QBUS 6840 Lecture 9

Seasonal ARIMA Models Model Combination

Professor Junbin Gao

The University of Sydney Business School

Review of $\overline{ARMA(p,q)}$ and $\overline{ARIMA(p,d,q)}$ Processes

• ARMA(p,q) Formulation with backshift operators

$$\left(1 - \sum_{i=1}^{p} \phi_i B^i\right) Y_t = c + \left(1 + \sum_{i=1}^{q} \theta_i B^i\right) \varepsilon_t,$$

ullet ARIMA(p,d,q) Formulation with backshift operators

$$\left(1 - \sum_{i=1}^{p} \phi_i B^i\right) (1 - B)^d Y_t = c + \left(1 + \sum_{i=1}^{q} \theta_i B^i\right) \varepsilon_t$$

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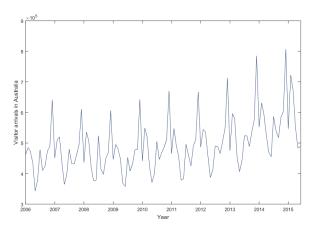
ullet ARIMA(p,d,q) Formulation with backshift operators

$$\left(1 - \sum_{i=1}^{p} \phi_i B^i\right) \quad \frac{\mathbf{Z_t}}{} = c + \left(1 + \sum_{i=1}^{q} \theta_i B^i\right) \varepsilon_t,$$

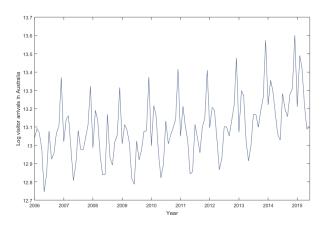
• Let $Z_t = (1 - B)^d Y_t$, then Z_t is the d-order differencing of Y_t . Hence ARMA(p, q) of Z_t is the ARMA(p, d, q) of Y_t

Procedure to Estimate ARMA(p, q)/ARIMA(p, d, q) processes: Lecture08_Example04.py

- For the given time series $\{Y_t\}$, check its stationarity by looking at its Sample ACF and Sample PACF.
- ② If ACF does not die down quickly, which means the given time series $\{Y_t\}$ is nonstationary, we seek for a transformation, e.g., log transformation $\{Z_t = log(Y_t)\}$, or the first order difference $\{Z_t = Y_t Y_{t-1}\}$, or even the difference of log time series, or the difference of the first order difference, so that the transformed time series is stationary by checking its Sample ACF
- When both Sample ACF and Sample PACF die down quickly, check the orders at which ACF or PACF die down. The order of ACF will be the lag q of the ARIMA and the order of PACF will be the lag p of the ARIMA, and the order of difference will be d.
- **3** Estimate the identified ARIMA(p, d, q), or ARMA(p, q) (if we did not do any difference transformation)
- **1** Make forecast with estimated ARIMA(p, d, q), or ARMA(p, q) model

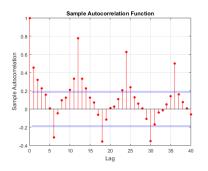


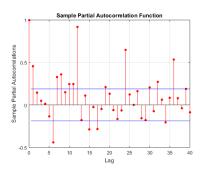
Variance stabilising transform



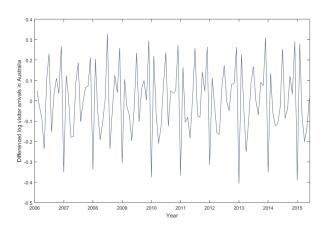
This is the Log transformed data.

ACF and PACF for the log visitors series

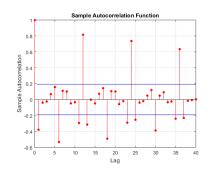


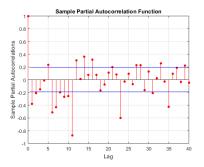


First differenced log visitors series



ACF and PACF for the first differenced log visitors series



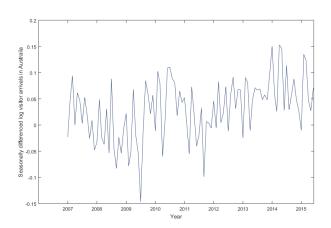


Seasonal differencing

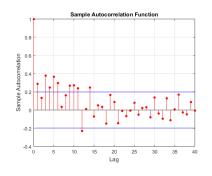
We can use seasonal differencing to remove the nonstationarity caused by the seasonality:

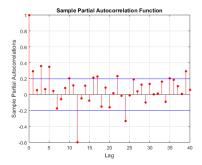
$$y_t - y_{t-12}$$

Seasonally differenced log visitors series



ACF and PACF for the seasonally differenced log visitors series





AR(1) specification

$$Y_t = c + \Phi_1 Y_{t-12} + \varepsilon_t$$

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In the form of B operator

$$(1 - \Phi_1 B^{12}) Y_t = c + \varepsilon_t$$

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In the form of B operator

$$(1 - \Phi_1 B^{12}) Y_t = c + \varepsilon_t$$

Considering the Seasonal Differencing series

$$Z_t = Y_t - Y_{t-12}$$

what is Z_t 's Seasonal AR(1)?

AR(1) specification

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$$Z_t = Y_t - Y_{t-12}$$

what is Z_t 's Seasonal AR(1)?

$$Z_t = c + \Phi_1 Z_{t-12} + \varepsilon_t$$

i.e., for Y_t ,

$$Y_t - Y_{t-12} = c + \Phi_1(Y_{t-12} - Y_{t-24}) + \varepsilon_t$$

AR(1) specification

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$$(1 - \Phi_1 B^{12}) Y_t = c + \varepsilon_t$$

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In the form of B operator

$$(1 - \Phi_1 B^{12})(1 - B^{12})Y_t = c + \varepsilon_t$$

MA(1) specification

$$Y_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

MA(1) specification

$$Y_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

In the form of B operator

$$Y_t = c + (1 + \Theta_1 B^{12})\varepsilon_t$$

Seasonal MA model MA(1) specification

$$Y_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

In the form of B operator

$$Y_t = c + (1 + \Theta_1 B^{12})\varepsilon_t$$

Considering seasonally differencing $Z_t = Y_t - Y_{t-12}$, its seasonal MA(1) is

$$Z_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

Seasonal MA model MA(1) specification

$$Y_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

In the form of B operator

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$$Z_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

Hence in terms of Y_t , it becomes

$$Y_t - Y_{t-12} = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

Seasonal MA model *MA*(1) specification

$$Y_t = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

In the form of B operator

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Hence in terms of Y_t , it becomes

$$Y_t - Y_{t-12} = c + \Theta_1 \varepsilon_{t-12} + \varepsilon_t$$

In the form of B operator

$$(1 - B^{12})Y_t = c + (1 + \Theta_1 B^{12})\varepsilon_t$$

 $ARIMA(p, d, q)(P, D, Q)_m$ models

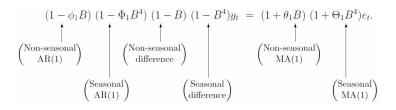
$$\begin{array}{ccc} \text{ARIMA} & \underbrace{(p,d,q)}_{\uparrow} & \underbrace{(P,D,Q)_m}_{\uparrow} \\ \left(\begin{array}{c} \text{Non-seasonal part} \\ \text{of the model} \end{array} \right) & \left(\begin{array}{c} \text{Seasonal part} \\ \text{of the model} \end{array} \right) \end{array}$$

where m = number of seasonal period (e.g. m = 12).

$$(1 - \phi_1 B - \phi_2 B^2 - \dots - \phi_p B^p)(1 - \Phi_1 B^m - \Phi_2 B^{2m} - \dots - \Phi_p B^{pm})(1 - B)^d (1 - B^m)^D Y_t$$

$$= c + (1 + \theta_1 B + \theta_2 B^2 + \dots + \theta_q B^q)(1 + \Theta_1 B^m + \Theta_2 B^{2m} + \dots + \Theta_Q B^{Qm}) \varepsilon_t$$

Seasonal Box-Jenkins models: Example



The above is an $ARIMA(1,1,1)(1,1,1)_4$ model (with c=0)

 $ARIMA(1,0,0)(0,1,1)_{12}$ for monthly data

 $ARIMA(1,0,0)(0,1,1)_{12}$ for monthly data:

$$(1 - \phi_1 B)(1 - B^{12})Y_t = c + (1 + \Theta_1 B^{12})\varepsilon_t$$

This is equivalent to

$$Y_t - Y_{t-12} = c + \phi_1(Y_{t-1} - Y_{t-13}) + \varepsilon_t + \Theta_1\varepsilon_{t-12}$$

 $ARIMA(1,0,0)(1,0,0)_{12}$ models

Factored:

$$(1 - \phi_1 B)(1 - \Phi_1 B^{12})Y_t = c + \varepsilon_t$$

Or write it out

$$Y_t = c + \phi_1 Y_{t-1} + \Phi_1 Y_{t-12} - \phi_1 \Phi_1 Y_{t-13} + \varepsilon_t$$

 $ARIMA(1,0,0)(1,0,0)_{12}$ models

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$$(1 - \phi_1 B)(1 - \Phi_1 B^{12})Y_t = c + \varepsilon_t$$

Or write it out

$$Y_{t} = c + \phi_{1} Y_{t-1} + \Phi_{1} Y_{t-12} - \phi_{1} \Phi_{1} Y_{t-13} + \varepsilon_{t}$$

This is because informally

$$(1 - \phi_1 B)(1 - \Phi_1 B^{12}) = 1 - \phi_1 B - \Phi_1 B^{12} + \phi_1 \Phi_1 B^{13}$$

Hence

$$(1 - \phi_1 B)(1 - \Phi_1 B^{12})Y_t = Y_t - \phi_1 Y_{t-1} - \Phi_1 Y_{t-12} + \phi_1 \Phi_1 Y_{t-13}$$

 $ARIMA(p, d, q)(P, D, Q)_m$ models

 $ARIMA(1,1,1)(1,1,0)_{12}$ model:

$$(1 - \phi_1 B)(1 - \Phi_1 B^{12})(1 - B)(1 - B^{12})Y_t = c + (1 + \theta_1 B)\varepsilon_t$$

 $ARIMA(p, d, q)(\overline{P, D, Q})_m$ models

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$$(1 - \phi_1 B)(1 - \Phi_1 B^{12})(1 - B)(1 - B^{12})Y_t = c + (1 + \theta_1 B)\varepsilon_t$$

First denote $Z_t = (1 - B)(1 - B^{12})Y_t$. For this new time series Z_t , the model is

$$(1 - \phi_1 B)(1 - \Phi_1 B^{12}) Z_t = c + (1 + \theta_1 B) \varepsilon_t$$

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$$(1 - \phi_1 B)(1 - \Phi_1 B^{12}) Z_t = c + (1 + \theta_1 B) \varepsilon_t$$

or

$$(1 - \phi_1 B - \Phi_1 B^{12} + \phi_1 \Phi_1 B^{13}) Z_t = c + (1 + \theta_1 B) \varepsilon_t$$

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Hence

$$Z_t = \phi_1 B Z_t + \Phi_1 B^{12} Z_t - \phi_1 \Phi_1 B^{13} Z_t + c + \varepsilon_t + \theta_1 B \varepsilon_t$$

or

$$Z_{t} = \phi_{1}Z_{t-1} + \Phi_{1}Z_{t-12} - \phi_{1}\Phi_{1}Z_{t-13} + c + \varepsilon_{t} + \theta_{1}\varepsilon_{t-1}$$

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 $ARIMA(1,1,1)(1,1,0)_{12}$ model:

$$(1 - \phi_1 B)(1 - \Phi_1 B^{12})(1 - B)(1 - B^{12})Y_t = c + (1 + \theta_1 B)\varepsilon_t$$

Finally from

$$Z_t = \phi_1 Z_{t-1} + \Phi_1 Z_{t-12} - \phi_1 \Phi_1 Z_{t-13} + c + \varepsilon_t + \theta_1 \varepsilon_{t-1}$$

 $ARIMA(p, d, q)(P, D, Q)_m$ models

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and

$$Z_t = (1 - B)(1 - B^{12})Y_t = Y_t - Y_{t-1} - Y_{t-12} + Y_{t-13}$$

= $(Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13})$

 $ARIMA(p, d, q)(P, D, Q)_m$ models

 $ARIMA(1,1,1)(1,1,0)_{12}$ model:

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and

$$Z_{t} = (1 - B)(1 - B^{12})Y_{t} = Y_{t} - Y_{t-1} - Y_{t-12} + Y_{t-13}$$
$$= (Y_{t} - Y_{t-1}) - (Y_{t-12} - Y_{t-13})$$

we

$$(Y_{t} - Y_{t-1}) - (Y_{t-12} - Y_{t-13}) = c + \phi_{1} [(Y_{t-1} - Y_{t-2}) - (Y_{t-13} - Y_{t-14})]$$

$$+ \Phi_{1} [(Y_{t-12} - Y_{t-13}) - (Y_{t-24} - Y_{t-25})]$$

$$- \phi_{1} \Phi_{1} [(Y_{t-13} - Y_{t-14}) - (Y_{t-25} - Y_{t-26})]$$

$$+ \varepsilon_{t} + \theta_{1} \varepsilon_{t-1} + \varepsilon_{t} + \theta_{1} \varepsilon_{t-1} + \varepsilon_{t} + \varepsilon_{t} = \varepsilon_{t} + \varepsilon_{t} = \varepsilon_{t} = \varepsilon_{t}$$

First and seasonal differencing

In our example for the log visitors series, we saw that seasonally differencing is not enough to make the series stationary. We can then consider the transform:

$$(1-B^{12})(1-B)Y_t = (Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13})$$

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Note that

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Note that

$$(Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13}) = (Y_t - Y_{t-12}) - (Y_{t-1} - Y_{t-13})$$

= $(1 - B^{12})Y_t - (1 - B^{12})Y_{t-1}$

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Note that

$$\begin{split} (Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13}) &= (Y_t - Y_{t-12}) - (Y_{t-1} - Y_{t-13}) \\ &= (1 - B^{12})Y_t - (1 - B^{12})Y_{t-1} \\ \text{denote } Z_t &= (1 - B^{12})Y_t : = Z_t - Z_{t-1} = (1 - B)Z_t \end{split}$$

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$$(1-B^{12})(1-B)Y_t = (Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13})$$

Note that

$$(Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13}) = (Y_t - Y_{t-12}) - (Y_{t-1} - Y_{t-13})$$

$$= (1 - B^{12})Y_t - (1 - B^{12})Y_{t-1}$$

$$denote \ Z_t = (1 - B^{12})Y_t : = Z_t - Z_{t-1} = (1 - B)Z_t$$

$$= (1 - B)(1 - B^{12})Y_t$$

First and seasonal differencing

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$$(1-B^{12})(1-B)Y_t = (Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13})$$

Note that

$$(Y_t - Y_{t-1}) - (Y_{t-12} - Y_{t-13}) = (Y_t - Y_{t-12}) - (Y_{t-1} - Y_{t-13})$$

$$= (1 - B^{12})Y_t - (1 - B^{12})Y_{t-1}$$

$$denote \ Z_t = (1 - B^{12})Y_t : = Z_t - Z_{t-1} = (1 - B)Z_t$$

$$= (1 - B)(1 - B^{12})Y_t$$

Hence

$$(1-B^{12})(1-B)Y_t = (1-B)(1-B^{12})Y_t$$

Seasonal Box-Jenkins models

 $ARIMA(p, d, q)(P, D, Q)_m$ models

ARIMA(0,0,0)(P,0,0)

- Sample autocorrelations die down for lags m, 2m, 3m, etc.
- Sample partial autocorrelations cut off at lag Pm.

ARIMA(0,0,0)(0,0,Q)

- Sample autocorrelations cuts off at lag Qm.
- Sample partial autocorrelations die down for lags m, 2m, 3m, etc.

ARIMA(0,0,0)(0,1,0)

• Sample autocorrelations and partial autocorrelations die down very slowly for lags m, 2m, 3m, etc.

Lecture09_Example01.py

Carefully read the scripts in Lecture09_Example01.py

Lecture09_Example01.py

Carefully read the scripts in Lecture09_Example01.py The concluded model is

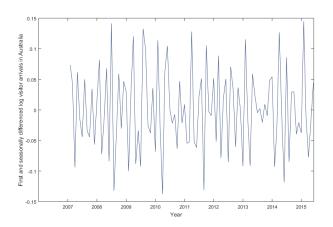
$$(1 - \phi_1 B - \phi_2 B^2 - \phi_3 B^3 - \phi_4 B^4 - \phi_5 B^5)(1 - B^{12})Z_t = \varepsilon_t + \Theta_1 B^{12} \varepsilon_t$$

or

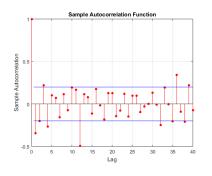
$$(1 - \phi_1 B - \phi_3 B^3 - \phi_5 B^5)(1 - B^{12})Z_t = \varepsilon_t + \Theta_1 B^{12}\varepsilon_t$$

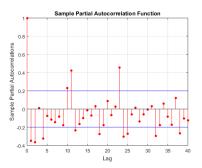
where Z_t is the quartic root data, i.e., $Z_t = Y_t^{1/4}$.

First and seasonal differencing



First and seasonal differencing





First and seasonally differenced log visitors: estimation

 $ARIMA(2,1,2)(0,1,1)_{12}$ model:

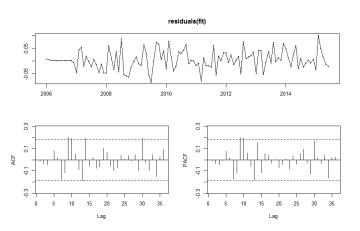
$$(1-\phi_1B-\phi_2B^2)(1-B)(1-B^{12})Y_t = c+(1+\theta_1B+\theta_2B^2)(1+\Theta_1B^{12})\varepsilon_t$$

Estimated coefficients (using R):

	ar1	ar2	ma1	ma2	sma1
	-0.7817	-0.3154	-0.0300	-0.4007	-0.7471
s.e.	0.2212	0.1227	0.2213	0.1909	0.1073

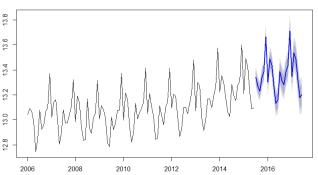
log likelihood=178.99, AIC=-345.97, AICc=-345.08, BIC=-330.28.

 $ARIMA(2,1,2)(0,1,1)_{12}$ model: residuals



 $ARIMA(2,1,2)(0,1,1)_{12}$ model: forecasts





Seasonal ARIMA models Notes

- Intercept terms induce permanent trends.
- Only seasonally difference once.
- Usually only either one seasonal AR or MA term is needed.
- Seasonal AR terms are often used when the lag m sample autocorrelation terms are positive.
- Seasonal MA terms are often used when the lag *m* sample autocorrelation terms are negative.

Introduction

Classical reference:

Bates, J. M., and C. W. J. Granger (1969). The combination of forecasts, *Operational Research Quarterly*, 20, 451–468.

They provide the following illustration:

Table 1. Errors in forecasts (actual less estimated) of passenger miles flown, 1953

	Brown's exponential smoothing forecast errors	Box-Jenkins adaptive forecasting errors	Combined forecas (½ Brown + ½ Box-Jenkins) errors
Jan	1	-3	-1
Feb.	6	-10	-2
March	18	24	21
April	18	22	20
May	3	-9	-3
June	17	-22	-19.5
July	-24	10	-7
Aug.	-16	2	-7
Sept.	-12	-11	-11.5
Oct.	-9	-10	-9.5
Nov.	-12	-12	-12
Dec.	-13	-7	-10
ariance of erro	ors 196	188	150

Introduction

- It is possible to combine unbiased forecasts $\hat{y}_{T+1|T}^{(i)}$ from models i = 1, ..., m.
- The models can be various ARIMA type of models or a set of ARIMA models, HW exponential smoothing models and regression models for example.
- $\hat{y}_{T+1|T}^{(i)}$, i = 1, ..., m could also be m expert forecasts.

Forecasting combinations Weights

The forecasts can be combined as follows

$$\hat{y}_{T+1|T}^{c} = \sum_{i=1}^{m} w_{i} \ \hat{y}_{T+1|T}^{(i)}$$

- The simplest way is to set $w_i = \frac{1}{m}$, then you are using a simple average.
- Simple averages often work surprisingly well.
- We often use convex combinations, that is $0 \le w \le 1$.
- The question is how to combine forecasts "optimally"?

Variance reduction: example of two forecasts

If you have two unbiased forecasts $\hat{y}_{T+1|T}^{(1)}$ and $\hat{y}_{T+1|T}^{(2)}$ with the corresponding variances σ_1^2 and σ_2^2 , then we can combine them linearly

$$\hat{y}_{T+1|T}^{c} = w\hat{y}_{T+1|T}^{(1)} + (1-w)\hat{y}_{T+1|T}^{(2)}.$$

The variance of the combined forecast will be

$$\sigma_c^2 = w^2 \sigma_1^2 + (1-w)^2 \sigma_2^2 + 2\rho w \sigma_1 (1-w) \sigma_2.$$

It will have minimum at

$$w = \frac{\sigma_2^2 - \rho \sigma_1 \sigma_2}{\sigma_1^2 + \sigma_2^2 - 2\rho \sigma_1 \sigma_2}.$$

where w is the "optimal" value. In case where $\hat{y}_{T+1|T}^{(1)}$ and $\hat{y}_{T+1|T}^{(2)}$ are uncorrelated $(\rho=0)$, then $w=\sigma_2^2/(\sigma_1^2+\sigma_2^2)$, which is no greater than the smaller of the two individual variances.

Empirical weights

- Unfortunately we dont know the actual σ_1^2 and σ_2^2 . Now we design a way to estimate them.
- ullet One-step ahead forecasts over a sample T+1 observations.
- Dividing the T+1 observations into an initial estimation (regression) subsample (e.g., from time 1 to t_0) and a second evaluation (prediction) subsample (from t_0+1 to T+1).
- The first subsample enables you to estimate the parameters of each model.
- In the second subsample, the forecasting performance of each model can be evaluated. Each model's performance will differ from period to period:

$$e_{1,t_0+1}, e_{1,t_0+2}, ..., e_{1,T}$$

 $e_{2,t_0+1}, e_{2,t_0+2}, ..., e_{2,T}$

Empirical weights

We are going to use the estimates (many possibilities)

$$\sigma_1^2pprox rac{1}{t_1-t_0}\sum_{t=t_0+1}^{t_1}e_{1,t}^2; \;\; ext{for } t_1=t_0+1,...,T$$
 $\sigma_2^2pprox rac{1}{t_1-t_0}\sum_{t=t_0+1}^{t_1}e_{2,t}^2; \;\; ext{for } t_1=t_0+1,...,T$

• In general, we can define The simplest version of such adaptive weights is, for $t_1 = t_0 + 1, ..., T$,

$$w_{t_1+1} = \frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2} \approx \frac{\sum_{t=t_0+1}^{t_1} (e_{2,t})^2}{\sum_{t=t_0+1}^{t_1} (e_{1,t})^2 + \sum_{t=t_0}^{t_1} (e_{2,t})^2},$$

Empirical weights

 At the time T, we can have the simplest version of such adaptive weights

$$w_{T+1} = \frac{\sum_{t=t_0+1}^{T} (e_{2,t})^2}{\sum_{t=t_0+1}^{T} (e_{1,t})^2 + \sum_{t=t_0+1}^{T} (e_{2,t})^2},$$

Or updating as (a clever way)

$$w_{T+1}^* = \alpha w_T^* + (1 - \alpha) \frac{\sum_{t=t_0+1}^T (e_{2,t})^2}{\sum_{t=t_0+1}^T (e_{1,t})^2 + \sum_{t=t_0+1}^T (e_{2,t})^2},$$

= $\alpha w_T^* + (1 - \alpha) w_{T+1}$

Alternative combination methods

Numerous other alternatives are available, see Clemen, R. T. (1989). Combining forecasts: a review and annotated bibliography, *International Journal of Forecasting*, 5, 559–583

Hendry, D. F., and M. P. Clements (2002). Pooling of forecasts, *The Econometrics Journal*, 7, 1–31

There is extensive empirical evidence in favour of combinations as a forecasting strategy.

- Forecasting combinations offer diversification gains that make them very useful compared to relying on a single model, as we have just seen.
- There may be structural breaks in the data, making it
 plausible that combining models with different levels
 adaptability will lead to better results than relying on a single
 model.

- Even without structural breaks, individuals models may be subject to misspecification bias: it is implausible that a single model dominates all others at all time periods.
- An additional argument for combining forecasts is that predictions from different forecasters may have been constructed under different loss functions.

- Estimation errors are a serious problem for obtaining the combination weights. Simple averages are often better.
- Similarly, nonstationarities can cause instabilities on the weights.

Additional references

If you are interested in this topic, you can also check:

- Stock and Watson (2004) Combination Forecasts of Output Growth in a Seven-Country Data Set, J. of Forecasting, 23, 405–430
- Timmermann (2006) Forecast combinations, Handbook of Economic Forecasting, vol 1, pp 135–196
- Vasnev A, Skirtun M and Pauwels L (2013) Forecasting Monetary Policy Decisions in Australia: A Forecast Combination Approach, Journal of Forecasting, 32, 151–156