

# CS230 Game Implementation Techniques

Lecture 20



## Questions?

- Reflection
- Animated Circle to Line Segment



#### Overview

- Animated Circular Object and Stationary Circular Object
- Collision Response (Reflection)



# Modeling Pinball Animation as Ray

- Located at center point  $B_s$  at top of frame
- Moving in direction given by normalized vector v and speed k units
- In other words, k is the magnitude of the vector v

$$B(t) = B_s + \vec{v}(t)$$

$$\Rightarrow B(t) = B_s + k\hat{v}(t) \qquad t \in [0,1]$$

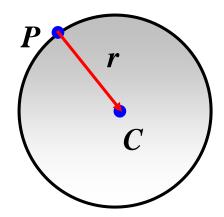


#### Circular Pillars

- Circular pillars are stationary and defined by center point *C* and radius *r*
- Boundary of circle defined as all points *P* whose distance from center *C* is equal to radius *r*

$$||C-P||=r \implies ||C-P||^2=r^2$$

$$\Rightarrow (C-P) \bullet (C-P) = r^2$$





# Ray-Circle Intersection (1/6)

• To solve for intersection between ray B(t) and circle, replace P with  $B(t_i)$  in circle equation

$$(C-B(t)) \bullet (C-B(t)) = r^2$$

$$\Rightarrow (C - B_s - t\vec{v}) \bullet (C - B_s - t\vec{v}) = r^2$$

$$\Rightarrow t^{2}(\vec{v} \bullet \vec{v}) - 2t(C - B_{s}) \bullet \vec{v} + (C - B_{s}) \bullet (C - B_{s}) - r^{2} = 0$$



# Ray-Circle Intersection (2/6)

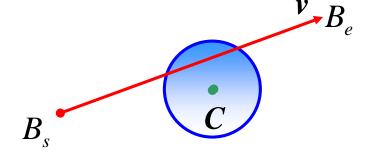
$$\Rightarrow$$
 at<sup>2</sup> + bt + c = 0

where

$$a = \vec{v} \bullet \vec{v}$$

$$b = -2\left(\overrightarrow{B_sC}\right) \bullet \overrightarrow{v}$$

$$c = \left(\overrightarrow{B_s C}\right) \bullet \left(\overrightarrow{B_s C}\right) - r^2$$





# Ray-Circle Intersection (3/6)

Solve for t,

$$t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

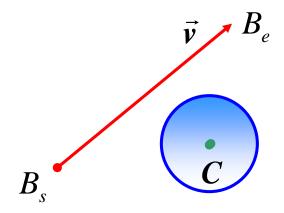


# Ray-Circle Intersection (4/6)

Given : 
$$\mathbf{a} = \vec{v} \bullet \vec{v}$$
,  $\mathbf{b} = -2(C - B_s) \bullet \vec{v}$ , and

$$c = (C - B_s) \bullet (C - B_s) - r^2$$

If  $b^2 - 4ac < 0 \Rightarrow$  ray misses circle



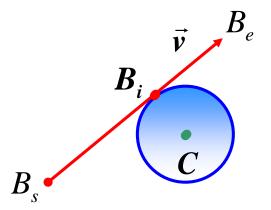


# Ray-Circle Intersection (5/6)

If  $b^2 - 4ac \equiv 0 \Rightarrow$  ray grazes circle

$$t_i = \frac{-b}{2a} \in [0,1]$$

$$\boldsymbol{B}_{i} = \boldsymbol{B}(\boldsymbol{t}_{i}) = \boldsymbol{B}_{s} + \vec{v}\boldsymbol{t}_{i}$$





# Ray-Circle Intersection (6/6)

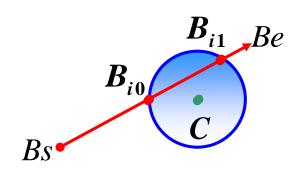
If  $b^2 - 4ac > 0 \Rightarrow$  ray intersects circle at  $B_{i0}$  and  $B_{i1}$ 

$$t_{i0} = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

$$t_{i1} = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

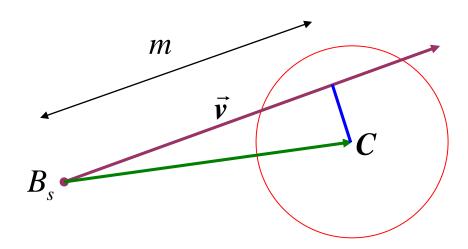
$$t_i = \min(t_{i0}, t_{i1}) \text{ and } t_i \in [0,1]$$

$$B(t_i) = B_i = B_s + \vec{v}t_i$$





# Test for Non-Collision (1/3)

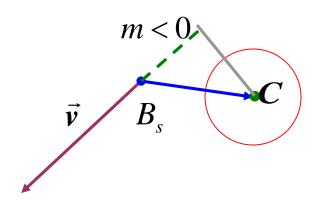


Compute projection of  $\overrightarrow{B_sC}$  onto  $\hat{v}$ 



## Test for Non-Collision (2/3)

$$m = \overrightarrow{B_s C} \bullet \frac{\overrightarrow{v}}{\|\overrightarrow{v}\|}$$



If  $m < 0 & B_s$  outside circle

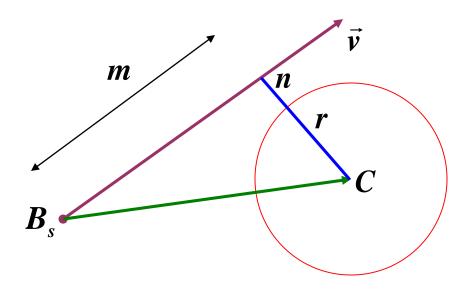
⇒ circle behind ray origin



# Test for Non-Collision (3/3)

Compute : 
$$n^2 = ||B_s C||^2 - m^2$$

If  $n^2 > r^2$  ray will miss the circle





## ... Otherwise: Compute t<sub>i</sub>

(1/2)

- There are two ways to compute the time of intersection:
  - Using the quadratic equation

$$t_{i0} = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

$$t_{i1} = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

$$t_{i} = \min(t_{i0}, t_{i1}) \text{ and } t_{i} \in [0,1]$$

(Or make sure that the intersection point is between B<sub>s</sub> and B<sub>e</sub>)



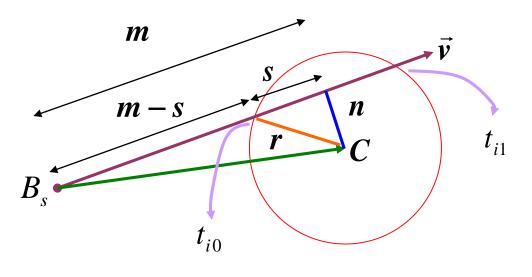
# Compute $t_i$ (2<sup>nd</sup> method) (2/2)

Compute: 
$$s^2 = r^2 - n^2$$

Since 
$$n^2 \le r^2 \Rightarrow s^2 \ge 0 \Rightarrow s \ge 0$$

$$t_{i0} = \frac{m - s}{\|\vec{v}\|}$$

$$t_{i1} = \frac{m+s}{\|\vec{v}\|}$$



(Make sure that the intersection point is between  $B_s$  and  $B_e$ )



#### Overview

- Animated Circular Object and Stationary Circular Object
- Collision Response (Reflection)

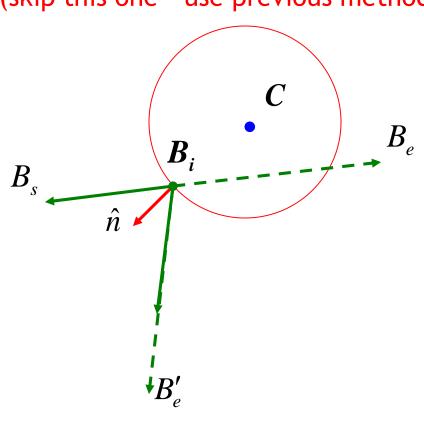


# Reflection (1/4) (skip this one - use previous method)

Compute:  $\mathbf{B}_{i} = \mathbf{B}_{s} + \vec{v}t_{i}$ 

Compute :  $\vec{n} = CB_{\cdot}$ 

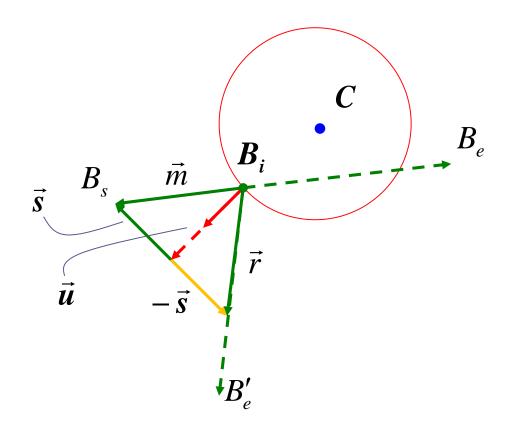
$$\hat{n} = \frac{\overrightarrow{CB_i}}{\left\| \overrightarrow{CB_i} \right\|}$$





#### Reflection (2/4) (skip this one - use previous method)

$$\vec{m} = \overrightarrow{B_i B_s} = B_s - B_i$$





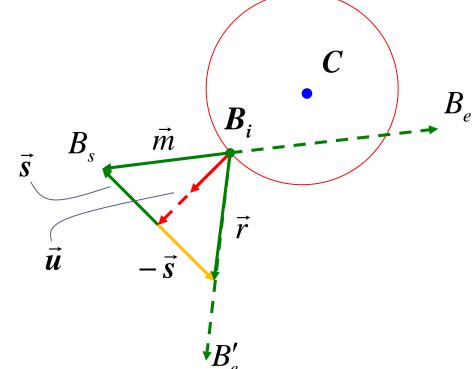
#### Reflection (3/4) (skip this one - use previous method)

$$\vec{u} + \vec{s} = \vec{m}$$

$$\vec{u} - \vec{s} = \vec{r}$$

$$2\vec{u} = \vec{m} + \vec{r} \implies \vec{r} = 2\vec{u} - \vec{m}$$

$$\vec{u} = (\vec{m} \bullet \hat{n})\hat{n}$$



Reflection:  $\vec{r} = 2(\vec{m} \cdot \hat{n})\hat{n} - \vec{m}$ 



## Reflection (4/4) (skip this one - use previous method)

Given : 
$$B_s$$
,  $B_i$ ,  $t_i$  and  $\vec{n}$ 

$$\vec{m} = \overrightarrow{B_i B_s} = B_s - B_i$$

$$\vec{r} = 2(\vec{m} \cdot \hat{n})\hat{n} - \vec{m}$$
  $\hat{r} = \frac{r}{\|\vec{r}\|}$ 

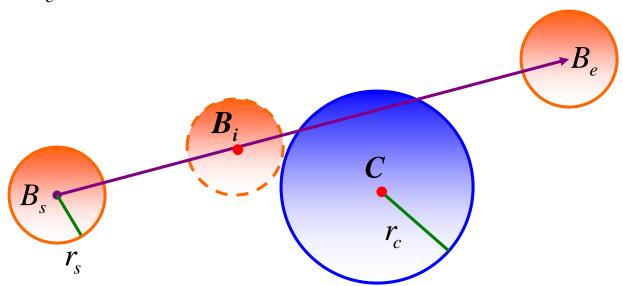
$$\Rightarrow B_e' = B_i + k\hat{r}(1 - t_i)$$

(k is the length of the original vector v. Refer to slide 4)



## Pinball-Circular Pillar Collision (1/2)

- Animated pinball modeled by a circle with center  $B_s$  and radius  $r_s$
- Stationary circular pillar defined by center point C and radius  $r_c$





## Pinball-Circular Pillar Collision (2/2)

• Similar to intersection tests between ray from  $B_s$  to  $B_e$  and circle of radius  $(r_s + r_c)$ 

