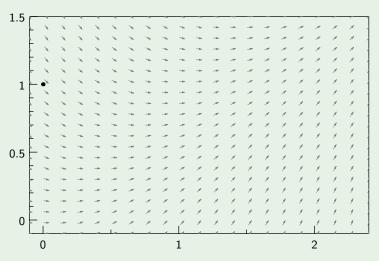
# Approximation Methods Numerical Analysis

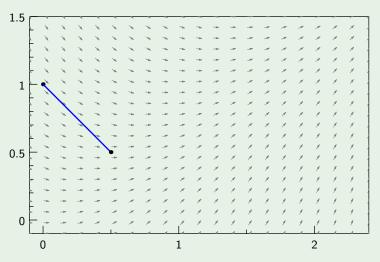
Department of Mathematics

Salt Lake Community College

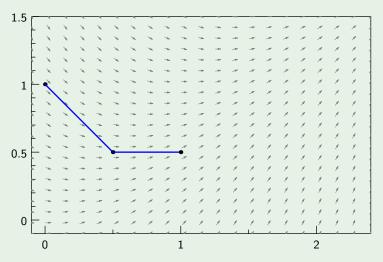
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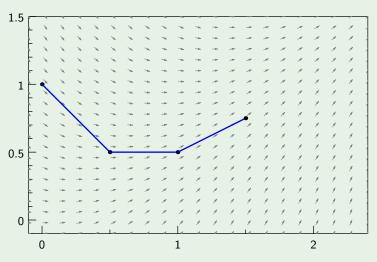
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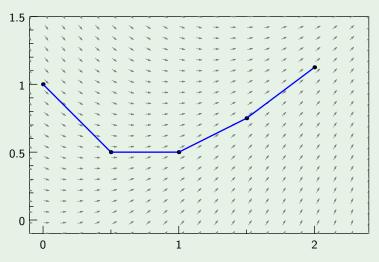
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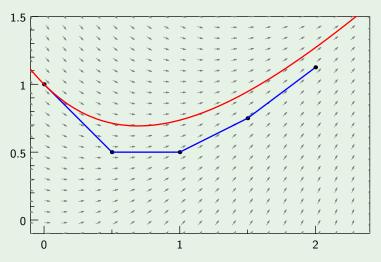
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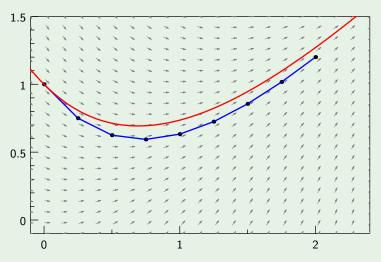
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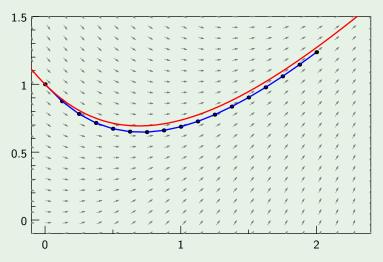
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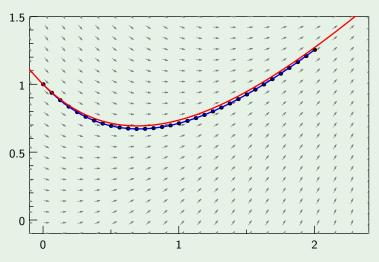
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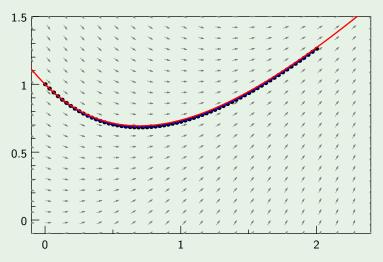
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Given the IVP

$$y' = f(t, y), \ y(t_0) = y_0$$

We want to compute approximate values for  $y(t_n)$  at the (finite) set of points  $t_1, t_2, t_3, \ldots, t_k$ .

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We can calculate the *t*-values, for 1, 2, 3, ..., k, with  $t_n = t_0 + n \cdot h$ .

Where h, called the **step size**, is the common difference between successive points.

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So, starting at  $(t_0, y_0)$  we want to follow the tangent line determined by

$$y - y_0 = (t - t_0)f(t_0, y_0)$$

to find the approximate solution  $(t_1, y(t_1))$ :

$$y_1 = y_0 + h \cdot f(t_0, y_0)$$

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$$\vdots$$

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We can extend this process to find all k points.

$$y_{1} = y_{0} + h \cdot f(t_{0}, y_{0})$$

$$y_{2} = y_{1} + h \cdot f(t_{1}, y_{1})$$

$$y_{3} = y_{2} + h \cdot f(t_{2}, y_{2})$$

$$\vdots$$

$$y_{k} = y_{k-1} + h \cdot f(t_{k-1}, y_{k-1})$$

The resulting piecewise-linear function (i.e. play connect-the-dots) is called the **Euler-approximate** solution.

#### Euler's Method

For the Initial-value problem

$$y' = f(t, y), \ y(t_0) = y_0$$

use the formulas

$$t_{n+1} = t_n + h$$
  
$$y_{n+1} = y_n + h \cdot f(t_n, y_n)$$

to iteratively compute the points, using step size h,

$$(t_1, y_1), (t_2, y_2), \ldots, (t_k, y_k).$$

The piecewise-linear function connecting these points is the Euler approximation to the solution y(t) of the IVP for  $t_0 \le t \le t_k$ .

Let us obtain the Euler-approximate solution of the IVP

$$y' = -2ty + t, \ y(0) = -1$$

with step size 0.1 on [0, 0.4].

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In other words:

$$f(t,y) = -2ty + t = t(1-2y)$$

$$t_0 = 0$$

$$y_0 = -1$$

$$h = 0.1$$

$$k = 1, 2, 3, 4$$

$$t_1 = t_0 + h = 0 + 0.1 = 0.1$$
  
 $y_1 = y_0 + h \cdot f(t_0, y_0) = -1 + (0.1)(0)(1 - 2(-1)) = -1$ 

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$$t_2 = t_1 + h = 0.1 + 0.1 = 0.2$$

$$y_2 = y_1 + h \cdot f(t_1, y_1)$$

$$= -1 + (0.1)(0.1)(1 - 2(-1)) = -0.97$$

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$$t_3 = t_2 + h = 0.2 + 0.1 = 0.3$$

$$y_3 = y_0 + h \cdot f(t_2, y_2)$$

$$= -0.97 + (0.1)(0.2)(1 - 2(-0.97)) = -0.9112$$

$$t_1 = t_0 + h = 0 + 0.1 = 0.1$$

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$$t_4 = t_3 + h = 0.3 + 0.1 = 0.4$$

$$y_4 = y_3 + h \cdot f(t_3, y_3)$$

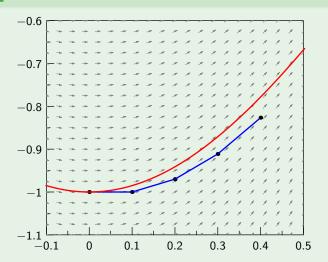
$$= -0.9112 + (0.1)(0.3)(1 - 2(-0.9112)) = -0.82652$$

How does this compare to the exact solution  $y(t) = 0.5 - 1.5e^{-t^2}$ ?

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n	tn	Уn	$y(t_n)$	Error
0	0.0	-1.000000	-1.000000	0.000000
1	0.1	-1.000000	-0.985075	-0.014925
2	0.2	-0.970000	-0.941184	-0.028815
3	0.3	-0.911200	-0.870897	-0.040303
4	0.4	-0.826528	-0.778216	-0.048312

Notice how the error grows rapidly.



Find the Euler-approximation of

$$y' = -2ty, \ y(0) = 1$$

using a step size of 0.2 over the range of [0, 2].

 $n t_n y_n y(t_n)$  Error

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n	tn	$y_n$	$y(t_n)$	Error
0	0.0	1.0000000	1.0000000	0.000000

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n	t <sub>n</sub>	Уn	$y(t_n)$	Error
0	0.0	1.0000000	1.0000000	0.000000
1	0.2	1.0000000	0.9607894	-0.039211

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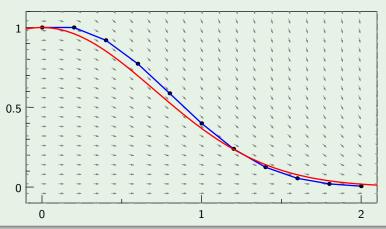
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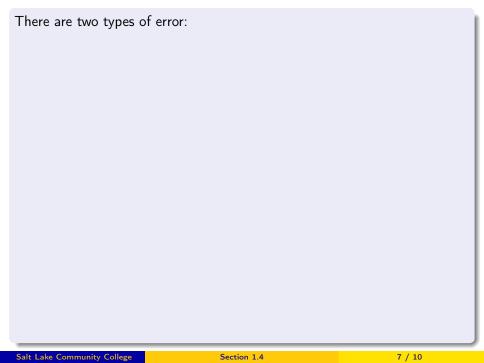
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8	1.6	0.0548273	0.0773047	0.022477
9	1.8	0.0197378	0.0391639	0.019426
10	2.0	0.0055265	0.0183156	0.012789

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It can be shown, using Taylor series expansions, that the error is proportional to the square of the step size.

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Where the constant C depends of the size of the second derivative of the exact solution.

We call this error the **local discretization error** because it estimates the error for a single step only. After n steps, we have n times the error. Which we call the **global discretization error**.

#### Global Discretization Error in Euler's Method

If the solution of the IVP y' = f(t,y),  $y(t_0) = y_0$  has a continuous second derivative on the interval  $[t_0, t_k]$ , and  $y_n$  is the value of the Euler approximation at  $t_n$ ,  $t_0 < t_1 < \cdots < t_n \cdots < t_k$ , then there exists a constant C such that

$$|y_n-y(t_n)|\leq C\cdot h, \quad n=1,2,\ldots,k.$$

where step size  $h = t_n - t_{n-1}$ .

### Second-Order Runge-Kutta Method

For the IVP y' = f(t, y),  $y(t_0) = y_0$ , use the following formulas to compute the points  $(t_1, y_1), (t_2, y_2), \ldots$  of the approximate solution, using step size h:

$$t_{n+1} = t_n + h$$
$$y_{n+1} = y_n + h \cdot k_{n_1}$$

where

$$k_{n_1} = f(t_n, y_n)$$
  
 $k_{n_2} = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} \cdot k_{n_1}\right)$ 

### Fourth-Order Runge-Kutta Method

For the IVP y' = f(t, y),  $y(t_0) = y_0$ , use the following formulas to compute the points  $(t_1, y_1), (t_2, y_2), \ldots$  of the approximate solution, using step size h:

$$t_{n+1} = t_n + h$$
  
$$y_{n+1} = y_n + \frac{h}{6}(k_{n_1} + 2k_{n_2} + 2k_{n_3} + k_{n_4})$$

where

$$k_{n_1} = f(t_n, y_n)$$

$$k_{n_2} = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} \cdot k_{n_1}\right)$$

$$k_{n_3} = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} \cdot k_{n_2}\right)$$

$$k_{n_2} = f\left(t_n + h, y_n + h \cdot k_{n_3}\right)$$