view_frames Result Recorded at time: 129.921 odom Broadcaster: /gazebo Average rate: 10.213 Hz Most recent transform: 129.838 (0.083 sec old) Buffer length: 4.700 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (129.921 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.213 Hz Average rate: 10.213 Hz Most recent transform: 0.000 (129.921 sec old) Most recent transform: 0.000 (129.921 sec old) Most recent transform: 129.828 (0.093 sec old) Most recent transform: 129.828 (0.093 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.700 sec Buffer length: 4.700 sec hokuyo left_wheel right_wheel camera