

CZ4079 Final Year Project

A Machine Learning-Based Approach to Time-Dependent Shortest Path Queries

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Agenda

- 1 Introduction
- 2 Preliminary Processing
- 3 Landmark Graph



Introduction: Problem



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- A **query** $Q(u, v, t)$ that asks for a shortest path from u to v departing at time moment t

Introduction: General Approach



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- The new **machine learning-based approach** draws on collective wisdom of thousands of taxi drivers
- **Unsupervised learning** is employed to figure out the time-dependent edge costs
- A modified Dijkstra's algorithm calculates a shortest path on the fly

Introduction: Challenges

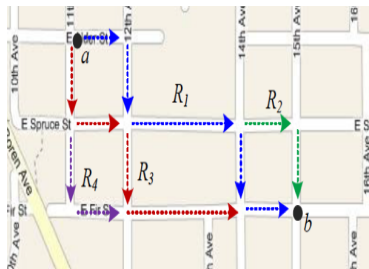


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- Arbitrary u and v
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- Limited GPS accuracy

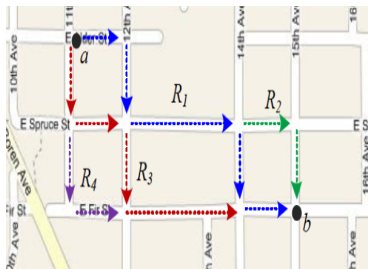


Figure 1: Examples of challenges

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Preliminary Processing: Data Description

- Is collected from Computational Sensing Lab at Tsinghua University
- Contains 83 million GPS records from 8,602 taxis in Beijing during May of 2009

Field	Explanation
CUID	ID for each taxi
UNIX_EPOCH	Unix timestamp
GPS_LONG	Longitude in WGS-84
GPS_LAT	Latitude in WGS-84
HEAD	Heading direction
SPEED	Instantaneous speed (m/s)
OCCUPIED	Hired (1) or not (0)

Table 1: A summary of the seven original fields

Preliminary Processing: Reverse Geocoding



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- GPS coordinate translation: 1.34°N , 103.68°E \rightarrow SCSE, NTU

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Figure 2: An example of China GPS shift problem

Preliminary Processing: Reverse Geocoding

- GPS coordinate translation: 1.34°N, 103.68°E → SCSE, NTU
- China GPS shift problem: WGS84 v.s. BD09
- Solution: WGS84 $\xrightarrow{\text{Baidu API}}$ BD09 $\xrightarrow{\text{Baidu API}}$ Street



Figure 2: An example of China GPS shift problem

Preliminary Processing: Outlier Detection

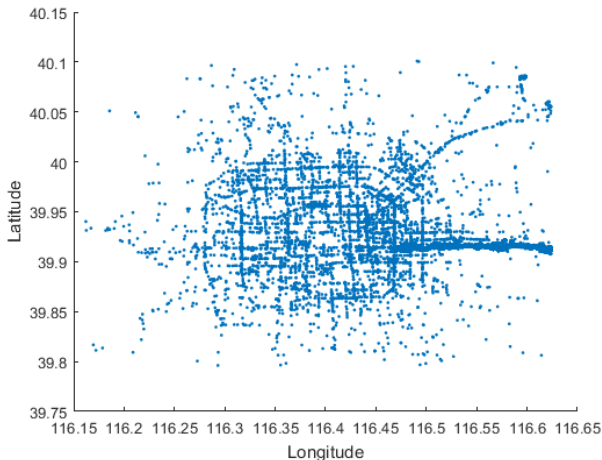


Figure 3: An example of outliers



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Theorem (*Majority Clustering Theorem*)

If a **reasonable reverse geocoder** is used to reverse-geocode a set of GPS data points which are mapped to a particular street *in reality*, then, when plotted on a 2-D plane, majority (more than 50%) of the points must be clustered together to form a rough shape that is similar to the shape of the street that they are supposed to be mapped to.

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Two-step procedure:

Outlier Detection = Outlier Identification + Outlier Removal

Outlier Identification: Clustering

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Outlier Removal: Distance Threshold d_{max}

- Assign sample points to legal centroids no farther than d_{max}
- Remove all “orphan” sample points
- Use real physical distance on the Earth
- Set $d_{max} = 30\text{m}$ or 50m

Preliminary Processing: Outlier Detection

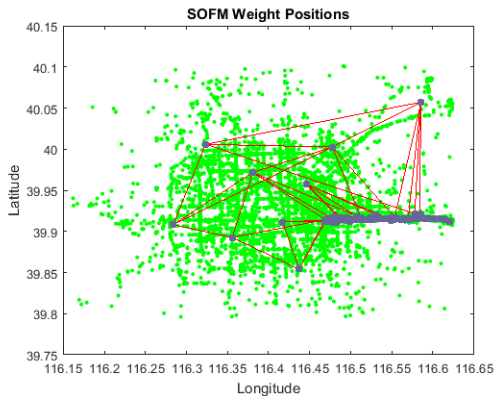


Figure 4: A plot of neuron positions after training



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Preliminary Processing: Outlier Detection

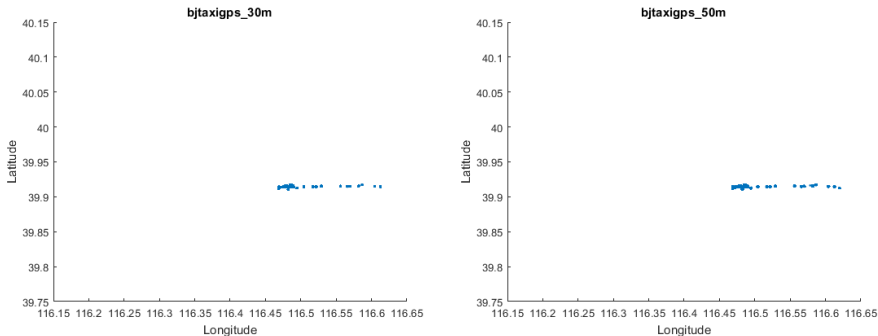


Figure 5: A plot of sample points after outlier removal

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Landmark Graph: Basic Ideas

Definition (*Landmark*)

A landmark is a road segment that is frequently traversed by taxi drivers according to the taxi GPS trajectory database.

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Step to build landmark graph

- Separate sample points into **trips**

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Step to build landmark graph

- Separate sample points into **trips**
- Count occurrences of each street
- Find connections between two landmarks



Landmark Graph: Trip Identification

CUID	UTC	GPS_LONG	GPS_LAT	OCCUPIED	TRIP_ID
1	1/5/2009 0:02:00	116.39616	39.81294	0	4552265
1	1/5/2009 0:04:00	116.39575	39.82296	0	4552265
1	1/5/2009 0:07:00	116.39567	39.82774	0	4552265
1	1/5/2009 17:08:00	116.30142	39.98105	1	1
1	1/5/2009 17:10:00	116.29514	39.98419	1	1
1	1/5/2009 17:11:00	116.28959	39.98289	1	1
1	1/5/2009 17:12:00	116.28087	39.97552	1	1
1	1/5/2009 17:16:00	116.26813	39.93537	1	1
1	1/5/2009 18:11:00	116.36537	39.95019	0	4552271
1	1/5/2009 18:12:00	116.36546	39.94886	0	4552271
1	1/5/2009 18:13:00	116.35927	39.94528	0	4552271

Table 2: An example of trip identification



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Landmark Graph: Frequency Counting

CUID	UTC	GPS_LONG	GPS_LAT	Street	TRIP_ID
1	1/5/2009 0:02:00	116.39616	39.81294	A	4552265
1	1/5/2009 0:04:00	116.39575	39.82296	A	4552265
1	1/5/2009 0:07:00	116.39567	39.82774	B	4552265
1	1/5/2009 17:08:00	116.30142	39.98105	C	1
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Table 3: An illustration of frequency counting



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Landmark Graph: Construction

For each trip

- Select a landmark j
- Record intermediate streets while searching for the next landmark k
- Repeat the process starting from k until all streets are examined