

Approximation Methods

Numerical Analysis

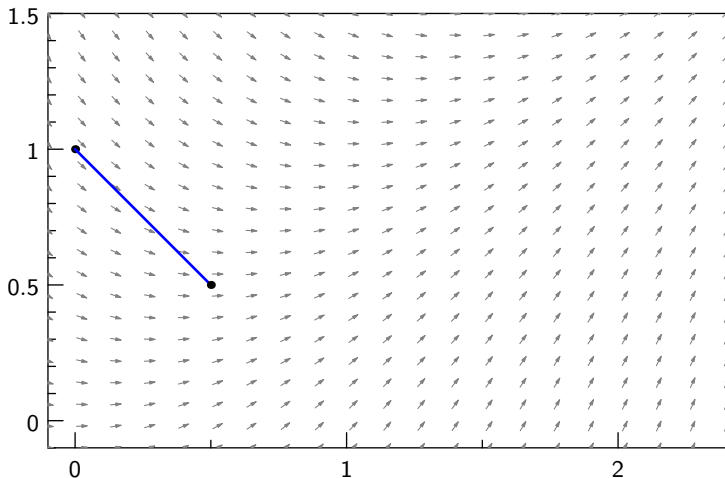
Adam Wilson

Salt Lake Community College

Euler's Method

Graphical Example

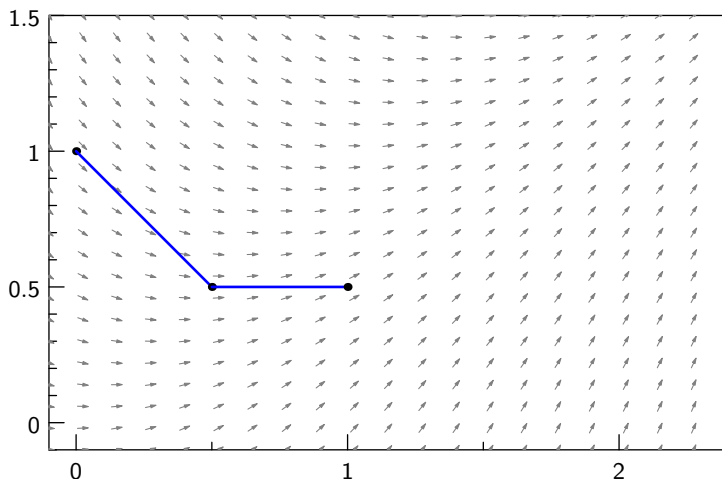
$$y' = t - y, \quad y(0) = 1$$



Euler's Method

Graphical Example

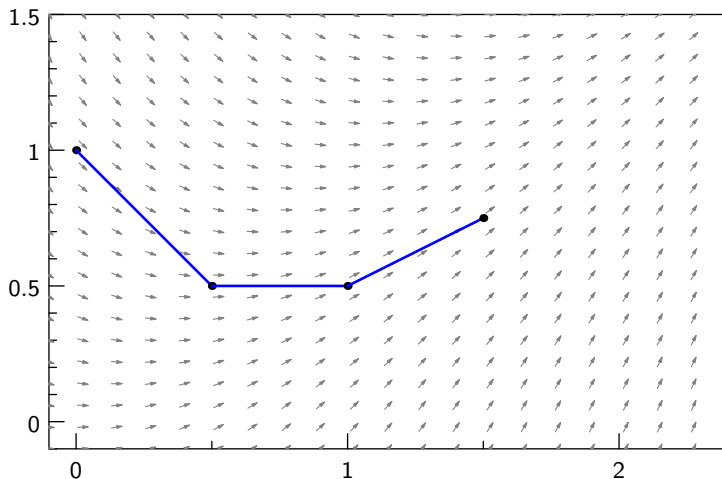
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Euler's Method

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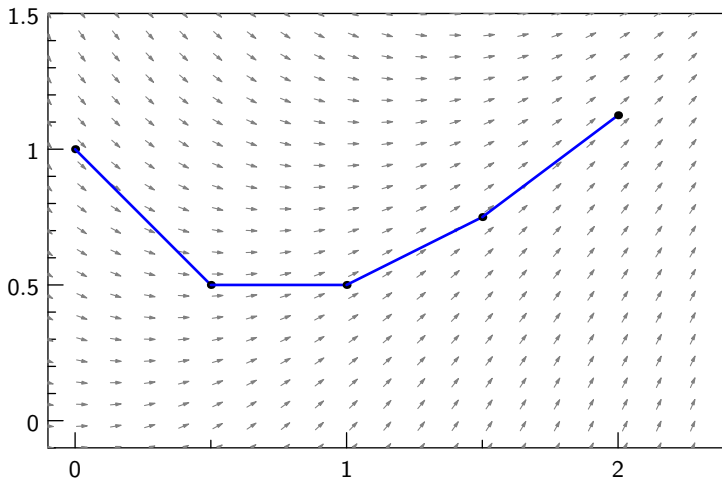
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Euler's Method

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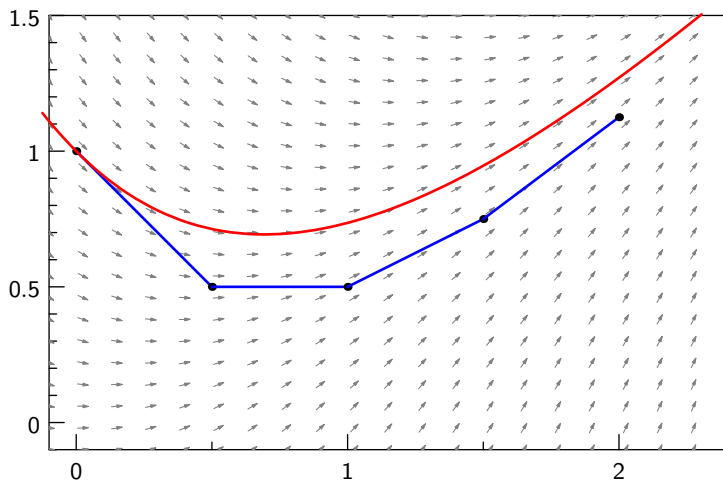
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Euler's Method

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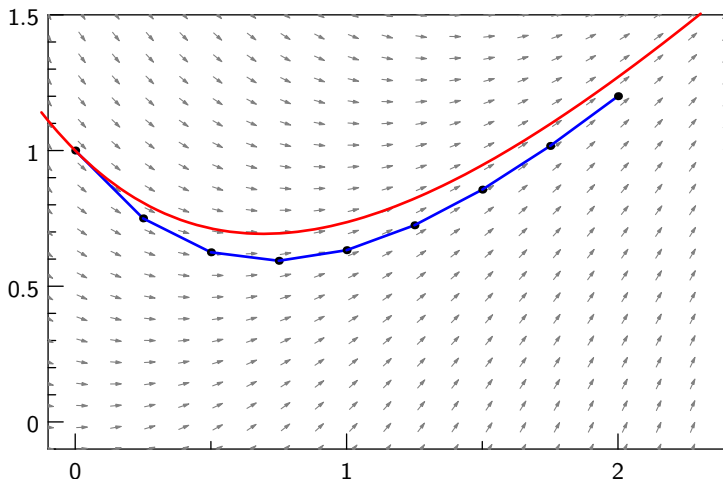
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Euler's Method

Graphical Example

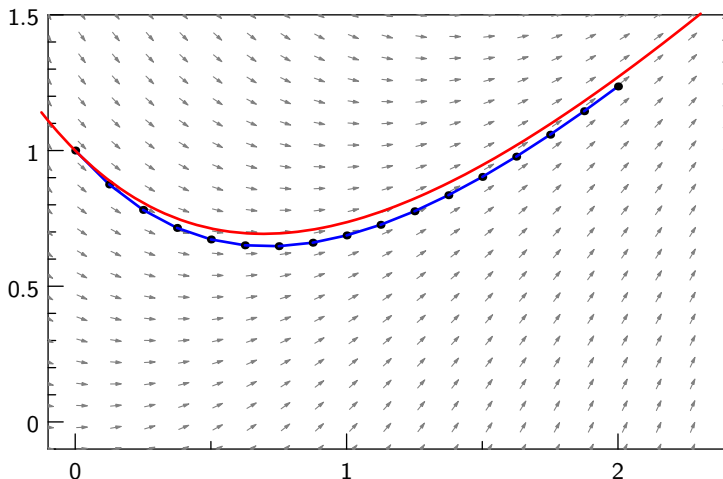
Reducing the step size improves our approximation.



Euler's Method

Graphical Example

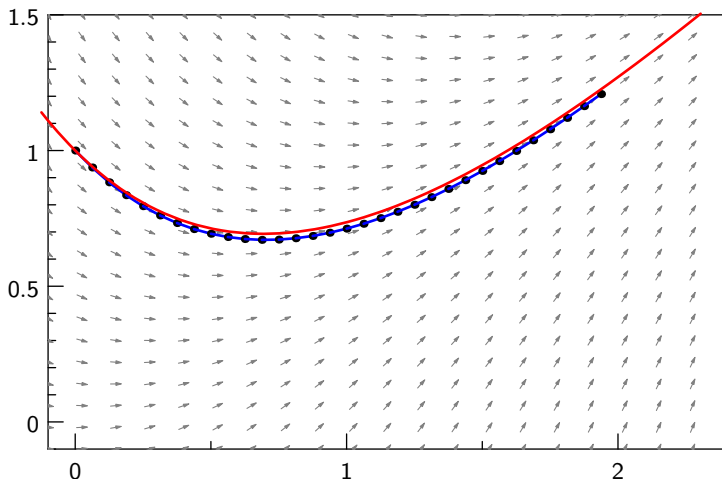
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Euler's Method

Graphical Example

Reducing the step size improves our approximation.



Euler's Method

Formal Approach

Consider the IVP

$$y' = f(t, y), \quad y(t_0) = y_0$$

We want to compute approximate values for $y(t_n)$ at the (finite) set of points $t_1, t_2, t_3, \dots, t_k$.

We can calculate the t -values, for $k = 1, 2, 3, \dots, k$, with

$$t_n = t_0 + n \cdot h$$

Where h , called the **step size**, is the common difference between successive points.

Euler's Method

Formal Approach

Starting at (t_0, y_0) we want to follow the tangent line determined by

$$y - y_0 = (t - t_0)f(t_0, y_0)$$

to find the approximate solution $(t_1, y(t_1))$:

$$y_1 = y_0 + h \cdot f(t_0, y_0)$$

(Remember that $h = t_1 - t_0$.)

Euler's Method

Formal Approach

We can extend this process to find all k points.

$$y_1 = y_0 + h \cdot f(t_0, y_0)$$

$$y_2 = y_1 + h \cdot f(t_1, y_1)$$

$$y_3 = y_2 + h \cdot f(t_2, y_2)$$

$$\vdots$$

$$y_k = y_{k-1} + h \cdot f(t_{k-1}, y_{k-1})$$

The resulting piecewise-linear function (i.e. play connect-the-dots) is called the **Euler-approximate** solution.

Euler's Method

Formal Approach

Euler's Method

For the Initial-value problem

$$y' = f(t, y), \quad y(t_0) = y_0$$

use the formulas

$$t_{n+1} = t_n + h$$

$$y_{n+1} = y_n + h \cdot f(t_n, y_n)$$

to iteratively compute the points, using step size h ,

$$(t_1, y_1), (t_2, y_2), \dots, (t_k, y_k).$$

The piecewise-linear function connecting these points is the Euler approximation to the solution $y(t)$ of the IVP for $t_0 \leq t \leq t_k$.

Euler's Method

Example 1

Obtain the Euler-approximate solution of the IVP

$$y' = -2ty + t, \quad y(0) = -1$$

with step size 0.1 on $[0, 0.4]$.

Euler's Method

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In other words:

$$f(t, y) = -2ty + t = t(1 - 2y)$$

$$t_0 = 0$$

$$y_0 = -1$$

$$h = 0.1$$

$$k = 1, 2, 3, 4$$

Euler's Method

Example 1

$$t_1 = t_0 + h = 0 + 0.1 = 0.1$$

$$y_1 = y_0 + h \cdot f(t_0, y_0) = -1 + (0.1)(0)(1 - 2(-1)) = -1$$

Euler's Method

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$$t_2 = t_1 + h = 0.1 + 0.1 = 0.2$$

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Euler's Method

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$$y_3 = y_0 + h \cdot f(t_2, y_2) = -0.97 + (0.1)(0.2)(1 - 2(-0.97)) = -0.9112$$

Euler's Method

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$$t_4 = t_3 + h = 0.3 + 0.1 = 0.4$$

$$\begin{aligned} y_4 &= y_3 + h \cdot f(t_3, y_3) \\ &= -0.9112 + (0.1)(0.3)(1 - 2(-0.9112)) = -0.82652 \end{aligned}$$

Euler's Method

Example 1

How does this compare to the exact solution $y(t) = 0.5 - 1.5e^{-t^2}$?

Euler's Method

Example 1

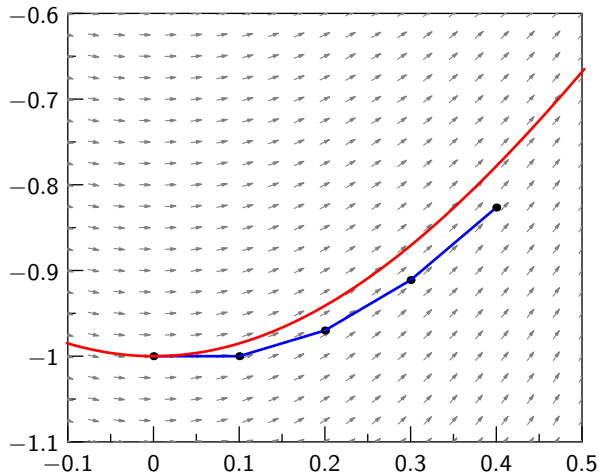
How does this compare to the exact solution $y(t) = 0.5 - 1.5e^{-t^2}$?

n	t_n	y_n	$y(t_n)$	Error
0	0.0	-1.000000	-1.000000	0.000000
1	0.1	-1.000000	-0.985075	-0.014925
2	0.2	-0.970000	-0.941184	-0.028815
3	0.3	-0.911200	-0.870897	-0.040303
4	0.4	-0.826528	-0.778216	-0.048312

Notice how the error grows rapidly.

Euler's Method

Example 1



Euler's Method

Example 2

Find the Euler-approximation of

$$y' = -2ty, \quad y(0) = 1$$

using a step size of 0.2 over the range of $[0, 2]$.

Compare it against the exact solution

$$y = e^{-t^2}$$

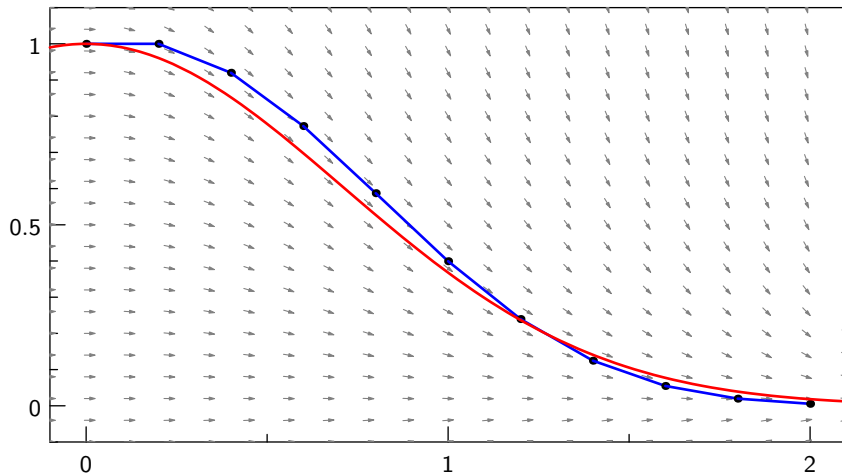
Euler's Method

Example 2

n	t_n	y_n	$y(t_n)$	Error
0	0.0	1.0000000	1.0000000	0.000000
1	0.2	1.0000000	0.9607894	-0.039211
2	0.4	0.9200000	0.8521437	-0.067856
3	0.6	0.7728000	0.6976763	-0.075124
4	0.8	0.5873280	0.5272925	-0.060036
5	1.0	0.3993830	0.3678794	-0.031504
6	1.2	0.2396298	0.2369277	-0.002702
7	1.4	0.1246075	0.1408584	0.016251
8	1.6	0.0548273	0.0773047	0.022477
9	1.8	0.0197378	0.0391639	0.019426
10	2.0	0.0055265	0.0183156	0.012789

Euler's Method

Example 2



Euler's Method

Measuring Error

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Euler's Method

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- **Roundoff error** is the discrepancy arising from rounding numbers. This tends to snowball pretty fast when you have a great many calculations.
- **Discretization error** is the error that results from the approximation method itself. For Euler's method this is caused by using the linear tangent lines to approximate a nonlinear curve.

Euler's Method

Measuring Error

It can be shown, using Taylor series expansions, that the error is proportional to the square of the step size.

$$|y_i - y(t_i)| \leq C \cdot h^2$$

Where the constant C depends of the size of the second derivative of the exact solution.

We call this error the **local discretization error** because it estimates the error for a single step only.

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After n steps, we have n times the error. Which we call the **global discretization error**.

(Note that the step size is inversely proportional to the step count.)

Euler's Method

Measuring Error

Global Discretization Error in Euler's Method

If the solution of the IVP $y' = f(t, y)$, $y(t_0) = y_0$ has a continuous second derivative on the interval $[t_0, t_k]$, and y_n is the value of the Euler approximation at t_n , $t_0 < t_1 < \cdots < t_n \cdots < t_k$, then there exists a constant C such that

$$|y_n - y(t_n)| \leq C \cdot h, \quad n = 1, 2, \dots, k.$$

where step size $h = t_n - t_{n-1}$.

Runge-Kutta Methods

Second-Order Runge-Kutta Method

For the IVP $y' = f(t, y)$, $y(t_0) = y_0$, use the following formulas to compute the points $(t_1, y_1), (t_2, y_2), \dots$ of the approximate solution, using step size h :

$$t_{n+1} = t_n + h$$

$$y_{n+1} = y_n + h \cdot k_{n1}$$

where

$$k_{n1} = f(t_n, y_n)$$

$$k_{n2} = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} \cdot k_{n1}\right)$$

Runge-Kutta Methods

Fourth-Order Runge-Kutta Method

For the IVP $y' = f(t, y)$, $y(t_0) = y_0$, use the following formulas to compute the points $(t_1, y_1), (t_2, y_2), \dots$ of the approximate solution, using step size h :

$$t_{n+1} = t_n + h$$

$$y_{n+1} = y_n + \frac{h}{6}(k_{n_1} + 2k_{n_2} + 2k_{n_3} + k_{n_4})$$

where

$$k_{n_1} = f(t_n, y_n)$$

$$k_{n_2} = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} \cdot k_{n_1}\right)$$

$$k_{n_3} = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} \cdot k_{n_2}\right)$$

$$k_{n_4} = f(t_n + h, y_n + h \cdot k_{n_3})$$