Determine two linearly independent solutions, y_1 and y_2 , of L(y) = 0.
- **2** Solve, for v'_1 , and v'_2 , the system

$$v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1 + v_2'y_2 = 0$$

(Cramer's Rule is recommended.)

Method for Determining a General Solution of L(y) = f(t)

- 1 Determine two linearly independent solutions, y_1 and y_2 , of L(y) = 0.
- 2 Solve, for v'_1 , and v'_2 , the system

$$v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1 + v_2'y_2 = 0$$

(Cramer's Rule is recommended.)

3 Integrate to determine v_1 and v_2 .

Method for Determining a General Solution of L(y) = f(t)

- 1 Determine two linearly independent solutions, y_1 and y_2 , of L(y) = 0.
- 2 Solve, for v'_1 , and v'_2 , the system

$$v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1 + v_2'y_2 = 0$$

(Cramer's Rule is recommended.)

- 3 Integrate to determine v_1 and v_2 .
- **4** Compute $y = y_h + y_p = c_1y_1 + c_2y_2 + v_1y_1 + v_2y_2$.

Method for Determining a General Solution of L(y) = f(t)

- **1** Determine two linearly independent solutions, y_1 and y_2 , of L(y) = 0.
- 2 Solve, for v'_1 , and v'_2 , the system

$$v_1'y_1' + v_2'y_2' = f$$

$$v_1'y_1 + v_2'y_2 = 0$$

(Cramer's Rule is recommended.)

- 3 Integrate to determine v_1 and v_2 .
- 4 Compute $y = y_h + y_p = c_1y_1 + c_2y_2 + v_1y_1 + v_2y_2$.

Note

This method can be extended to higher orders.

Consider

$$y'' - 2y' + y = \frac{e^t}{t^2 + 1}$$

Consider

$$y'' - 2y' + y = \frac{e^t}{t^2 + 1}$$

The associated homogeneous system has solutions $y_1 = e^t$ and $y_2 = te^t$.

Consider

$$y'' - 2y' + y = \frac{e^t}{t^2 + 1}$$

The associated homogeneous system has solutions $y_1 = e^t$ and $y_2 = te^t$.

The Wronskian is
$$W(y_1,y_2)=\begin{vmatrix} e^t & te^t \\ e^t & (t+1)e^t \end{vmatrix}=(t+1)e^{2t}-te^{2t}=e^{2t}$$

Consider

$$y'' - 2y' + y = \frac{e^t}{t^2 + 1}$$

The associated homogeneous system has solutions $y_1 = e^t$ and $y_2 = te^t$.

The Wronskian is
$$W(y_1, y_2) = \begin{vmatrix} e^t & te^t \\ e^t & (t+1)e^t \end{vmatrix} = (t+1)e^{2t} - te^{2t} = e^{2t}$$

So, using the Cramer's Rule formulas from before

$$v_1' = -\frac{y_2 f}{W(y_1, y_2)} = -\frac{t}{t^2 + 1}$$
 and $v_2' = \frac{y_1 f}{W(y_1, y_2)} = \frac{1}{t^2 + 1}$

Consider

$$y'' - 2y' + y = \frac{e^t}{t^2 + 1}$$

The associated homogeneous system has solutions $y_1 = e^t$ and $y_2 = te^t$.

The Wronskian is
$$W(y_1, y_2) = \begin{vmatrix} e^t & te^t \\ e^t & (t+1)e^t \end{vmatrix} = (t+1)e^{2t} - te^{2t} = e^{2t}$$

So, using the Cramer's Rule formulas from before

$$v_1' = -\frac{y_2 f}{W(y_1, y_2)} = -\frac{t}{t^2 + 1}$$
 and $v_2' = \frac{y_1 f}{W(y_1, y_2)} = \frac{1}{t^2 + 1}$

Integrating gives

$$v_1 = -rac{1}{2} \ln \left(t^2+1
ight) \quad ext{and} \quad v_2 = an^{-1} \left(t
ight)$$

Consider

$$y'' - 2y' + y = \frac{e^t}{t^2 + 1}$$

The associated homogeneous system has solutions $y_1 = e^t$ and $y_2 = te^t$.

The Wronskian is
$$W(y_1,y_2)=\begin{vmatrix} e^t & te^t \\ e^t & (t+1)e^t \end{vmatrix}=(t+1)e^{2t}-te^{2t}=e^{2t}$$

So, using the Cramer's Rule formulas from before

$$v_1' = -\frac{y_2 f}{W(y_1, y_2)} = -\frac{t}{t^2 + 1}$$
 and $v_2' = \frac{y_1 f}{W(y_1, y_2)} = \frac{1}{t^2 + 1}$

Integrating gives

$$v_1 = -rac{1}{2} \ln \left(t^2+1
ight) \quad ext{and} \quad v_2 = an^{-1} \left(t
ight)$$

Thus, the general solution is

$$y = c_1 e^t + c_2 t e^t - \frac{1}{2} \ln(t^2 + 1) e^t + \tan^{-1}(t) t e^t$$

Consider

$$t^2y''-2ty'+2y=t\ln\left(t\right), \qquad t>0$$

Consider

$$t^{2}y'' - 2ty' + 2y = t \ln(t), \qquad t > 0$$
$$y'' - \frac{2}{t}y' + \frac{2}{t^{2}}y = \frac{\ln(t)}{t}$$

Consider

$$t^{2}y'' - 2ty' + 2y = t \ln(t), \qquad t > 0$$
$$y'' - \frac{2}{t}y' + \frac{2}{t^{2}}y = \frac{\ln(t)}{t}$$

Two solutions of L(y) = 0 are $y_1 = t$ and $y_2 = t^2$.

Consider

$$t^{2}y'' - 2ty' + 2y = t \ln(t), \qquad t > 0$$
$$y'' - \frac{2}{t}y' + \frac{2}{t^{2}}y = \frac{\ln(t)}{t}$$

Two solutions of L(y) = 0 are $y_1 = t$ and $y_2 = t^2$.

The Wronskian is
$$W(y_1, y_2) = \begin{vmatrix} t & t^2 \\ 1 & 2t \end{vmatrix} = 2t^2 - t^2 = t^2$$

Consider

$$t^{2}y'' - 2ty' + 2y = t \ln(t), \qquad t > 0$$
$$y'' - \frac{2}{t}y' + \frac{2}{t^{2}}y = \frac{\ln(t)}{t}$$

Two solutions of L(y) = 0 are $y_1 = t$ and $y_2 = t^2$.

The Wronskian is
$$W(y_1, y_2) = \begin{vmatrix} t & t^2 \\ 1 & 2t \end{vmatrix} = 2t^2 - t^2 = t^2$$

So, using Cramer's Rule

$$\begin{aligned} v_1' &= -\frac{y_2 f}{W(y_1, y_2)} = -\frac{\ln(t)}{t} &\to v_1 = -\frac{1}{2} \ln^2(t) \\ v_2' &= \frac{y_1 f}{W(y_1, y_2)} = \frac{\ln(t)}{t^2} &\to v_2 = -\frac{\ln(t) + 1}{t} \end{aligned}$$

Consider

$$t^{2}y'' - 2ty' + 2y = t \ln(t), \qquad t > 0$$
$$y'' - \frac{2}{t}y' + \frac{2}{t^{2}}y = \frac{\ln(t)}{t}$$

Two solutions of L(y) = 0 are $y_1 = t$ and $y_2 = t^2$.

The Wronskian is
$$W(y_1, y_2) = \begin{vmatrix} t & t^2 \\ 1 & 2t \end{vmatrix} = 2t^2 - t^2 = t^2$$

So, using Cramer's Rule

$$\begin{aligned} v_1' &= -\frac{y_2 f}{W(y_1, y_2)} = -\frac{\ln(t)}{t} &\to v_1 = -\frac{1}{2} \ln^2(t) \\ v_2' &= \frac{y_1 f}{W(y_1, y_2)} = \frac{\ln(t)}{t^2} &\to v_2 = -\frac{\ln(t) + 1}{t} \end{aligned}$$

The general solution is

$$y = c_1 t + c_2 t^2 - \frac{t}{2} \ln^2(t) - t \ln(t) - t$$