view_frames Result Recorded at time: 447.181 odom Broadcaster: /gazebo Average rate: 10.208 Hz Most recent transform: 447.096 (0.085 sec old) Buffer length: 4.800 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (447.181 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (447.181 sec old) Most recent transform: 0.000 (447.181 sec old) Most recent transform: 447.176 (0.005 sec old) Most recent transform: 447.176 (0.005 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec hokuyo left_wheel right_wheel camera