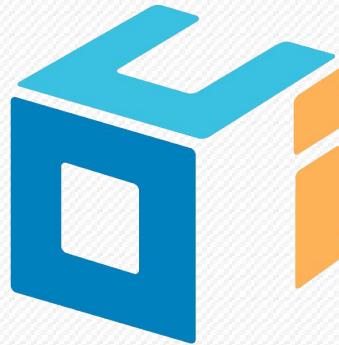


Pronghorn Embedded Toolkit

A simple, effective Java solution for IoT



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What is the Internet of Things (IoT)?

Automatically exchange
data over a network

Between physical **devices**,
machines, and **things**

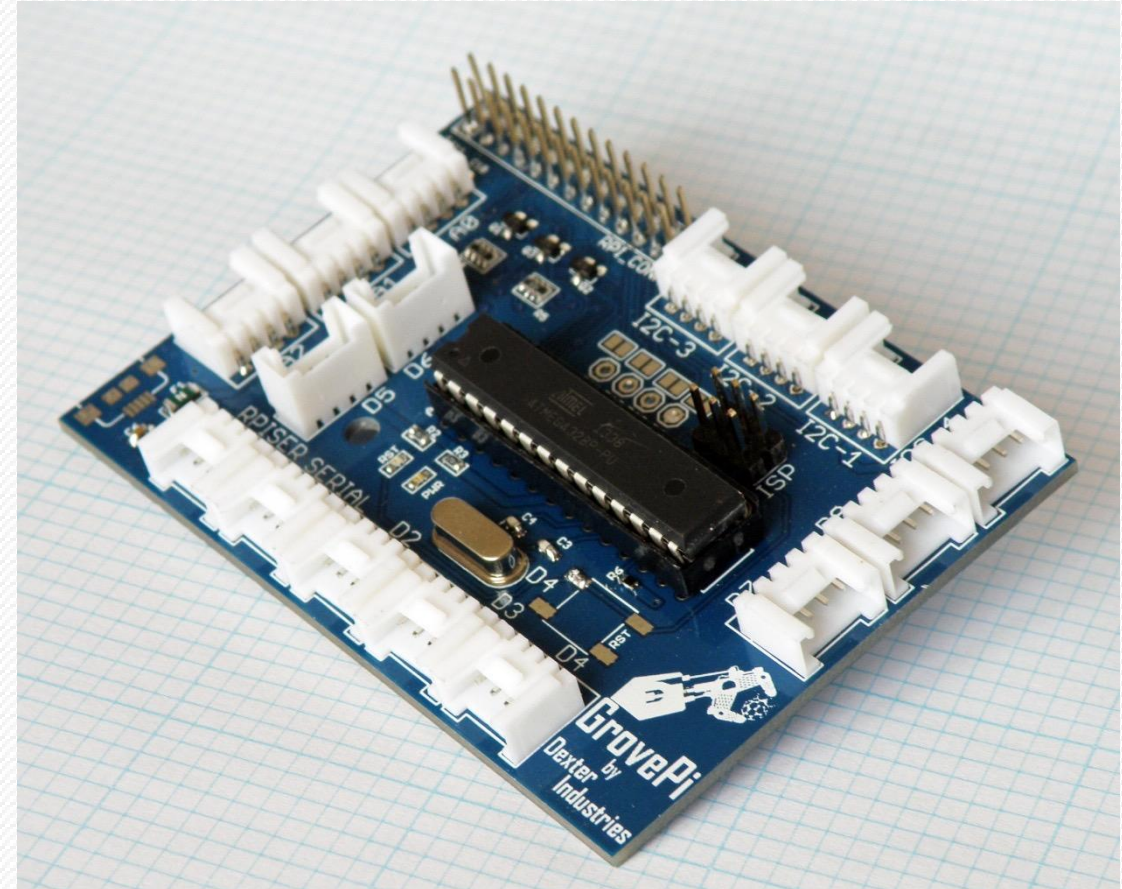
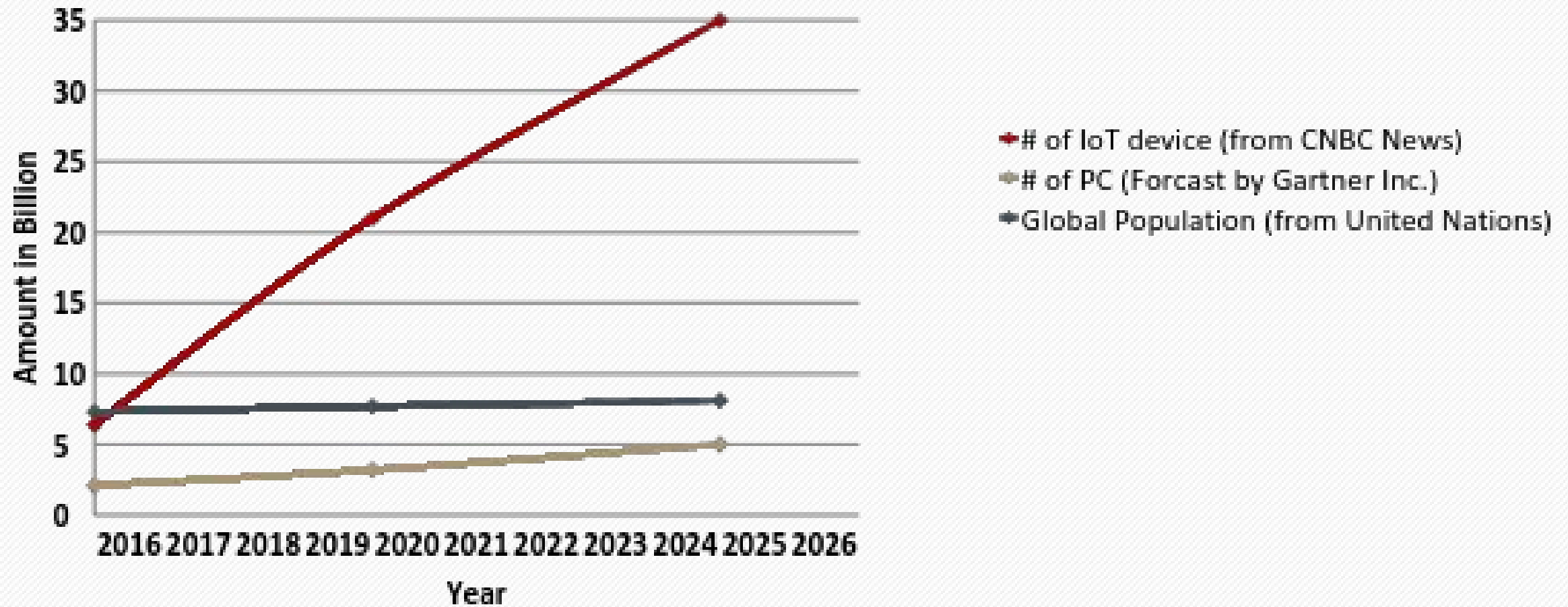
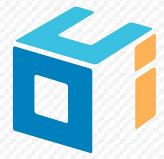


Photo of a Grove-Pi IoT
device



Rapid Growth Rate of IoT Devices





IoT Development Needs

- **Security** (data are connected to the Internet)
- **Remote management** of the device and applications
- **Local processing** and analytics of sensor data (filtering)
- **Java APIs** for industry-specific IO protocol stacks



What is Pronghorn Embedded Toolkit?

- Makers: primarily middle/high school students
- Devices: Embedded devices that run **Java Virtual Machine (JVM)**
- Makers learn Java 8 functional programming
- Easy to understand (**declarative programming**)



Low System Requirement

- Low System Requirement:
 - Compact 1 profile comes in less than 16MB
 - Jar is 1.5MB
- Open JDK



A Different Approach

Declarative Programming

- Makers describe what to do but not necessarily how to do it
- Declare Result ("What")
- Easier to Use/Learn
- Ex. Turn on light

Imperative Programming

- Makers provide step-by-step procedure to the compiler
- Declare the procedure ("How")
- Commonly used by programmers
- Ex. Write HIGH to the register



Imperative and Declarative Example

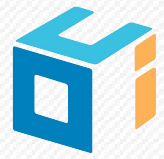
Goal: Find all odd number in List<int> collection = new List<int> { 1, 2, 3, 4, 5 };

Declarative Approach Example

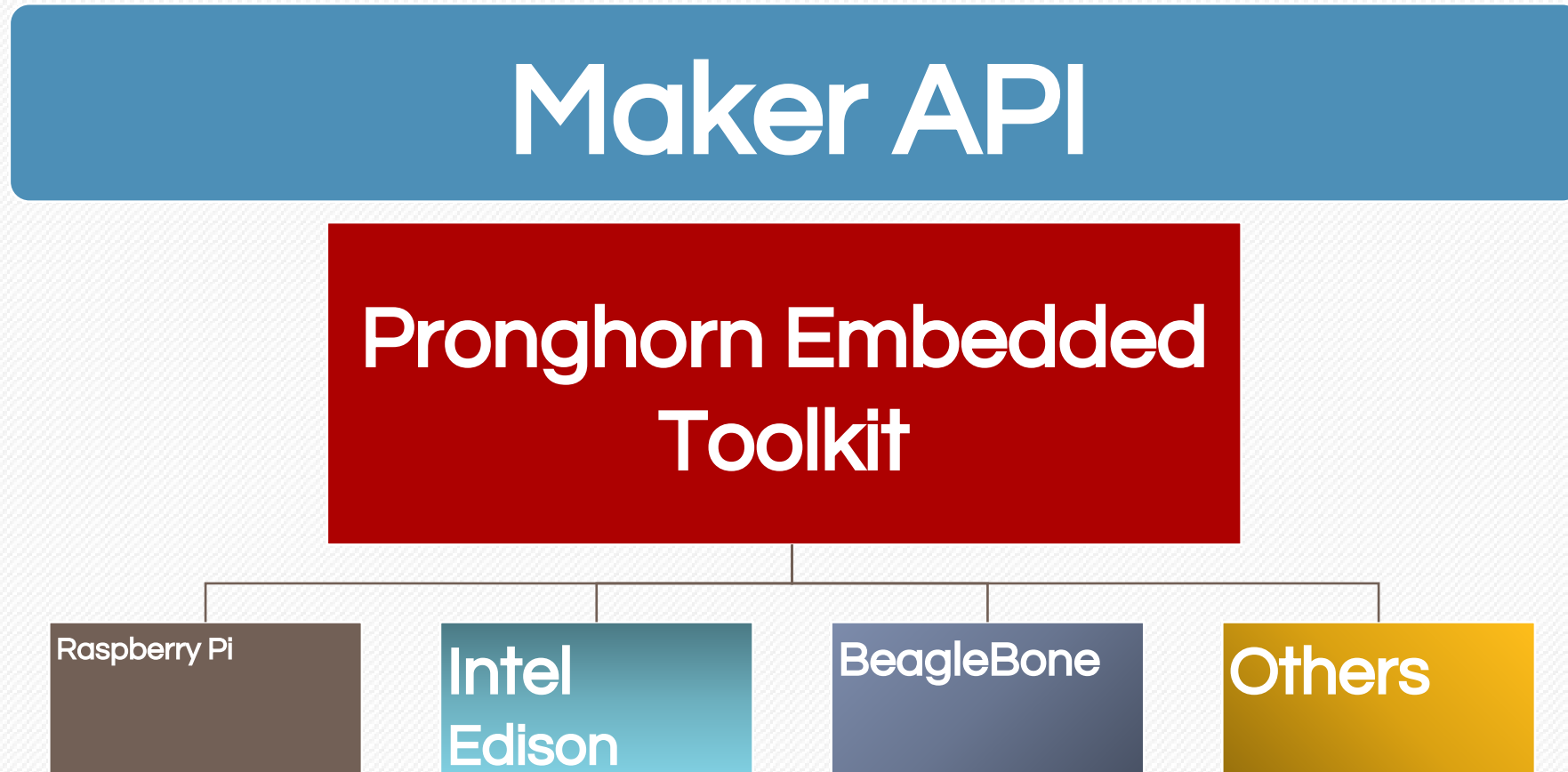
```
var results = collection.Where( num => num % 2 != 0);
```

Imperative Approach Example

```
List<int> results = new List<int>();  
  
for (int i=0; i<collection.length;i++) {  
  
    if (collection[i] % 2 != 0){  
  
        results.Add(num);  
  
    }  
  
}
```



Leave the “How” Part to Pronghorn





Compare to Arduino

Arduino

- Single Process Thread
- Procedural (C language)/Imperative

Programming

Pronghorn Embedded Toolkit

- Multiple Process Thread (Faster for multi-core embedded devices)
- Event driven
- Functional/Declarative Approach



Arduino and Pronghorn

```
int buttonPin1 = 5;
int buttonPin2 = 6;
int ledPin1 = 7;
int ledPin2 = 8;
int buttonDelta = 10;
int lightDelta = 5000;
long lastButton1 = 0;
long lastButton2 = 0;
long lightEnd = 0;

void setup() {
    pinMode(buttonPin1, INPUT);
    pinMode(buttonPin2, INPUT);
    pinMode(ledPin1, OUTPUT);
    pinMode(ledPin2, OUTPUT);
}

void loop() {
    if(lastButton1 + buttonDelta > millis()){
        lastButton1 = millis();
        digitalWrite(ledPin1, digitalRead(buttonPin1));
    }
    if(lastButton2 + buttonDelta > millis()){
        lastButton2 = millis();
        lightEnd = millis() + lightDelta;
    }
    digitalWrite(ledPin2, millis() < lightEnd);
}
```

```
public class IoTApp implements IoTSetup

    public static final Port BUTTON1_CONNECTION = D5;
    public static final Port BUTTON2_CONNECTION = D6;
    public static final Port LED1_CONNECTION = D7;
    public static final Port LED2_CONNECTION = D8;

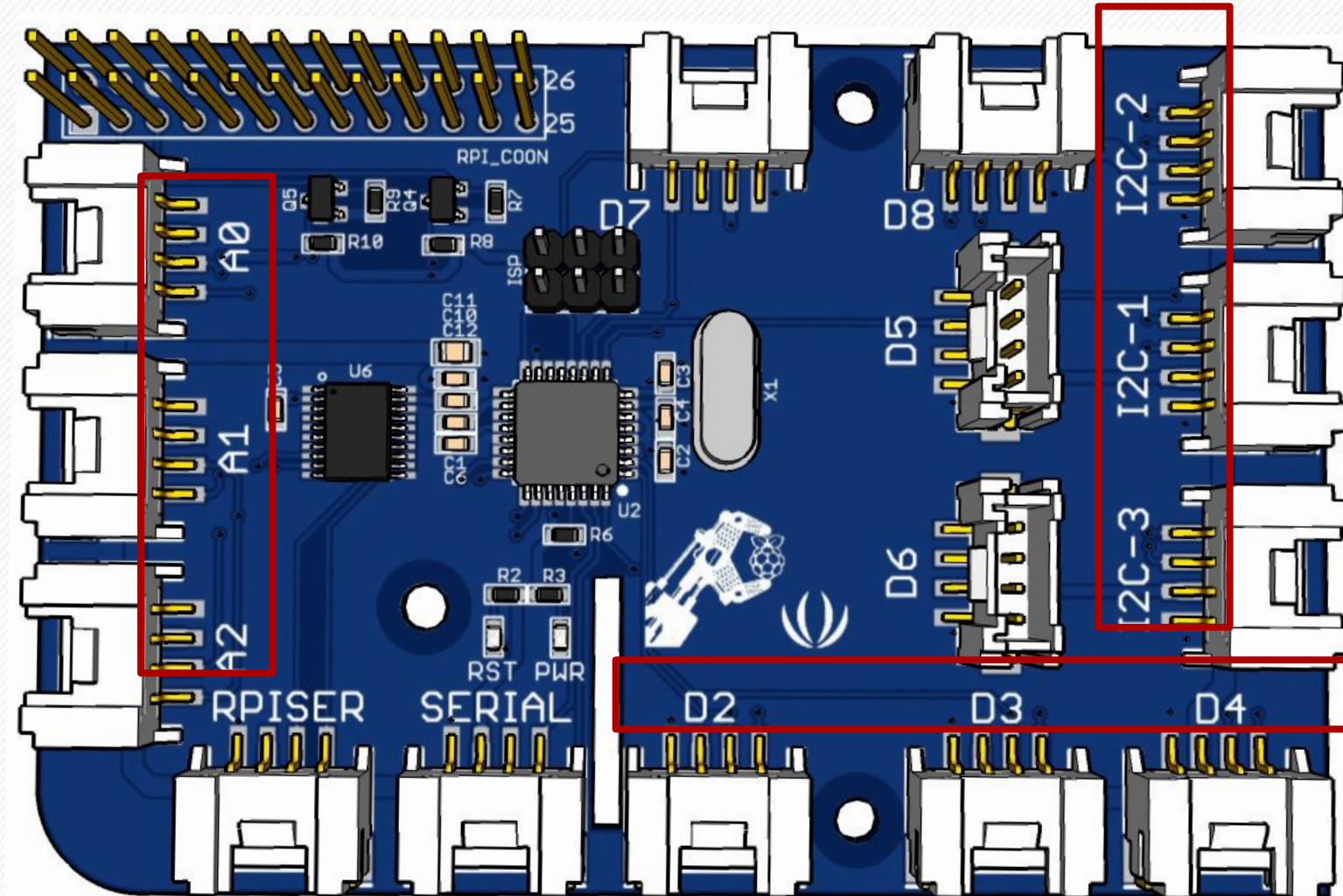
    public static void main( String[] args ) {
        DeviceRuntime.run(new IoTApp());
    }

    @Override
    public void declareConnections(Hardware c) {
        c.connect(Button, BUTTON1_CONNECTION);
        c.connect(Button, BUTTON2_CONNECTION);
        c.connect(LED, LED1_CONNECTION);
        c.connect(LED, LED2_CONNECTION);
        c.useI2C();
    }

    @Override
    public void declareBehavior(DeviceRuntime runtime) {
        CommandChannel channel1 = runtime.newCommandChannel();
        CommandChannel channel2 = runtime.newCommandChannel();
        runtime.addDigitalListener((connection, time, durationMillis, value)->{
            if(connection == BUTTON1_CONNECTION){
                channel1.digitalSetValue(LED1_CONNECTION, value);
            }
            else if(connection == BUTTON2_CONNECTION){
                channel2.digitalPulse(LED2_CONNECTION, 5000);
            }
        });
    }
}
```

Ports on the Board

Analog
Input/Output



I²C
Input/Output

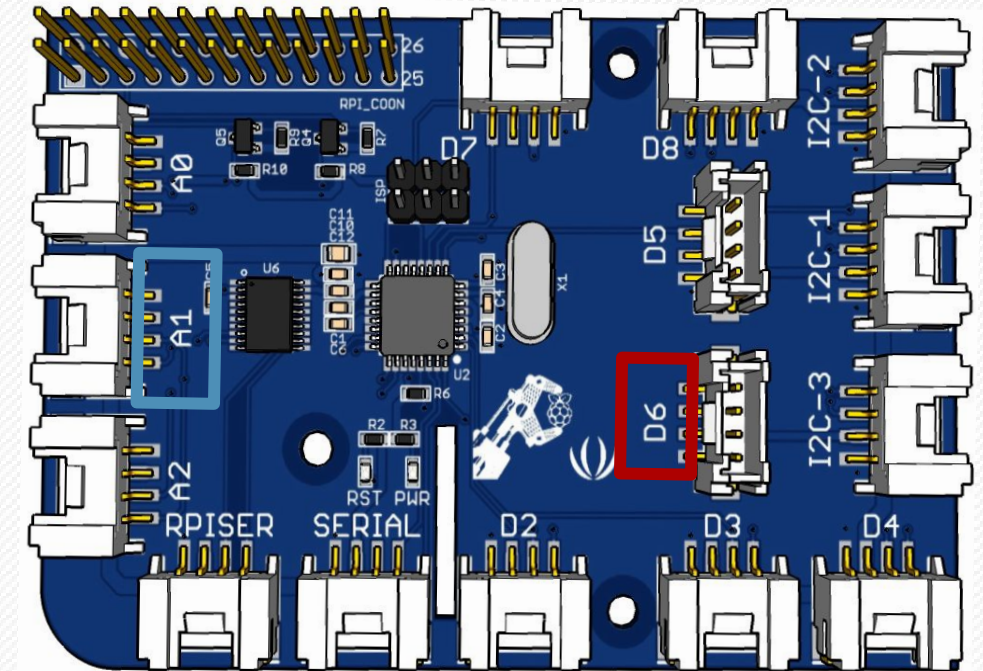
Digital
Input/Output



Connecting to Ports

Assume:

- Digital twig (LED) connect to **D6**
Port connection = **D6**;
- Analog twig (Light Sensor) connect to **A1**
Port connection = **A1**;





Hello World Sketch in Arduino

// initialize the library with the numbers of the interface pins

```
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
```

```
void setup() {
```

```
  // set up the LCD's number of columns and rows:
```

```
  lcd.begin(16, 2);
```

```
  lcd.print("hello, world!");
```

```
}
```

```
void loop() {
```

```
  lcd.setCursor(0, 1);
```

```
}
```

Maker needs to know:

- LCD RS pin to digital pin 12
- LCD Enable pin to digital pin 11
- LCD D4 pin to digital pin 5
- LCD D5 pin to digital pin 4
- LCD D6 pin to digital pin 3
- LCD D7 pin to digital pin 2

Single Process Thread



Hello World Example in Pronghorn

```
public void declareConnections(Hardware c) {  
  c.useI2C(); }
```

No pin
needed

specification

```
public void declareConnections (DeviceRuntime runtime) {  
  final CommandChannel channel0 =runtime.newCommandChannel();
```

```
  runtime.addStartupListener(() -> {  
    Grove_LCD_RGB.commandForText(channel0, "Hello World"); });  
}
```

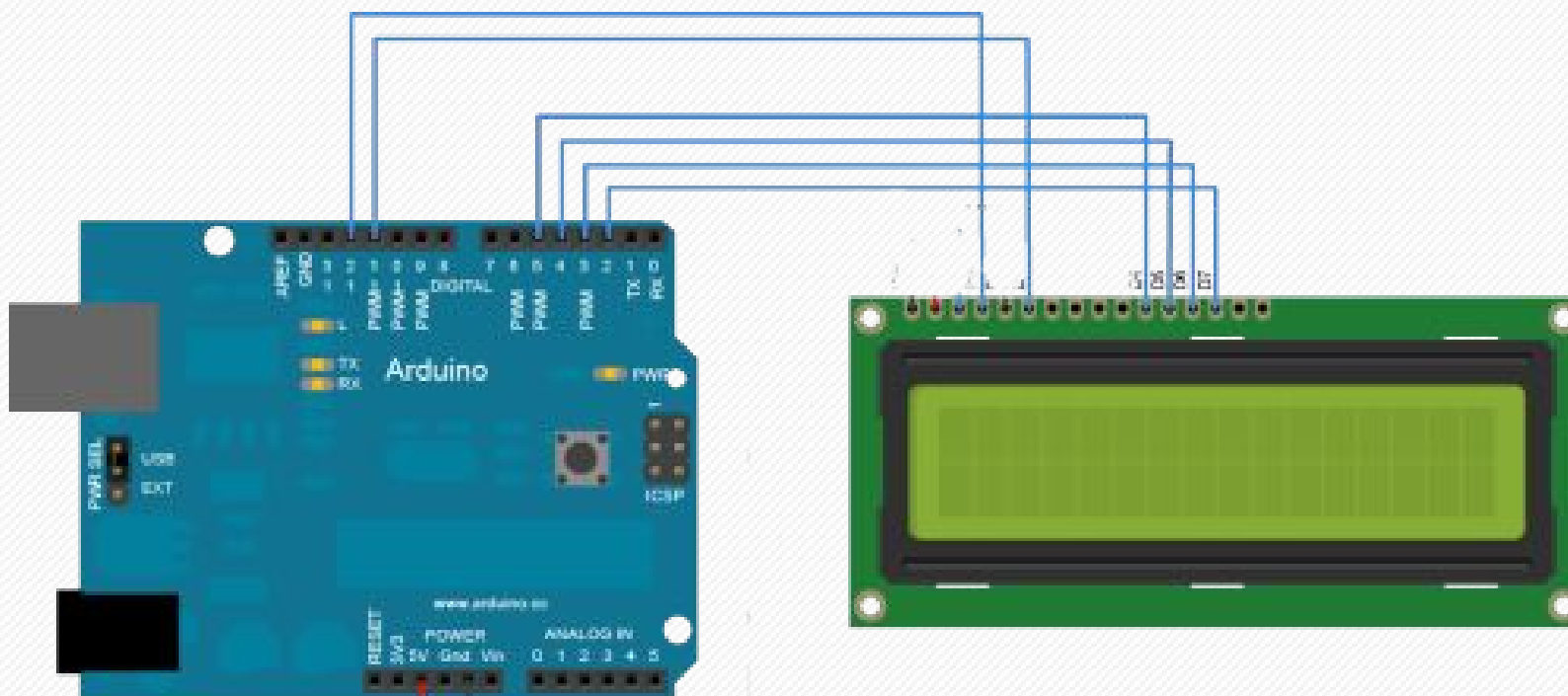
```
public static void main(String[] args){  
  DeviceRuntime.run(new DeviceTestDemo());  
}}
```

Multiple Process Thread



Introduction

Connecting A LCD Could Be Challenging





General Format

```
public class IoTDeviceDemo implements IoTSetup {
```

```
public static void main(String[] args) {
```



Look at main()

```
/** execute the behavior declared in the declareBehavior() method**/
```

```
}
```

```
public void declareConnections(Hardware c) {
```

```
/**Connect kits to the specific ports on Base Shield Board**/
```

```
}
```

```
public void declareBehavior(IOTDeviceRuntime runtime) {
```

```
/**Write instructions to the devices for specific function (Ex. Turn on a LED)**/
```

```
}}
```

Turn on a LED

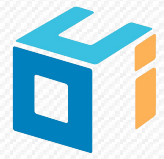


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In the main function

```
public static void main(String[] args) {  
    DeviceRuntime.run(new IoTDeviceDemo ()); }  
}
```

- Generic
- Only change: class name (*IoTDeviceDemo* ())

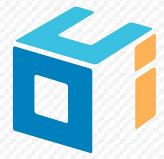


General Format

```
public class IoTDeviceDemo implements IoTSetup {  
  
    public static void main(String[] args) {  
  
        /** execute the behavior declared in the declareBehavior() method**/  
  
    }  
  
    public void declareConnections(Hardware c) {  
  
        /**Connect kits to the specific ports on Base Shield Board**/  
  
    }  
  
    public void declareBehavior(DeviceRuntime runtime) {  
  
        /**Write instructions to the devices for specific function (Ex. Turn on a LED)**/  
  
    }  
}
```



Connection()



Specify Pin Configuration

- The makers don't need to know the startup pin configuration
- For Analog and Digital, makers need to specify:

```
c.connectDigital (LED, D6); // connect a digital twig
```

```
c.connectAnalog (LightSensor, A1); // connect an analog twig
```

- For I2C, no pin specification is needed

```
c.useI2C();
```



General Format

```
public class IoTDeviceDemo implements IoTSetup {  
  
    public static void main(String[] args) {  
  
        /** execute the behavior declared in the declareBehavior() method**/  
  
    }  
  
    public void declareConnections(Hardware c) {  
  
        /**Connect kits to the specific ports on Base Shield Board**/  
  
    }  
  
    public void declareBehavior(DeviceRuntime runtime) {  
  
        /**Write instructions to the devices for specific function (Ex. Turn on a LED)**/  
  
    } }  
}
```

declareBehavior to turn on the LED



Declare to Turn on the LED

- Need to instantiate a channel for analog, digital, or I2C object:

```
final CommandChannel channel0 = runtime.newCommandChannel();
```

- A listener is needed to start or get input from a twig:

```
runtime.addStartupListener(() ->{  
    Channel0.digitalSetValue(6,1);});
```

"6" is the connection, "1" is "ON"



The Built-in Timing Framework

- For time sensitive device
- Rate of polling data:
 - Not to miss data
 - Polling frequently is costly
- Makers don't need to deal with the timing concept



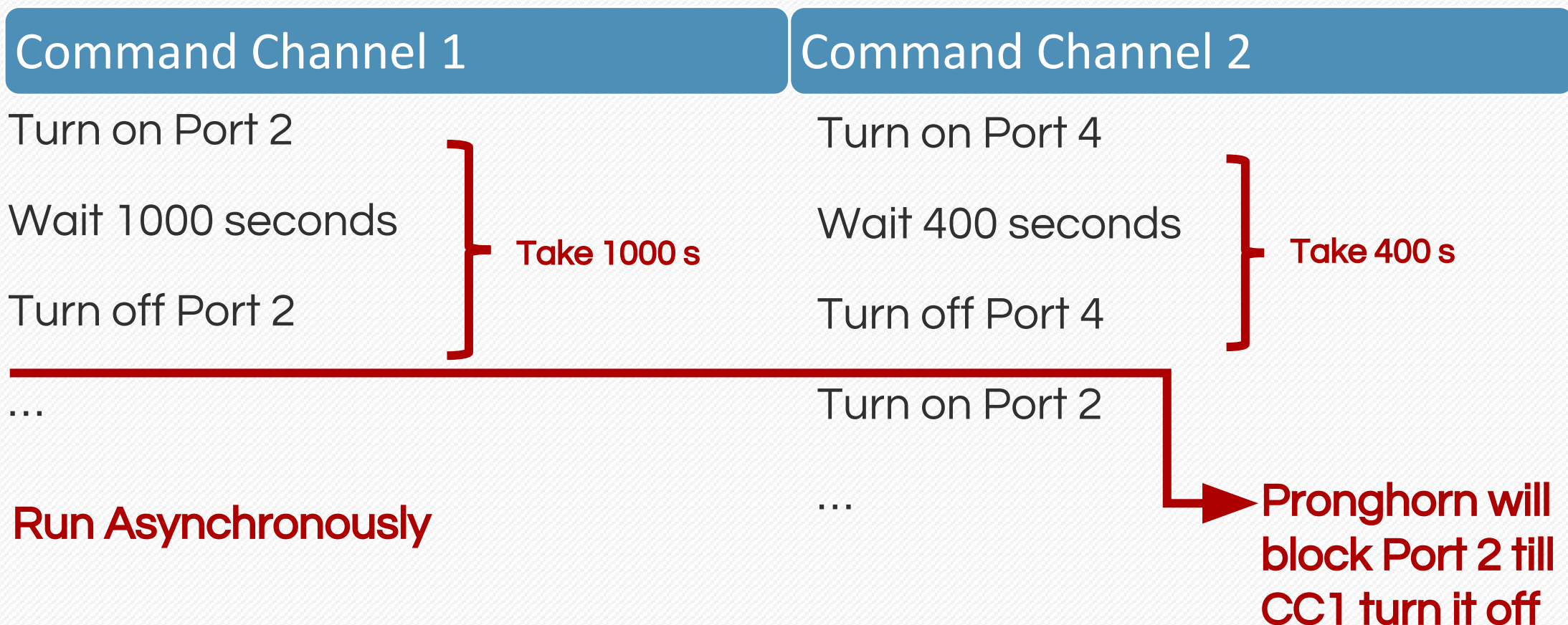
Timing and States

```
runtime.addDigitalListener((connection, time, value)->{  
    count +=value;  
    state = (count)%NUM_STATES;//define number of states  
    System.out.println("the state is:" + state);  
}); // this method will create states for a state machine
```

- Introduce the states concept instead of loops



Achieve Concurrent Programming



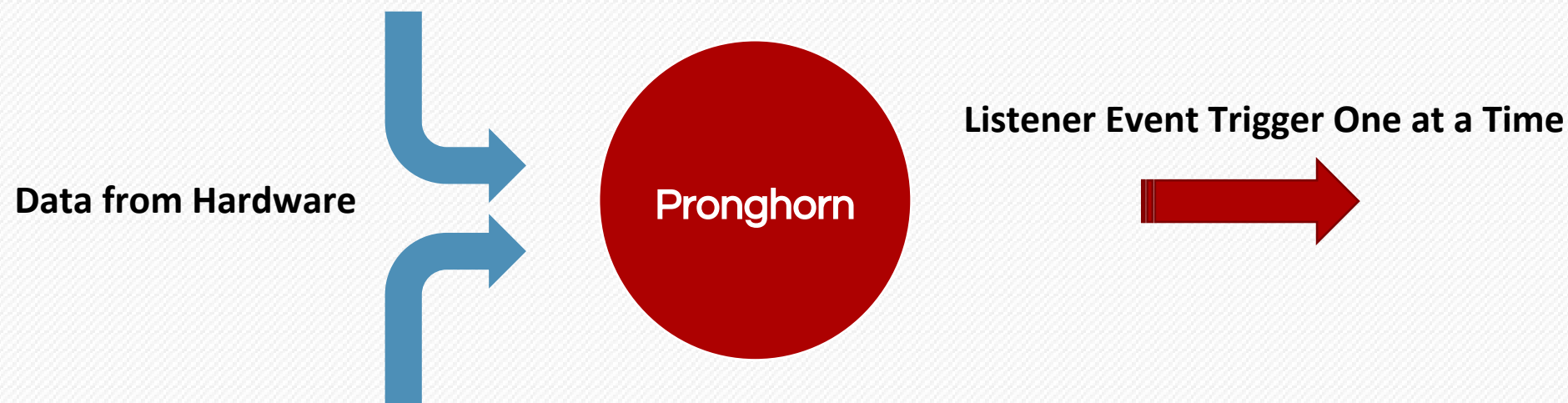


Pronghorn IoT Approach

Achieve Concurrent Programming

The other half of solving concurrency:

- Responses are back one after another





Pronghorn IoT Approach

Same Code Runs on Many Devices

Pronghorn Embedded Toolkit

Intel Edison

BeagleBone

Pi



Pronghorn IoT Approach

Simple Programing

Maker

- Specify Twig connection
- **Declarative** instructions
- Focus on implementing the IoT device

Pronghorn API

- Pin configuration
- Manage **concurrency**
- Abstracts the low-level native integration



Alternatives to Pronghorn

Pi4J

- Java
- Only for Pi
- Low level
- Imperative Programming

LibMraa

- Mostly JavaScript/Python
- For Intel product and Pi
- Low level
- Imperative Programming



Compare Pronghorn IoT to Alternatives

Turn on a LED using LibMraa in Java

Try to load the “mraajava” library

```
public class BlinkIO {  
    static {  
        try {  
            System.loadLibrary("mraajava");  
        } catch (UnsatisfiedLinkError e) {  
            System.err.println(e);  
            System.exit(1);  
        }  
    }  
}
```

The Body of the main()

```
public static void main(String argv[]) throws InterruptedException {  
    int iopin = 6;  
  
    Gpio gpio = new Gpio(iopin);  
  
    Result result = gpio.dir(Dir.DIR_OUT);  
  
    if (result != Result.SUCCESS) {  
        mraa.printError(result);  
        System.exit(1);  
    }  
  
    gpio.write(1);}}
```



Turn on a LED using LibMraa

(JavaScript)

```
var m = require('mraa');  
  
var myDigitalPin = new m.Gpio(6);  
  
myDigitalPin.dir(m.DIR_OUT);  
  
myDigitalPin.write(1);
```

(Python)

```
import mraa  
  
x = mraa.Gpio(6)  
  
x.dir(mraa.DIR_OUT)  
  
x.write(1)
```




The Java approach

Change Color of a LCD using LibMraa

Python Using LibMraa

```
import mraa

# Change the LCD back light
x = mraa.I2c(0)
x.address(0x62)

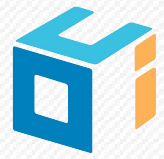
# initialise device
x.writeReg(0, 0)
x.writeReg(1, 0)

# sent RGB color data
x.writeReg(0x08, 0xAA)
x.writeReg(0x04, 255)
x.writeReg(0x02, 255)
```

Java Using Pronghorn

```
final CommandChannel channelcd
=runtime.newCommandChannel();

runtime.addStartupListener(() -> {
    Grove_LCD_RGB.commandForColor( channelcd,
    170,255,255); });
```



Why Pronghorn Embedded Toolkit

- Pronghorn is simple
- Makers will learn the low level programming later
- Hide concepts that makers don't need to learn
- Still can access all functions of the Embedded device



The Teaching Goal

- Top down Approach
- Allow students with little CS background to turn on a LED in 15m
- Effective (for more sophisticated programming)

Pronghorn API



API Design

- Lock free
- Garbage free
- Simple interface

Result

- Low overhead
- Low latency
- Low memory usage
- Great responsiveness
- Easy for the users



Traffic Light

```
public class IoTApp implements IoTSetup
{
    private static final Port LED3_PORT = D3;
    private static final Port LED1_PORT = D7;
    private static final Port LED2_PORT = D8;
    private static long prevTime = 0;
    private enum State {
        REDLIGHT(1200), GREENLIGHT(1000), YELLOWLIGHT(200);
        private int deltaTime;
        State(int deltaTime) { this.deltaTime = deltaTime; }
        public int getTime() { return deltaTime; }
    };
    private State state = State.YELLOWLIGHT;

    public static void main( String[] args ) {
        DeviceRuntime.run(new IoTApp());
    }

    @Override
    public void declareConnections(Hardware c) {
        c.connect(LED, LED1_PORT);
        c.connect(LED, LED2_PORT);
        c.connect(LED, LED3_PORT);
        c.setTriggerRate(500);
        c.useI2C();
    }

    @Override
    public void declareBehavior(DeviceRuntime runtime) {
        final CommandChannel channel1 = runtime.newCommandChannel();
        final CommandChannel channelLCD = runtime.newCommandChannel();
        runtime.addTimeListener((time) -> {
            switch(state) {
                case YELLOWLIGHT:
                    channel1.setValue(LED1_PORT, 0);
                    channel1.setValue(LED2_PORT, 1);
                    channel1.setValue(LED3_PORT, 0);
                    Grove_LCD_RGB.commandForTextAndColor(channelLCD, "YELLOW", 255, 255, 0);
                    if(time - prevTime >= state.getTime()) {
                        state = State.REDLIGHT;
                        prevTime = time;
                    }
                    break;
                case REDLIGHT:
                    channel1.setValue(LED1_PORT, 1);
                    channel1.setValue(LED2_PORT, 0);
                    channel1.setValue(LED3_PORT, 0);
                    Grove_LCD_RGB.commandForTextAndColor(channelLCD, "RED", 255, 0, 0);
                    if(time - prevTime >= state.getTime()) {
                        state = State.GREENLIGHT;
                        prevTime = time;
                    }
                    break;
                case GREENLIGHT:
                    channel1.setValue(LED1_PORT, 0);
                    channel1.setValue(LED2_PORT, 0);
                    channel1.setValue(LED3_PORT, 1);
                    Grove_LCD_RGB.commandForTextAndColor(channelLCD, "GREEN", 0, 255, 0);
                    if(time - prevTime >= state.getTime()) {
                        state = State.YELLOWLIGHT;
                        prevTime = time;
                    }
                    break;
            }
        });
    }
}
```

```
switch(state) {
    case YELLOWLIGHT:
        channel1.setValue(LED1_PORT, 0);
        channel1.setValue(LED2_PORT, 1);
        channel1.setValue(LED3_PORT, 0);
        Grove_LCD_RGB.commandForTextAndColor(channelLCD, "YELLOW", 255, 255, 0);
        if(time - prevTime >= state.getTime()) {
            state = State.REDLIGHT;
            prevTime = time;
        }
        break;
    case REDLIGHT:
        channel1.setValue(LED1_PORT, 1);
        channel1.setValue(LED2_PORT, 0);
        channel1.setValue(LED3_PORT, 0);
        Grove_LCD_RGB.commandForTextAndColor(channelLCD, "RED", 255, 0, 0);
        if(time - prevTime >= state.getTime()) {
            state = State.GREENLIGHT;
            prevTime = time;
        }
        break;
    case GREENLIGHT:
        channel1.setValue(LED1_PORT, 0);
        channel1.setValue(LED2_PORT, 0);
        channel1.setValue(LED3_PORT, 1);
        Grove_LCD_RGB.commandForTextAndColor(channelLCD, "GREEN", 0, 255, 0);
        if(time - prevTime >= state.getTime()) {
            state = State.YELLOWLIGHT;
            prevTime = time;
        }
        break;
}
```



References

Image of "Grove-Pi IoT device"

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Rapid Growth of IoT device

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Image of "Grove base shield board"

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