## CZ4079 Final Year Project

A Machine Learning-Based Approach to Time-Dependent Shortest Path Queries

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# Agenda

- Introduction
- Preliminary Processing
- 3 Landmark Graph
- 4 Travel Time Estimation
- 5 Shortest Path Calculation
- 6 Conclusion and Q&A



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#### Introduction: Problem



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- A **dynamic road network** G = (V, E) with a time-dependent weight function  $w : E, t \to \mathbb{R}$
- A query Q(u, v, t) that asks for a shortest path from u to v departing at time moment t





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- The new machine learning-based approach draws on collective wisdom of thousands of taxi drivers
- **Unsupervised learning** is employed to figure out the time-dependent edge costs
- A modified Dijkstra's algorithm calculates a shortest path on the fly





• Arbitrary *u* and *v* 



- Arbitrary *u* and *v*
- Sparse sample points





- Arbitrary *u* and *v*
- Sparse sample points
- Limited GPS accuracy



Figure 1: Examples of challenges



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### Preliminary Processing: Data Description

- Is collected from Computational Sensing Lab at Tsinghua University
- Contains 83 million GPS records from 8,602 taxis in Beijing during May of 2009

Field	Explanation
CUID	ID for each taxi
UNIX_EPOCH	Unix timestamp
GPS_LONG	Longitude in WGS-84
GPS_LAT	Latitude in WGS-84
HEAD	Heading direction
SPEED	Instantaneous speed (m/s)
OCCUPIED	Hired (1) or not (0)

Table 1: A summary of the seven original fields





ullet GPS coordinate translation: 1.34°N, 103.68°E ightarrow SCSE, NTU



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Figure 2: An example of China GPS shift problem



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- GPS coordinate translation: 1.34°N, 103.68°E  $\rightarrow$  SCSE, NTU
- China GPS shift problem: WGS84 v.s. BD09
- Solution: WGS84  $\xrightarrow{Baidu}$  BD09  $\xrightarrow{Baidu}$  Street



Figure 2: An example of China GPS shift problem



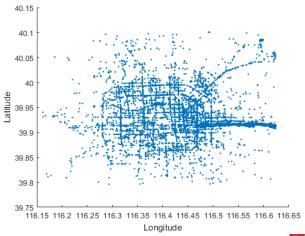


Figure 3: An example of outliers



#### Theorem (Majority Clustering Theorem)

If a **reasonable reverse geocoder** is used to reverse-geocode a set of GPS data points which are mapped to a particular street *in reality*, then, when plotted on a 2-D plane, majority (more than 50%) of the points must be clustered together to form a rough shape that is similar to the shape of the street that they are supposed to be mapped to.



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Two-step procedure:

 $Outlier\ Detection = Outlier\ Identification + Outlier\ Removal$ 



Outlier Identification: Clustering



#### Outlier Identification: Clustering

ullet Sample point concentration o cluster concentration



#### **Outlier Identification**: Clustering

- Sample point concentration → cluster concentration
- Top k% (k = 50) largest clusters as groups of correct sample points



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**Outlier Removal**: Distance Threshold  $d_{max}$ 

• Assign sample points to legal centroids no farther than  $d_{max}$ 



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- Remove all "orphan" sample points
- Use real physical distance on the Earth
- Set  $d_{max} = 30$ m or 50m



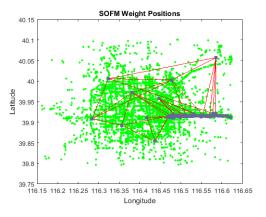


Figure 4: A plot of neuron positions after training

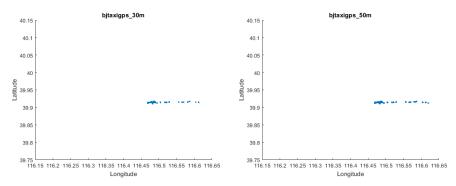


Figure 5: A plot of sample points after outlier removal



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A landmark is a road segment that is frequently traversed by taxi drivers according to the taxi GPS trajectory database.



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#### Step to build landmark graph

- Separate sample points into trips
- Count occurrences of each street
- Find connections between two landmarks



### Landmark Graph: Trip Identification

CUID	UTC	<b>GPS_LONG</b>	GPS_LAT	OCCUPIED	TRIP_ID
1	1/5/2009 0:02:00	116.39616	39.81294	0	4552265
1	1/5/2009 0:04:00	116.39575	39.82296	0	4552265
1	1/5/2009 0:07:00	116.39567	39.82774	0	4552265
1	1/5/2009 17:08:00	116.30142	39.98105	1	1
1	1/5/2009 17:10:00	116.29514	39.98419	1	1
1	1/5/2009 17:11:00	116.28959	39.98289	1	1
1	1/5/2009 17:12:00	116.28087	39.97552	1	1
1	1/5/2009 17:16:00	116.26813	39.93537	1	1
1	1/5/2009 18:11:00	116.36537	39.95019	0	4552271
1	1/5/2009 18:12:00	116.36546	39.94886	0	4552271
1	1/5/2009 18:13:00	116.35927	39.94528	0	4552271

Table 2: An example of trip identification



# Landmark Graph: Frequency Counting

CUID	UTC	<b>GPS_LONG</b>	GPS_LAT	Street	TRIP_ID
1	1/5/2009 0:02:00	116.39616	39.81294	А	4552265
1	1/5/2009 0:04:00	116.39575	39.82296	А	4552265
1	1/5/2009 0:07:00	116.39567	39.82774	В	4552265
1	1/5/2009 17:08:00	116.30142	39.98105	С	1
1	1/5/2009 17:10:00	116.29514	39.98419	С	1
1	1/5/2009 17:11:00	116.28959	39.98289	С	1
1	1/5/2009 17:12:00	116.28087	39.97552	А	1
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1	1/5/2009 18:13:00	116.35927	39.94528	С	4552271

Table 3: An illustration of frequency counting



### Landmark Graph: Construction

#### For each trip

- Select a landmark j
- ullet Record intermediate streets while searching for the next landmark k
- ullet Repeat the process starting from k until all streets are examined



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- Build a predictive model for travel time of each significant edge
- Separate weekday's travel time from weekend's
- Evaluate results against Baidu's estimates



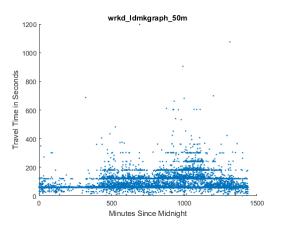


Figure 6: An example of travel time patterns



#### Possible Explanations

• Drivers choose different routes to travel between the two landmarks



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- Drivers choose different routes to travel between the two landmarks
- Drivers have different driving skills, preferences and behaviours



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- Drivers choose different routes to travel between the two landmarks
- Drivers have different driving skills, preferences and behaviours
- The GPS devices report locations **periodically**, therefore, durations like 60 seconds or 120 seconds are very common



# Travel Time Estimation: Clustering

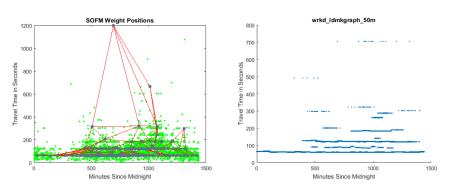


Figure 7: An illustration of travel time clustering



#### Travel Time Estimation: Distribution Fit

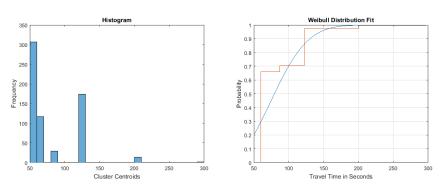


Figure 8: An illustration of fitting distribution



### Travel Time Estimation: Implementation

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- ullet Calculate and store lpha and eta for each 30-minute window
- Use optimism index p to find out travel time



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Landmark Graph	RMSE	Mean Error Ratio	Mean No. of Samples Per Edge
wrkd_ldmkgraph_50m	78.84	-0.009	1824.60
wrkd_ldmkgraph_30m	87.96	-0.065	1507.56
holi_ldmkgraph_50m	87.39	-0.16	832.96
holi_ldmkgraph_30m	76.41	-0.14	681.89

Table 4: A summary of evaluation results



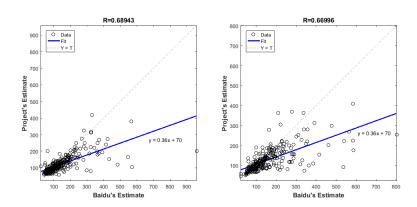


Figure 9: A plot of linear regression for weekday landmark graph



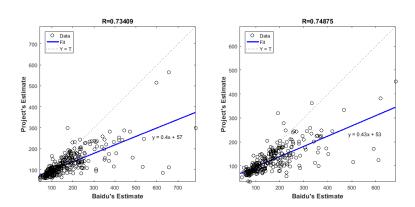


Figure 10: A plot of linear regression for weekend landmark graph



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- Shortest Path Calculation



#### Shortest Path Calculation: Basic Ideas

### Definition (FIFO Graph)

A time-dependent graph G=(V,E) with a dynamic weight function  $w:E,t\to\mathbb{R}$  is a FIFO graph iff for every edge  $(u,v)\in E$ 

$$\forall \Delta t \geq 0, \quad w(u, v, t_0) \leq \Delta t + w(u, v, t_0 + \Delta t)$$
 (1)



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 (1)

- Consider a landmark graph as a FIFO graph (usually true)
- Modify Dijkstra's algorithm to calculate edge costs in an online fashion



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### Shortest Path Calculation: Modified Dijkstra's Algorithm

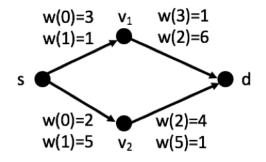


Figure 11: An example of modified Dijkstra's algorithm



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### Shortest Path Calculation: Real Test Example

- Departing at 8:25 p.m.
- 19.08 mins v.s. 21 mins (Baidu's estimate)



Figure 12: An example of shortest path query



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- Identified challenges in solving the problem



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- Identified challenges in solving the problem
- Proposed an innovative outlier detection approach
- Introduced algorithms for building landmark graphs
- Described procedures for estimating travel time
- Illustrated the modified Dijkstra's algorithm



### Conclusion and Q&A: Questions & Answers

# Any questions?

