Complex Characteristic Roots

Department of Mathematics

Salt Lake Community College

(Slides by Adam Wilson)

Solution for Complex Characteristic Roots

For Δ < 0, the characteristic roots of the DE

are

$$ay'' + by' + cy = 0$$

$$r_1 = \alpha + i\beta = -\frac{b}{2a} + i\frac{\sqrt{-(b^2 - 4ac)}}{2a}$$

$$r_2 = \alpha - i\beta = -\frac{b}{2a} - i\frac{\sqrt{-(b^2 - 4ac)}}{2a}$$

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The functions $e^{\alpha t} \cos(\beta t)$ and $e^{\alpha t} \sin(\beta t)$ are linearly independent solutions, and the general solution is given by

$$y(t) = e^{\alpha t} \left(c_1 \cos \left(\beta t \right) + c_2 \sin \left(\beta t \right) \right)$$

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The set $\{e^{\alpha t}\cos(\beta t), e^{\alpha t}\sin(\beta t)\}$ forms a basis for the solution space \mathbb{S} .

Let us find the general solution of

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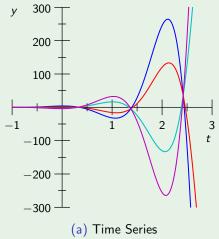
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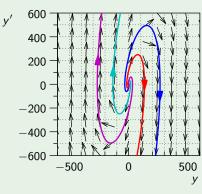
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(b) Phase Portrait

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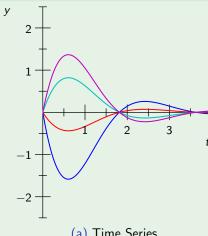
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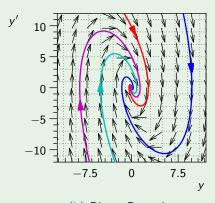
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(a) Time Series



(b) Phase Portrait

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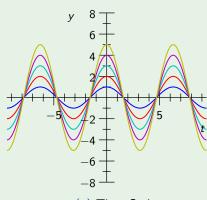
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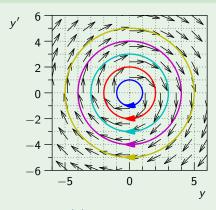
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(a) Time Series



(b) Phase Portrait

Underdamped Mass-Spring System

The motion of a mass-spring system is called **underdamped** when we have $\Delta = b^2 - 4mk < 0$. Both characteristic roots are complex and the solutions are given by

$$x(t) = e^{-\frac{b}{2m}} \left(c_1 \cos \left(\omega_d t \right) + c_2 \sin \left(\omega_d t \right) \right), \quad \omega_d = \frac{\sqrt{4mk - b^2}}{2m}$$

$$x(t) = A(t)\cos(\omega_d t - \delta), \quad \omega_d = \frac{\sqrt{4mk - b^2}}{2m}$$

- Time-varying amplitude $A(t) = Ae^{-\frac{b}{2m}}$
- Phase angle &
- Phase shift $\varphi = \frac{\delta}{\omega_d}$
- Circular quasi-frequency ω_d
- Natural quasi-frequency $f_d = \frac{\omega_d}{2\pi}$
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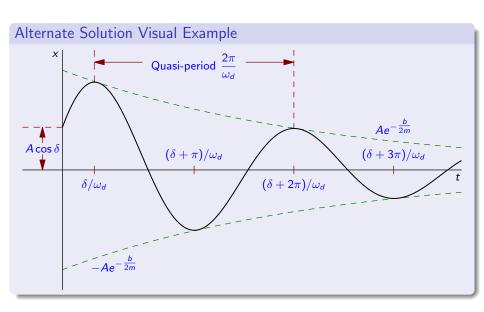
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Consider the Mass-Spring IVP where

$$\ddot{x} + \dot{x} + x = 0$$
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Which means $\alpha = -\frac{1}{2}$ and $\beta = \frac{\sqrt{3}}{2}$.

The general solution is

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If we substitute in the initial conditions x(0)=1 and $\dot{x}(0)=0$, we find that $c_1=1$ and $c_2=\frac{1}{\sqrt{3}}$.

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In alternate polar form

$$x(t) = \frac{2}{\sqrt{3}}e^{-\frac{t}{2}}\cos\left(\frac{\sqrt{3}}{2}t - \frac{\pi}{6}\right)$$

Where

$$A = \sqrt{1^2 + \left(\frac{1}{\sqrt{3}}\right)^2} = \frac{2}{\sqrt{3}} \quad \text{and} \quad \delta = \tan^{-1}\left(\frac{\frac{1}{\sqrt{3}}}{1}\right) = \frac{\pi}{6}$$

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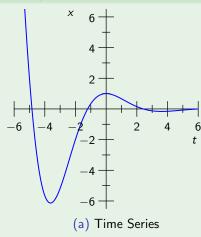
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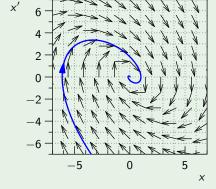
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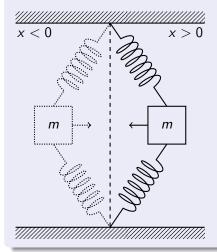
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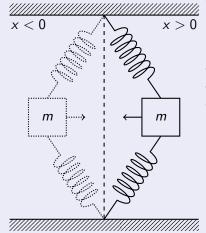




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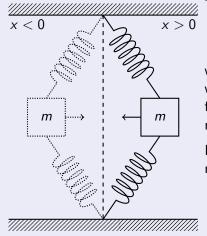


The motion of this spring is given by

$$\ddot{x} + \omega_0^2 x = 0$$

where ω_0 is the circular frequency at which the string vibrates. (In music, the frequency $f_0=\frac{\omega_o}{2\pi}$ is often used. A middle C has 512 vibrations per second.)

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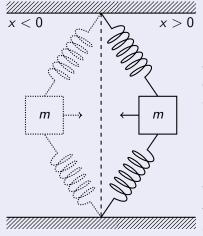
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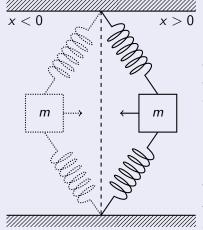
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$$\ddot{x} + 2\dot{x} + 26x = 0$$

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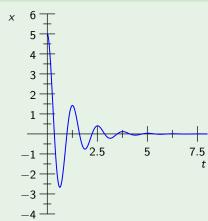
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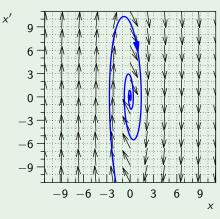
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If we pluck the string, which means x(0) = 5 and $\dot{x}(0) = 0$, we find that $c_1 = 5$ and $c_2 = 1$.



(a) Time Series



(b) Phase Portrait

Solutions to the Second-Order Linear DE with Constant Coefficients

The differential equation

$$ay'' + by' + cy = 0$$

has the characteristic equation

$$ar^2 + br + c = 0$$

The quadratic formula gives rise to three different general solutions, depending on the discriminant $\Delta = b^2 - 4ac$.

Characteristic Roots General Solution $\Delta > 0 \qquad r_1, r_2 = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \qquad y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$ $\Delta = 0 \qquad r = -\frac{b}{2a} \qquad y = c_1 e^{rt} + c_2 t e^{rt}$ $\Delta < 0 \qquad r_1, r_2 = \alpha \pm \beta \qquad y = e^{\alpha t} \left(c_1 \cos \left(\beta t \right) + c_2 \sin \left(\beta t \right) \right)$ $\alpha = -\frac{b}{2a}, \ \beta = \frac{\sqrt{4ac - b^2}}{2a}$

Consider the fourth-order DE

$$\frac{d^4y}{dy^4} - 16y = 0$$

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$$0 = r4 - 16 = (r2 - 4)(r2 + 4) = (r + 2)(r - 2)(r2 + 4)$$

Which has the characteristic solutions

$$r_1 = 2$$
, $r_2 = -2$, $r_3 = 2i$, $r_4 = -2i$

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Thus, $\{e^{2t}, e^{-2t}, \cos(2t), \sin(2t)\}$ form a basis of \mathbb{S} and the general solution is

$$y = c_1 e^{2t} + c_2 e^{-2t} + c_3 \cos(2t) + c_4 \sin(2t)$$

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Thus, $\{e^t, te^t, e^{-3t}\}$ form a basis of $\mathbb S$ and the general solution is

$$y = c_1 e^t + c_2 t e^t + c_3 e^{-3t}$$

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$$r_1 = -1$$
, $r_2 = -1$, $r_3 = -1$, $r_4 = 0$, $r_5 = 0$

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, $r_2 = -1$, $r_3 = -1$, $r_4 = 0$, $r_5 = 0$

Thus, $\{e^{-t}, te^{-t}, t^2e^{-t}, 1, t\}$ form a basis of $\mathbb S$ and the general solution is

$$y = (c_1 + c_2t + c_3t^2)e^{-t} + (c_4 + c_5t)$$
for triple root
for double root

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, $r_2 = 2i$, $r_3 = -2i$, $r_4 = -2i$

Thus, $\{\cos(2t), t\cos(2t), \sin(2t), t\sin(2t)\}\$ form a basis of \mathbb{S} and the general solution is

$$y = (c_1 + c_2 t) \cos(2t) + (c_3 + c_4 t) \sin(2t)$$
for double root
for double root