

Bay-Area Radiation Transport (**BART**), a Research-purpose Parallel Transport Code Framework

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- Introductions
- Equations/Discretizations
- Parallelism/Linear Algebra/Meshing
- Unit Testing, documentation Continuous Integration and Code Coverage
- Ongoing Projects

Introductions



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BART

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What is **BART**?

A open-source research-purpose code

- We hold BART on Github with MIT license.
- We build BART to be a research-purpose transport code.
- We aim to provide a framework s.t. graduate students only need necessary amount of knowledge on C++ and third-party libraries to implement new ideas for research

A finite element code based on deal.II

- We build BART to be a finite element code based on deal.II
 - Finite element is wired-shape mesh friendly
 - BART computes in general dimension as deal.II does.
 - BART only call generic functions instead of dimension specified ones.
- Any specs of finite elements are wrapped by deal.II s.t. BART developers focus only on physical/symbolically mathematical aspects.

A code in parallel

- We build **BART** to be a parallel code computing on distributed memory
 - Even small-size problems (¡10 million DoFs) can be overwhelming for local computers
- It is natural to enable parallelism as deal. II has nice wrappers.

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• Coding style: [Google Style](google.com)



Finite elements in **BART**

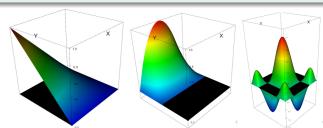
Introductions

Finite elements in general dimensions

- deal.II supports finite elements in general dimensions by templates
 - BART developers only need to call generic trial functions when implementing weak forms for 1/2/3
 - Specs of trial functions are hidden under the hood by deal.II for different dimensions.
- BART supports DFEM, CFEM, FV and RTk.
 - For high-order-low-order (HOLO), BART can assign individual finite elements to different equations.
 - All you need to do is to tell BART in input file:

```
set ho spatial discretization = cfem
set nda spatial discretization = dfem
```

 Polynomial orders can be changed in input file as well (see the following demos for Q1(left), Q2(middle) and Q4(right) trial functions)



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What can **BART** do?

Introductions

What approximations can have?

- Transport approximations that can be decoupled to individual equations
 - Discrete ordinates approximation
 - Diffusion equations
 - Canonical form of simplified spherical harmonics (SPN)
- PN is feasible through extension of current framework.

Solve small-to-median-sized problems

- A transport code doing all real-world large problems with billions/trillions of degrees of freedom is charming, BUT
 - It can require tens/hundreds of man-year of work.
 - It requires tons of optimizations.
 - It is hard for newbies to get started
- We restrict BART to small (e.g. one-group) to median sized problems (e.g. C5G7)

Equations/Discretizations



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Equations **BART** solves transport equation

BART is solving multi-group transport equation with discrete-ordinates in angle

• Transport equation in operator form with:

$$\mathcal{T}_{g,m}\psi_{g,m} + \mathcal{C}_{g,m}\psi_{g,m} = \sum_{\substack{1 \le g' \le G\\1 \le m' \le M}} \left(\mathcal{S}_{g',m' \to g,m} + \mathcal{F}_{g',m' \to g,m} \right) \psi_{g',m'} \tag{1}$$

Parallelism/Linear Algebra/Meshing

$$\psi_{\mathrm{g,m}} = \psi_{\mathrm{g,m}}^{\mathrm{inc}}, \ \vec{r} \in \partial \mathcal{D}, \ \vec{n} \cdot \vec{\Omega}_{\mathrm{m}} < 0$$

 \mathcal{T} : Streaming operator

C: Collision operator, $\sigma_{\rm t}$

S: Scattering operator

 \mathcal{F} : Fission operator

 ψ : Angular flux

g, g': Group indicies

m, m': Angular indices

G, M: Numbers of groups and directions

The formulation generalizes to diffusion and nonlinear diffusion

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BART solves first-order form of transport equations

First-order form and DFEM discretization in space

• Transport equation has differential order of 1 in the streaming term, we refer it to as "first-order" form (FOF)

$$\vec{\Omega}_{m} \cdot \nabla \psi_{g,m} + \sigma_{t,g} \psi_{g,m} = \mathcal{Q}_{g,m} \left(\mathbf{\Psi} \right)$$
 (2)

$$Q_{g,m} := \sum_{\substack{1 \le g' \le G \\ 1 < m' < M}} \left(\mathbf{S}_{g',m' \to g,m} + \mathbf{\mathcal{F}}_{g',m' \to g,m} \right) \psi_{g',m'} \tag{3}$$

• FOF is discretized using DFEM in **BART**: given polynomial function space \mathcal{V} , $\forall \psi_{\pi,m}^* \in \mathcal{V}$, find $\psi_{g,m} \in \mathcal{V}$, s.t.

$$\begin{split} & \sum_{e \in \mathcal{D}} \left[\left(-\vec{\Omega}_{m} \cdot \nabla \psi_{g,m}^{*}, \psi_{g,m} \right) + \left(\psi_{g,m}^{*}, \sigma_{t,g} \psi_{g,m} \right) \right]_{e} + \sum_{f \in \mathcal{D}} \left| \vec{n} \cdot \vec{\Omega}_{m} \right| \left\langle \left[\psi_{g,m}^{*} \right], \tilde{\psi}_{g,m} \right\rangle_{f} \\ & + \sum_{\substack{f \in \partial \mathcal{D} \\ \vec{n} \cdot \vec{\Omega}_{m} > 0}} \vec{n} \cdot \vec{\Omega}_{m} \left\langle \psi_{g,m}^{*}, \psi_{g,m} \right\rangle_{f} = \sum_{e \in \mathcal{D}} \left(\psi_{g,m}^{*}, \mathcal{Q}_{g,m} \right)_{e} + \sum_{\substack{f \in \partial \mathcal{D} \\ \vec{n} \cdot \vec{\Omega}_{m} < 0}} \left| \vec{n} \cdot \vec{\Omega}_{m} \right| \left\langle \psi_{g,m}^{*}, \psi_{g,m}^{inc} \right\rangle_{f} \end{split}$$

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BART solves second-order forms of transport equations

Second-order forms (SOF) of transport equations

- FOF can be cast to diffusion-like equations having streaming term with differential order of 2
- The casting allows for use of CFEM
- BART solves even-parity equation and self-adjoint angular flux equation (SAAF)

SOF example: SAAF

SAAF equation

$$-\vec{\Omega}_{\rm m} \cdot \nabla \frac{1}{\sigma_{\rm t,g}} \vec{\Omega}_{\rm m} \cdot \nabla \psi_{\rm g,m} + \sigma_{\rm t,g} \psi_{\rm g,m} = \mathcal{Q}_{\rm g,m} - \frac{1}{\sigma_{\rm t,g}} \vec{\Omega}_{\rm m} \cdot \nabla \mathcal{Q}_{\rm g,m}$$
 (5)

CFEM discretization

$$\left(\vec{\Omega}_{m} \cdot \nabla \psi_{g,m}^{*}, \frac{1}{\sigma_{t,g}} \vec{\Omega}_{m} \cdot \nabla \psi_{g,m}\right)_{\mathcal{D}} + \left(\psi_{g,m}^{*}, \sigma_{t,g} \psi_{g,m}\right)_{\mathcal{D}} + \sum_{\substack{f \in \partial \mathcal{D} \\ \vec{n} \cdot \vec{\Omega}_{m} > 0}} \vec{n} \cdot \vec{\Omega}_{m} \left\langle \psi_{g,m}^{*}, \psi_{g,m} \right\rangle_{f}$$

$$= \left(\psi_{g,m}^{*} + \frac{\vec{\Omega}_{m} \cdot \nabla \psi_{g,m}^{*}}{\sigma_{t,g}}, \mathcal{Q}_{g,m}\right)_{\mathcal{D}} + \sum_{\substack{f \in \partial \mathcal{D} \\ \vec{n} \cdot \vec{\Omega}_{m} < 0}} \left|\vec{n} \cdot \vec{\Omega}_{m}\right| \left\langle \psi_{g,m}^{*}, \psi_{g,m}^{inc} \right\rangle_{f}$$
(6)

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BART solves diffusion and nonlinear diffusion

BART solves diffusion equation

Diffusion could be solved within the framework of BART

$$-\nabla \frac{1}{3\sigma_{t,g}} \cdot \nabla \phi_{g} + \sigma_{t,g} \phi_{g} = Q_{g} := \sum_{g'} \left[\left(\sigma_{s,g' \to g} + \frac{\chi_{g} \nu \sigma_{f,g'}}{k_{eff}} \right) \phi_{g'} \right]$$
(7)

Nonlinear diffusion for acceleration (NDA)

Diffusion can also be written in P₁ form

$$\nabla \cdot \vec{J}_{g} + \sigma_{t,g} \phi_{g} = \mathcal{Q}_{g}, \quad \vec{J}_{g} = -\frac{1}{3\sigma_{t,g}} \nabla \phi_{g} \text{ (Fick's law)}$$
 (8)

- NDA is derived from correcting Fick's law using transport corrections
- Correction to preserve current is derived from transport high-order solutions (HO)

$$\vec{J}_{g} = -\frac{1}{3\sigma_{t,g}} \nabla \phi_{g} + \left| \frac{\sum_{m < M} w_{m} \vec{\Omega}_{m} \vec{\Omega}_{m} \cdot \nabla \psi_{g,m}^{HO} + \frac{1}{3\sigma_{t,g}} \nabla \phi_{g}^{HO}}{\phi_{g}^{HO}} \phi \right|$$
(9)

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BART solves diffusion and nonlinear diffusion (cont'd)

BART solves in multiple ways

- CFEM is natural to use to solve diffusion/nonlinear diffusion
- DFEM is realizable through penalty method
 - Useful when accelerating transport solves with DFEM
- A hybrid-FEM is a near-future project for NDA in P₁-like form
 - Piece-wise constant test function for $\phi_{\rm g}$ while Raviat-Thomas test functions for $\vec{J_{\rm g}}$

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BART is designed/implemented to be a parallel code

computes on distributed memory

- Message Passing Interface, aka MPI, is used for distributed computations.
- Meshing is correspondingly distributed based on p4est's functionality wrapped by deal.II.
 - Each processor mainly knows mesh cells on itself
- Linear algebra related objects are distributed as well
 - PETSc data structure wrappers in deal.II are heavily used to enable the parallel linear algebra.

BART is parallelizing in space

- While extending parallelism to be suitable for other dimensions in phase space, we currently only parallelize in space
 - No special treatment on MPI/scheduling, natural support from deal.II
- Computational efficiency in parallel rather depends on solvers/preconditioners, but little on the mesh

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Linear algebra in **BART**

Sparse matrix-vector product based computations

- Current implementation of BART assembles global matrices and utilize sparse matrix-vector product in linear algebraic solvers.
 - Easy implementation.
 - High computational efficiency with (bi/tri-) linear elements.

BART is interfaced with PETSc

- Most PETSc solvers/preconditioners wrapped in deal.II are used in PreconditionerSolver class of BART
 - Direct solver: parallel direct solver MUMPS
 - Iterative solvers and preconditioners
- Performance remedy: as solving will happen multiple times due to source/power iterations, we initialize the preconditioning/factorization only once then preconditioning/factorization matrices will be stored for reuse.

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BART was initially implemented for homogenized mesh

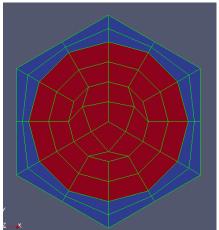
- Hyper-rectangle meshing based on deal.II:
 - Lines in 1D, rectangles in 2D and regular cuboid in 3D
 - Material ID assigned to coarsest mesh and stored in cell objects tractable when refining

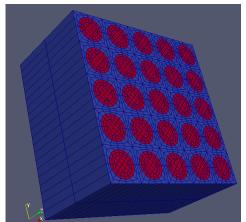
Pin-resolved meshing

- Recent development enables the use of pin-resolved mesh
 - Rectangular (prism) pin is supported; hexagonal (prism) pin is under development
 - Goodness: meshing does NOT depend on Cubit or gmsh. BART realizes wrapper functions based on deal. II to draw complex geometries.
- We compose different pin models and replicate based on pin types in 2D.
- 3D meshes is realized by extruding 2D mesh.

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Pin-resolved mesh demos



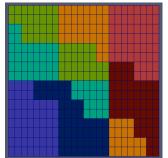


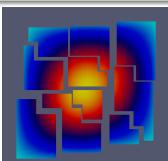
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Meshing in Parallel

Distributed triangulation

- Triangulation (meshing) needs to support parallelism for parallel computations.
- deal.II supports two ways of triangulation in parallel
 - Shared (ParMETIS based): every processor has a copy of the global triangulation.
 - Distributed (p4est based): every processor only knows cells living on itself and a layer of neighboring
 cells from other processors on the local triangulation boundary
- BART supports distributed meshing from deal.II.
- 1D meshing is serial as deal. II has no parallel support





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Testing

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Unit testing and documentation

We document and test everything possible

- We rewrote BART twice:
 - First time, we restructured BART and documented everything with doxygen.
 - · Second time, we added unit testing.
- Philosophy: everything be documented and every function/class be tested if possible.
 - Documentation leads to better understandability of code in the future development.
 - Unit testing ensures new codes do not affect correctness of existing code.

G(oogle)Test and CTest are both used

- We want unit testing to be efficient and compatible with MPI
 - GTest is super efficient but hard to obtain compatibility with MPI.
 - CTest is slow but compatible with MPI.
- Not all the testings require MPI
 - · We use GTest for all serial testing
 - We leave all MPI related testings to CTest.

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We are conducting projects on **BART**

Ongoing projects

- Advanced spatial discretization methods.
- Advanced energy acceleration methods.

We are designing students' projects in

- We are designing students' projects based on BART
 - BART will grow, so intellectually do students.

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