CZ4079 Final Year Project

A Machine Learning-Based Approach to Time-Dependent Shortest Path Queries

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Agenda

1. Introduction

2. Preliminary Processing

Introduction: Problem

- A **dynamic road network** $G = (V, E)$ with a time-dependent weight function $w : E, t \to \mathbb{R}$

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- A **dynamic road network** $G = (V, E)$ with a time-dependent weight function $w : E, t \to \mathbb{R}$
- A **query** $Q(u, v, t)$ that asks for a shortest path from u to v departing at time moment t

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Introduction: General Approach

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- **Unsupervised learning** is employed to figure out the time-dependent edge costs
- A modified Dijkstra's algorithm calculates a shortest path on the fly

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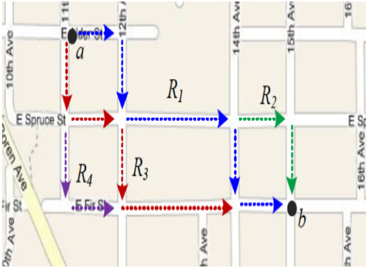

Introduction: Challenges

- Arbitrary u and v
- Sparse sample points
- Limited GPS accuracy

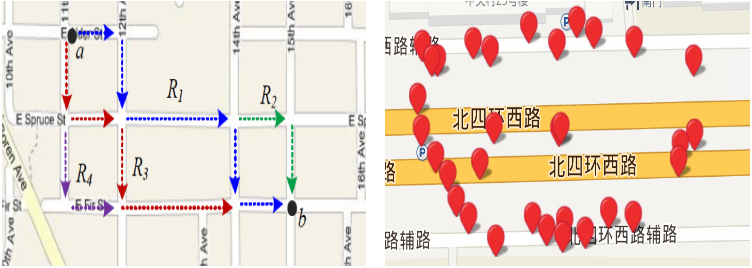

Figure 1: Examples of challenges

Agenda

Preliminary Processing: Data Description

- Is collected from Computational Sensing Lab at Tsinghua University
- Contains 83 million GPS records from 8,602 taxis in Beijing during May of 2009

Field	Explanation
CUID	ID for each taxi
UNIX_EPOCH	Unix timestamp
GPS_LONG	Longitude in WGS-84
GPS_LAT	Latitude in WGS-84
HEAD	Heading direction
SPEED	Instantaneous speed (m/s)
OCCUPIED	Hired (1) or not (0)

Table 1: A summary of the seven original fields

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Preliminary Processing: Reverse Geocoding

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- GPS coordinate translation: 1.34°N, 103.68°E $\rightarrow$ SCSE, NTU
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- Solution: WGS84 $\xrightarrow{Baidu\ \ API}$ BD09 $\xrightarrow{Baidu\ \ API}$ Street

Figure 2: An example of China GPS shift problem

Preliminary Processing: Outlier Detection

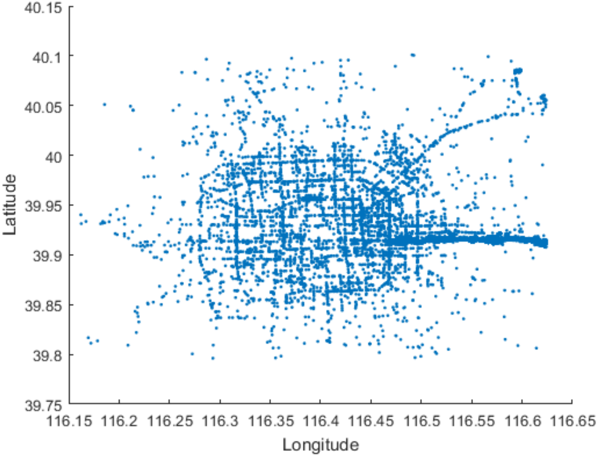

Figure 3: An example of outliers

Preliminary Processing: Outlier Detection

Theorem (*Majority Clustering Theorem*)

If a **reasonable reverse geocoder** is used to reverse-geocode a set of GPS data points which are mapped to a particular street *in reality*, then, when plotted on a 2-D plane, majority (more than 50%) of the points must be clustered together to form a rough shape that is similar to the shape of the street that they are supposed to be mapped to.

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Two-step procedure:
Outlier Detection = Outlier Identification + Outlier Removal

Preliminary Processing: Outlier Detection

Outlier Identification: Clustering

- Sample point concentration $\rightarrow$ cluster concentration
- Top $k\%$ ($k = 50\%$) largest clusters as groups of correct sample points
- 10×10 self-organising feature maps implementation