

# cs380su21-meta.sg

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 Description

 Submission view

## Grade

Reviewed on Friday, 28 May 2021, 4:38 PM by Yi Lin YEE  
**grade:** 85.00 / 100.00

### Assessment report [-]

[\[-\] Summary of tests](#)

+-----+  
| 10 tests run/10 tests passed |  
+-----+

Memory leak -15%

Submitted on Wednesday, 26 May 2021, 7:00 PM ([Download](#))

functions.cpp

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16

17

18

```
/*!*****  
 \file functions.cpp  
 \author Vadim Surov, Goh Wei Zhe  
 \par DP email: vsurov\@digipen.edu, weizhe.goh\@digipen.edu  
 \par Course: CS380  
 \par Section: A  
 \par Programming Assignment 2  
 \date 05-26-2021  
 \brief  
 This file has declarations and definitions that are required for submission  
 *****/  
 #include "functions.h"  
  
 namespace AI  
 {  
  
 }  

```

functions.h

```

1  /*!*****
2  \file functions.h
3  \author Vadim Surov, Goh Wei Zhe
4  \par DP email: vsurov@digipen.edu, weizhe.goh@digipen.edu
5  \par Course: CS380
6  \par Section: A
7  \par Programming Assignment 2
8  \date 05-26-2021
9  \brief
10 This file has declarations and definitions that are required for submission
11 *****/
12
13 #ifndef FUNCTIONS_H
14 #define FUNCTIONS_H
15
16 #include <stack>
17 #include <algorithm>
18 #include <queue>
19
20 #include "data.h"
21
22 #define UNUSED(expr) (void)expr;
23
24 namespace AI
25 {
26     // Domain specific functor that returns adjacent nodes
27     class GetMapAdjacents : public GetAdjacents
28     {
29     public:
30         int* map; // the map with integers where 0 means an empty cell
31         int size; // width and height of the map in elements
32
33         GetMapAdjacents(int* map=nullptr, int size=0)
34             : GetAdjacents(), map{ map }, size{ size }{}
35
36         virtual ~GetMapAdjacents(){}
37
38         /*!*****
39         \brief
40         Set grid positions and grid color
41
42         \param key
43         Position of cell in grid
44
45         \param color
46         Color of cell
47
48         \return
49         None.
50         *****/
51         void setValue(Key key, int color)
52         {
53             int j = key.j;
54             int i = key.i;
55
56             this->map[j * this->size + i] = color;
57         }
58
59         /*!*****
60         \brief
61         An Operator Overloading function that finds all empty adjacent cells and
62         insert into an array vector of nodes and return it.
63
64         \param key
65         Position of cell in grid
66
67         \return
68         Returns an array vector of nodes
69         *****/
70         std::vector<AI::Node*> operator()(Key key)
71         {
72             int j = key.j;
73             int i = key.i;
74
75             std::vector<AI::Node*> list = {};
76
77             // Find and return all empty adjacent cells
78             if (j >= 0 && j < this->size && i >= 0 && i < this->size)
79             {
80                 if (i > 0 && this->map[j * this->size + i - 1] == 0)
81                 {
82                     Node* newNode = new Node;
83                     newNode->key.i = i - 1;
84                     newNode->key.j = j;
85
86                     list.push_back(newNode);
87                 }
88
89                 if (i < this->size-1 && this->map[j * this->size + i + 1] == 0)
90                 {
91                     Node* newNode = new Node;
92                     newNode->key.i = i + 1;
93                     newNode->key.j = j;
94
95                     list.push_back(newNode);
96                 }
97
98                 if (j > 0 && this->map[(j - 1) * this->size + i] == 0)
99                 {
100                     Node* newNode = new Node;
101                     newNode->key.j = j - 1;
102                     newNode->key.i = i;
103
104                     list.push_back(newNode);
105                 }
106
107                 if (j < this->size-1 && this->map[(j + 1) * this->size + i] == 0)

```

```

109 {
110     Node* newNode = new Node;
111     newNode->key.j = j + 1;
112     newNode->key.i = i;
113
114     list.push_back(newNode);
115 }
116 }
117
118     return list;
119 }
120 };
121
122 // Domain specific functor that returns shuffled adjacent nodes
123 class GetMapStochasticAdjacents : public GetMapAdjacents
124 {
125 public:
126
127     GetMapStochasticAdjacents(int* map, int size)
128         : GetMapAdjacents{ map, size }{}
129
130     /*!*****
131     \brief
132     An Operator Overloading function that finds all empty adjacent cells and
133     insert into an array vector of Nodes, then shuffles the result and
134     return it.
135
136     \param key
137     Position of cell in grid
138
139     \return
140     Returns an array vector of nodes
141     *****/
142     std::vector<AI::Node*> operator()(Key key)
143     {
144         std::vector<AI::Node*> list = {};
145
146         // Find and return all empty adjacent cells
147         // Use the base class operator() and then shuffle the result
148
149         list = GetMapAdjacents::operator()(key);
150         std::random_shuffle(list.begin(), list.end());
151
152         return list;
153     }
154 };
155
156 // Wrappers that provide same interface for queue and stack
157
158 struct Interface
159 {
160     virtual void clear() = 0;
161     virtual void push(Node* pNode) = 0;
162     virtual Node* pop() = 0;
163 };
164
165 struct Queue : Interface
166 {
167     std::vector<Node*> Q;
168     int count = 0;
169
170     /*!*****
171     \brief
172     Clears all nodes in the vector array
173
174     \param
175     None.
176
177     \return
178     None.
179     *****/
180     void clear()
181     {
182         Q.clear();
183         count = 0;
184     }
185
186     /*!*****
187     \brief
188     Add nodes by pushing back to the vector array
189
190     \param
191     None.
192
193     \return
194     None.
195     *****/
196     void push(Node* pNode)
197     {
198         Q.push_back(pNode);
199         ++count;
200     }
201
202     /*!*****
203     \brief
204     Remove nodes by popping it from the back of the vector array
205
206     \param
207     None.
208
209     \return
210     None.
211     *****/
212     Node* pop()
213     {
214         Node* pNode = nullptr;
215
216         pNode = Q.back();

```

```

217         Q.pop_back();
218         --count;
219
220         return pNode;
221     }
222
223     /*!*****
224     \brief
225     Check if the vector array is empty
226
227     \param
228     None.
229
230     \return
231     Returns true if vector is empty, else returns false
232     *****/
233     bool empty()
234     {
235         return (count == 0) ? true : false;
236     }
237 };
238
239 struct Stack : Interface
240 {
241     std::vector<Node*> Stack;
242     int count = 0;
243
244     /*!*****
245     \brief
246     Clears all nodes in the vector array
247
248     \param
249     None.
250
251     \return
252     None.
253     *****/
254     void clear()
255     {
256         Stack.clear();
257     }
258
259     /*!*****
260     \brief
261     Add nodes by pushing back to the vector array
262
263     \param
264     None.
265
266     \return
267     None.
268     *****/
269     void push(Node* pNode)
270     {
271         Stack.push_back(pNode);
272         ++count;
273     }
274
275     /*!*****
276     \brief
277     Remove nodes by popping it from the back of the vector array
278
279     \param
280     None.
281
282     \return
283     None.
284     *****/
285     Node* pop()
286     {
287         Node* pNode = nullptr;
288
289         pNode = Stack.back();
290         Stack.pop_back();
291         --count;
292
293         return pNode;
294     }
295
296     /*!*****
297     \brief
298     Check if the vector array is empty
299
300     \param
301     None.
302
303     \return
304     Returns true if vector is empty, else returns false
305     *****/
306     bool empty()
307     {
308         return (count == 0) ? true : false;
309     }
310 };
311
312 // Recursive Flood Fill
313 class Flood_Fill_Recursive
314 {
315     GetAdjacents* pGetAdjacents;
316
317 public:
318     Flood_Fill_Recursive(GetAdjacents* pGetAdjacents)
319         : pGetAdjacents{ pGetAdjacents }{}
320
321     /*!*****
322     \brief
323     Implement Recursive Flood Fill Algorithm
324

```

```
325     \param key
326     Position of cell in grid
327
328     \param color
329     Color of cell
330
331     \return
332     None
333     *****/
334     void run(Key key, int color)
335     {
336         // Implement the flood fill
337         std::vector<AI::Node*> adjacentList =
338             this->pGetAdjacents->operator()(key);
339
340         for (auto adj : adjacentList)
341         {
342             GetMapAdjacents* mapAdj =
343                 dynamic_cast<GetMapAdjacents*>(this->pGetAdjacents);
344
345             mapAdj->setValue(adj->key, color);
346             this->run(adj->key, color);
347         }
348     }
349 };
350
351 // Iterative Flood Fill
352 // Type T defines is it depth- or breadth-first
353 template<typename T>
354 class Flood_Fill_Iterative
355 {
356     GetAdjacents* pGetAdjacents;
357     T openlist;
358
359 public:
360     Flood_Fill_Iterative(GetAdjacents* pGetAdjacents)
361         : pGetAdjacents{ pGetAdjacents }, openlist{{}}
362
363     /*!*****
364     \brief
365     Implement Iterative Flood Fill Algorithm, depth or breadth-first
366
367     \param key
368     Position of cell in grid
369
370     \param color
371     Color of cell
372
373     \return
374     None
375     *****/
376     void run(Key key, int color)
377     {
378         // Implement the flood fill
379         openlist.clear();
380         openlist.push(new Node(key));
381
382         while (!openlist.empty())
383         {
384             Node* current = openlist.pop();
385             std::vector<Node*> adjacentList =
386                 this->pGetAdjacents->operator()(current->key);
387
388             for (auto adj : adjacentList)
389             {
390                 GetMapAdjacents* mapAdj =
391                     dynamic_cast<GetMapAdjacents*>(this->pGetAdjacents);
392
393                 mapAdj->setValue(adj->key, color);
394                 this->openlist.push(adj);
395             }
396         }
397     }
398 };
399
400 } // end namespace
401
402 #endif
```

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⌵

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28/5/2021 9:00am-12:20pm ▶

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