

AE HW 1

Chunyu Qu

Chapter 2. Conditional Expectation.

I. Chapter Summary

1. Role of Conditional Expectation

(1) Express Conditional Expectation w/ $u(x)$

(i) Let $\underline{x} = (x_1, \dots, x_k)$ be the explanatory variables

(ii) If $E[y] < \infty$

then $\exists u: \mathbb{R}^k \rightarrow \mathbb{R} \ni E[y|x_1, \dots, x_k] = u(x_1, \dots, x_k)$

Remark 1: $u(x)$ is a random variable, i.e. $E(y|x)$ is a function of x

Remark 2: $u(x)$ is the average value of y given x

(2) Basics of Conditional Expectation (more in handout 1)

• Joint PDF of \underline{x}, y : $f_{\underline{x}, y}(x, y)$

• Joint CDF of \underline{x}, y : $F_{\underline{x}, y}(x, y) = \int_{-\infty}^s \int_{-\infty}^y f_{\underline{x}, y}(t, s) dt ds$

• Marginal PDF of \underline{x} : $f_{\underline{x}}(x) = \int_{-\infty}^{\infty} f_{\underline{x}, y}(x, t) dt$

• Conditional PDF of \underline{x} : $f_{y|\underline{x}=x}(y) = \frac{f_{\underline{x}, y}(x, y)}{f_{\underline{x}}(x)}$

• Conditional CDF of \underline{x} : $F_{y|\underline{x}=x}(y) = \int_{-\infty}^y f_{y|\underline{x}=x}(s) ds$

$$\text{One more key property} \Rightarrow = \frac{\partial F_{\underline{x}, y}(x, y)/\partial x}{f_{\underline{x}}(x)}$$

• Conditional Expectation

$$E[y|\underline{x}=x] = \int_{-\infty}^{\infty} y f_{y|\underline{x}=x}(y) dy$$

(3) Basic Properties of Conditional Expectation

① Constancy: $E[a|Y] = a$

② Additivity: $E[aX+bZ|Y] = aE[X|Y] + bE[Z|Y]$

③ Independence: $E[X|Y] = E[X]$ iff. X & Y are independent

④ Scalar multiplier: $E[Xg(Y)|Y] = g(Y)E[X|Y]$ esp. $E[g(Y)|Y] = g(Y)$

⑤ Tediumness: $E[X|Y, g(Y)] = E[X|Y]$

eg: $E[\text{wage}|\text{educ, exper, exper}^2, \log(\text{educ}), \text{exper-ell}] = E[\text{wage}|\text{educ, exper}]$

⑥ LIE: $E[E[Y|X]] = E[Y]$

A Times Series version: $E[E[Y_{t+1}|I_t] | I_{t-1}] = E[Y_{t+1} | I_{t-1}]$

(4) Stronger formats

• Mean independence: $E[Y|X=x] = E[Y]$

Remark 3: Independence \Rightarrow Mean independence

eg: Let X be race, then if we know X, Y are independent ($E[Y|X] = E[Y]$)

we also know Y is independent at any level of X $E[Y|X=x] = E[Y]$

• Conditional VS unconditional

Remark 4: $E[u|X] = 0 \Rightarrow E[u] = 0$

proof: $\Rightarrow E[u] = E[E[u|X]] = 0$

\Leftarrow when $E[u] = 0 \Rightarrow E[u] = E[u|X] = 0$

iff. x and u are independent

• Independence \Rightarrow uncorrelated

uncorrelated $\not\Rightarrow$ Independence

(5) Advanced properties

① Decompose y : (i) $y = E[y|X] + u$ (ii) $E[u|X] = 0$

Remark 4: $E[u|X] = 0 \Rightarrow$ (i) $E[u] = 0$

(ii) $\text{cov}(u, x_i) = 0 \quad i=1, 2, \dots, k$

(iii) $\text{cov}(u, g(x)) = 0$

② Functional Invariant LIE - I

(CE3) (i) (2.19) $E[y|\underline{x}] = E[E[y|w]|\underline{x}]$, where $\underline{x} = f(w)$

ex: $x_1 = f_1(w_1, w_2)$ $x_2 = f_2(w_2)$

Then $E[y|\underline{x}, \underline{w}] = E[y|w_1, w_2]|\underline{x}, \underline{w}$

(ii) (2.20) $E[y|\underline{x}] = E[E[y|\underline{x}]|w]$

Remark 5: From 2.19 we find the position of \underline{x} and w does not make difference to the values of iterated conditional expectation.

Since \underline{x} is function of w knowing w implies knowing \underline{x}

Remark 6: Let us suppose y is the wage, w is all the related variables

such as education years, experience, ability, family wealth ...

But in real world, we only have the data for education, experience,

which is our $\underline{x} = (\text{educ, exper})$. i.e. we have limited information.

* Even if we may not know $E[y|w]$.

Suppose, fortunately, we know $\text{edu} = f_1(w)$ $\text{exp} = f_2(w)$. And it will

but we know

be easy to get $E[y|\underline{x}]$. Then the average effect of $E[y|w]$ given limited information (\underline{x}) is the same as $E[y|\underline{x}]$ if

$E[E[y|\underline{x}]|\underline{x}]$

we estimate $E[y|\underline{x}]$ w/ a parametric model, without necessarily of knowing all the information.

③ Functional Invariant of LIE - II.

$$E[y|\underline{x}] = E[E[y|\underline{x}, \underline{z}]|\underline{x}]$$

where \underline{x} is observed variable, \underline{z} is unobserved ones

e.g: $E[y|x_1, x_2, z] = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 z$. which is our target

But z is unobserved here.

By ③ $E[y|x_1, x_2] = E[E[y|x_1, x_2, z]|x_1, x_2] = E[\beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 z|x_1, x_2]$

$$= \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 E[z|x_1, x_2] [1]$$

In many cases, we can assume $E[z|x_1, x_2] = f(x_1, x_2)$. say $E[z|x_1, x_2] = \delta_0 + \delta_1 x_1 + \delta_2 x_2$ [2]

$$\text{Then } (1)+(2) \Rightarrow \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 (\delta_0 + \delta_1 x_1 + \delta_2 x_2)$$

$$= (\beta_0 + \beta_3 \delta_0) + (\beta_1 + \beta_3 \delta_1) x_1 + (\beta_2 + \beta_3 \delta_2) x_2$$

This has nothing to do w/ z , it is purely function of x_1 and x_2 .

(4) CES If (u, v) are independent of x ,
then $E(u|x, v) = E(u|v)$

2. Partial Effects, Elasticities, semielasticities.

(1) Partial Effects of x_i on $E[y|x]$: $PE(y|x) = \frac{\partial E[y|x]}{\partial x_i}$

w.l. $x_1 \dots x_{i-1}, x_{i+1} \dots$ fixed

(2) Elasticity (partial w.l. x_i): $\frac{E[y|x]\% \text{ change}}{\% \text{ change}} = \frac{\Delta E[y|x]/E[y|x]}{\Delta x_i / x_i}$

$$= \frac{\frac{\partial E[y|x]}{\partial x_i} \cdot x_i}{E[y|x]}$$

Since $d \log x = \frac{dx}{x}$, thus $\textcircled{C} = \frac{\partial \log E[y|x]}{\partial \log x_i}$

\textcircled{C}

Remark 7: Elasticity can be constant or variant. In production function framework, this means
constant-return-to-scale or increasing(decreasing)
return-to-scale

(3) Semielasticity of $E[y|x]$ w.r.t. x_i : $100 \cdot \frac{\partial \log E[y|x]}{\partial x_i}$

3. APE

(4) Average partial effects: the partial effects of γ on $E[y|x]$ averaged across the distribution of x 's
i.e. $APE(y|x_i) = E \left[\frac{\partial \log E[y|x]}{\partial \log x_i} \mid x \right]$

Remark 8: An important case is to consider \tilde{x}_i w.l. observed part x ,
and unobserved part q . the $APE(y|x) = E \left[\frac{\partial E[y|x]}{\partial x_i} \Big|_{\tilde{x}=x_i} \mid q \right]$
At specific x level \tilde{x}_i .

- q : unobserved heterogeneity.

$$\hat{\beta} = \text{Var}(\tilde{x}) \text{Cov}(y, \tilde{x})$$

which is exactly linear regression

(2) Proxy variables

(i) One key assumption to generate unbiased estimates on \tilde{x} in a parametric model of $E(y|\tilde{x})$ have the observed ones (x) and unobserved ones, $L(x|\tilde{x}) = x$, $L(x|C, \tilde{x}) = x$ are independent.

(ii) Eliminate unobserved heterogeneity

[1] Good Proxy

$$D(q|\tilde{x}, w) = D(q|w)$$

\downarrow
Distribution good proxies for q .

$$(2.44) L(y|I, \tilde{x}) = L[L(y|I, \tilde{x}, z)|I, \tilde{x}] \Leftrightarrow \text{LP.4} \quad ||$$

$$(2.45) L(y|I, \tilde{x}) = L[E(y|x, z)|I, \tilde{x}] \Leftrightarrow \text{LP.5} \quad \text{here } x \text{ does not include 1's.}$$

[2] Redundant proxy

$$E[y|\tilde{x}, q, w] = E[y|\tilde{x}, q]$$

When we have a good proxy w for q .

The APE($y|x_i$)
$$\frac{\partial E[y|\tilde{x}, w]}{\partial x_i} \Big|_{\tilde{x}=\tilde{x}_0, w=w_0}$$
 is free of q .

4. Linear Projections

(1) Basics of LP

By the definition of LP,

$$L(y|I, \tilde{x}_1, \dots, \tilde{x}_k) = \beta_0 + \beta_1 \tilde{x}_1 + \dots + \beta_k \tilde{x}_k = \beta_0 + \tilde{x} \beta$$

$$\beta = \text{Var}(\tilde{x}) \text{Cov}(y, \tilde{x})$$

which is exactly linear regression of y on $\tilde{x}_1, \dots, \tilde{x}_k$.

Thus, we have

$$\bullet L(C|x) = C, L(x|x) = x, L(x|C, x) = x$$

where C is constant vector.

(2) Properties of LP

$$(2.44) L(y|x, \bar{z}) = L[L(y|x, z)|x, \bar{z}]$$

\Leftrightarrow LP.4

||

$$(2.45) L(y|x, \bar{z}) = L[E(y|x, z)|x, \bar{z}]$$

\Leftrightarrow LP.5 *here x does not include 1's.

[LP.1] If $E(y|x) = x\beta$, then

$$L(y|x) = x\beta$$

[LP.2] $\hat{u} \equiv y - L(y|x)$,

$$\Rightarrow E(x'u) = 0$$

[LP.4] (LIE) *For all LP's, x include 1's.

$$L(L(y|x, z)|x) = L(y|x)$$

||

$$[LP.5] L(E(y|x, z)|x) = L(y|x)$$

[LP.7] If $L(y|x, \bar{z}) = x\beta + z\gamma$

Then by constructing projections

$$r \equiv x - L(x|z) \equiv x - \hat{x}_{OLS}$$

which are the residuals from regression

$$and \quad \hat{y} \equiv y - L(y|z) \equiv y - \hat{y}_{OLS}$$

we have $L(y|r) = r\beta = L(y|r)$

II. HW Problem Set 1.

2.1 Given RV's y, x_1, x_2 .

$$E(y|x_1, x_2) = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_2^2 + \beta_4 x_1 x_2$$

a Find the PE of x_1, x_2 on $E(y|x_1, x_2)$

$$\frac{\partial E(y|x_1, x_2)}{\partial x_1} = \beta_1 + \beta_4 x_2$$

$$\frac{\partial E(y|x_1, x_2)}{\partial x_2} = \beta_2 + 2\beta_3 x_2 + \beta_4 x_1$$

b $y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_2^2 + \beta_4 x_1 x_2 + u$

What can we say about $E(u|x_1, x_2)$ $E(u|x_1, x_2, x_2^2, x_1 x_2)$?

$E(u|x_1, x_2)$ assumed to be zero ($\Rightarrow E(u)=0$ by LIE)

$E(u|x_1, x_2, f_1(x_1), g_1(x_2), \dots) = 0$ by my CE note Part 1.

Thus u and $x_1, x_2, x_2^2, x_1 x_2$ are independent (\Rightarrow uncorrelated)

$E[u|x_1, x_2] = 0$ is a stronger condition than $E[u] = 0$.

Since by LIE $E[E[u|x_1, x_2]|x_1, x_2] = E[D|x_1, x_2] = 0 = E[u]$

but $E[u]$ does not guarantee that $E[u|x_1, x_2] = 0$

C Discuss $\text{Var}(u|x_1, x_2)$

Recap $V(\tilde{y}|\tilde{x}) \equiv \sigma^2(\tilde{x}) \equiv E[(y - E[y|\tilde{x}])^2 | \tilde{x}] = E[y^2|\tilde{x}] - (E[y|\tilde{x}])^2$

①

$$V(\tilde{u}|\tilde{x}) \equiv E[u^2|\tilde{x}] \quad \text{if } \sigma^2 \text{ is invariant of } x.$$

$$\therefore V(\tilde{u}|\tilde{x}) = E[u^2|\tilde{x}] - (E[u|\tilde{x}])^2 = E[u^2|\tilde{x}]$$

②

$$E[u^2] \stackrel{\text{def}}{=} E[E[u^2|x]] = E[\sigma^2(\tilde{x})] = \sigma^2, \text{ if } \sigma^2 \text{ is invariant of } x.$$

Thus $\sigma^2(\tilde{x}) = V(\tilde{y}|\tilde{x}) = V(\tilde{u}|\tilde{x}) = E[u^2|\tilde{x}]$

$$= E[u^2] \text{ if } \sigma^2 \text{ is invariant of } x$$

We can only claim that $V(u|x_1, x_2)$ is positive here.

* If we assume u_i and x_1, x_2 are independent, then.

$$SSE \equiv \tilde{u}'\tilde{u} \quad \text{where } \tilde{u} \equiv \tilde{y} - \hat{y}$$

\tilde{y} is $n \times 1$ vector
 \tilde{x} is $(p+1)$ vector

$$\hat{\sigma}^2 \equiv \frac{MSE}{n-p}$$

2.2

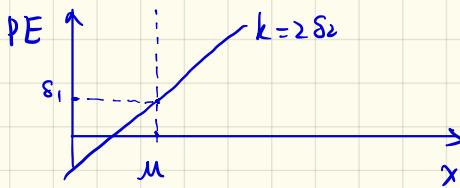
$$E(y|x) = \delta_0 + \delta_1(x-\mu) + \delta_2(x-\mu)^2$$

$$\mu = E(x)$$

[a] Find $\frac{\partial E(y|x)}{\partial x}$; comment

PE: $\frac{\partial E(y|x)}{\partial x} = \delta_1 + 2\delta_2(x-\mu) \equiv l(x),$

which is very flexible, depending on the values of δ_1 , δ_2 and μ all, as shown in the graph.



[b] Show that δ_1 is equal to $\frac{\partial E(y|x)}{\partial x}$ averaged across the distribution of x .

W.t.s. $E_x\left(\frac{\partial E(y|x)}{\partial x}\right) = \delta_1,$

i.e. $E_x\left(\frac{\partial E(y|x)}{\partial x}\right) = E_x[\delta_1 + 2\delta_2(x-\mu)]$
 $= \delta_1 + 2\delta_2 E[x-\mu] = \delta_1 + 2\delta_2 E[x - E(x)]$
 $= \delta_1$ $E(x)$

C Let $E[(x-\mu)^3] = 0$. Show that

$$L(y|I, x) = \alpha_0 + \delta_1 x, \text{ for some } \alpha_0$$

By 2.45 (or LP.5)

Since $E[y|x] = \delta_0 + \delta_1(x-\mu) + \delta_2(x-\mu)^2$, $E(y|x)$ has already include I (so as δ_0) as parameter, i.e. $E[y|x] = E(y|I, x)$

$$L(y|I, x) \equiv L\left[E[y|I, x] \mid I, x\right] \stackrel{\downarrow}{=} L\left[E[y|x] \mid I, x\right]$$

$$= L\left[\delta_0 + \delta_1(x-\mu) + \delta_2(x-\mu)^2 \mid I, x\right]$$

$$= \delta_0 + \delta_1(x-\mu) + \delta_2 L[(x-\mu)^2 \mid I, x]$$

Now let us check if $(x-\mu)^2$ and x are correlated.

$$\text{Denote } Y \equiv (x-\mu)^2, \quad Z = x - \mu = x - E[x]$$

$$\text{Thus } \text{cov}((x-\mu)^2, x) = \text{cov}(Y, Z + E[x])$$

$$= \text{cov}[Y, E[x]] + \text{cov}(Y, Z) \quad * \text{by cov property}$$

$$= E[Y E[x]] - E[Y] E[x] + E[YZ] - E[Y] E[Z]$$

$$= \mu \underbrace{E[(x-\mu)^2]}_0 - \mu E[(x-\mu)^2] + \underbrace{E[(x-\mu)^3]}_0 - \underbrace{E[(x-\mu)^2]}_0 \underbrace{E(x-\mu)}_0$$

$$= 0 \quad * \text{since } \mu = E[x] \text{ which is an arbitrary value instead of } \mu(x), \text{ it can be taken out from the bracket.}$$

As $(x-\mu)^2$ is uncorrelated with x , thus, for $L[(x-\mu)^2 \mid I, x] = y_0 + \gamma_1 x$

$$\gamma_1 = 0$$

$$\text{Thus, } L(y|I, x) = \delta_0 + \delta_1(x-\mu) + y_0 = (\delta_0 - \delta_1\mu + y_0) + \delta_1 x = \alpha_0 + \delta_1 x$$

$$\text{where } \alpha_0 = \delta_0 - \delta_1\mu + y_0$$

2.4. For random scalars u, v , and random vector \tilde{x} , suppose

- (1) $E[u|\tilde{x}, v]$ is a linear function of (\tilde{x}, v) (2) $E[u] = E[v] = 0$
- (3) u, v are uncorrelated with \tilde{x} . Show that

$$E[u|\tilde{x}, v] = E[u|v] = p_1 v, \text{ for some } p_1.$$

Note here we only have uncorrelation assumption, which does not imply independence, thus, we cannot use CE.S.

Assume $E[u|\tilde{x}, v] = \tilde{x} \beta + p_1 v, \quad x = [1, x_1, x_2 \dots]$

We want to find β to be zero

Since we are only given that $E[u|\tilde{x}, v]$ is linear of (\tilde{x}, v) , we have no idea if β are equal to that by LP.

By LP.1 $E[u|\tilde{x}, v] = \tilde{x} \beta + p_1 v = (\tilde{x}, v) \begin{pmatrix} \beta \\ p_1 \end{pmatrix} = L(u|\tilde{x}, v)$
 $\tilde{x} \text{ Aug } v$

Now, we can use LP.7 to estimate the β in CE, since they are consistent by LP.2

Let $r \equiv \tilde{x} - L(x|v)$, which is the residuals of x regressed on v . As \tilde{x}, u are uncorrelated, thus,
 $L(\tilde{x}|v) = 0$ i.e. $r = \tilde{x}$

Thus by LP.7. $L(u|r) = \beta r$, and u, r uncorrelated
 $L(u|x) \Rightarrow \beta = 0$

Thus, $E[u|\tilde{x}, v] = E[u|v] = p_1 v, \text{ for some } p_1$

2.7.

For conditional expectation $E(y|\underline{x}, \underline{z}) = g(\underline{x}) + \underline{z} \beta$

where $g(\cdot)$ is a general function of \underline{x} , β is $1 \times M$ vector. Show that $E[\tilde{y}|\tilde{\underline{z}}] = \tilde{\underline{z}} \beta$

where $\tilde{y} \equiv y - E[y|\underline{x}]$, $\tilde{\underline{z}} \equiv \underline{z} - E[\underline{z}|\underline{x}]$

$$\therefore y - u = E[y|\underline{x}, \underline{z}] = g(\underline{x}) + \underline{z} \beta$$

$\therefore y = g(\underline{x}) + \underline{z} \beta + u$ ①, u is the error w/ $E[u|\underline{x}, \underline{z}] = 0$

Take ① conditional expectation on \underline{x}

$$E[y|\underline{x}] = E[g(\underline{x})|\underline{x}] + E[\underline{z}|\underline{x}] \beta + E[u|\underline{x}]$$

$g(\underline{x}) \qquad \qquad \qquad \beta \qquad \qquad \qquad u$

$$E[y|\underline{x}] = g(\underline{x}) + E[\underline{z}|\underline{x}] \beta \quad ②$$

$$\textcircled{1} - \textcircled{2} \Rightarrow$$

$$y - E[y|\underline{x}] = (\underline{z} - E[\underline{z}|\underline{x}]) \beta + u$$

$$\Rightarrow \tilde{y} = \tilde{\underline{z}} \beta + u$$

$$\Rightarrow E[\tilde{y}|\tilde{\underline{z}}] = E[\tilde{\underline{z}}|\tilde{\underline{z}}] \beta + E[u|\tilde{\underline{z}}]$$

$$\therefore E[\tilde{y}|\tilde{\underline{z}}] = \tilde{\underline{z}} \beta$$

!! since $\tilde{\underline{z}}$ is
a function of
 \underline{z} & \underline{x}