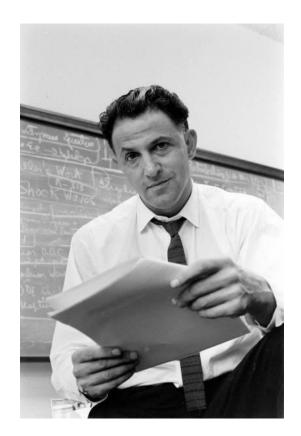
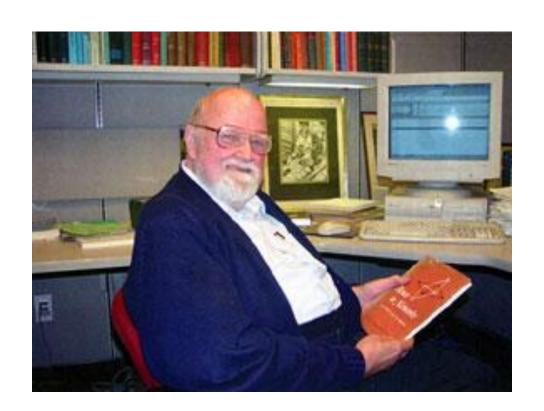
CS380 Artificial Intelligence for Games



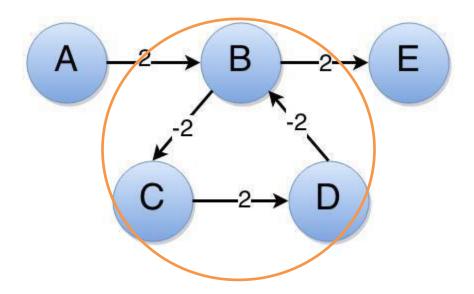
Richard Ernest <u>Bellman</u> 1925-2003



Lester Randolph <u>Ford</u>, Jr 1927-2017

- It finds the shortest path from a source node to all other nodes in a graph for <u>any positive or negative</u> edge cost values in a digraph or tells whether the graph contains **negative cycles**.
- It may consider nodes that are already expanded as long as they are reachable with a less cost.
- Dynamic programming algorithm
 - Optimal Substructure

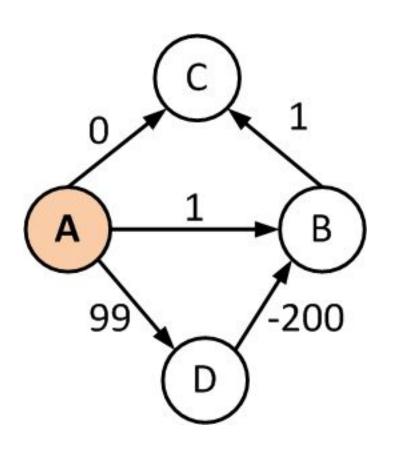
Cycles with negative total weights



- Negative edges make the shortest path problem harder.
- Negative cycles make the path problem non-traceable.

• Claim: If G has **no** negative cycles, then there is a <u>shortest</u> path from s to t that is simple (i.e. does not repeat nodes), and hence has at most n-1 edges.

```
for (each vertex v in Graph) {
  dist[v] = +\infty;
 previous[v] = null;
dist[source] = 0;
counter = 0;
for (i=0; i < numberOfVertices; i++) {</pre>
   for (each edge (u, v) with cost w) // A
         if (dist[u] + w < dist[v]) {
             dist[v] = dist[u] + w;
             previous[v] = u;
             counter++;
     if (counter==0) break;
 if (counter==0) then there is no negative cycles
 else {
   run loop A again
   if (counter==0) then there is no negative cycles
   else there is a negative cycle
```



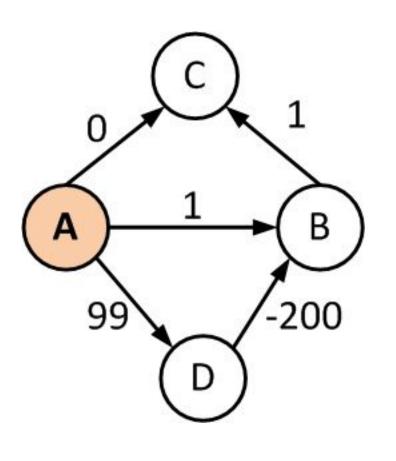
$$dist[A] = 0$$

$$dist[B] = +\infty$$

$$dist[C] = +\infty$$

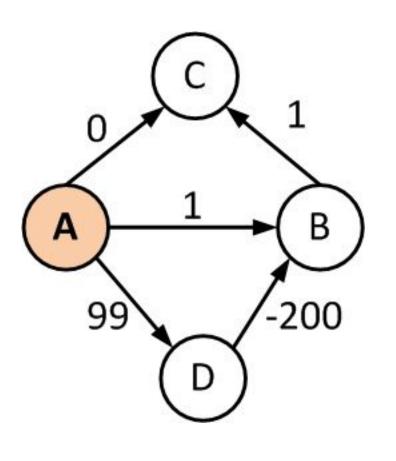
$$dist[D] = +\infty$$

$$counter = 0$$



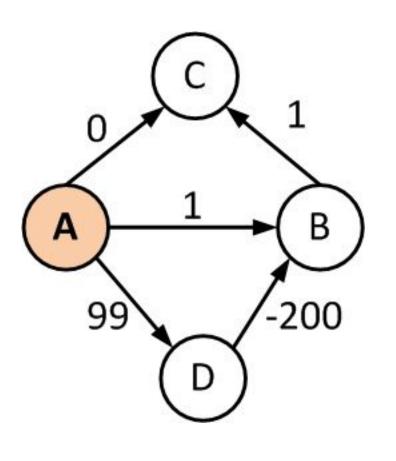
```
dist[A] = 0
dist[B] = +\infty
dist[C] = 0
dist[D] = +\infty
```

```
previous[A] = NA
previous[B] = NA
previous[C] = A
previous[D] = NA
```



```
dist[A] = 0
dist[B] = +\infty
dist[C] = 0
dist[D] = 99
```

```
previous[A] = NA
previous[B] = NA
previous[C] = A
previous[D] = A
```



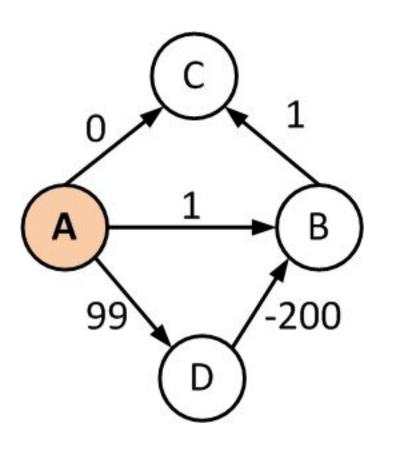
```
dist[A] = 0

dist[B] = 1

dist[C] = 0

dist[D] = 99
```

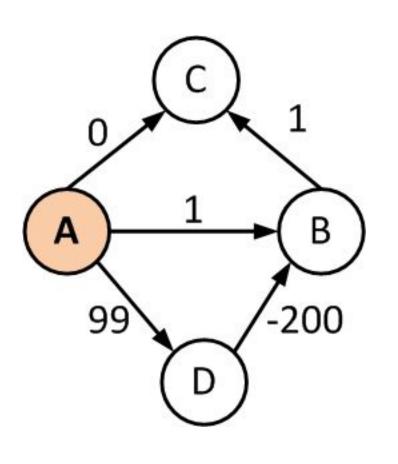
```
previous[A] = NA
previous[B] = A
previous[C] = A
previous[D] = A
```



```
dist[A] = 0
dist[B] = 1
dist[C] = 0
dist[D] = 99
```

```
previous[A] = NA
previous[B] = A
previous[C] = A
previous[D] = A
```

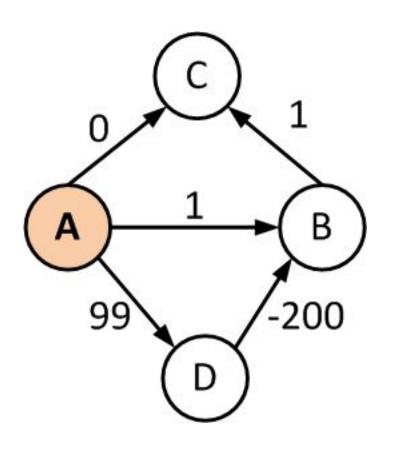
$$i=2$$
 counter = 0



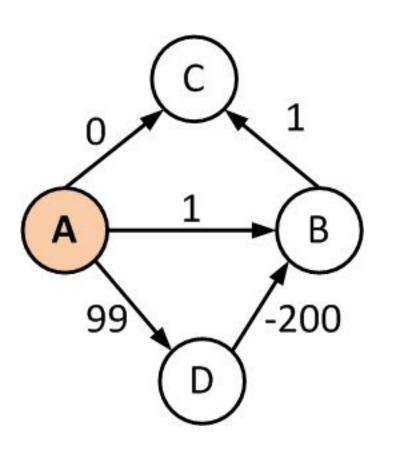
```
dist[A] = 0
dist[B] = -101
dist[C] = 0
dist[D] = 99
```

```
previous[A] = NA
previous[B] = D
previous[C] = A
previous[D] = A
```

$$counter = 1$$

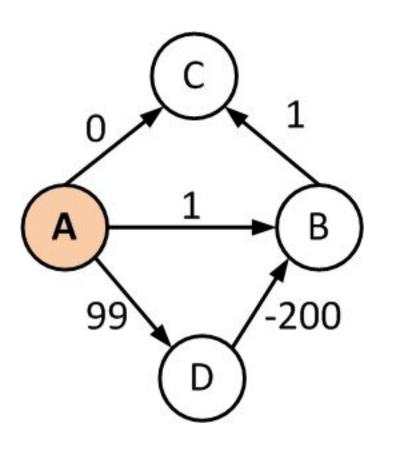


```
previous[A] = NA
previous[B] = D
previous[C] = A
previous[D] = A
```



```
dist[A] = 0
dist[B] = -101
dist[C] = -100
dist[D] = 99
```

```
previous[A] = NA
previous[B] = D
previous[C] = B
previous[D] = A
```



```
dist[A] = 0
dist[B] = -101
dist[C] = -100
dist[D] = 99
```

```
previous[A] = NA
previous[B] = D
previous[C] = B
previous[D] = A
```

- Complete?
 - Yes.
- Optimal?
 - Yes, if the state space doesn't contain cycles with negative total values.
- Complexity in terms of number of vertices: n and number of edges: m
 - Time complexity: $O(m*n) = O(n^3)$, note: $m = O(n^2)$.
 - Space complexity: O(n)

Self-Test

Question: How many invocations of a single source shortest-path subroutine are needed to solve the all-pairs shortest path problem? [n = # of vertices]

- a) 1
- b) n-1
- c) n
- d) n²

Self-Test

Question: How many invocations of a single source shortest-path subroutine are needed to solve the all-pairs shortest path problem? [n = # of vertices]

- a) 1
- b) n-1
- c) <u>n</u>
- d) n^2