Module 2: Introduction to Forecasting and Time Series References:

- Chapter 2 in Tsay
- Chapter 5 in Brooks

Section 2: Forecast combination and Autocorrelation testing (2.1) Forecast combination

- When forecasting is done, often more than one set of forecasts are produced
- In these cases, usually all forecasts are assessed jointly.
- Managers often change forecasts subjectively based on their own pre-conceived ideas.

- Question: are there optimal ways to combine different forecasts? Objectively?
- Formal methods include specifically choosing weights that allow forecasts to be combined into a weighted average forecast.
- If we have K forecasts, denoted $\hat{r}_{i;t+1|t}$ (adhoc choice of horizon 1), a weighted average of these is:

$$\hat{r}_{t+1|t} = \sum_{i=1}^{K} w_i \hat{r}_{i;t+1|t}$$

• The question is, what weights should we choose?

- Some common objective choices include:
 - 1. Equal weights: $w_i = \frac{1}{K}$
 - 2. Weights chosen to minimise (forecast) variance (e.g. Markowitz, hedging)
 - 3. Weights chosen to maximise previous forecast accuracy (or model fit in-sample)
 - 4. Weights chosen to optimise some other criteria (e.g. profit, manager's beliefs, etc)
- As you can see, when we are forecasting financial returns, forecast combination is related to portfolio optimisation.
- A portfolio of K assets has a log-return, in period t+1, that is:

$$r_{p;t+1} = \sum_{i=1}^{K} w_i r_{t+1}$$

• Generally, it is hard to beat equal weighting.

- You will practice with combining forecasts in lab session 6. Here I give a bit of the theory behind it.
- Classic reference: Bates, J. M., and C. W. J. Granger (1969). The combination of forecasts, *Operational Research Quarterly*, 20, 451–468.

 They provide the following illustration

TABLE 1. ERRORS IN FORECASTS (ACTUAL LESS ESTIMATED) OF PASSENGER MILES FLOWN, 1953

	Brown's exponential smoothing forecast errors	Box-Jenkins adaptive forecasting errors	Combined forecast (½ Brown+ ½ Box-Jenkins) errors		
Jan	1	-3	-1		
Feb.	6	-10	-2		
March	18	24	21		
April	18	22	20		
May	3	-9	-3		
June	-17	-22	-19.5		
July	-24	10	-7		
Aug.	-16	2	-7		
Sept.	-12	11	-11.5		
Oct.	-9	-10	− 9·5		
Nov.	-12	-12	-12		
Dec.	-13	-7	-10		
Variance of erro	ors 196	188	150		

• Variance reduction:

If you have two unbiased forecasts $\hat{y}_{T+1|T}^{(1)}$ and $\hat{y}_{T+1|T}^{(2)}$ with the corresponding variances σ_1^2 and σ_2^2 , then we can combine them linearly

$$\hat{y}_{T+1|T}^c = w * \hat{y}_{T+1|T}^{(1)} + (1-w) * \hat{y}_{T+1|T}^{(2)}.$$

The variance of the combined forecast will be

$$\sigma_c^2 = w^2 * \sigma_1^2 + (1 - w)^2 * \sigma_2^2 + 2 * \rho * w\sigma_1 * (1 - w)\sigma_2.$$

It will have minimum at

$$w^* = \frac{\sigma_2^2 - \rho \sigma_1 \sigma_2}{\sigma_1^2 + \sigma_2^2 - 2\rho \sigma_1 \sigma_2}.$$

In case where $\hat{y}_{T+1|T}^{(1)}$ and $\hat{y}_{T+1|T}^{(2)}$ are uncorrelated $(\rho = 0)$, then $w^* = \sigma_2^2/(\sigma_1^2 + \sigma_2^2)$.

• The variance of the combined forecast will be no greater than the smaller of the two individual forecast variances.

• Weights estimation: Adaptive weight is recommended. The simplest version is

$$\widehat{w}_{T+1}^* = \frac{\sum_{t=T-v}^{T} (e_{2,t})^2}{\sum_{t=T-v}^{T} (e_{1,t})^2 + \sum_{t=T-v}^{T} (e_{2,t})^2},$$

where $e_{1,t}$ and $e_{2,t}$ are known forecasting errors.

• Numerous other alternatives are available. For those interested in this topic, a few key references are:

Timmermann (2006) Forecast combination, Handbook of Economic Forecasting, vol 1, pp 135–196

Clemen, R. T. (1989). Combining forecasts: a review and annotated bibliography, *International Journal of Forecasting*, 5, 559–583

Hendry, D. F., and M. P. Clements (2004). Pooling of forecasts, *The Econometrics Journal*, 7, 1–31

Gibbs, C. G. and A. L. Vasnev (2017). Conditionally Optimal Weights and Forward-Looking Approaches to Combining Forecasts, ssrn.com/abstract=2919117

• Applications:

Stock and Watson (2004) Combination Forecasts of Output Growth in a Seven-Country Data Set, J. of Forecasting, 23, 405–430.

Vasnev A, Skirtun M and Pauwels L (2013) Forecasting Monetary Policy Decisions in Australia: A Forecast Combination Approach, Journal of Forecasting, 32, 151–156.

Matsypura, D., R. Thompson and A. L. Vasnev (2017). Optimal Selection of Expert Forecasts with Integer Programming, ssrn.com/abstract=2894083

(2.2) Assessing and testing for autocorrelation

- (Mean) stationarity for individual time series can be assessed via an autocorrelation (ACF) plot.
- The ACF plots the correlations between observations separated by a lag of k time periods, with k on the x-axis., i.e.

$$\rho_k = corr(y_t, y_{t-k}) = \frac{Cov(y_t, y_{t-k})}{\sqrt{Var(y_t)Var(y_{t-k})}}$$

$$\hat{\rho}_k = \frac{\sum_{t=k+1}^n (y_t - \bar{y})(y_{t-k} - \bar{y})}{\sum_{t=1}^n (y_t - \bar{y})^2}$$

- A variance stabilising transform should be applied to the data first. why?
- A stationary in mean series has an ACF that *dies down* reasonably quickly.
- A series that is **not** mean stationary has an ACF that dies down extremely slowly.

- A white noise process consists of a series of i.i.d. observations with mean 0 and fixed variance.
- What would the ACF for a white noise process look like?
- Matlab assumes that all lower lag correlations are 0 and approximates with:

$$s_{\hat{\rho}_k} = \frac{1}{\sqrt{n}}$$

for all lags k.

- In large samples we can form a t-statistic, $\frac{\hat{\rho}_k}{s_{\hat{\rho}_k}}$ and test ...
- To assess when we should fit an AR or MA model, we can do tests on these auto-correlations.

• A joint test considers the hypotheses:

$$H_0: \rho_1 = \rho_2 = \ldots = \rho_m = 0$$

- $H_1: \rho_i \neq 0 \text{ for some } i \in \{1, 2, ..., m\}$
- Box and Pierce (1970, JASA) introduced the Box-Pierce statistic for such a test.
- They noted that asymptotically $\hat{\rho}_l \sim N(0, \frac{1}{T})$ and introduced the Box-Pierce statistic as

$$BP(m) = T \sum_{l=1}^{m} \hat{\rho}_l^2$$

- If $\{y_t\}$ is an iid sequence weakly stationary process, BP(m) is asymptotically distributed as χ_m^2 , i.e. chi-squared with m degrees of freedom.
- Ljung and Box (1978, Biometrika) modified the BP(m) statistic to have more power in finite samples.

- The power of a statistical test measures the probability of rejecting a false null hypothesis.
- The more powerful test of Ljung and Box is thus better at detecting non-zero autocorrelations in a time-series process.
- Their Q(m) statistic is

$$Q(m) = T(T+2) \sum_{l=1}^{m} \frac{\hat{\rho}_{l}^{2}}{T-l}$$

- Q(m) is also asymptotically distributed χ^2 with m degrees of freedom.
- It is the preferred choice among econometricians and time series analysts to test for (absence of) autocorrelation.
- \bullet In practice, the choice of m can significantly affect the performance of the statistic.

- Quant. analysts often use $m \approx \ln(T)$ as a rule of thumb; or simply m = 5, 10, 15.
- When testing **residuals** (**not observations**) for autocorrelation, the degrees of freedom of the test must be adjusted to account for parameter estimation.
- This is done by subtracting from m the number of terms in the mean and variance equations, **not including those for a constant mean and constant variance**.
- For example, when fitting an AR(p) model to data and using the Q(m) statistic above on the residuals, the correct degrees of freedom would be m-p.
- Significant auto-correlations in $\{y_t\}$ indicate that an AR, MA or ARMA model may be useful.

(2.3) Example

- Consider again the CBA daily prices on the ASX.
- First, are there autocorrelation effects that may need to be modelled?
- Figure 1 shows the returns and their ACF.

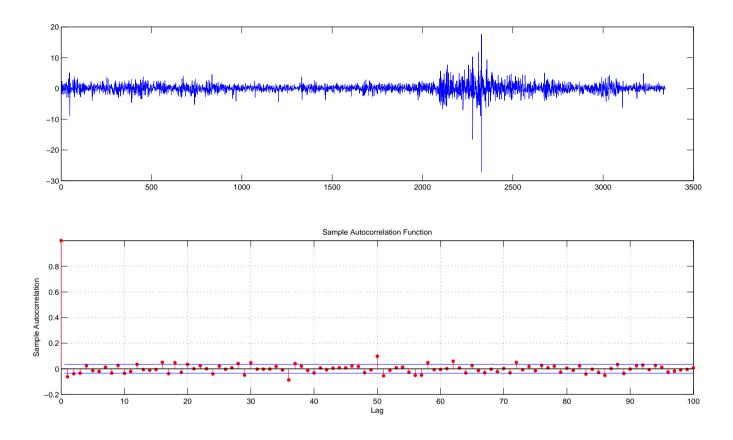


Figure 1: Log-returns and their ACF for CBA from Jan, 2000 to Feb, 2011.

• The Ljung-Box test was carried out on the first m=8 autocorrelations.

QBUS6830 (2019); Module 2;

- The null hypothesis is H_0 : $\rho_1 = \rho_2 = \ldots = \rho_8 = 0$.
- The p-value from the Q(8) statistic is 0.0002.
- As such we reject the null and conclude that at least one of the first 8 sample auto-correlations in the CBA return data are significantly different to 0.
- We consider the AR(1), AR(2) and ARMA(1,1) models to capture this autocorrelation.
- The three estimated models are:
 - 1. AR(1): $y_t = 0.022 0.066y_{t-1} + e_{1t}$
 - 2. AR(2): $y_t = 0.023 0.069y_{t-1} 0.044y_{t-2} + e_{2t}$
 - 3. ARMA(1,1): $y_t = 0.010 + 0.55y_{t-1} 0.61e_{3,t-1} + e_{3t}$
- If the models adequately capture the correlation or time series pattern in the mean

of the data, then their residuals should be iid and have no remaining autocorrelation in them.

• Ljung-Box tests were applied to the residual series e_1 , e_2 , e_3 , using the same degrees of freedom in each case of 5, 8 and 10.

• Figure 2 shows the time series plots for each of e_1, e_2, e_3 . Under the assumptions of the models fit, we expect these to show no pattern over time.

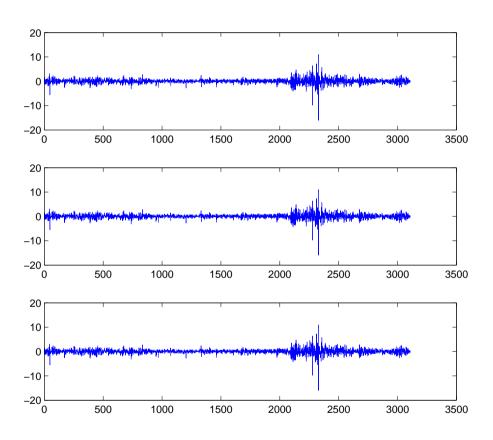


Figure 2: Residuals from AR(1), AR(2) and ARMA(1,1) models applied to CBA returns

• Figure 3 shows the ACF plots for each of e_1, e_2, e_3 .

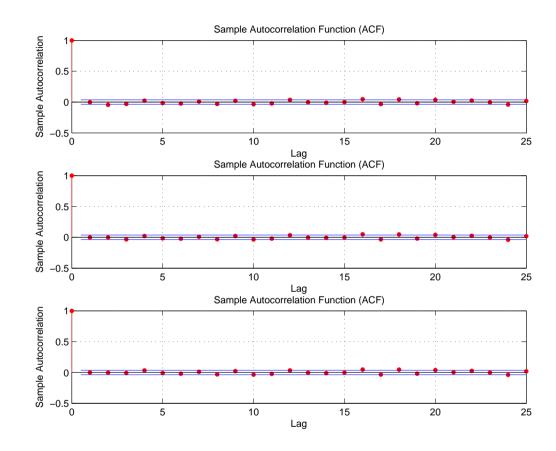


Figure 3: ACF for residuals from AR(1), AR(2) and ARMA(1,1) models applied to CBA returns

• Table 1 shows the results of these tests.

Table 1: Ljung-Box tests applied to the residual series e_1, e_2, e_3

Model	lags	df	p-val
AR(1)	6	5	0.02
	9	8	0.02
	11	10	0.008
AR(2)	7	5	0.17
	10	8	0.037
	12	10	0.018
ARMA(1,1)	7	5	0.33
	10	8	0.075
	12	10	0.034

• The ARMA(1,1) model appears to fit the data the best, while the AR(1) model fits the worst in terms of capturing the autocorrelation pattern in the data.

TIME SERIES REGRESSION

- Regression terms can be added to ARMA models OR ARMA terms can be added to regression models
- In the context of forecasting, it would be most usual to include lagged explanatory variables in the model. why??

• Figure 4 shows the daily index and log return values for the AORD and S&P500 indices, from January, 2000 until Feb, 2013.

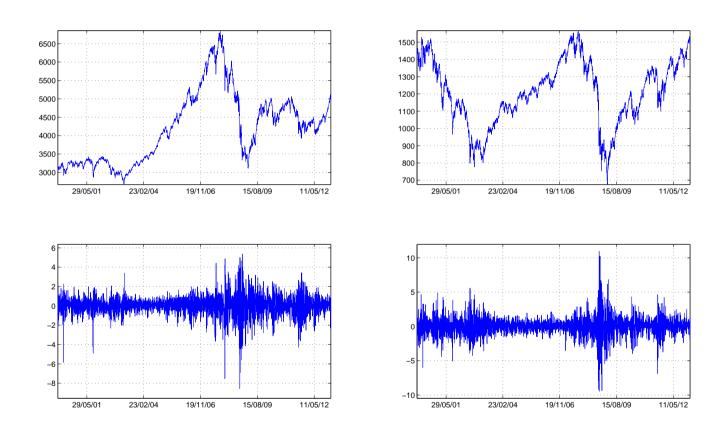


Figure 4: Index values and daily log returns for AORD and SP500 indices

- The sample from Jan, 2008 Feb, 2013 will be used as as forecast sample; the learning sample from January, 2000 to January, 2008
- Question: is there a relationship between AORD and S&P500 daily returns that we can use to forecast?

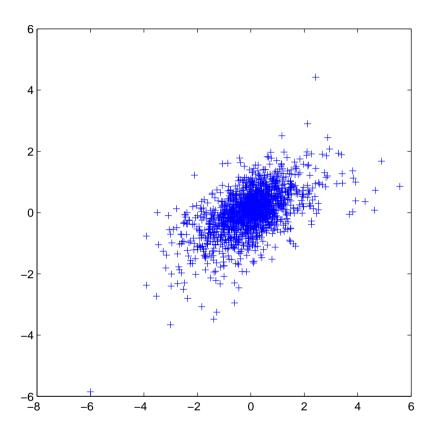


Figure 5: Scatterplot of daily log returns for AORD vs lagged SP500 indices

• The estimated regression relationship is:

$$AORD_t = 0.031 + 0.396 \times S\&P500_{t-1} + \hat{\epsilon_t}$$

OR

$$\hat{AORD}_t = 0.031 + 0.396 \times S\&P500_{t-1}$$

- $R^2 = 40\%$ indicating that 40% of the variation in AORD returns is captured by the straight line relationship with S&P500 returns.
- In other words, 40% of the daily movements in the AORD index are explained by the previous day's movements in the S&P500 index.
- Should we add ARMA terms to this model?

• Figure 6 shows residuals over time and then their ACF from this regression model.

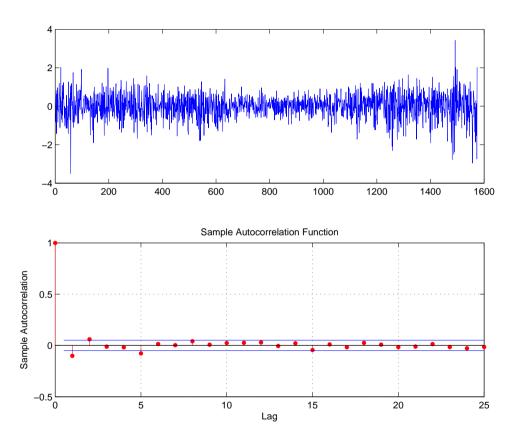


Figure 6: Residuals from regression of AORD(t) on SP500(t-1) for Jan, 2000 to Feb, 2013.

- Significant autocorrelations seem to exist at lags 1, 2 and 5.
- LB statistics using 5 and 10 degrees of freedom (using 6 and 11 lags) reveal statistically significant correlations, with p-values both close to 0.
- Based on this I will try three more time series regression models:

$$AORD_{t} = \alpha + \beta \times S\&P500_{t-1} + \phi_{1} \times AORD_{t-1} + \epsilon_{t}$$

$$AORD_{t} = \alpha + \beta \times S\&P500_{t-1} + \phi_{1} \times AORD_{t-1}$$

$$+ \phi_{2} \times AORD_{t-2} + \epsilon_{t}$$

$$AORD_{t} = \alpha + \beta \times S\&P500_{t-1} + \phi_{1} \times AORD_{t-1}$$

$$+ \phi_{2} \times AORD_{t-2} + \phi_{3} \times AORD_{t-3}$$

$$+ \phi_{4} \times AORD_{t-4} + \phi_{5} \times AORD_{t-5} + \epsilon_{t}$$

• These are time series regression models: I label them Reg-AR(1), Reg-AR(2) and, Reg-AR(5).

- It is also possible to add extra lags of the X variable: e.g. here we could add $S\&P500_{t-2}, S\&P500_{t-3}$, etc.
- I leave that to you.
- I will now forecast the last 1000 days: from March, 2009 Jan, 2013 of AORD returns using these models.
- I will use a forecast horizon of 1 day, a fixed size moving window of T=1574 and I will re-estimate all parameters with each new forecast.
- I also include the naive model and the 25 day sample mean forecast model.
- I use Gaussian maximum likelihood to estimate all the models, but the estimates will be only negligibly away from their LS counterparts.

• The models are initially estimated as:

$$AORD_{t} = 0.032 + 0.396 \times S\&P500_{t-1} - 0.044 \times AORD_{t-1}$$

$$+ \epsilon_{t}$$

$$AORD_{t} = 0.030 + 0.396 \times S\&P500_{t-1} - 0.042 \times AORD_{t-1}$$

$$+ 0.062 \times AORD_{t-2} + \epsilon_{t}$$

$$AORD_{t} = 0.032 + 0.394 \times S\&P500_{t-1} - 0.045 \times AORD_{t-1}$$

$$+ 0.064 \times AORD_{t-2} + 0.012 \times AORD_{t-3}$$

$$- 0.030 \times AORD_{t-4} - 0.062 \times AORD_{t-5} + \epsilon_{t}$$

• Figure 7 shows the data being forecast and the forecast from the five time series regression models.

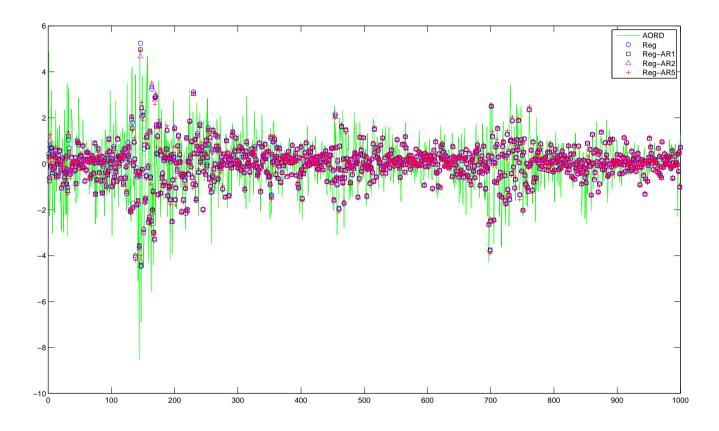


Figure 7: Forecasts from time series regression models of AORD for March, 2009 to Jan, 2013.

• Comments?

• Forecast accuracy is measured by RMSE, MAD and by Mincer-Zarnawitz regressions, without outputs in Table 2:

Table 2:	Forecast	accuracy	measures	for	100	days	of	CBA	returns

	Reg	Reg-AR(1)	Reg-AR(2)	Reg-AR(5)	Naive	Adhoc
Measure				Last day	Last day	25 days
RMSE	1.201	1.198	1.200	1.207	1.846	1.331
MAD	0.839	0.838	0.839	0.844	1.348	0.962
R^2	0.187	0.189	0.186	0.182	0.0001	0.0003
\hat{lpha}	0.0072	0.0072	0.0074	0.0066	0.0142	0.0142
\hat{eta}	0.722	0.730	0.726	0.707	0.0087	0.0823
F-stat $(2,998)$	34.177	31.78	32.58	38.07	984.50	33.87
p-val	0.000	0.000	0.000	0.000	0	0.000

- The AR terms only marginally improve on the original regression in terms of forecast accuracy.
- R^2 during the forecast period is a maximum, of 19%, for the Reg-AR(1) model.

- All models can be strongly rejected as accurate forecasters in the sense of $\alpha = 0$; $\beta = 1$ in a Mincer-Zarnawitz regression.
- Clearly all the β s are significantly below 1.
- The naive and adhoc models do the worst under all measures.
- Regarding forecast accuracy, this is about the maximum accuracy that can be achieved for forecasting returns.
- For most assets and portfolios, the forecast accuracy of the best models will be much less.
- You'll get a taste of this in the lab session.