

# QBUS6840 Lecture 6

## Exponential Smoothing (Seasonal)

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## Exponential smoothing

- Holt-Winters smoothing
  - Exponential smoothing methods for seasonal data.
  - Additive seasonality.
  - Multiplicative seasonality.
- Damped Trend Exponential Smoothing
- Damped Trend Seasonal

## Reading

- Online Textbook Sections 7.3-7.4 and 7.6:  
<https://otexts.org/fpp2/expsmooth.html> and/or
- BOK Sec 8.4-8.5

# Introducing Additive Holt-Winters smoothing

- The ideal scenario

$$y_t = \overset{\text{trend}}{\omega_0 + \omega_1 t} + S_t + \varepsilon_t$$

- Additive decomposition model: assuming  $\omega_0$ ,  $\omega_1$  and  $S_t$  ( $M$  different values) are fixed constants.
- Simple exponential method: modelling the case where  $S_t = 0$ ,  $\omega_1 = 0$  (or constant) and  $\omega_0$  changes with time
- Trend corrected exponential method: modelling the case where  $S_t = 0$ , both  $\omega_1$  and  $\omega_0$  are changing
- How to model the data if the level, the level growth rate (the trend), and seasonal patterns are changing?

# Additive Holt-Winters smoothing

$$\begin{aligned}l_t &= \alpha(y_t - S_{t-M}) + (1 - \alpha)(l_{t-1} + b_{t-1}), & 0 \leq \alpha \leq 1 \\b_t &= \beta(l_t - l_{t-1}) + (1 - \beta)b_{t-1}, & 0 \leq \beta \leq 1 \\S_t &= \gamma(y_t - l_{t-1} - b_{t-1}) + (1 - \gamma)S_{t-M}, & 0 \leq \gamma \leq 1\end{aligned}$$

$$\hat{y}_{t+1|1:t} = l_t + b_t + S_{t+1-M}.$$

Always read this as

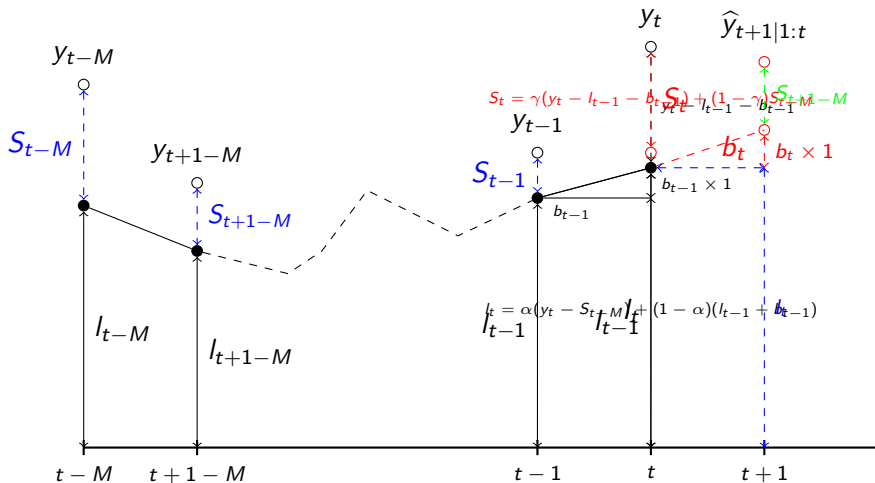
$$\hat{y}_{t+1|1:t} = l_t + b_t \times 1 + S_{t+1-M}.$$

Sometimes we also write the seasonal update as

$$S_t = \gamma(y_t - l_t) + (1 - \gamma)S_{t-M}, \quad 0 \leq \gamma \leq 1$$

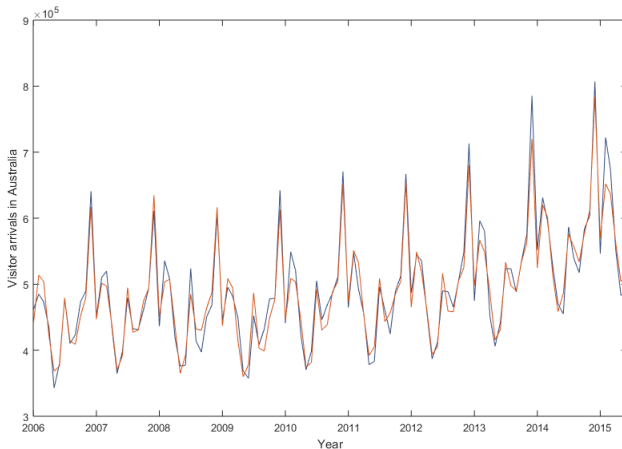
# Explanation

## Additive Holt-Winters smoothing



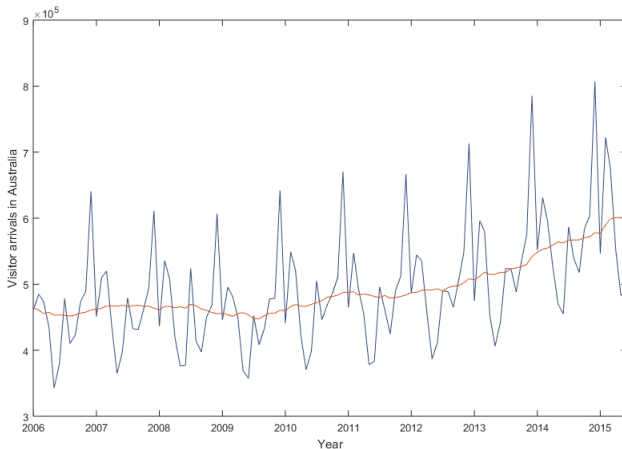
# Visitor arrivals in Australia: Lecture06\_Example01.py

Additive Holt-Winters method



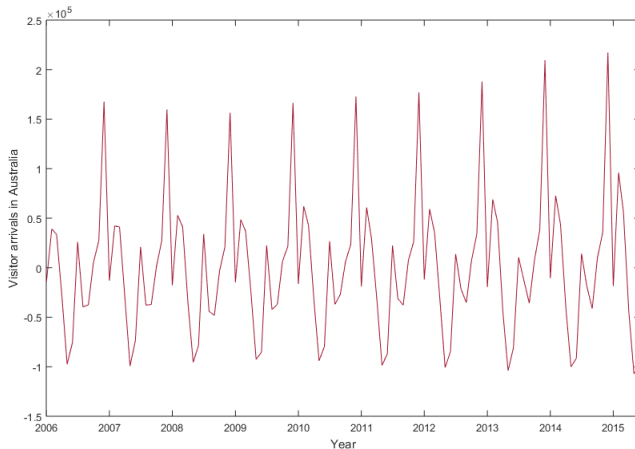
# Visitor arrivals in Australia

Additive Holt-Winters level component estimate



# Visitor arrivals in Australia

Additive Holt-Winters seasonal factors





# Additive Holt-Winters smoothing

## Choice of initial values

How should we set the initial values  $l_0, b_0, s_0, s_{-1}, \dots, s_{2-M}, s_{1-M}$ ?

### Suggested Method

- 1 Do a linear least square regression over the data  $y_1, \dots, y_T$  to find out

$$\hat{y}_t = \hat{\omega}_0 + \hat{\omega}_1 t$$

- 2 Take  $l_0 = \hat{\omega}_0$  and  $b_0 = \hat{\omega}_1$
- 3 Find out  $\hat{s}_t = y_t - \hat{y}_t$ , then take the average of  $\hat{s}_t$  as one of  $s_0, s_{-1}, \dots, s_{2-M}, s_{1-M}$  according to each season.

# Additive Holt-Winters smoothing

## Some notes

- Useful when level and/or trend and seasonal variation is changing
- Most useful when seasonal pattern changing in a cyclical or irregular fashion – but not too much!
- Choice of initial seasonal indices can be important.

# Additive Holt-Winters smoothing

## Model

$$l_t = \alpha(y_t - S_{t-M}) + (1 - \alpha)(l_{t-1} + b_{t-1}),$$

$$b_t = \beta(l_t - l_{t-1}) + (1 - \beta)b_{t-1},$$

$$S_t = \gamma(y_t - l_t) + (1 - \gamma)S_{t-M},$$

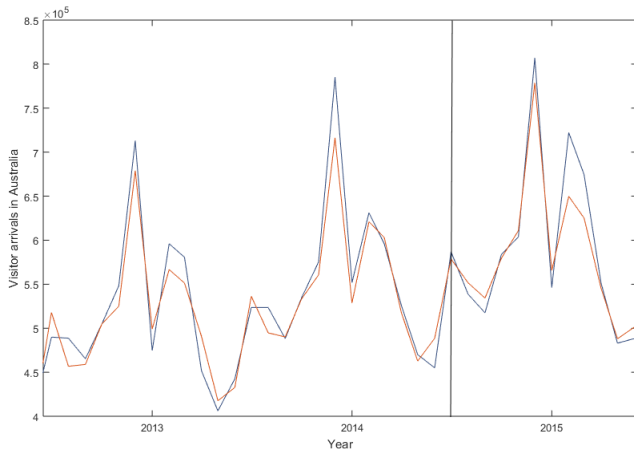
$$y_{t+1} = l_t + b_t + S_{t+1-M} + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim N(0, \sigma^2).$$

We can choose the parameters  $\alpha$ ,  $\beta$  and  $\gamma$  by minimising

$$SSE = \sum_{t=1}^n (y_t - l_{t-1} - b_{t-1} - S_{t-M})^2$$

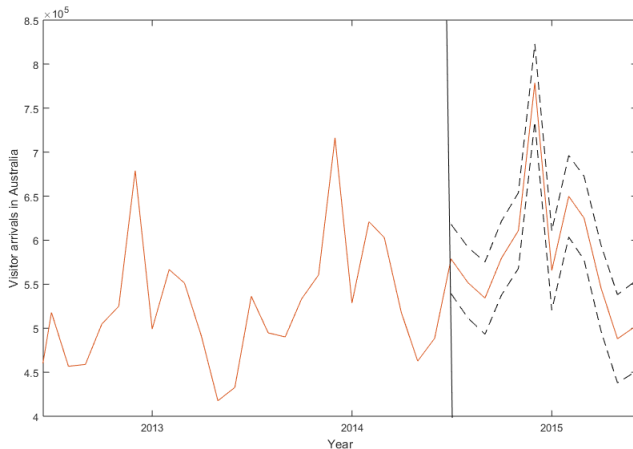
# Visitor arrivals in Australia

Additive Holt-Winters forecast



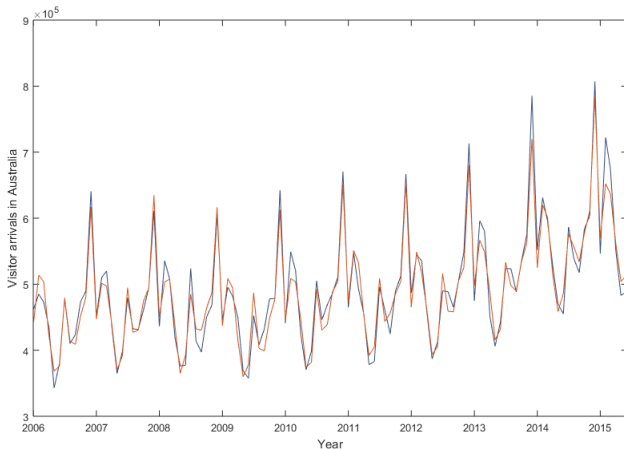
# Visitor arrivals in Australia

Additive Holt-Winters forecast



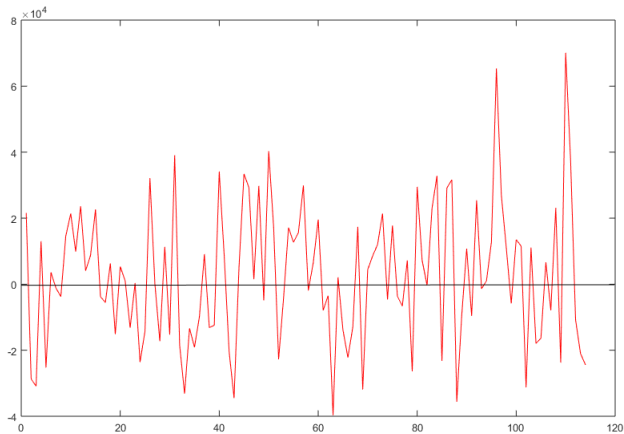
# Visitor arrivals in Australia

Additive Holt-Winters fit



# Visitor arrivals in Australia

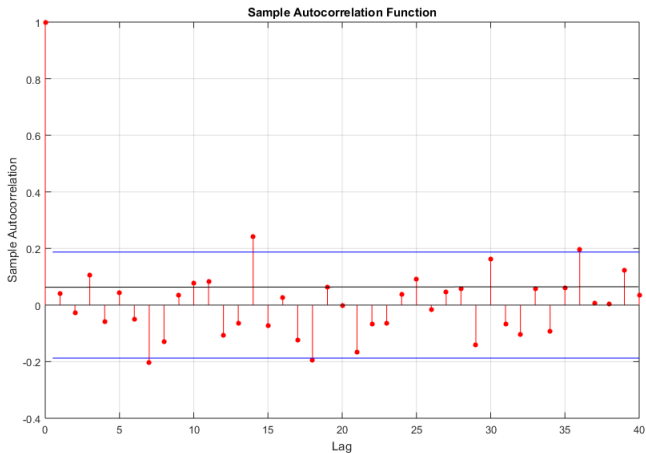
Additive Holt-Winters residuals



# Visitor arrivals in Australia

## Additive Holt-Winters residual autocorrelations

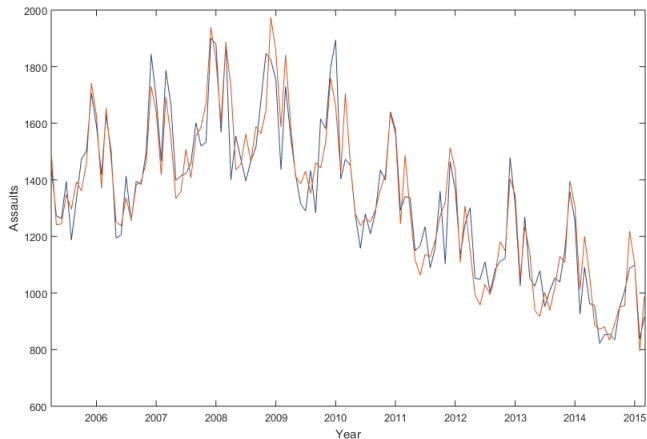
We will talk about this in Week 7





# Alcohol related assaults in NSW

Additive Holt-Winters fit



# Additive Holt-Winters smoothing

## Error correction formulation

$$\begin{aligned}l_t &= \alpha(y_t - S_{t-M}) + (1 - \alpha)(l_{t-1} + b_{t-1}) \\&= l_{t-1} + b_{t-1} + \alpha(y_t - l_{t-1} - b_{t-1} - S_{t-M}) \\&= l_{t-1} + b_{t-1} + \alpha\varepsilon_t\end{aligned}$$

# Additive Holt-Winters smoothing

## Error correction formulation

First from the first model, we have

$$\begin{aligned}l_t &= \alpha(y_t - S_{t-M}) + (1 - \alpha)(l_{t-1} + b_{t-1}) \\ &= l_{t-1} + b_{t-1} + \alpha(y_t - S_{t-M} - l_{t-1} - b_{t-1})\end{aligned}$$

Hence

$$l_t - l_{t-1} - b_{t-1} = \alpha(y_t - S_{t-M} - l_{t-1} - b_{t-1})$$

Hence,

$$\begin{aligned}b_t &= \beta(l_t - l_{t-1}) + (1 - \beta)b_{t-1} \\ &= b_{t-1} + \beta(l_t - l_{t-1} - b_{t-1}) \\ &= b_{t-1} + \beta\alpha(y_t - l_{t-1} - b_{t-1} - S_{t-M}) \\ &= b_{t-1} + \alpha\beta\varepsilon_t\end{aligned}$$

# Additive Holt-Winters smoothing

## Error correction formulation

First from the first model, we

$$\begin{aligned}y_t - l_t - S_{t-M} &= y_t - S_{t-M} - \alpha(y_t - S_{t-M}) - (1 - \alpha)(l_{t-1} + b_{t-1}) \\&= (1 - \alpha)(y_t - S_{t-M}) - (1 - \alpha)(l_{t-1} + b_{t-1}) \\&= (1 - \alpha)(y_t - l_{t-1} - b_{t-1} - S_{t-M}) = (1 - \alpha)\varepsilon_t\end{aligned}$$

Hence

$$\begin{aligned}S_t &= \gamma(y_t - l_t) + (1 - \gamma)S_{t-M} \\&= S_{t-M} + \gamma(y_t - l_t - S_{t-M}) \\&= S_{t-M} + \gamma(1 - \alpha)\varepsilon_t\end{aligned}$$

# Additive Holt-Winters smoothing

## Error correction formulation

$$l_t = l_{t-1} + b_{t-1} + \alpha \varepsilon_t$$

$$b_t = b_{t-1} + \alpha \beta \varepsilon_t$$

$$S_t = S_{t-M} + \gamma(1 - \alpha)\varepsilon_t$$

$$y_t = l_{t-1} + b_{t-1} + S_{t+1-M} + \varepsilon_t$$

$$\text{e.g. } y_{t+1} = l_{t-1} + 2b_{t-1} + S_{t-M+1} + \alpha(1 + \beta)\varepsilon_t + \varepsilon_{t+1}$$

# Additive Holt-Winters smoothing

## Forecasting equations

$$\begin{aligned}\hat{y}_{t+1|1:t} &= E(l_t + b_t + S_{t-M+1} + \varepsilon_{t+1} | y_{1:t}) \\ &= l_t + b_t + S_{t-M+1} \\ & (= l_{t-1} + 2b_{t-1} + S_{t-M+1} + \alpha(1 + \beta)\varepsilon_t)\end{aligned}$$

$$\begin{aligned}\hat{y}_{t+2|1:t} &= E(l_{t+1} + b_{t+1} + S_{t-M+2} + \varepsilon_{t+2} | y_{1:t}) \\ &= E(l_t + 2b_t + S_{t-M+2} + \alpha(1 + \beta)\varepsilon_{t+1} + \varepsilon_{t+2} | y_{1:t}) \\ &= l_t + 2b_t + S_{t-M+2}\end{aligned}$$

$\vdots$

$$\hat{y}_{t+h|1:t} = l_t + hb_t + S_{t-M+(h \bmod M)}$$

# Additive Holt-Winters smoothing

## Variance for interval forecasts

$$y_{t+1} = l_{t-1} + 2b_{t-1} + S_{t-M+1} + \alpha(1 + \beta)\varepsilon_t + \varepsilon_{t+1}$$

$$\begin{aligned}\text{Var}(y_{t+1}|y_{1:t}) &= \text{Var}(l_t + b_t + S_{t-M+1} + \varepsilon_{t+1}|y_{1:t}) \\ &= \sigma^2\end{aligned}$$

$$\begin{aligned}\text{Var}(y_{t+2}|y_{1:t}) &= \text{Var}(l_{t+1} + b_{t+1} + S_{t-M+2} + \varepsilon_{t+2}|y_{1:t}) \\ &= \text{Var}(l_t + 2b_t + S_{t-M+2} + \alpha(1 + \beta)\varepsilon_{t+1} + \varepsilon_{t+2}|y_{1:t}) \\ &= \sigma^2(1 + \alpha^2(1 + \beta)^2)\end{aligned}$$

# Additive Holt-Winters smoothing

## Variance for interval forecasts

$$y_{t+1} = l_{t-1} + 2b_{t-1} + S_{t-M+1} + \alpha(1 + \beta)\varepsilon_t + \varepsilon_{t+1}$$

$$\begin{aligned}\text{Var}(y_{t+3}|y_{1:t}) &= \text{Var}(l_{t+2} + b_{t+2} + S_{t-M+3} + \varepsilon_{t+3}|y_{1:t}) \\ &= \text{Var}(l_{t+1} + 2b_{t+1} + S_{t-M+3} + \alpha(1 + \beta)\varepsilon_{t+2} + \varepsilon_{t+3}|y_{1:t}) \\ &= \text{Var}(l_t + 3b_t + S_{t-M+3} + \alpha(1 + 2\beta)\varepsilon_{t+1} + \alpha(1 + \beta)\varepsilon_{t+2} + \varepsilon_{t+3}) \\ &= \sigma^2(1 + \alpha^2(1 + \beta)^2 + \alpha^2(1 + 2\beta)^2)\end{aligned}$$

$$\begin{aligned}\text{Var}(y_{t+h}|y_{1:t}) &= \text{Var}\left(l_t + hb_t + S_{t-M+h} + \alpha \sum_{i=1}^{h-1} (1 + i\beta)\varepsilon_{t+i} + \varepsilon_{t+h} | y_{1:t}\right) \\ &= \sigma^2 \left(1 + \alpha^2 \sum_{i=1}^{h-1} (1 + i\beta)^2\right), \quad \text{for } h \leq M \text{ only.}\end{aligned}$$



# Additive Holt-Winters smoothing

## Variance for interval forecasts

$$y_{t+1} = l_{t-1} + 2b_{t-1} + S_{t-M+1} + \alpha(1 + \beta)\varepsilon_t + \varepsilon_{t+1}$$

For  $h > M$ ,

$$\begin{aligned}\text{Var}(y_{t+h}|y_{1:t}) &= \text{Var}\left(l_t + hb_t + S_{t-M+h} + \alpha \sum_{i=1}^{h-1} (1 + i\beta)\varepsilon_{t+i} + \varepsilon_{t+h} | y_{1:t}\right) \\ &= \text{Var}\left(l_t + hb_t + S_{t-2M+h} + \gamma(1 - \alpha)\varepsilon_{t-M+h} \right. \\ &\quad \left. + \alpha \sum_{i=1}^{h-1} (1 + i\beta)\varepsilon_{t+i} + \varepsilon_{t+h} | y_{1:t}\right) \\ &= \sigma^2 \left(1 + \sum_{i=1}^{h-1} [\alpha(1 + i\beta) + l_{i,M}\gamma(1 - \alpha)]^2\right),\end{aligned}$$

where  $l_{i,M} = 1$  if  $i$  is an integer multiple of  $M$  and 0 otherwise.

# Additive Holt-Winters smoothing

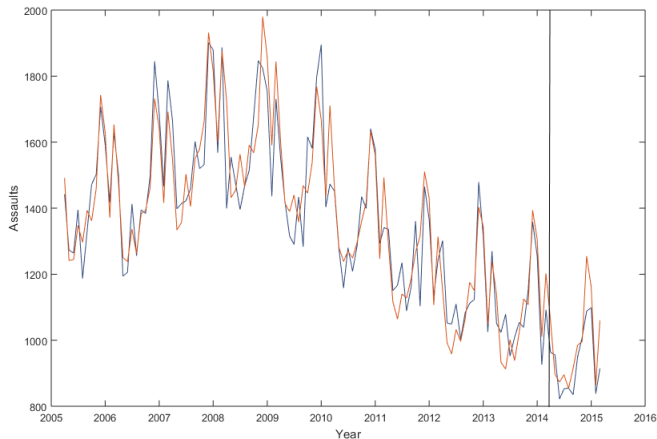
Forecasting: collecting the results

$$\hat{y}_{t+h|1:t} = \hat{l}_t + h\hat{b}_t + S_{t-M+(h \bmod M)}.$$

$$\text{Var}(y_{t+h}|y_{1:t}) = \sigma^2 \left( 1 + \sum_{i=1}^{h-1} [\alpha(1 + i\beta) + l_{i,M}\gamma(1 - \alpha)]^2 \right).$$

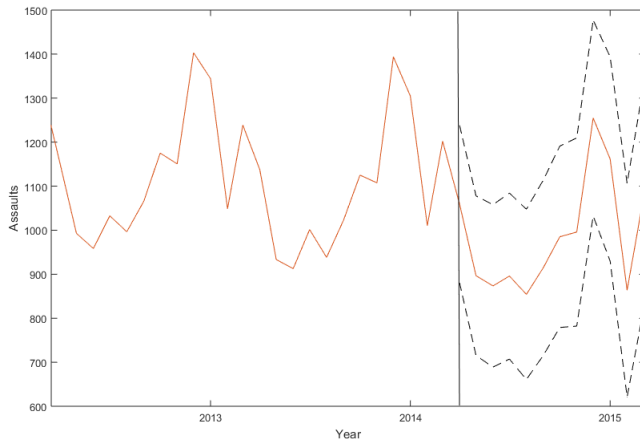
# Alcohol related assaults in NSW

Additive Holt-Winters forecast



# Alcohol related assaults in NSW

Additive Holt-Winters forecast



# Multiplicative Holt-Winters smoothing

Most useful when the seasonal pattern changes in a strong pattern and is proportional to the level of the series.

# Multiplicative Holt-Winters smoothing

## Model

$$l_t = \alpha(y_t/S_{t-M}) + (1 - \alpha)(l_{t-1} + b_{t-1}),$$

$$b_t = \beta(l_t - l_{t-1}) + (1 - \beta)b_{t-1},$$

$$S_t = \gamma(y_t/l_t) + (1 - \gamma)S_{t-M},$$

$$y_{t+1} = (l_t + b_t) \times S_{t+1-M} + \varepsilon_{t+1}, \quad \varepsilon_{t+1} \sim N(0, \sigma^2).$$

We can choose the parameters  $\alpha$ ,  $\beta$  and  $\gamma$  by minimising

$$SSE = \sum_{t=1}^n (y_t - (l_{t-1} + b_{t-1})S_{t-M})^2$$

# Multiplicative Holt-Winters smoothing

## Error correction formulation

$$\begin{aligned}l_t &= \alpha(y_t/S_{t-M}) + (1 - \alpha)(l_{t-1} + b_{t-1}) \\&= l_{t-1} + b_{t-1} + \alpha(y_t/S_{t-M} - l_{t-1} - b_{t-1}) \\&= l_{t-1} + b_{t-1} + \alpha \left( \frac{y_t - (l_{t-1} + b_{t-1})S_{t-M}}{S_{t-M}} \right) \\&= l_{t-1} + b_{t-1} + \alpha \frac{\varepsilon_t}{S_{t-M}}\end{aligned}$$

# Multiplicative Holt-Winters smoothing

## Error correction formulation

$$\begin{aligned}b_t &= \beta(l_t - l_{t-1}) + (1 - \beta)b_{t-1} \\&= b_{t-1} + \beta\alpha \left( \frac{y_t - (l_{t-1} + b_{t-1})S_{t-M}}{S_{t-M}} \right) \quad \text{see previous slide} \\&= b_{t-1} + \alpha\beta \frac{\varepsilon_t}{S_{t-M}}\end{aligned}$$



# Multiplicative Holt-Winters smoothing

## Error correction formulation

$$S_t = \gamma(y_t/l_t) + (1 - \gamma)S_{t-M} = S_{t-M} + \gamma \frac{y_t - l_t S_{t-M}}{l_t}$$

From the first model we have

$$l_t S_{t-M} = (l_{t-1} + b_{t-1})S_{t-M} + \alpha(y_t - (l_{t-1} + b_{t-1})S_{t-M})$$

Hence

$$\begin{aligned} y_t - l_t S_{t-M} &= (y_t - (l_{t-1} + b_{t-1})S_{t-M}) - \alpha(y_t - (l_{t-1} + b_{t-1})S_{t-M}) \\ &= (1 - \alpha)(y_t - (l_{t-1} + b_{t-1})S_{t-M}) = (1 - \alpha)\varepsilon_t \end{aligned}$$

Hence

$$S_t = S_{t-M} + \gamma(1 - \alpha) \frac{\varepsilon_t}{l_t}$$

# Multiplicative Holt-Winters smoothing

## Error correction formulation

$$l_t = l_{t-1} + b_{t-1} + \alpha \frac{\varepsilon_t}{S_{t-M}}$$

$$b_t = b_{t-1} + \alpha \beta \frac{\varepsilon_t}{S_{t-M}}$$

$$S_t = S_{t-M} + \gamma(1 - \alpha) \frac{\varepsilon_t}{l_t}$$

$$y_t = (l_{t-1} + b_{t-1}) \times S_{t-M} + \varepsilon_t$$

# Multiplicative Holt-Winters smoothing

## Forecasting equations

$$\begin{aligned}\hat{y}_{t+1|1:t} &= E((l_t + b_t)S_{t-M+1} + \varepsilon_{t+1} | y_{1:t}) \\ &= (l_t + b_t)S_{t-M+1}\end{aligned}$$

$$\begin{aligned}\hat{y}_{t+2|1:t} &= E((l_{t+1} + b_{t+1})S_{t-M+2} + \varepsilon_{t+2} | y_{1:t}) \\ &= E\left(\left[l_t + 2b_t + \alpha(1 + \beta)\frac{\varepsilon_{t+1}}{S_{t-M+1}}\right] S_{t-M+2} + \varepsilon_{t+2} \mid y_{1:t}\right) \\ &= (l_t + 2b_t)S_{t-M+2}\end{aligned}$$

$\vdots$

$$\hat{y}_{t+h|1:t} = (l_t + hb_t)S_{t-M+(h \bmod M)}$$

# Multiplicative Holt-Winters smoothing

## Variance for interval forecasts

$$y_{t+1} = \left[ l_{t-1} + 2b_{t-1} + \alpha(1 + \beta) \frac{\varepsilon_t}{S_{t-M}} \right] S_{t-M+1} + \varepsilon_{t+1}$$

$$\begin{aligned}\text{Var}(y_{t+1}|y_{1:t}) &= \text{Var}((l_t + b_t)S_{t-M+1} + \varepsilon_{t+1}|y_{1:t}) \\ &= \sigma^2\end{aligned}$$

$$\begin{aligned}\text{Var}(y_{t+2}|y_{1:t}) &= \text{Var}((l_{t+1} + b_{t+1})S_{t-M+2} + \varepsilon_{t+2}|y_{1:t}) \\ &= \text{Var} \left( \left[ l_t + 2b_t + \alpha(1 + \beta) \frac{\varepsilon_{t+1}}{S_{t-M+1}} \right] S_{t-M+2} + \varepsilon_{t+2} | y_{1:t} \right) \\ &= \sigma^2(1 + \alpha^2(1 + \beta)^2(S_{t-M+2}^2/S_{t-M+1}^2))\end{aligned}$$

# Multiplicative Holt-Winters smoothing

## Forecasting formula

$$\hat{y}_{t+h|1:t} = (\hat{l}_t + h\hat{b}_t) \times \hat{S}_{t+h-M}.$$

无限期地推断未来的趋势可能会有问题。

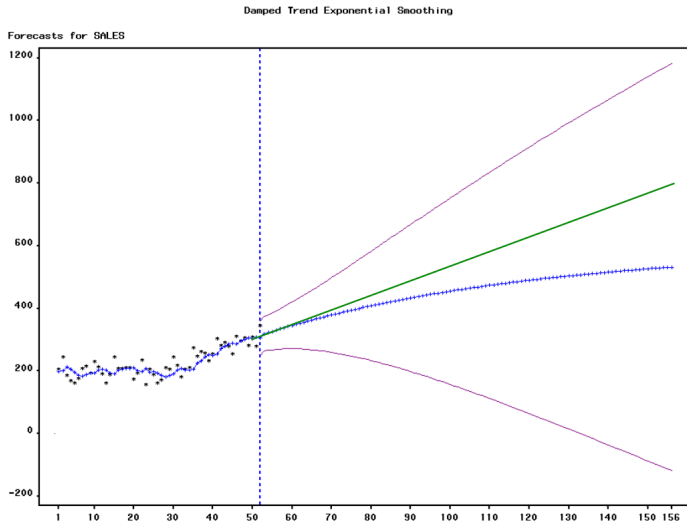
Extrapolating trends indefinitely into the future can be problematic.

**Dampened** trend exponential smoothing aims to deal with this problem.

阻尼趋势指数平滑旨在解决这个问题。

# Dampened trend ES

## Illustration



# Dampened trend ES

## Model

$$l_t = \alpha y_t + (1 - \alpha)(l_{t-1} + \phi b_{t-1}),$$

$$b_t = \beta(l_t - l_{t-1}) + (1 - \beta)\phi b_{t-1},$$

$$y_{t+1} = l_t + \phi b_t + \varepsilon_{t+1},$$

where  $\phi$  is the dampening factor, with  $0 \leq \phi \leq 1$ .



# Dampened trend ES

Forecasting and variance equations

$$y_{t+1} = l_t + \phi b_t + \varepsilon_{t+1}$$

$$\hat{y}_{t+1|1:t} = l_t + \phi b_t$$

$$\text{Var}(y_{t+1}|y_{1:t}) = \sigma^2$$

# Dampened trend ES

## Forecasting and variance equations

$$\begin{aligned}y_{t+2} &= l_{t+1} + \phi b_{t+1} + \varepsilon_{t+2} \\&= l_t + \phi b_t + \phi^2 b_t + \alpha(1 + \phi\beta)\varepsilon_{t+1} + \varepsilon_{t+2}\end{aligned}$$

$$\hat{y}_{t+2|1:t} = l_t + b_t(\phi_t + \phi^2)$$

$$\text{Var}(y_{t+1}|y_{1:t}) = \sigma^2(1 + \alpha^2(1 + \phi\beta)^2)$$

# Dampened trend ES

## Forecasting formula

$$\hat{y}_{t+h|1:t} = l_t + \phi b_t + \phi^2 b_t + \phi^3 b_t + \dots + \phi^h b_t$$

Compared with the forecast of the trend correct exponential method

$$\hat{y}_{t+h|1:t} = l_t + h \times b_t$$

What happens as  $h$  gets larger?

For the dampened forecast  $\hat{y}_{t+h|1:t} \rightarrow l_t + \frac{\phi}{1-\phi} b_t$

For the trend corrected forecast

$$\hat{y}_{t+h|1:t} \rightarrow \infty$$

# Dampened trend seasonal

## Model

$$l_t = \alpha(y_t - S_{t-M}) + (1 - \alpha)(l_{t-1} + \phi b_{t-1}),$$

$$b_t = \beta(l_t - l_{t-1}) + (1 - \beta)\phi b_{t-1},$$

$$S_t = \gamma(y_t - l_t) + (1 - \gamma)S_{t-M},$$

$$y_{t+1} = l_t + \phi b_t + S_{t-M+1} + \varepsilon_{t+1},$$

where  $\phi$  is the dampening factor, with  $0 \leq \phi \leq 1$ .

# Dampened trend seasonal

## Forecasting formula

$$\hat{y}_{t+h|1:t} = l_t + \phi b_t + \phi^2 b_t + \phi^3 b_t + \dots + \phi^h b_t + S_{t+h-M}$$