

Threads

Instructor: William Zheng

Email:

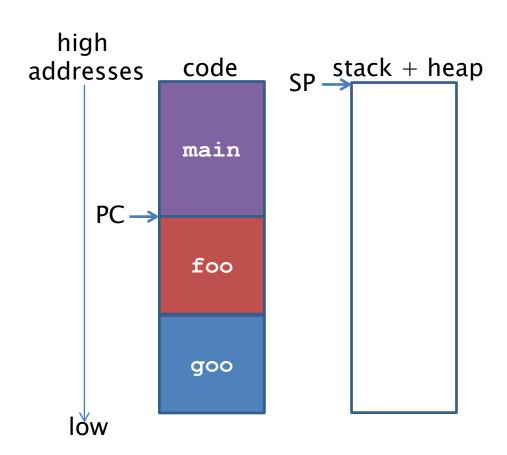
william.zheng@digipen.edu

PHONE EXT: 1745

Lecture Outline

- Review on stack
- Intro to Multithreading
- Multithreading Models
- Multithreading APIs

Stack Pointer and Program Counter



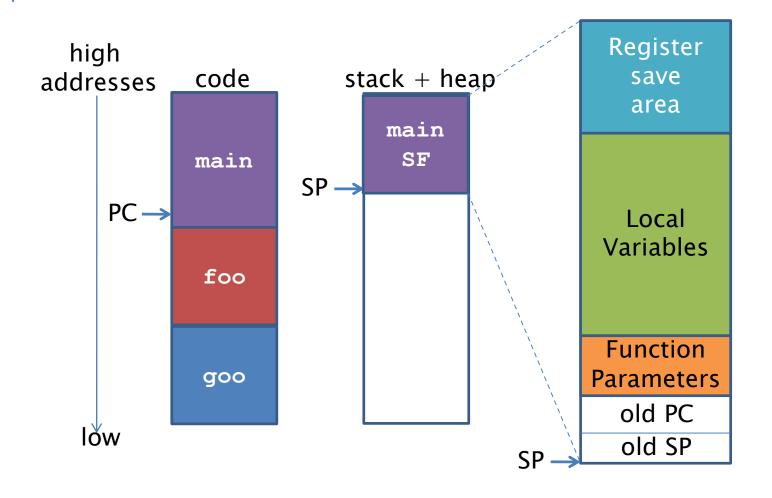
Consider a code with the following functions:

Assume that the functions are called:

```
main->foo->goo
```

PC pointing to main Stack is empty

Stack Frame



Stack Frame Organization – I

```
char *foo(int x, int y , int z)
{
    int a;
    char array[500];
    double d;
    ...
    a = x+y+goo(d,z);
    ...
}
```

Register save area

Local Variables

Function Parameters

old PC

old SP

Stack Frame Organization - II

```
Register
                                                  save
char *foo(int x, int y , int z)
                                                  area
     int a;
     char array[500];
     double d;
                                                  Local
                                                Variables
     a = x+y+goo(d,z);
                                                Function
                                               Parameters
                                                 old PC
                                                 old SP
a and d could be in registers
```

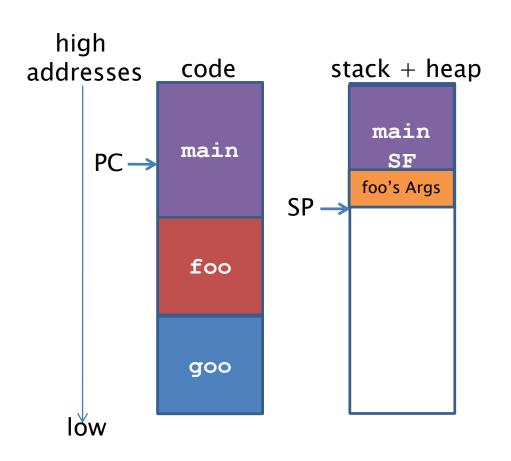
Stack Frame Organization - III

```
Register
                                                save
char *foo(int x, int y , int z)
                                                area
    int a;
    char array[500]
    double d;
                                                Local
                                              Variables
    a = x+y+goo(d, z);
                                              Function
                                             Parameters
                                               old PC
                                                old SP
```

Stack Frame Organization – IV

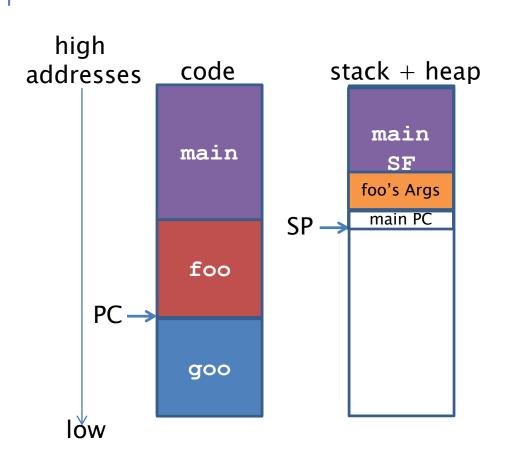
```
Register
                                                save
char *foo(int x, int y , int z)
                                                area
    int a;
    char array[500]
    double d;
                                               Local
                                              Variables
        x+y+goo(d,z);
                                              Function
                                             Parameters
                                               old PC
                                               old SP
```

Function Call and SF Creation - I



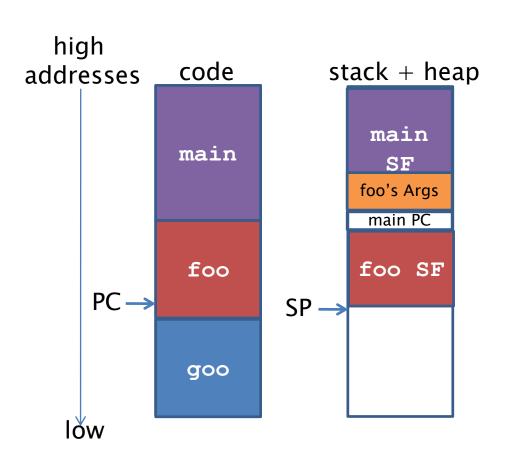
Push foo's Args

Function Call and SF Creation - II



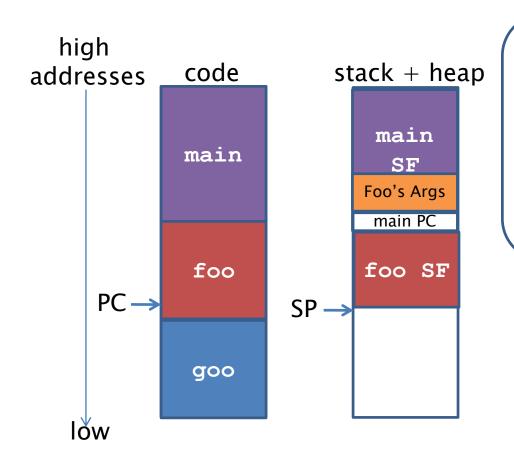
- Push foo's Args
- 2. Call foo

Function Call and SF Creation -III



- Push foo's Args
- 2. Call foo
- Save main SP and decrement SP

Function Call and SF Creation -IV



- Push foo's Args
- 2. Call foo
- Save main SP and decrement SP

Done in software i.e., done by instructions generated by the compiler!

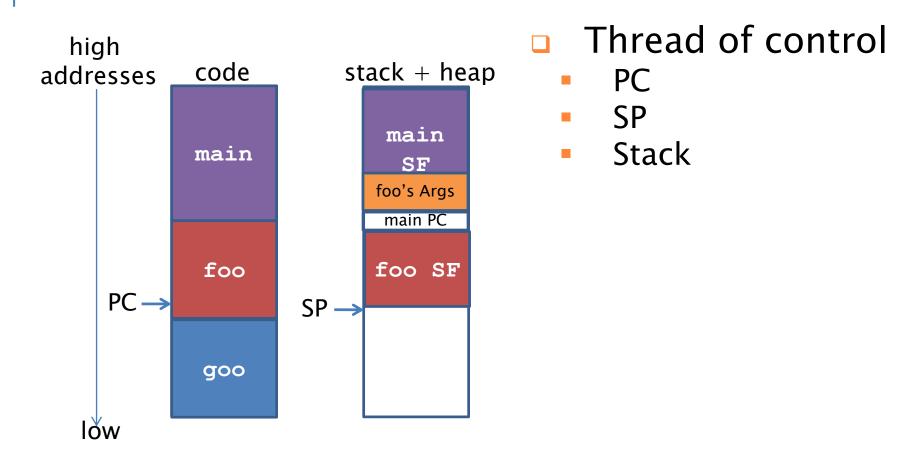
Q & A

- Does each function use the same stack frame size?
 - No. Depends on the size of local variables
- How and when is the size of stack frame determined?
 - Compiler determines by looking at the code.
 Compile-time.
- How is the stack frame allocated during run-time?
 - Decrementing the stack pointer

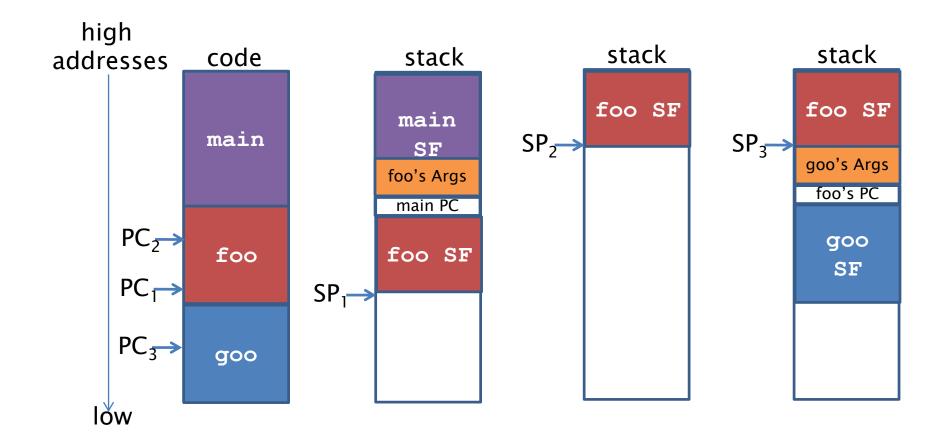
Q & A

- What is the stack pointer?
 - A value stored in stack pointer register (%esp) pointing to the beginning of the stack frame
- What is a program counter?
 - A value stored in program counter register (%eip) pointing to a point in the text

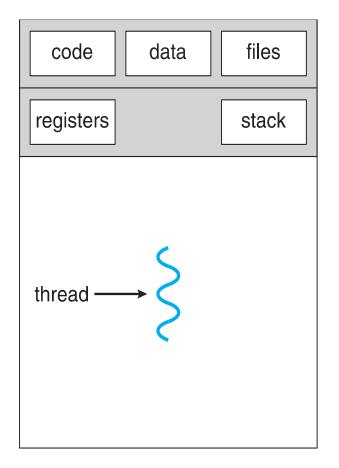
Single-thread process

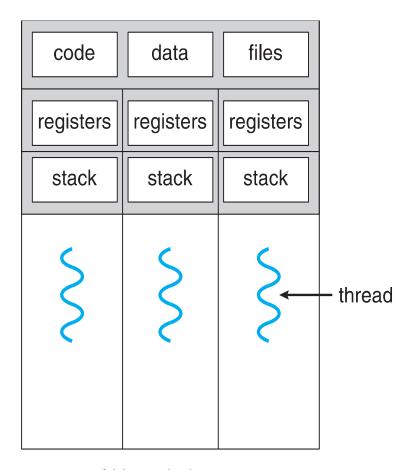


Multi-threaded process



Multi-threaded versus single threaded





single-threaded process

multithreaded process

Why Multithreading?

- Responsiveness
- Resource Sharing
- Economy
- Scalability

Matrix multiplication

$$c_{ij} = \sum_{r=1}^{n} a_{ir} \times b_{rj}$$
 How many arithmetic operations?

$$\begin{pmatrix} a_{11} & \dots & a_{1n} \\ \dots & \dots & \dots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} \times \begin{pmatrix} b_{11} & \dots & b_{1k} \\ \dots & \dots & \dots \\ b_{n1} & \dots & b_{nk} \end{pmatrix} = \begin{pmatrix} c_{11} & \dots & c_{1k} \\ \dots & \dots & \dots \\ c_{m1} & \dots & c_{mk} \end{pmatrix}$$

An initial solution

```
void slow multiply (Matrix A, Matrix B, Matrix C)
    for (int i=0; i < m; i++)
        for (int j=0; j< k; j++)
             acc = 0;
             for (int r=0; r< n; r++)
                 acc += A[i][r]*B[r][j];
             C[i][j] = acc;
```

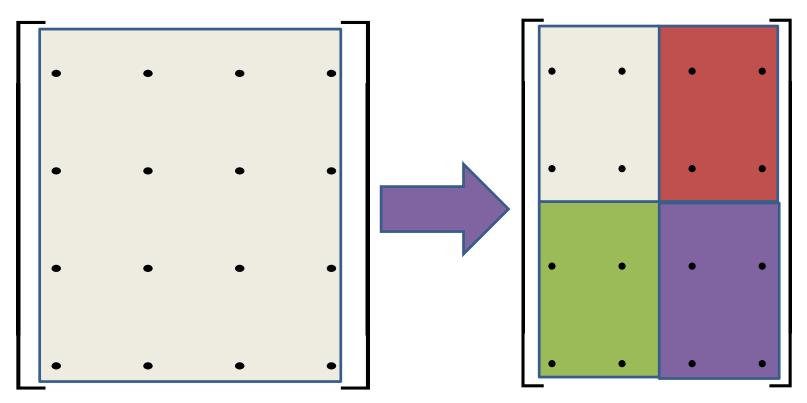
Resources Usage

```
void
                    void slow multiply (Matrix A,
slow multip
                    Matrix B, Matrix C)
ly(Matrix
A, Matrix
B, Matrix
C)
      CPU<sub>1</sub>
                     CPU<sub>1</sub>
                                CPU<sub>2</sub>
                                           CPU<sub>3</sub>
                                                            CPU_n
```

Doing better

Instead of computing C_{00} , C_{01} , C_{02} , C_{03} ,....

Why don't we split up the computation?



Multithreads of Multiplication

Procedure multiply(*C*, *A*, *B*):

- •Base case: if n = 1, set $c_{11} \leftarrow a_{11} \times b_{11}$ (or multiply a small block matrix).
- •Otherwise, allocate space for a new matrix T of shape $n \times n$, then:
 - Partition A into A_{11} , A_{12} , A_{21} , A_{22} .
 - Partition *B* into B_{11} , B_{12} , B_{21} , B_{22} .
 - Partition C into C₁₁, C₁₂, C₂₁, C₂₂.
 - Partition T into T_{11} , T_{12} , T_{21} , T_{22} .
 - Parallel execution:
 - Fork multiply(C_{11} , A_{11} , B_{11}).
 - Fork multiply(C_{12} , A_{11} , B_{12}).
 - Fork multiply(C_{21} , A_{21} , B_{11}).
 - Fork multiply(C_{22} , A_{21} , B_{12}).
 - Fork multiply(T_{11} , A_{12} , B_{21}).
 - Fork multiply(T_{12} , A_{12} , B_{22}).
 - Fork multiply(T_{21} , A_{22} , B_{21}).
 - Fork multiply(T_{22} , A_{22} , B_{22}).
 - Join (wait for parallel forks to complete).
 - add(*C*, *T*).
 - Deallocate T.

Two kinds of stack

- User Stack
 - Used for user-level programs
- Kernel Stack
 - Used by system-calls

User Threads and Kernel Threads

- User threads management done by user-level threads library
- Three primary thread libraries:
 - POSIX Pthreads
 - Windows threads
 - Java threads
- Kernel threads Supported by the Kernel
- Examples virtually all general purpose operating systems, including:
 - Windows
 - Linux
 - Mac OS X

Single thread execution

user mode execution System call kernel mode execution

Multithreading Model

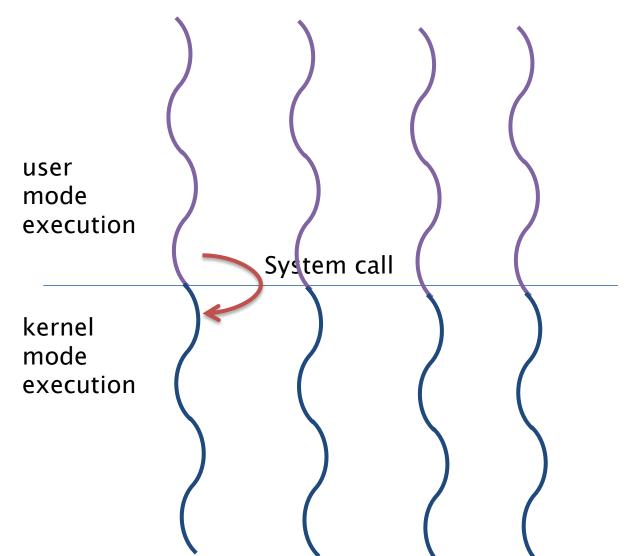
- Ratio of User Level Threads to Kernel Level Threads in a Process
 - M:1
 - 1:1
 - M:N

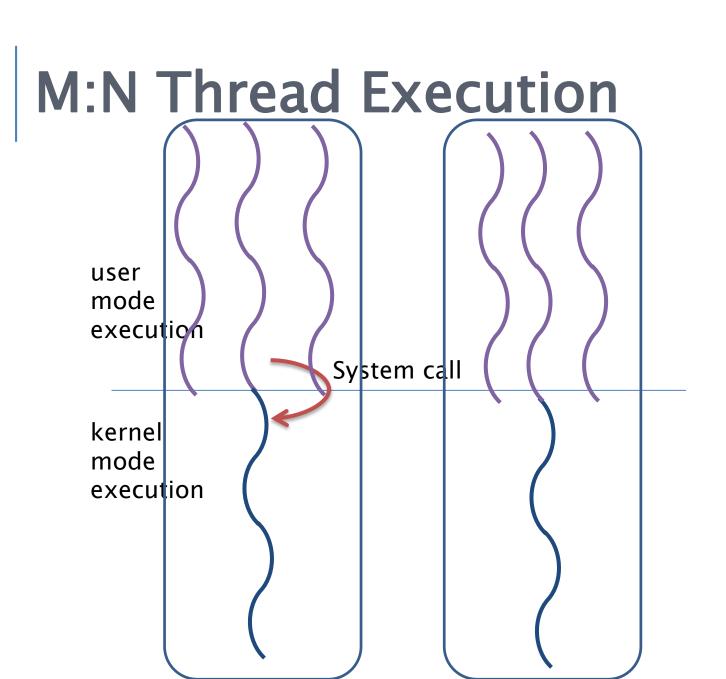
M: 1 Model

user mode execution

kernel mode execution System call

1:1 Thread Execution





Threads API

- Basic
 - Thread Creation
 - Thread Joining & Exit
- Advanced
 - ProcessorAffinity
 - Yield CPU

Threads Creation

- Thread ID
- Passing Arguments to thread
- Starting function for thread
 - pthread_create in Linux/Unix
 - CreateThread in Win32

Threads Joining and Exit

- Linux
 - pthread_join and pthread_exit
- Win32
 - WaitForSingleObject
 - ExitThread