

QBUS6830: Financial Time Series and Forecasting

Matrix Algebra and Regression

Semester 1, 2017

Introduction

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- Square matrices:

- symmetry and inversion rules

- Square matrices:

- inversion rules

- OLS

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Tsay, Chapter 8, Appendix A

Brooks, Appendix 1 Other resources:

Magnus and Neudecker (2007) "Matrix Differential Calculus with Applications in Statistics and Econometrics"

There are many free online resources available., e.g.

<http://matrixcookbook.com/>

<http://www.ssc.wisc.edu/bhansen/econometrics/> (see Appendix A)

An $m \times n$ matrix \mathbf{A} is a rectangular array of numbers,

$$\mathbf{A} := \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}.$$

Alternative notation $\mathbf{A} = \{a_{ij}\}$.

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Background and motivation

Systems of linear equations (simultaneous equations)

$$2x_1 + 3x_2 = 1$$

$$3x_1 - 2x_2 = 2$$

can also be represented as a matrix and vector system:

$$\begin{pmatrix} 2 & 3 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

or in general:

$$Ax = b$$

the general (exact) solution to this system is:

$$x = A^{-1}b$$

when A^{-1} exists. Under what conditions does it exist??

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- addition: If A is an $m \times n$ matrix and B a $m \times n$ matrix, then

$$A + B = \{a_{ij} + b_{ij}\}.$$

Note: this can ONLY be performed if A and B have EXACTLY the same dimensions

- i.e.

$$\begin{pmatrix} 2 & 3 \\ 3 & -2 \end{pmatrix} + \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 2+1 & 3+2 \\ 3+3 & -2+4 \end{pmatrix} = \begin{pmatrix} 3 & 5 \\ 6 & 2 \end{pmatrix}$$

- But ...

$$\begin{pmatrix} 2 & 3 \\ 3 & -2 \end{pmatrix} + \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \text{undefined}$$

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Operations

- multiplication: If A is an $m \times n$ matrix and B a $n \times q$ matrix, then

$$AB = \left\{ \sum_{j=1}^n a_{ij} b_{jk} \right\}.$$

Note, often $AB \neq BA$ (only sometimes could these be equal, see below) .

- Thus:

$$\begin{pmatrix} 2 & 3 \\ 3 & -2 \end{pmatrix} \times \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 2 \times 1 + 3 \times 3 & 2 \times 2 + 3 \times 4 \\ 3 \times 1 - 2 \times 3 & 3 \times 2 - 2 \times 4 \end{pmatrix} \\ = \begin{pmatrix} 11 & 16 \\ -3 & -2 \end{pmatrix}$$

- Each row of A is "poured" down each column of B

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Operations

- multiplication: Also

$$\begin{pmatrix} 2 & 3 \\ 3 & -2 \end{pmatrix} \times \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 5 \\ -3 \end{pmatrix}$$

- But ...

$$\begin{pmatrix} 1 \\ 3 \end{pmatrix} \times \begin{pmatrix} 2 & 3 \\ 3 & -2 \end{pmatrix} = \text{undefined}$$

- multiplication (AB) is ONLY defined when the column dimension of A EQUALS the row dimension of B .

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Operations

- transpose:

$$A' = (\tilde{a}_{ij}), \tilde{a}_{ij} = a_{ji}.$$

- thus

$$\begin{pmatrix} 2 & 1 \\ 3 & -2 \end{pmatrix}' = \begin{pmatrix} 2 & 3 \\ 1 & -2 \end{pmatrix}$$

- Useful: $(AB)' = B'A'$
- Note that the reverse order is required since if A has the same column dimension as B 's row dimension then B' has the same COLUMN dimension as the ROW dimension of A'
- i.e. if AB exists, then $B'A'$ also exists, but $A'B'$ may not!

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$$\mathbf{x} := \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}$$

Inner product: $\mathbf{x}'\mathbf{x} = \sum x_i^2$

Outer product: $\mathbf{x}\mathbf{x}'$ is an $m \times m$ matrix(!) which is:

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Recall the SLR model

$$y_1 = \beta_0 + \beta_1 x_1 + u_1$$

$$\vdots$$

$$y_n = \beta_0 + \beta_1 x_n + u_n$$

It can be rewritten in a compact way

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{u},$$

where

$$\mathbf{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}, \mathbf{X} = \begin{pmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix}, \boldsymbol{\beta} = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}, \mathbf{u} = \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix}.$$

Much of the LS and sampling distribution theory becomes EASIER
this way !

Regression ctd

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Note that

$$X\beta = \begin{pmatrix} \beta_0 + \beta_1 x_1 \\ \beta_0 + \beta_1 x_2 \\ \vdots \\ \beta_0 + \beta_1 x_n \end{pmatrix}$$

as required

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Identity

- identity matrix

$$\mathbf{I}_n := \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}.$$

This is a matrix version of 1

- i.e. when these multiplications exist: $\mathbf{A}\mathbf{I} = \mathbf{A} = \mathbf{I}\mathbf{A}$
- this is a square matrix (i.e. column dimension = row dimension)
- So, e.g.

$$\begin{pmatrix} 2 & 1 \\ 3 & -2 \end{pmatrix} \times \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} =$$

Try it!

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Inversion

- inverse: A matrix A has an inverse, A^{-1} , if and only if

$$AA^{-1} = A^{-1}A = I$$

- Only square matrices can have an inverse
- Why can't

$$A = \begin{pmatrix} 2 & 3 & 1 \\ 1 & 2 & 3 \end{pmatrix}$$

have an inverse??

- What about A' ??

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Regression estimation

- Imagine the SLR model

$$y = X\beta + u,$$

with 0 error, $u = 0$.

-

$$y = X\beta$$

implies that

$$\beta = X^{-1}y$$

- Is this correct? Is it possible?
- Recall: only square matrices can have an inverse.
- What is the dimension of X ? Why might it preclude X^{-1} existing?

Square matrices: symmetry and inversion rules

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- symmetric matrices are such that: $A' = A$
- Only square matrices can be symmetric!
- Matrix inversion has nice properties: $(A^{-1})' = (A')^{-1}$ and $(AB)^{-1} = B^{-1}A^{-1}$
- This last result must be true since $B^{-1}A^{-1}AB = I$ and $AB B^{-1}A^{-1} = I$.
- Note that I is always symmetric and square.

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Square matrices: inversion rules

- determinant: A square matrix A has a determinant, denoted $|A|$.
- A matrix A has a determinant only if it is square.
- A square matrix A has an inverse if and only if $|A| \neq 0$.
- $|A|$ can only equal 0 if
 1. any column (or row) of A is a linear combination of two or more columns (or rows) of A .
 2. a row or column of A is entirely full of 0s.

OLS

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OLS estimator minimizes the sum of squared residuals, which can be written as

$$\sum u_i^2 = \mathbf{u}'\mathbf{u} = (\mathbf{y} - \mathbf{X}\boldsymbol{\beta})'(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})$$

or

$$\mathbf{y}'\mathbf{y} - \boldsymbol{\beta}'\mathbf{X}'\mathbf{y} - \mathbf{y}'\mathbf{X}\boldsymbol{\beta} + \boldsymbol{\beta}'\mathbf{X}'\mathbf{X}\boldsymbol{\beta}$$

To minimise this, we need to know how to differentiate vectors and matrices ...

First, note that, for two equal dimension vectors \mathbf{a} , \mathbf{b} :

$$(\mathbf{a} + \mathbf{b})'(\mathbf{a} + \mathbf{b}) = \mathbf{a}'\mathbf{a} + \mathbf{a}'\mathbf{b} + \mathbf{b}'\mathbf{a} + \mathbf{b}'\mathbf{b}$$

and also that $\mathbf{a}'\mathbf{b} = \mathbf{b}'\mathbf{a} = \sum_i b_i a_i$ (for vectors ONLY!).

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Matrix and vector calculus

Let x and a be equal dimension vectors and A a matrix with column dimension the same as number of rows in x . Then:

●

$$\frac{d(x'a)}{dx} = a$$

●

$$\frac{d(x'Ax)}{dx} = (A + A')x$$

● i.e.

$$u'u = y'y - 2\beta'X'y + \beta'X'X\beta$$

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Solution

Returning to OLS

$$\begin{aligned}\frac{d(\mathbf{u}'\mathbf{u})}{d\boldsymbol{\beta}} &= \frac{d(\mathbf{y}'\mathbf{y})}{d\boldsymbol{\beta}} - \frac{d(2\boldsymbol{\beta}'\mathbf{X}'\mathbf{y})}{d\boldsymbol{\beta}} + \frac{d(\boldsymbol{\beta}'\mathbf{X}'\mathbf{X}\boldsymbol{\beta})}{d\boldsymbol{\beta}} = \\ &= \mathbf{0} - 2\mathbf{X}'\mathbf{y} + 2\mathbf{X}'\mathbf{X}\boldsymbol{\beta}\end{aligned}$$

First Order Condition:

$$\frac{d(\mathbf{u}'\mathbf{u})}{d\boldsymbol{\beta}} = \mathbf{0}$$

gives $\hat{\boldsymbol{\beta}}_{OLS}$ which solves $\mathbf{X}'\mathbf{y} = \mathbf{X}'\mathbf{X}\hat{\boldsymbol{\beta}}_{OLS}$.
Left multiplication with $(\mathbf{X}'\mathbf{X})^{-1}$ and

$$\hat{\boldsymbol{\beta}}_{OLS} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$$

!!! The formula (and its derivation) is valid, regardless of dimensions of \mathbf{X} and $\boldsymbol{\beta}$ (must match!)

!!! Second order condition is satisfied (but no proof here)

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Alternative Solution

$$y = X\beta + u,$$

gives

$$X'y = X'X\beta + X'u$$

which implies that:

$$\beta = (X'X)^{-1}X'y - (X'X)^{-1}X'u,$$

and/or

$$(X'X)^{-1}X'y = \beta + (X'X)^{-1}X'u.$$

i.e.

$$\hat{\beta}_{OLS} = \beta + (X'X)^{-1}X'u$$

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LS Assumptions

1. $E(u|X) = 0$
2. X, Y contain vectors of i.i.d. variables.
3. The 4th moments of X, Y are finite.

Note that, e.g.

$$E(u|X) = 0 \rightarrow E(X'u|X) = 0$$

which implies that:

$$\begin{aligned} E(\hat{\beta}_{OLS}|X) &= E(\beta + (X'X)^{-1}X'u|X) \\ &= \beta + (X'X)^{-1}X'E(u|X) = \beta \end{aligned}$$

i.e. $\hat{\beta}_{OLS}$ is unbiased, since

$$E(\hat{\beta}_{OLS}) = E(E(\hat{\beta}_{OLS}|X)) = \beta$$

more on this later

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Properties

- Linearity
 $\hat{\beta}_{OLS} = (X'X)^{-1}X'y = Hy$, so that each element of $\hat{\beta}_{OLS}$ IS a linear combination of the observations in y .
- Unbiasedness
- Covariance and consistency?: see later