Predictive Modeling Time Series Analysis

Mirko Birbaumer

HSLU T&A

- Introduction
- Examples of Time Series
- Time Series with R and Python
- Transformation of Time Series Data
- Decomposition of Time Series

Example Time Series: PAN AM

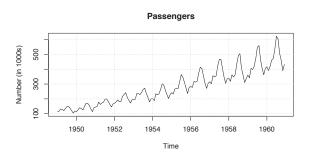
 The following table contains the number of airline passenger bookings (in thousands) per month of the airline PanAm (1927-1991) from 1949 to 1960

```
## 1949 112 118 132 129 121 135 148 148 148 133 114 140 ## 1950 115 126 141 135 125 149 170 170 158 133 114 140 ## 1951 145 150 178 163 172 178 179 189 184 162 146 166 ## 1952 171 180 193 181 183 218 230 242 209 191 172 194 ## 1954 204 188 235 227 243 264 272 237 211 180 201 ## 1955 242 233 267 269 270 315 364 347 312 274 237 278 ## 1955 242 233 267 269 270 315 364 347 312 274 237 278 ## 1955 242 233 267 269 270 315 364 347 312 274 237 278 ## 1957 315 301 356 348 355 422 465 467 404 347 305 336 ## 1958 340 318 362 348 363 435 491 505 404 359 310 337 ## 1959 360 342 406 396 420 472 535 622 606 508 461 390 432 405
```

• Is there a better way of representing this data set?

Example: PAN AM

ullet Presentation of data as table not convenient ullet visualize data



- The following patterns become visible:
 - ▶ global increase of flight bookings over time → trend
 - ightharpoonup more flight bookings during summer months ightharpoonup seasonality
 - lacktriangle observations are *not* independent ightarrow serial correlation

Examples Time Series

- PAN AM data was originally used to forecast future flight bookings in order to plan aircraft and crew demand
- Many real life measuring and data recording processes result in data sets that are serially correlated. Examples of such situations are:
 - ► Machine monitoring: Temperature, pressure, acoustic emissions, vibrations, etc. are measured at various locations in/at/around an operating engine (motor, generator, compressor, etc.)
 - Stock: Stock prices and exchange rates are recorded at the end of a trading day
 - ► Environmental observations: Temperature, humidity, pollen concentration, pollution, precipitation are recorded at a specific weather station
 - ▶ Federal statistics: Population census, income, accidents, . . .
- This kind of data is called time series data

Time Series Analysis

 There are several goals that one wants to achieve with time series analysis:

Descriptive Analysis:

By means of summary statistics and visualizations, the basic properties of a time series are understood

Modeling and Interpretation:

By modeling the underlying process that governs the observed time series, a deeper understanding can be gained. In particular, tests and confidence intervalls/bands can be constructed from the model. The sequential dependency of the time series is also often quantified.

Time Series Analysis

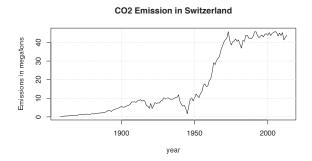
- Openion Decomposition:
 - ▶ Seasonality, in particular a periodic pattern in the data
 - Trend, gradually changing average of the series which is directly correlated with the time axis
- Prediction: By means of the model, future values of the time series can be predicted. Prediction for time series is often alternatively termed forecasting
- Regression:

One often tries to explain a time series (*response*) by several other time series (*predictors*). This idea is wide-spread in industry, where the goal is to replace in a multi-sensor setup a particular (expensive or hard to install) sensor by a model that predicts its values from the other sensor values. This is called *virtual sensoring* or *soft sensoring*.

Example: Kyoto Protocol

- Kyoto Protocol: amendment to the United Nations Framework Convention on Climate Change
- It opened for signature in December 1997 and came into force on February 16, 2005
- The arguments for reducing greenhouse gas emissions rely on a combination of science, economics, and time series analysis
- Decisions made in the next few years will affect the future of the planet

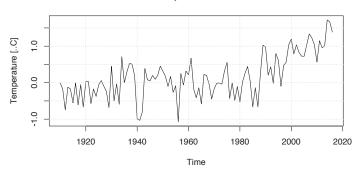
Example: Kyoto Protocol



- \bullet Figure shows the yearly emission of the greenhouse gas CO_2 in Switzerland from 1858 to 2013
- No seasonal effect (due to the yearly averaging)
- Peculiar trend is observable: The emissions increased heavily in the post WW2 era between the 1950s and 1970s

Global warming:





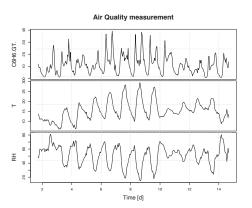
- Annual average temperature anomalities with respect to the average between 1910 and 2000 in Europe are shown
- Upward trend starting in the 1980s
- Previous figure (CO₂): a correlation between CO₂ emission and global warming is not deniable: physical theories support causal relation

Example: Air Quality

- AirQuality data set contains 9358 instances of hourly averaged responses from an array of 5 metal oxide chemical sensors embedded in an Air Quality Chemical Multisensor Device
- The device was located on the field in a significantly polluted area, at road level, within an Italian city
- Data were recorded from March 2004 to February 2005
- All in all, 13 variables are measured by the device

Example: Air Quality

Data set AirQuality:



• Concentration of benzene (C_6H_6), the air temperature in C° and the relative humidity (in %) are plotted over a period of 2 weeks

Example: Stock Index of Tesla

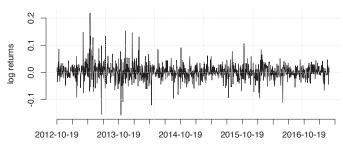
- Typical instance of time series are trading indices, and exchange rates in economics.
- Stock indices are often analyzed and subject to prediction attempts
- Trends in stock indices, however, are nearly impossible to forecast
- Here: stock index of Tesla

Example: Stock Index of Tesla



- Daily closing of 1112 consecutive trading days starting at 19.12.2012
- The Tesla stock index: impressive increase between March and June 2013
- Breakdown around February 2016 with subsequent sharp increase
- Presentation of the Model 3 in April 2016

Log returns of Tesla, Inc.



- Instead stock indices, log-returns are displayed, i.e. day-to-day changes of the logarithm of the index, are analyzed and modeled
- log-returns: approximation of relative change with respect to previous trading day
- ullet No trend anymore ullet this data is uncorrelated.
- Making predictions for log-returns based on historical data is fruitless endaveour (however, change of variance may be predicted)

Time Series with R and Python

Please see examples 2.1, 2.2, 2.3, and 2.4 of the Introduction to Time Series chapter

Basic transformation, Visualization and Decomposition of Time Series

- ullet Analysis of time series begins with the description, transformation and visualization of data ullet No modeling
- Does not give rise to proper predictions, confidence intervalls etc.
- Important insights and a profound understanding of the data can be achieved by these techniques
- Here:
 - Most important data transformations in the context of time series
 - ► Toolbox of helpful visualization techniques for exploring time series
 - Decomposition of time series into seasonal, trend and irregular components

Transformation of Time Series Data

- It is desirable or even necessary to transform a time series before the application of models and predictions
- In partiular, many methods assume a:
 - ▶ Gaussian or at least a symmetric distribution of the data
 - ▶ Linear trend relationship between time and data
 - ► Constant variance across time
- Example: for highly skewed or heteroskedastic data, it is often better not to use the original series

$$\{x_1,x_2,\ldots\}$$

but a transformed series

$$\{g(x_1), g(x_2), \ldots\}$$

Box-Cox-Transformationen

• A family of transformations, that is well suited for correcting skewness and variance are the *Box-Cox-transformations*:

Box-Cox-Transformations

For a time series $\{x_1, x_2, \dots\}$ with positive values the Box-Cox transformations are defined as

$$g(x) = \begin{cases} \frac{x^{\lambda} - 1}{\lambda} & \text{if } \lambda \neq 0\\ \log(x) & \text{if } \lambda = 0. \end{cases}$$

- Goal: choose the parameter λ such that desired properties hold
- See examples 3.1 of the Introduction to Time Series chapter

Time-shift Transformation

- Box-Cox family of transforms amounts to a modification of the values of the time series
- Sometimes, it is necessary to transform the time-axis as well
- Most simple version of time transforms: shifting

Time-shift transformation

Let $\{x_1, x_2, \dots\}$ be a time series.

① The time-shift by a *lag* of $k \in \mathbb{Z}$ is defined by

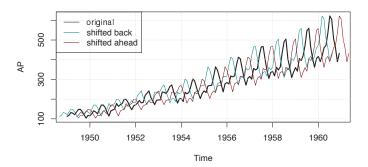
$$g(x_i) = x_{i-k}$$

② For the particular case where k=1 the time-shift is called backshift

$$B(x_i) = x_{i-1}$$

• Applying a time-shift to a time series amounts to go **back** k steps (if k > 0) or go **ahead** -k steps (if k < 0) in the series

Example Time-shift: AirPassengers



- Time-shift for k = 4 und k = -5
- See example 3.2 of the Introduction to Time Series chapter

Log-Returns

 Back-shift operator is applied when differences of time series are computed, since

$$x_i - x_{i-1} = x_i - B(x_i)$$

- Differencing is often combined with Box-Cox transformations
- Example: log-returns of a (financial) time series are defined as

$$y_i = \log(x_i) - \log(x_{i-1}) = \log\left(\frac{x_i}{x_{i-1}}\right) = \log\left(\frac{x_i - x_{i-1}}{x_{i-1}} + 1\right) \approx \frac{x_i - x_{i-1}}{x_{i-1}}$$

• Last equation: Taylor series expansion of the logarithm:

$$\log(s+1) = s - s^2/2 + \dots$$

Log-Returns

- Log-return time series y_i approximates the relative increase of the time series x_i at each time instance
- This quantity is often studied in financial applications: The original series

$$\{x_1, x_2, \ldots\}$$

may exhibit seemingly significant patterns

- but the series $\{y_1, y_2, \dots\}$ often is rather *random*
- See example 3.3 of the Introduction to Time Series chapter for log-return on Tesla stock index
- Tesla log-return looks quite random despite some large fluctuations from time to time
- Analysts try to model the waiting time between these fluctuations

Visualizations of Time Series

- See examples 3.4 to 3.6 of the Introduction to Time Series chapter
- Please solve exercises 1

Decomposition of Time Series

- Many time series are dominated by a trend and/or seasonal effects
- Models in this section are based on these components
- A simple additive decomposition model is given by

$$x_k = m_k + s_k + z_k$$

where

- k time index
- \triangleright x_k observed time series
- $ightharpoonup m_k$ trend
- ▶ s_k seasonal effect
- z_k error term that is, in general, a sequence of correlated random variables with mean zero

Decomposition of Time Series

- AirPassengers data: the seasonal effects may increase as the trend increases
- Thus, a multiplicative model seems more appropriate:

$$x_k = m_k \cdot s_k + z_k$$

• If the noise is multiplicative as well, i.e., $x_k = m_k \cdot s_k \cdot z_k$, the logarithm of x_k is a linear model again

$$\log(x_k) = \log(m_k) + \log(s_k) + \log(z_k)$$

Moving Average

• Moving average: method for estimating the trend m_k and the seasonal effect s_k by means of the moving average filter:

Moving average filter

Assume that $\{x_1, x_2, \dots, x_n\}$ is a time series and that $p \in \mathbb{N}$. The *moving* average filter of length p is defined as follows

▶ If p is odd, then p = 2l + 1 and the filtered sequence is defined by

$$g(x_i) = \frac{1}{\rho}(x_{i-1} + \cdots + x_i + \cdots + x_{i+1})$$

▶ If p is even, then p = 2I and the filtered sequence is defined by

$$g(x_i) = \frac{1}{p} \left(\frac{1}{2} x_{i-l} + x_{i-l+1} + \cdots + x_i + \cdots + x_{i+l-1} + \frac{1}{2} x_{i+l} \right)$$

The value p is referred to as window width.

Moving Average

- Moving average filter amounts to replace the i-th value in the time series by the average of the p nearest neighbors of x_i
- If p is **odd**, then the window stretches symmetrically around x_i
- For an **even** p one constructs a window of length p+1 (which is then odd) but counts the end points only by one half.
- ullet Example: If a time series has the frequency 12 (for monthly data), then the trend component of the time series can be estimated by applying the moving average filter with window width p=12
- Since we average at each point exactly over one period, the seasonal effects vanish and the trend component remains. This yields the trend estimator \hat{m}_k

Seasonal Effect

To estimate the seasonal additive effect one computes

$$\hat{s}_k = x_k - \hat{m}_k$$

- Now the time series \hat{s}_k is averaged for each time point in one cycle
- We obtain a single estimate of the effect for each cycle point

Remainder Effect

 We subtract the trend and seasonality estimates and arrive at the estimate for the remainder term:

$$\hat{r}_i = x_i - \hat{m}_i - \hat{s}_i$$

- The remainder term should consist of (possibly correlated) random values without structure/periodicity
- See examples 3.7 and 3.8 of the Introduction to Time Series chapter

Seasonal Decomposition of Time Series by Loess (STL)

- Although the decomposition method gives promising results for our example data set, it is rarely used in practice, for several reasons:
 - Lacking robustness with respect to outliers in the data.
 - ▶ The seasonal component is assumed to be constant over time
- State-of-the-art method for decomposing time series that does not suffer from the above drawbacks is seasonal decomposition of time series by loess (STL)
- Please see 3.10 of the Introduction to Time Series chapter

STL Decomposition

- STL procedure is iterative : outliers in the estimated remainder terms are detected and their effect mitigated by proper reweighting
- Moving average smoothing is replaced by loess regression which gives more flexibility and better results as the moving average.
- Loess regression is a form of **local** (mostly linear) regression which means that the regression line through data $(x_1, y_1), \ldots, (x_n, y_n)$ at a point x is only computed using the observations in **a neighborhood** of x

STL Decomposition

- Seasonal component is not assumed to be constant: the method considers cycle-subseries, i.e. the subseries of values at each position of the seasonal cycle
- For example, for a monthly series with frequency 12, the first cycle-subseries consists of the January values, the second of the February values etc
- These sub-cycles are also smoothed by loess and may change over time