

Embedded Systems

CS 397

TRIMESTER 3, AY 2021/22

Hands-On 1-3

STM32CubeIDE: DAC, ADC with Interrupt and DMA

Dr. LIAW Hwee Choo

Department of Electrical and Computer Engineering

DigiPen Institute of Technology Singapore

HweeChoo.Liaw@DigiPen.edu

STM32CubeIDE – DAC ADC

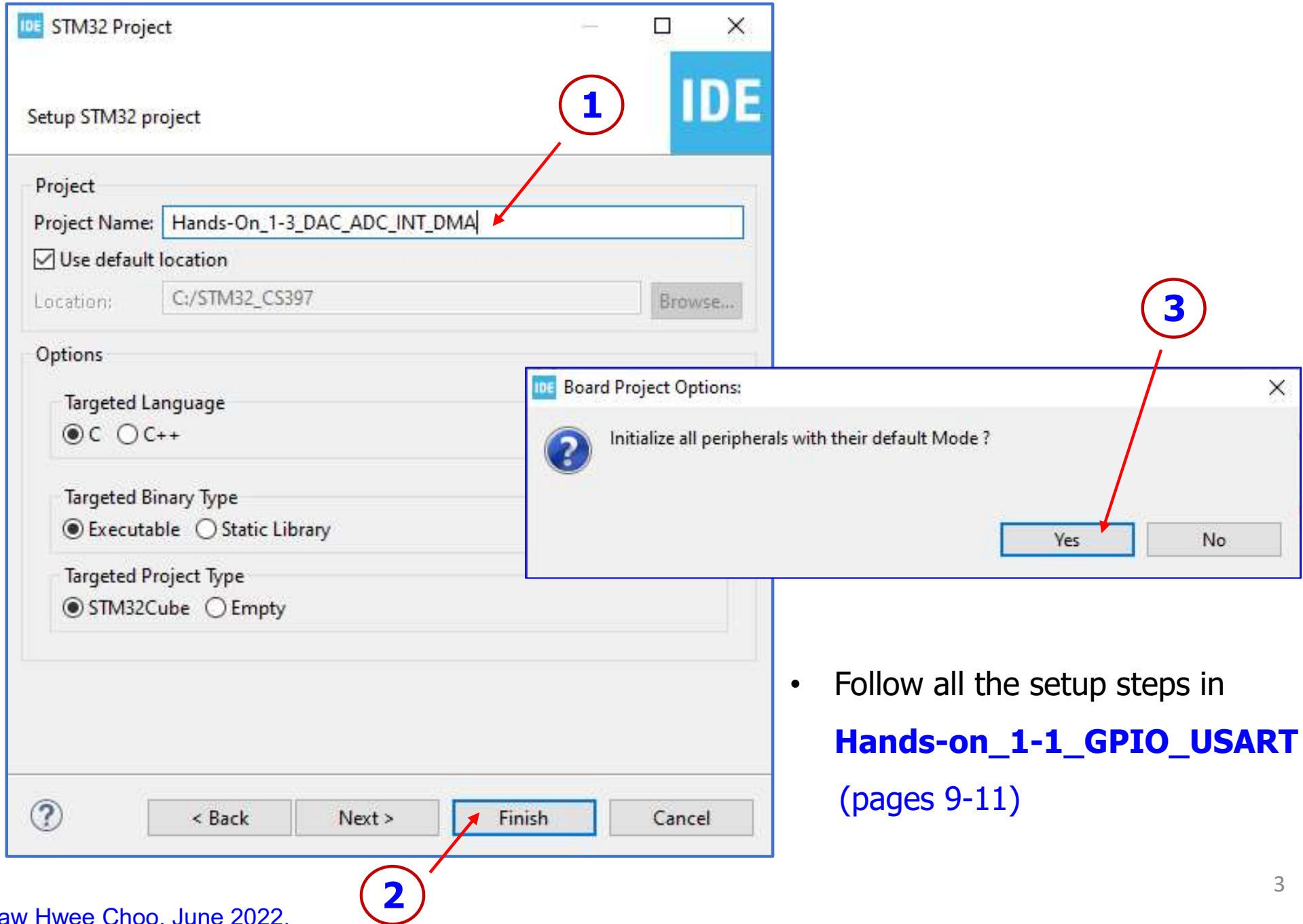
Objectives

The aims of this session are to

- implement a STM32 (STM32CubeIDE) project
- develop an application using STM32F767ZI microcontroller
- program the DAC and ADC with interrupt and DMA
- test programs using “TM Terminal” or “RealTerm”, a serial terminal (COM port) software
- build-up the development knowledge of embedded application
 - Run [STM32CubeIDE](#)
 - Select workspace: [C:\STM32_CS397](#)
 - File -> Close All Editors
 - Start a [New STM32 Project](#)
 - Select the [Nucleo-F767ZI Board](#)

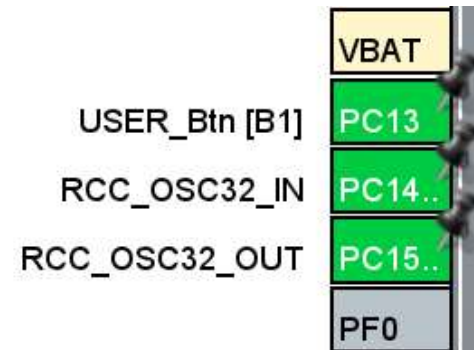
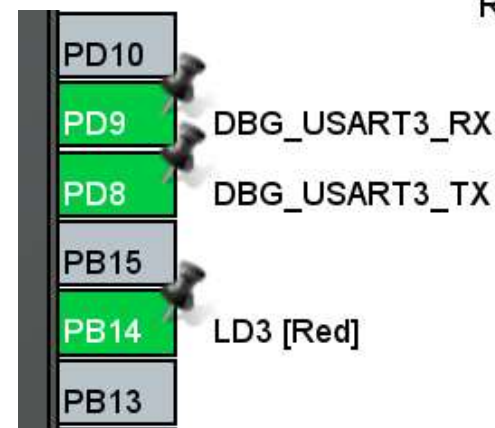
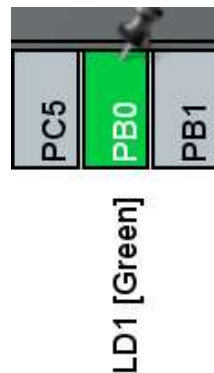
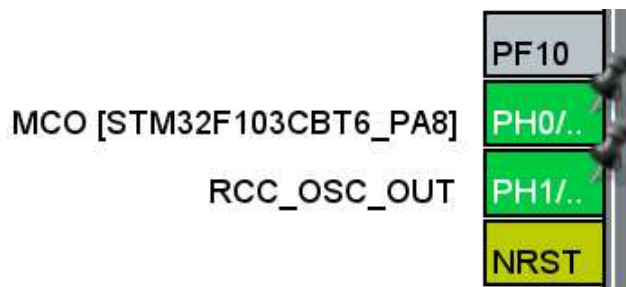
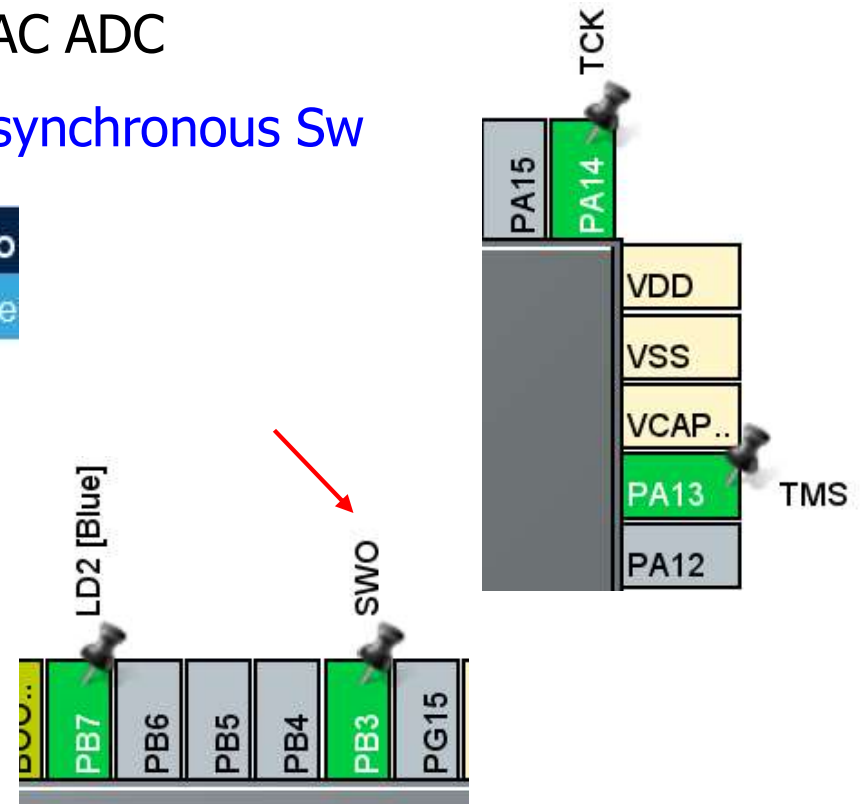
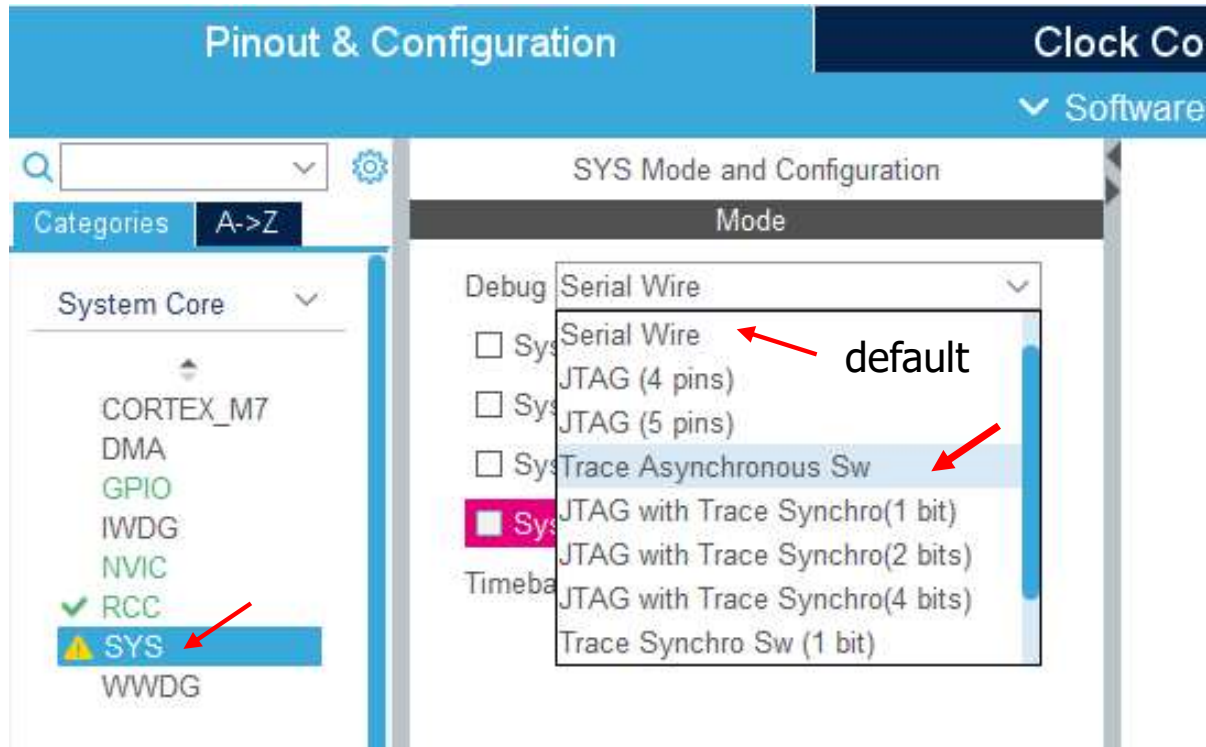
STM32CubeIDE – DAC ADC

Enter Project Name: **Hands-On_1-3_DAC_ADC_INT_DMA**



STM32CubeIDE – DAC ADC

Select: System Core -> SYS -> Debug: [Trace Asynchronous Sw](#)

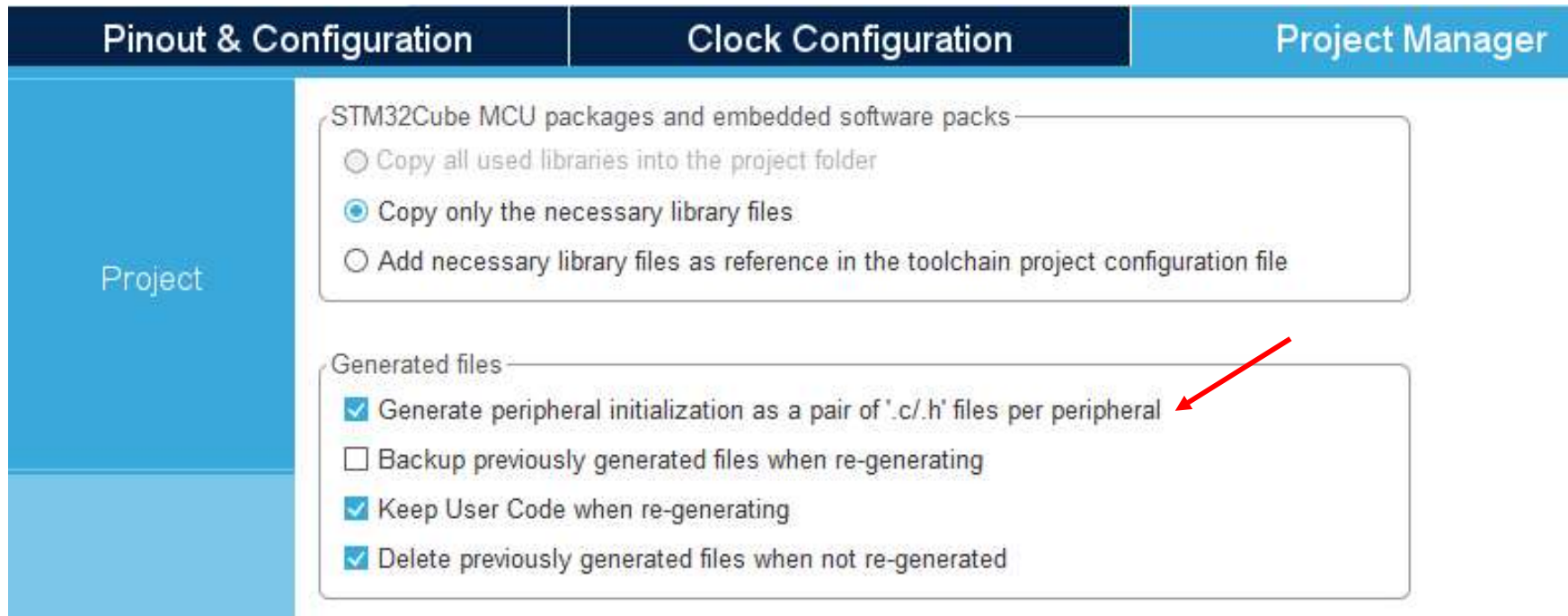


PD9: DBG_USART3_RX
PD8: DBG_USART3_TX

TCK (Test Clock)
TMS (Test Mode Select)
SWO (Single/Serial Wire Output)

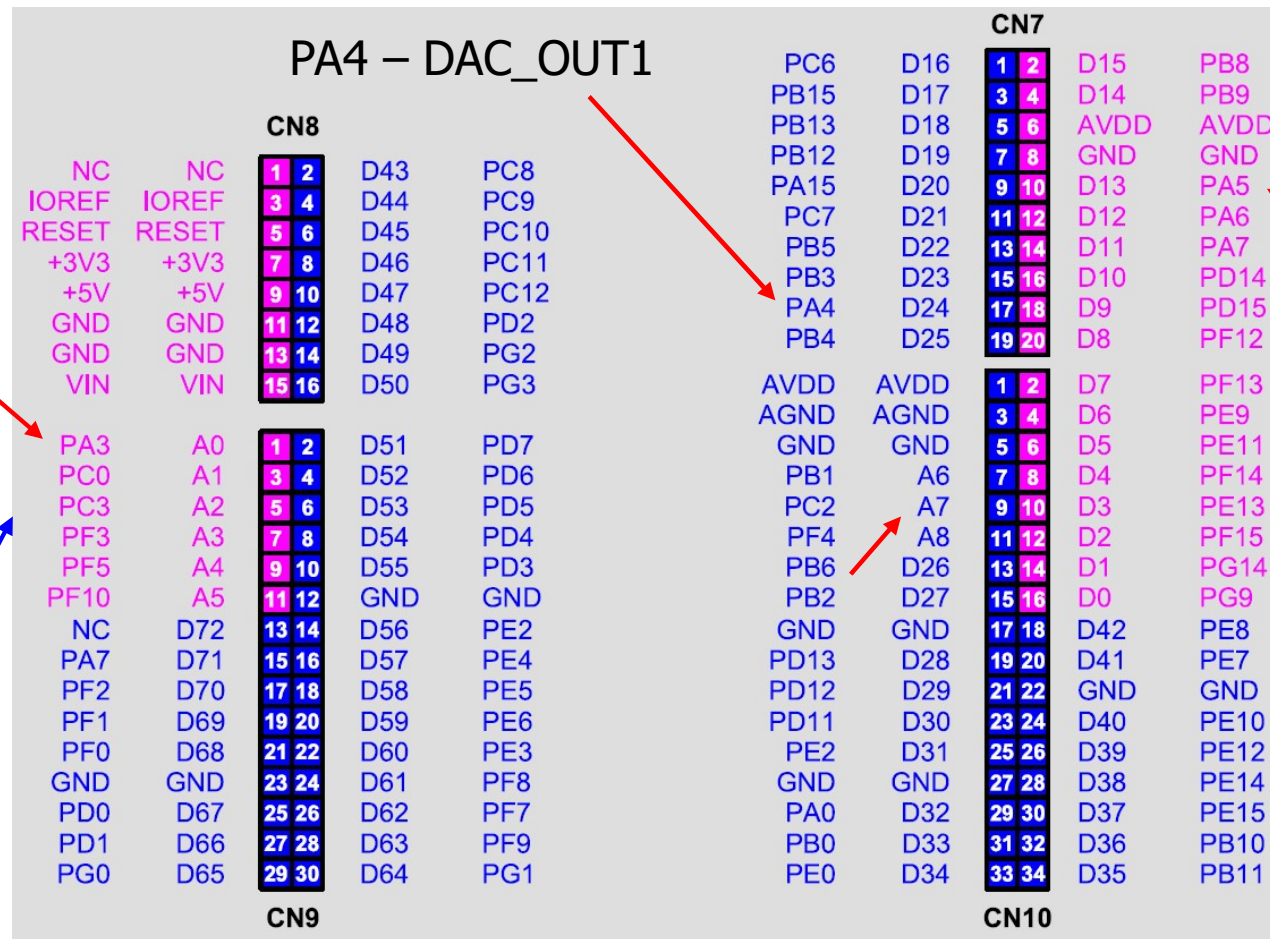
STM32CubeIDE – DAC ADC

Enable Interrupt for EXTI line[15:10] for USER_Btn [B1], and set Project Manager



STM32CubeIDE – DAC ADC

Nucleo-F767ZI Board Pinout – DAC and ADC Pins on [ST Zio](#)



PA3 (A0) – ADC1_IN3, ADC2_IN3, ADC3_IN3
 PC0 (A1) – ADC1_IN10, ADC2_IN10, ADC3_IN10
 PC3 (A2) – ADC1_IN13, ADC2_IN13, ADC3_IN13
 PF3 (A3) – ADC3_IN9
 PF5 (A4) – ADC3_IN15
 PF10 (A5) – ADC3_IN8

PB1 (A6) – ADC1_IN9, ADC2_IN9
 PC2 (A7) – ADC1_IN12, ADC2_IN12, ADC3_IN12
 PF4 (A8) – ADC3_IN14

STM32CubeIDE – DAC ADC

Set up one DAC channel (OUT1, pin PA4, default name: DAC_OUT1)

The screenshot shows the STM32CubeIDE interface with the 'DAC Mode and Configuration' window open. The 'Pinout & Configuration' tab is selected. The 'Software Packs' and 'Pinout' sections are visible. The 'DAC Mode and Configuration' window has a 'Mode' section with 'OUT1 Configuration' checked (annotated with a red circle 2). The 'Configuration' section has a 'Parameter Settings' tab selected (annotated with a red circle 4). The 'DAC Out1 Settings' section shows 'Output Buffer' set to 'Disable' (annotated with a red circle 3) and 'Trigger' set to 'None'. The 'GPIO Settings' tab is also visible (annotated with a red circle 4). The 'Pinout' section shows the pin configuration for PA4, which is labeled 'DAC_OUT1' (annotated with a red circle 4). The 'System Core' section on the left shows 'RCC' checked (annotated with a red circle 5). The 'Analog' section shows 'DAC' checked (annotated with a red circle 1).

Check 5

1

2

3

Check 4

DAC_OUT1

Pin Name	Signal on Pin	GPIO outp...	GPIO mode	GPIO Pull-up/Pull-down	Maxi...	Fast ...	User ...	Modif...
PA4	DAC_OUT1	n/a	Analog mode	No pull-up and no pull-down	n/a	n/a		<input type="checkbox"/>

STM32CubeIDE – DAC ADC

Set up one DAC channel – Check GPIO (pin PA4, default name: DAC_OUT1)

The screenshot displays the STM32CubeIDE configuration environment. On the left, the 'System Core' sidebar shows 'GPIO' selected under 'Cortex_M7'. The 'Analog' sidebar lists 'DAC' as a checked component. The main 'Configuration' window has a 'Group By Peripherals' dropdown and a row of peripheral checkboxes: GPIO, DAC, RCC, SYS, USART, and NVIC. The 'DAC' checkbox is highlighted with a red arrow. Below this is a 'Search Signals' field. A table lists pin configurations, with the row for 'PA4' and signal 'DAC_OUT1' highlighted. Red arrows point from the 'DAC_OUT1' signal name in the table to the 'PA4 Configuration' section below. In this section, the 'GPIO mode' is set to 'Analog mode', 'GPIO Pull-up/Pull-down' is set to 'No pull-up and no pull-down', and the 'User Label' field is empty. Red arrows also point to these three configuration fields.

System Core

- Cortex_M7
- DMA
- GPIO
- IWDG
- NVIC
- RCC
- SYS
- WWDG

Analog

- ADC1
- ADC2
- ADC3
- DAC

Timers

Connectivity

- CAN1
- CAN2
- CAN3

Configuration

Group By Peripherals

GPIO DAC RCC SYS USART NVIC

Search Signals

Search (Ctrl+F)

☐ Show only Modified Pins

Pin Name	Signal on Pin	GPIO output ...	GPIO mode	GPIO Pull-up...	Maximum ou...	Fast Mode	User Label	Modified
PA4	DAC_OUT1	n/a	Analog mode	No pull-up an...	n/a	n/a		<input type="checkbox"/>

PA4 Configuration :

GPIO mode: Analog mode

GPIO Pull-up/Pull-down: No pull-up and no pull-down

User Label:

Set up two ADC channels (IN3, pin PA3, name: ADC1_IN3, and Temperature Sensor)

Pinout & Configuration

Categories: A-Z

System Core

- CORTEX_M7
- DMA
- GPIO
- IWDG
- NVIC
- ✓ RCC
- ⚠ SYS
- WWDG

Analog

- ⚠ ADC1
- ⚠ ADC2
- ADC3
- ✓ DAC

Timers

Connectivity

- CAN1
- CAN2
- CAN3
- ⚠ ETH

ADC1 Mode and Configuration

Mode

- ✓ IN3
- IN4
- IN5
- IN6
- IN7
- IN8
- IN9
- IN10
- IN11
- IN12
- IN13
- IN14
- IN15
- ✓ Temperature Sensor Channel

Configuration

Reset Configuration

✓ NVIC Settings | ✓ DMA Settings | ✓ GPIO Settings

Parameter Settings | User Constants

Pin Na...	Signal on ...	GPIO out...	GPIO mode	GPIO Pull...
PA3	ADC1_IN3	n/a	Analog mo...	No pull-up ...

Pinout

PC3

VDD

VSSA

VREF+

VDDA

PA0/..

PA1

PA2

PA3

VSS

VDD

PA4

PA5

ADC1_IN3

DAC_OUT1

STM32CubeIDE – DAC ADC

ADC channel – GPIO Settings: pin PA3, name: ADC1_IN3

System Core

- CORTEX_M7
- DMA
- GPIO**
- IWDG
- NVIC
- ✓ RCC
- ▲ SYS
- WWDG

Analog

- ▲ ADC1
- ▲ ADC2
- ADC3
- ✓ DAC

Timers

Connectivity

- CAN1
- CAN2
- CAN3
- ▲ ETH

Configuration

Group By Peripherals

GPIO ADC DAC RCC SYS USART NVIC

Search Signals

Search (Ctrl+F)

☐ Show only Modified Pins

Pin Name	Signal on Pin	GPIO out...	GPIO mode	GPIO Pull...	Maximu...	Fast Mode	User La...	Modified
PA3	ADC1_IN3	n/a	Analog mode	No pull-up ...	n/a	n/a		<input type="checkbox"/>

PA3 Configuration

GPIO mode: Analog mode

GPIO Pull-up/Pull-down: No pull-up and no pull-down

User Label:

Pin Map

PC3 VDD VSSA VREF+ VDDA PA0/.. PA1 PA2 PA3 VSS VDD PA4 PA5

ADC1_IN3 DAC_OUT1

Clock Configuration: Use default clock settings



DMA Settings

STM32CubeIDE – DAC ADC

Pinout & Configuration | Clock Configuration | Project Manager

Software Packs | Pinout

ADC1 Mode and Configuration

Mode

- ☐ IN0
- ☐ IN1
- ☐ IN2
- ☒ IN3
- ☒ IN4
- ☐ IN5

Configuration

Reset Configuration

Parameter Settings | User Constants | NVIC Settings | **DMA Settings** | GPIO Settings

DMA Request	Stream	Direction	Priority
ADC1	DMA2 Stream 0	Peripheral To Memory	Low

Add | Delete

DMA Request Settings

Mode: **Circular** | Increment Address: ☐

Use Fifo: ☐ | Threshold:

Data Width: **Word** | Burst Size:

Peripheral: ☐ | Memory: ☒

PA3 | VSS | VDD | PA4

ADC1_IN3 | DAC_OUT1

12

ADC Parameter Settings STM32CubeIDE – DAC ADC

The screenshot displays the STM32CubeIDE interface for configuring the ADC1. The left sidebar shows the 'Analog' category with 'ADC1' selected. The main window shows the 'ADC1 Mode and Configuration' settings. The 'Mode' section has 'IN3' selected. The 'Configuration' section has 'Parameter Settings' selected. The 'ADCs_Common_Settings' section shows 'Mode' as 'Independent mode'. The 'ADC_Settings' section shows 'Clock Prescaler' as 'PCLK2 divided by 4', 'Resolution' as '12 bits (15 ADC Clock cycles)', 'Data Alignment' as 'Right alignment', 'Scan Conversion Mode' as 'Enabled', 'Continuous Conversion Mode' as 'Disabled', and 'Discontinuous Conversion Mode' as 'Disabled'. The 'DMA Continuous Requests' are set to 'Enabled'. The 'ADC_Regular_ConversionMode' section shows 'Number Of Conversion' as '2', 'External Trigger Conversion Source' as 'Regular Conversion launched by software', and 'External Trigger Conversion Edge' as 'None'. The 'Rank' section shows 'Rank 1' with 'Channel 3' and '480 Cycles', and 'Rank 2' with 'Channel Temperature Sensor' and '3 Cycles'. A red circle highlights the 'Regular Conversion' settings, and a blue arrow points to the '3 Cycles' value.

Section	Parameter	Value
Mode	Mode	IN3
Configuration	Parameter Settings	Selected
ADCs_Common_Settings	Mode	Independent mode
ADC_Settings	Clock Prescaler	PCLK2 divided by 4
ADC_Settings	Resolution	12 bits (15 ADC Clock cycles)
ADC_Settings	Data Alignment	Right alignment
ADC_Settings	Scan Conversion Mode	Enabled
ADC_Settings	Continuous Conversion Mode	Disabled
ADC_Settings	Discontinuous Conversion Mode	Disabled
ADC_Settings	DMA Continuous Requests	Enabled
ADC_Settings	End Of Conversion Selection	EOC flag at the end of single channel conversion
ADC_Regular_ConversionMode	Number Of Conversion	2
ADC_Regular_ConversionMode	External Trigger Conversion Source	Regular Conversion launched by software
ADC_Regular_ConversionMode	External Trigger Conversion Edge	None
ADC_Regular_ConversionMode	Rank 1 Channel	Channel 3
ADC_Regular_ConversionMode	Rank 1 Sampling Time	480 Cycles
ADC_Regular_ConversionMode	Rank 2 Channel	Channel Temperature Sensor
ADC_Regular_ConversionMode	Rank 2 Sampling Time	3 Cycles
ADC_Injected_ConversionMode	Number Of Conversions	0

Enable NVIC Interrupt for ADC

STM32CubeIDE – DAC ADC

Pinout & Configuration

Clock Configuration

Project Manager

Software Packs

Pinout

ADC1 Mode and Configuration

Mode

- ☒ IN3
- ☐ IN4
- ☐ IN5
- ☐ IN6
- ☐ IN7
- ☐ IN8
- ☐ IN9
- ☐ IN10
- ☐ IN11
- ☐ IN12
- ☐ IN13
- ☐ IN14
- ☐ IN15
- ☒ Temperature Sensor Channel

Configuration

Reset Configuration

- ☒ Parameter Settings
- ☒ User Constants
- ☒ NVIC Settings
- ☒ DMA Settings
- ☒ GPIO Settings

NVIC Interrupt Table	Enabled	Preemption Priority	Sub Priority
ADC1, ADC2 and ADC3 global interrupts	<input checked="" type="checkbox"/>	0	0
DMA2 stream0 global interrupt	<input checked="" type="checkbox"/>	0	0

Pinout

NRST

PC0

PC1

PC2

PC3

VDD

VSSA

VREF+

VDDA

PA0/...

PA1

PA2

PA3

VSS

ADC1_IN3

Set automatically by DMA settings

Need to set this value higher than 0

STM32CubeIDE – DAC ADC

NVIC Interrupt Table Settings

Pinout & Configuration | Clock Configuration | Project Manager

Software Packs | Pinout

NVIC Mode and Configuration

Configuration

Categories: A->Z

System Core

- CORTEX_M7
- DMA
- GPIO
- IWDG
- NVIC**
- RCC
- SYS
- WWDG

Analog

- ADC1
- ADC2
- ADC3
- DAC**

Timers >

Connectivity >

Multimedia >

Priority Group: 4 bits for pre-emption priority 0 bits for subpriority

Sort by Preemption Priority and Sub Priority ☐ Sort by interrupts names ☐

Search: Search (Ctrl+F)

Show: available interrupts ☒ Force DMA channels Interrupts

NVIC Interrupt Table:	Enabled	Preemption Priority	Sub Priority
Non maskable interrupt	<input checked="" type="checkbox"/>	0	0
Hard fault interrupt	<input checked="" type="checkbox"/>	0	0
Memory management fault	<input checked="" type="checkbox"/>	0	0
Pre-fetch fault, memory access fault	<input checked="" type="checkbox"/>	0	0
Undefined instruction or illegal state	<input checked="" type="checkbox"/>	0	0
System service call via SWI instruction	<input checked="" type="checkbox"/>	0	0
Debug monitor	<input checked="" type="checkbox"/>	0	0
Pendable request for system service	<input checked="" type="checkbox"/>	0	0
Time base: System tick timer	<input checked="" type="checkbox"/>	0	0
PVD interrupt through EXTI line 16	<input type="checkbox"/>	0	0
Flash global interrupt	<input type="checkbox"/>	0	0
RCC global interrupt	<input type="checkbox"/>	0	0
ADC1, ADC2 and ADC3 global interrupts	<input checked="" type="checkbox"/>	1	0
USART3 global interrupt	<input type="checkbox"/>	0	0
EXTI line[15:10] interrupts	<input checked="" type="checkbox"/>	0	0
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	<input type="checkbox"/>	0	0
DMA2 stream0 global interrupt	<input checked="" type="checkbox"/>	0	0
FPU global interrupt	<input type="checkbox"/>	0	0

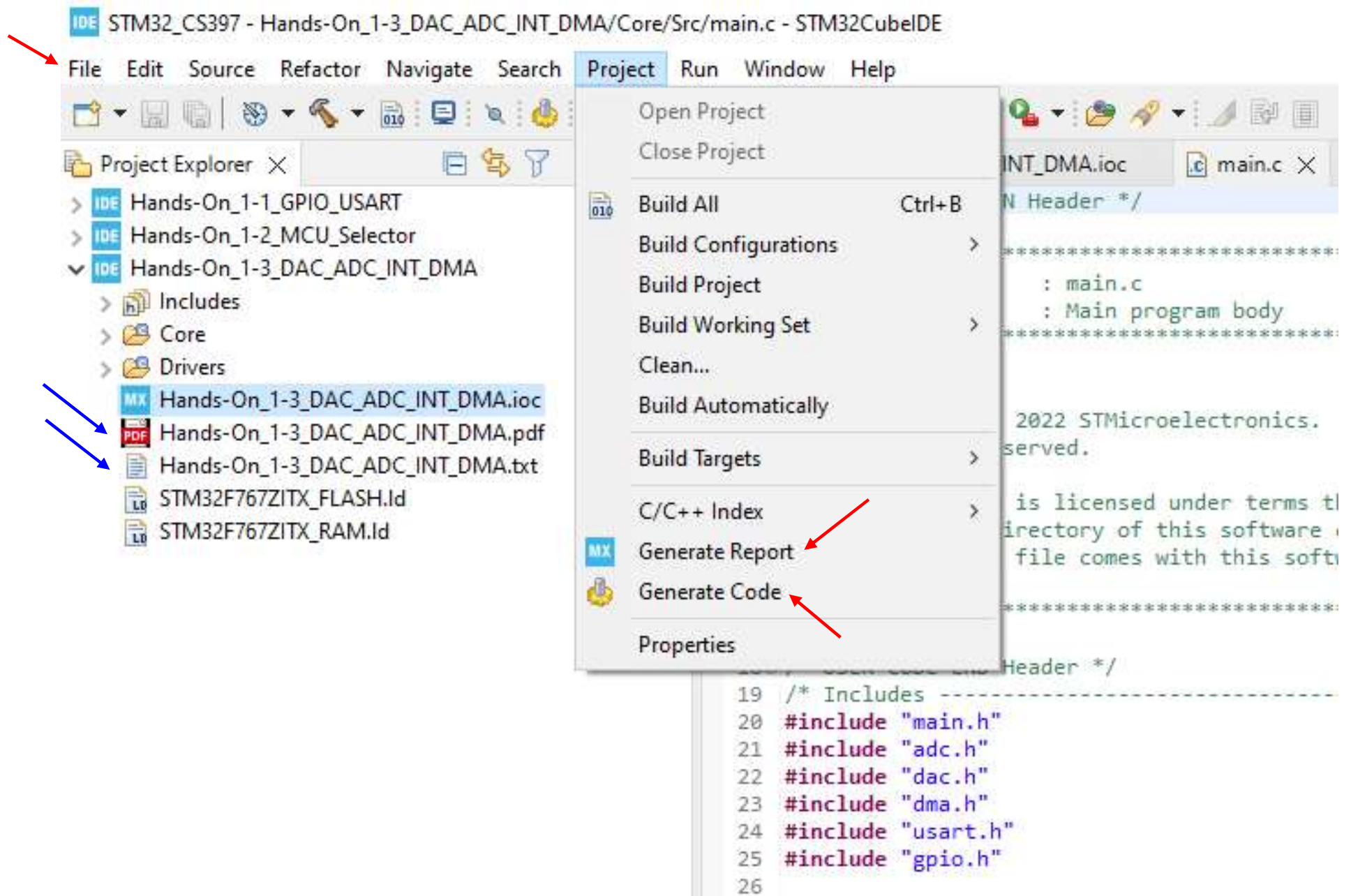
Set automatically by DMA settings

Set

Set ADC interrupt priority lower than the SysTick timer in case **HAL_Delay()** is needed in ADC interrupt routine.

STM32CubeIDE – DAC ADC

Save Project (File -> Save All), Generate Code, and Generate Report



STM32CubeIDE – DAC ADC

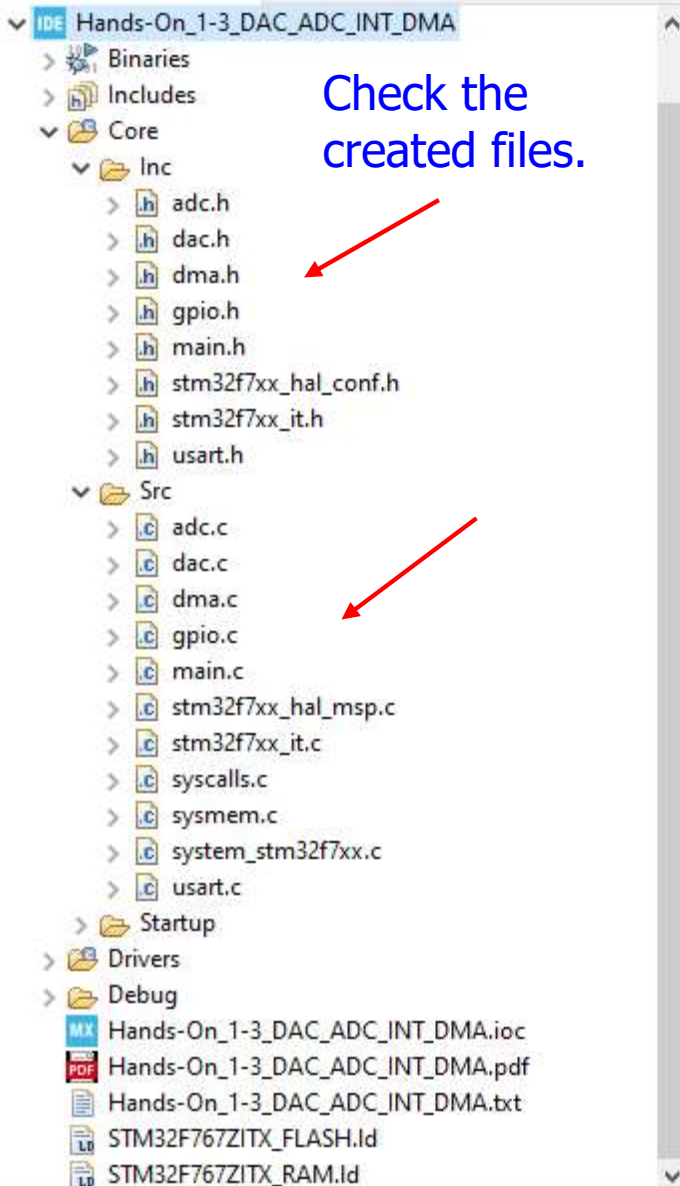
Build

STM32_CS397 - Hands-On_1-3_DAC_ADC_INT_DMA/Core/Src/main.c - STM32CubeIDE

File Edit Source Refactor Navigate Search Project Run Window Help



Project Explorer



Check the created files.

Hands-On_1-3_DAC_ADC_INT_DMA.ioc main.c

```
1 /* USER CODE BEGIN Header */
2 /**
3  *
4  * @file          : main.c
5  * @brief         : Main program body
6  *
7  * @attention
8  *
9  * Copyright (c) 2022 STMicroelectronics.
10 * All rights reserved.
11 *
12 * This software is licensed under terms that can be found in the LICENSE file
13 * in the root directory of this software component.
14 * If no LICENSE file comes with this software, it is provided AS-IS.
15 *
16 */
17 /*
18 /* USER CODE END Header */
19 /* Includes -----*/
20 #include "main.h"
21 #include "adc.h"
22 #include "dac.h"
23 #include "dma.h"
24 #include "usart.h"
25 #include "gpio.h"
```

Problems Tasks Console Properties Terminal

CDT Build Console [Hands-On_1-3_DAC_ADC_INT_DMA]

```
arm-none-eabi-objdump -h -S Hands-On_1-3_DAC_ADC_INT_DMA.elf > "Hands-On_1-3_DAC_ADC_INT_DMA.list"
text    data    bss    dec    hex filename
15760    20      1892   17672   4508 Hands-On_1-3_DAC_ADC_INT_DMA.elf
Finished building: default.size.stdout
```

Finished building: Hands-On_1-3_DAC_ADC_INT_DMA.list

21:12:39 Build Finished. 0 errors, 0 warnings. (took 5s.424ms)

Hands-On_1-3_DAC_ADC_INT_DMA

STM32CubeIDE – DAC ADC

Add code to **main.c**,

```
/* main.c */
/* Includes */
#include "main.h"
#include "adc.h"
#include "dac.h"
#include "dma.h"
#include "usart.h"
#include "gpio.h"
/* Private includes */
/* USER CODE BEGIN Includes */
#include <stdio.h>
/* USER CODE END Includes */

/* Private variables */
/* USER CODE BEGIN PV */
uint32_t adc[2], buffer[2];
uint32_t dac = 0;

float vsense = 3.3 / 4096.0;
float temperature = 0.0;
/* USER CODE END PV */

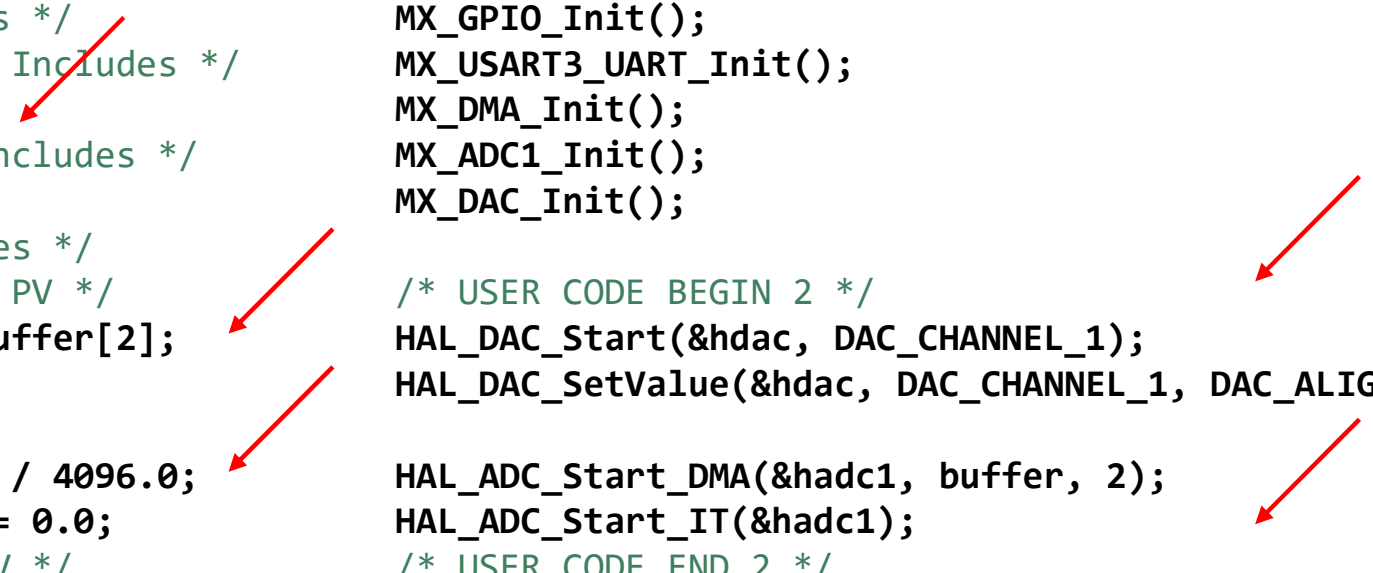
/* Private function prototypes */
void SystemClock_Config(void);

int main(void)
{
    /* MCU Configuration */
    /* Reset of all peripherals, Initializes ... */
    HAL_Init();
    /* Configure the system clock */
    SystemClock_Config();
    /* Initialize all configured peripherals */
    MX_GPIO_Init();
    MX_USART3_UART_Init();
    MX_DMA_Init();
    MX_ADC1_Init();
    MX_DAC_Init();

    /* USER CODE BEGIN 2 */
    HAL_DAC_Start(&hdac, DAC_CHANNEL_1);
    HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);

    HAL_ADC_Start_DMA(&hadc1, buffer, 2);
    HAL_ADC_Start_IT(&hadc1);
    /* USER CODE END 2 */

    /* Infinite loop */
    /* USER CODE BEGIN WHILE */
    while (1)
    {
```



STM32CubeIDE – DAC ADC

Add code to **main.c**, USER CODE WHILE

```
/* Infinite loop */
/* USER CODE BEGIN WHILE */
while (1)
{
    HAL_GPIO_TogglePin(GPIOB, LD3_Pin);

    // project -> properties -> C/C++ Build - Settings -> Tool Settings -> MCU GCC Linker -
    // - Miscellaneous -> Other Flags: -u _printf_float


    printf("DAC ADC vales = %ld %ld %ld %4.2f deg.C \r\n", dac, adc[0], adc[1], temperature);

    ++dac;
    if( dac > 4095 ) dac = 0;
    HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);
    HAL_Delay(500);

    HAL_ADC_Start_IT(&hadc1);
    HAL_Delay(500);

    /* USER CODE END WHILE */

    /* USER CODE BEGIN 3 */
}
/* USER CODE END 3 */
```



STM32CubeIDE – DAC ADC


Add code to **main.c**, USER CODE 4

```
/* USER CODE BEGIN 4 */
void HAL_ADC_ConvCpltCallback(ADC_HandleTypeDef* hadc)
{
    if( hadc->Instance == ADC1 )
    {
        for (int i = 0; i < 2; i++)
        {
            adc[i] = buffer[i];
        }
        temperature = (((adc[1] * vsense ) - 0.76 ) / 0.0025) + 25.0;
    }
}

void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
{
    if(GPIO_Pin == GPIO_PIN_13)
    {
        HAL_GPIO_TogglePin(GPIOB, LD2_Pin);
    }
}

int __io_putchar(int ch)
{
    uint8_t c[1];
    c[0] = ch & 0x00FF;
    HAL_UART_Transmit(&huart3, &c, 1, 10);
    return ch;
}

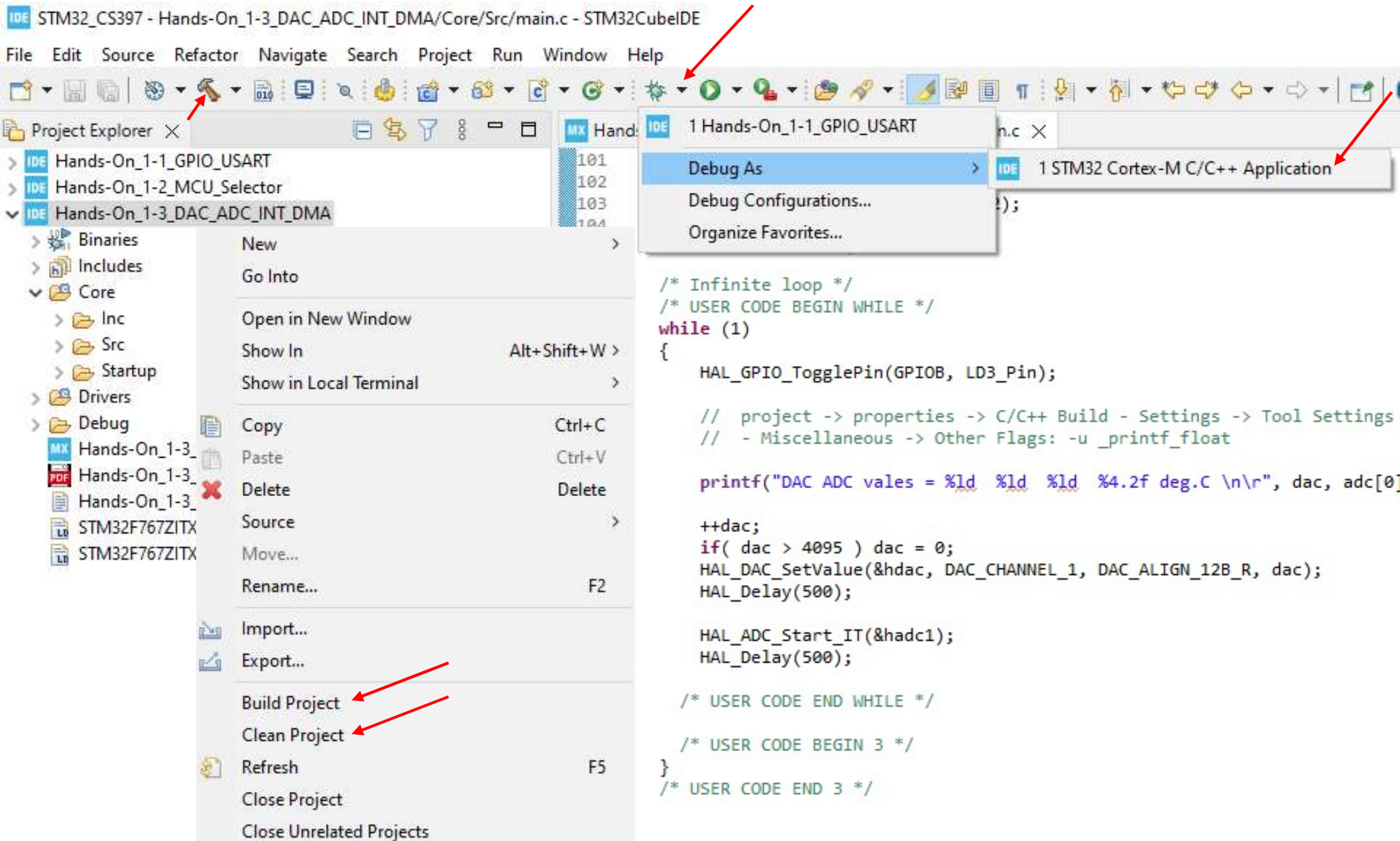
/* USER CODE END 4 */
```



```
/*
int _write(int file, char *ptr, int len)
{
    int DataIdx;
    for(DataIdx= 0; DataIdx < len; DataIdx++)
    {
        __io_putchar(*ptr++);
    }
    return len;
}
*/
```

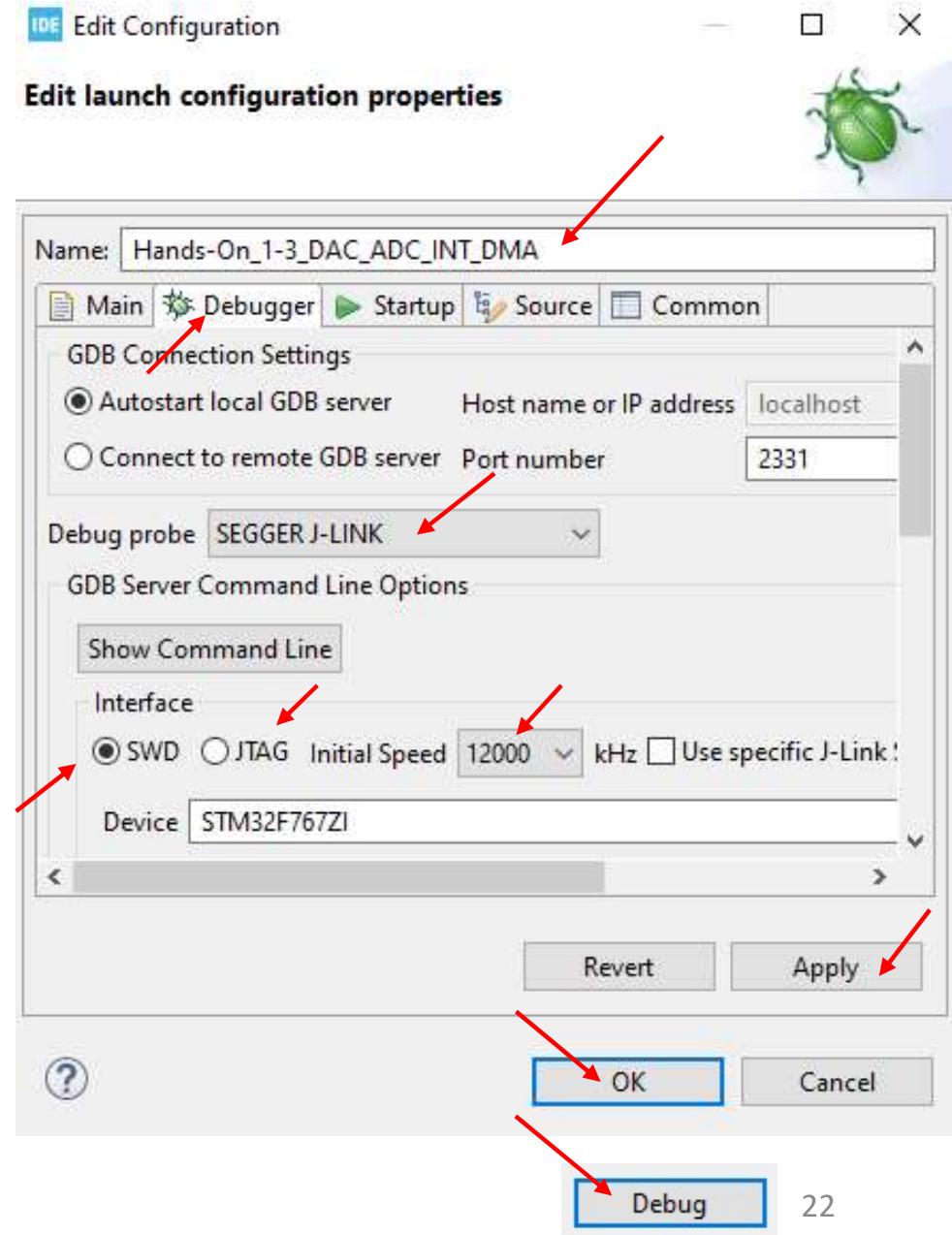
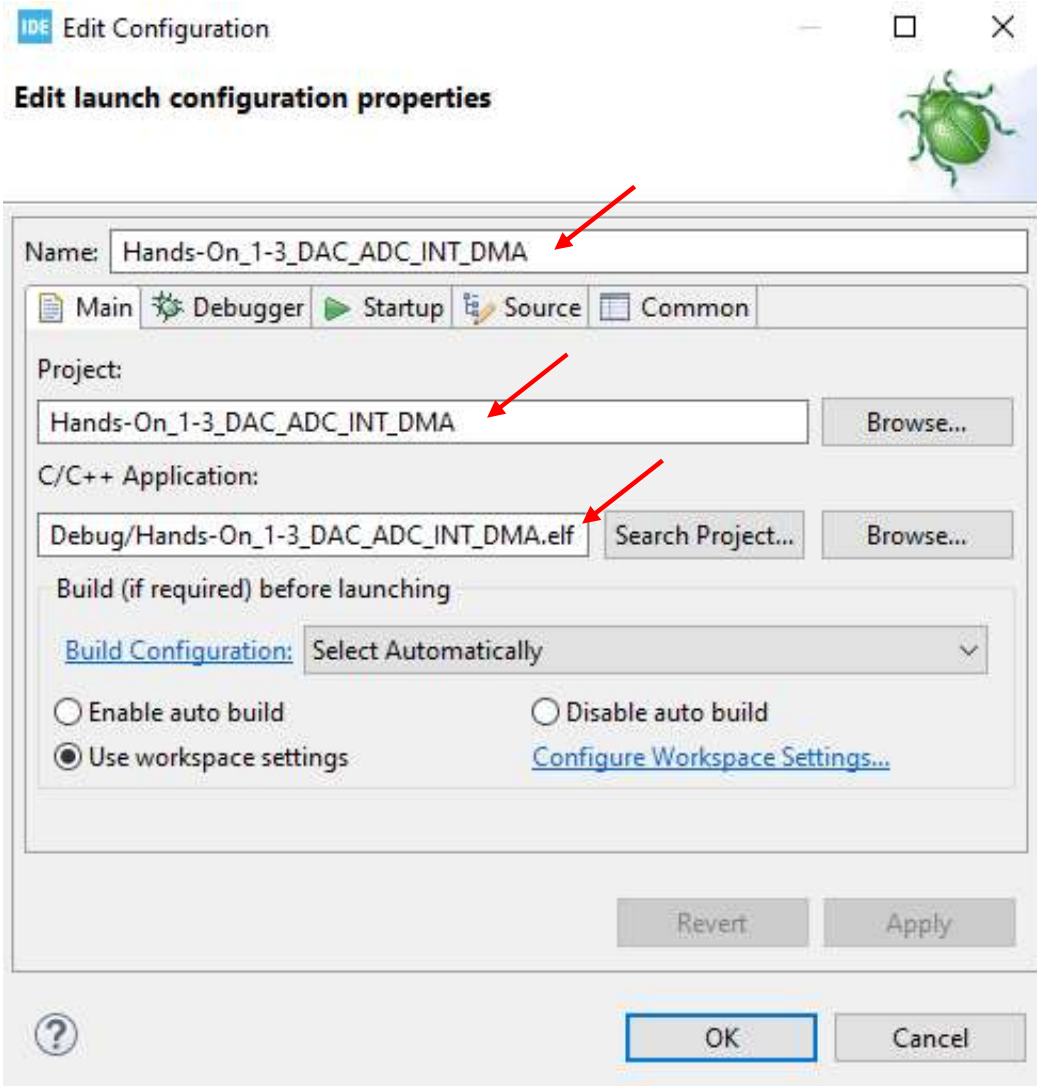
STM32CubeIDE – DAC ADC

Build Project and Select "Debug As" -> "1 STM32 Cortex-M C/C++ Application"



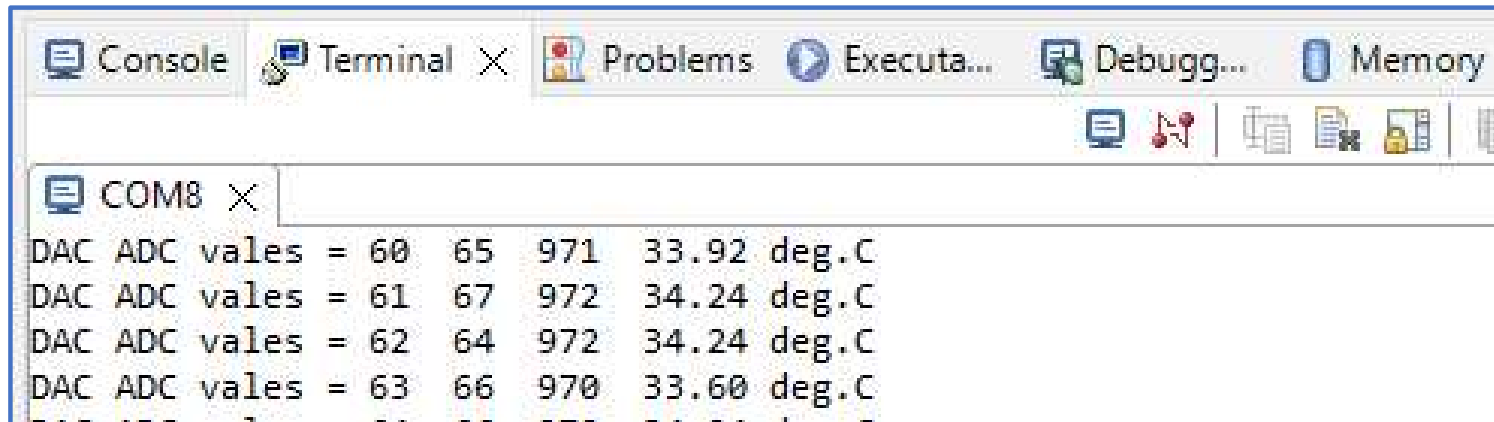
STM32CubeIDE – DAC ADC

Edit/Debug Configuration, Select “Apply” then “OK” or “Debug” to download program



STM32CubeIDE – DAC ADC

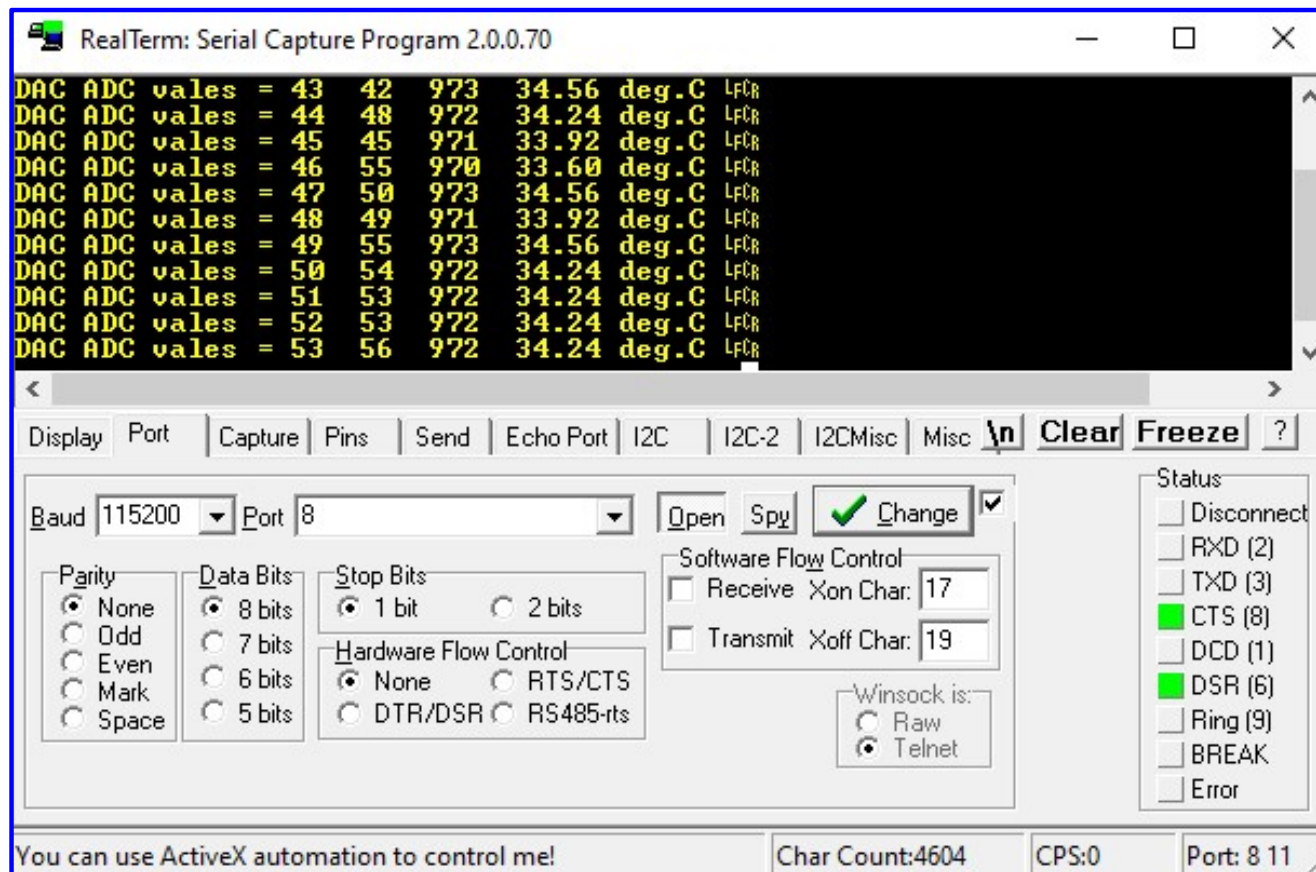
Test the developed program with TM Terminal or RealTerm



The screenshot shows the STM32CubeIDE interface with the Terminal window active. The terminal displays the following output:

```
COM8 X
DAC ADC vales = 60 65 971 33.92 deg.C
DAC ADC vales = 61 67 972 34.24 deg.C
DAC ADC vales = 62 64 972 34.24 deg.C
DAC ADC vales = 63 66 970 33.60 deg.C
```

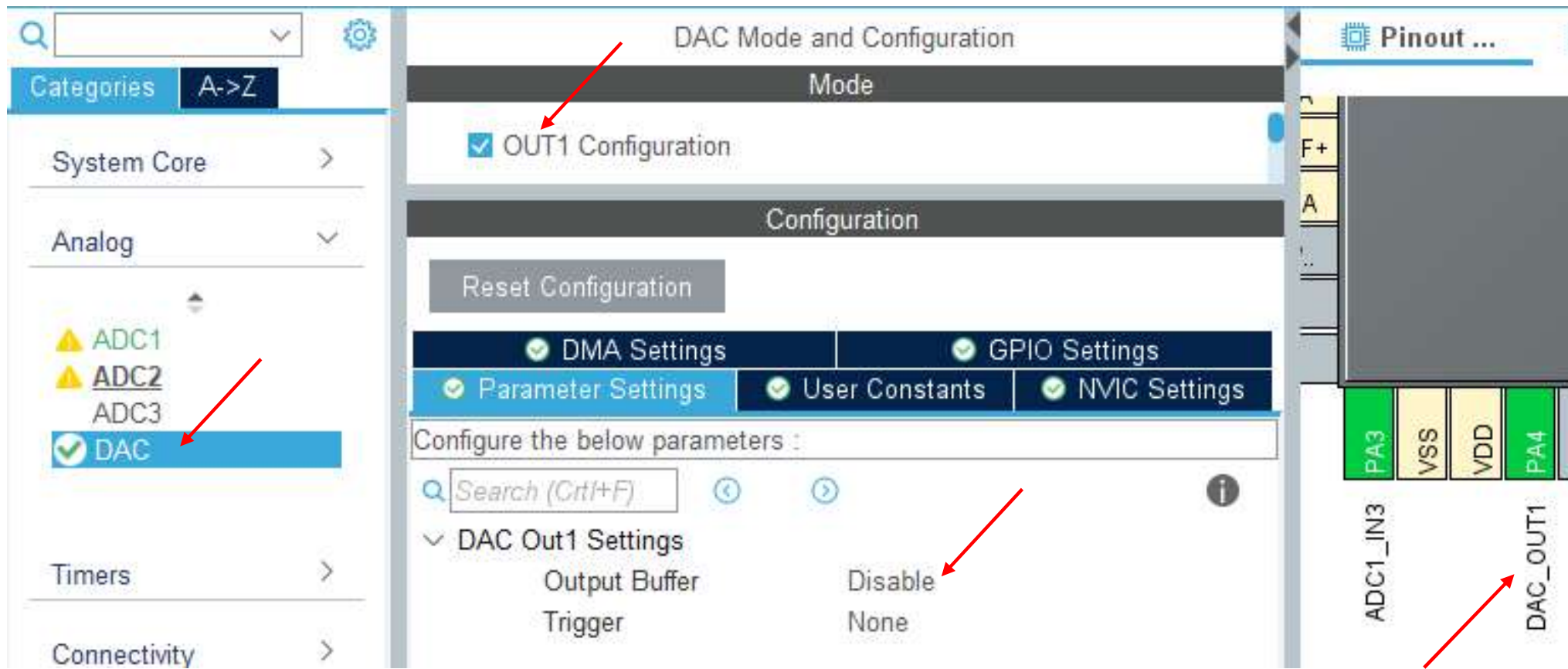
Study the results and understand the program.



STM32CubeIDE – DAC ADC

DAC Output Buffer

- The DAC has an output buffer that can be either enabled or disabled.
- With a disabled buffer, it has about 1.5 M Ω output impedance and very little offset.
- With an enabled buffer, it has 15 k Ω output impedance and may have up to 200 mV offset.



DAC Output Buffer

```
/* Code generated automatically by STM32CubeMX */


/* dac.c */

/* Includes */
#include "dac.h"

DAC_HandleTypeDef hdac;

/* DAC init function */
void MX_DAC_Init(void)
{
    DAC_ChannelConfTypeDef sConfig = {0};

    /* DAC Initialization */
    hdac.Instance = DAC;
    if (HAL_DAC_Init(&hdac) != HAL_OK)
    {
        Error_Handler();
    }
    /* DAC channel OUT1 config */
    sConfig.DAC_Trigger = DAC_TRIGGER_NONE;
    sConfig.DAC_OutputBuffer = DAC_OUTPUTBUFFER_DISABLE;
    if (HAL_DAC_ConfigChannel(&hdac, &sConfig, DAC_CHANNEL_1) != HAL_OK)
    {
        Error_Handler();
    }
}
```



HAL_DAC_SetValue()

STM32CubeIDE – DAC ADC

```
MX Hands-On_1-3_DAC_AD... | main.c | stm32f7xx_it.c | stm32f7xx_hal.c | stm32f7xx_hal_adc.c
91  /* USER CODE END SysInit */
92
93  /* Initialize all configured peripherals */
94  MX_GPIO_Init();
95  MX_DMA_Init();
96  MX_USART3_UART_Init();
97  MX_ADC1_Init();
98  MX_DAC_Init();
99  /* USER CODE BEGIN 2 */
100 HAL_DAC_Start(&hdac, DAC_CHANNEL_1);
101 HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);
```

Hover mouse pointer over the function to understand it.

```
/**
 * @brief Set the specified data holding register value for DAC channel.
 * @param hdac pointer to a DAC_HandleTypeDef structure that contains
 *         the configuration information for the specified DAC.
 * @param Channel The selected DAC channel.
 *         This parameter can be one of the following values:
 *         @arg DAC_CHANNEL_1: DAC Channel1 selected
 *         @arg DAC_CHANNEL_2: DAC Channel2 selected
 * @param Alignment Specifies the data alignment.
 *         This parameter can be one of the following values:
 *         @arg DAC_ALIGN_8B_R: 8bit right data alignment selected
 *         @arg DAC_ALIGN_12B_L: 12bit left data alignment selected
 *         @arg DAC_ALIGN_12B_R: 12bit right data alignment selected
 * @param Data Data to be loaded in the selected data holding register.
 * @retval HAL status
 */
HAL_StatusTypeDef HAL_DAC_SetValue(DAC_HandleTypeDef *hdac, uint32_t Channel, uint32_t Alignment, uint32_t Data)
{
    __IO uint32_t tmp = 0UL;

    /* Check the parameters */
    assert_param(IS_DAC_CHANNEL(Channel));
    assert_param(IS_DAC_ALIGN(Alignment));
    assert_param(IS_DAC_DATA(Data));
```

STM32CubeIDE – DAC ADC

```
/* stm32f7xx_hal_adc.c */
```

```
*** Execution of ADC conversions ***
```

```
=====
```

```
[..]
```

```
(#) ADC driver can be used among three modes: polling, interruption, transfer by DMA.
```

```
*** Polling mode IO operation ***
```

```
=====
```

```
[..]
```

- (+) Start the ADC peripheral using `HAL_ADC_Start()`
- (+) Wait for end of conversion using `HAL_ADC_PollForConversion()`, at this stage user can specify the value of timeout according to his end application
- (+) To read the ADC converted values, use the `HAL_ADC_GetValue()` function.
- (+) Stop the ADC peripheral using `HAL_ADC_Stop()`

```
*** Interrupt mode IO operation ***
```

```
=====
```

```
[..]
```

- (+) Start the ADC peripheral using `HAL_ADC_Start_IT()`
- (+) Use `HAL_ADC_IRQHandler()` called under `ADC_IRQHandler()` Interrupt subroutine
- (+) At ADC end of conversion `HAL_ADC_ConvCpltCallback()` function is executed, and user can add his own code by customization of function pointer
`HAL_ADC_ConvCpltCallback`
- (+) In case of ADC Error, `HAL_ADC_ErrorCallback()` function is executed, and user can add his own code by customization of function pointer
`HAL_ADC_ErrorCallback`
- (+) Stop the ADC peripheral using `HAL_ADC_Stop_IT()`

STM32CubeIDE – DAC ADC

```
/* stm32f7xx_hal_adc.c*/
```

```
*** Execution of ADC conversions ***
```

```
=====
```

```
[..]
```

```
(#) ADC driver can be used among three modes: polling, interruption, transfer by DMA.
```

```
*** DMA mode IO operation ***
```

```
=====
```

```
[..]
```

- (+) Start the ADC peripheral using `HAL_ADC_Start_DMA()`, at this stage the user specify the length of data to be transferred at each end of conversion
- (+) At The end of data transfer by `HAL_ADC_ConvCpltCallback()` function is executed, and user can add his own code by customization of function pointer `HAL_ADC_ConvCpltCallback`
- (+) In case of transfer Error, `HAL_ADC_ErrorCallback()` function is executed, and user can add his own code by customization of function pointer `HAL_ADC_ErrorCallback`
- (+) Stop the ADC peripheral using `HAL_ADC_Stop_DMA()`

Polling mode

STM32CubeIDE – DAC ADC

Two ADC channel Settings in Scan and Continuous Conversion Modes

ADC1 Mode and Configuration

Mode

☒ IN3

Configuration

Reset Configuration

Parameter Settings User Constants NVIC Settings DMA Settings GPIO Settings

Search (Ctrl+F)

ADCs_Common_Settings

Mode Independent mode

ADC_Settings

Clock Prescaler PCLK2 divided by 4

Resolution 12 bits (15 ADC Clock cycles)

Data Alignment Right alignment

Scan Conversion Mode Enabled

Continuous Conversion Mode Enabled

Discontinuous Conversion Mode Disabled

DMA Continuous Requests Disabled

End Of Conversion Selection EOC flag at the end of single channel conversion

ADC_Regular_ConversionMode

Number Of Conversion 2

External Trigger Conversion Source Regular Conversion launched by software

External Trigger Conversion Edge None

Rank 1

Channel Channel 3

Sampling Time 480 Cycles

Rank 2

Channel Channel Temperature Sensor

Sampling Time 480 Cycles

Pinout view

PC1 PC2 PC3 VDD VSSA VREF+ VDDA PA0/... PA1 PA2 PA3 VSS VDD PA4

ADC1_IN3 DAC_OUT1

Polling mode

STM32CubeIDE – DAC ADC

Add code to **main.c**, USER CODE Includes, USER CODE PV, USER CODE 2

```
/* main.c */
/* Includes */
#include "main.h"
#include "adc.h"
#include "dac.h"
#include "usart.h"
#include "gpio.h"

/* Private includes */
/* USER CODE BEGIN Includes */
#include <stdio.h>
/* USER CODE END Includes */

/* Private variables */
/* USER CODE BEGIN PV */
uint32_t adc[2];
uint32_t dac = 0;
float vsense = 3.3 / 4096.0;
float temperature = 0.0;
/* USER CODE END PV */

/* Private function prototypes */
void SystemClock_Config(void);
```

```
int main(void)
{
    /* MCU Configuration */
    /* Reset of all peripherals, Initializes ... */
    HAL_Init();

    /* Configure the system clock */
    SystemClock_Config();

    /* Initialize all configured peripherals */
    MX_GPIO_Init();
    MX_USART3_UART_Init();
    MX_ADC1_Init();
    MX_DAC_Init();

    /* USER CODE BEGIN 2 */
    HAL_DAC_Start(&hdac, DAC_CHANNEL_1);
    HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);
    /* USER CODE END 2 */

    /* Infinite loop */
    /* USER CODE BEGIN WHILE */
    while (1)
    {
```

Polling mode

STM32CubeIDE – DAC ADC

Add code to **main.c**, USER CODE WHILE

```
/* USER CODE BEGIN WHILE */
while (1)
{
    HAL_GPIO_TogglePin(GPIOB, LD3_Pin);
    HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);

    ++dac;
    if(dac > 4095) dac = 0;

    HAL_ADC_Start(&hadc1);

    HAL_ADC_PollForConversion(&hadc1,100);
    adc[0] = HAL_ADC_GetValue(&hadc1);


    HAL_ADC_PollForConversion(&hadc1,100);
    adc[1] = HAL_ADC_GetValue(&hadc1);

    HAL_ADC_Stop(&hadc1);

    temperature = (( adc[1] * vsense - 0.76 ) / 0.0025) + 25.0;

    // project -> properties -> C/C++ Build - Settings -> Tool Settings -> MCU GCC Linker -
    // - Miscellaneous -> Other Flags: -u _printf_float
    printf("DAC ADC vales = %ld %ld %ld %4.2f degC \n\r", dac, adc[0], adc[1], temperature);

    HAL_Delay(1000);
}
/* USER CODE END WHILE */
```



Interrupt mode

Enable NVIC Interrupt for ADC

STM32CubeIDE – DAC ADC

MX *Hands-On_03_DAC_ADC_INT.ioc

Pinout & Configuration | Clock Configuration | Project Manager

Software Packs | Pinout

Categories: A->Z

- CORTEX_M7
- DMA
- GPIO
- IWDG
- NVIC
- ✓ RCC
- ⚠ SYS
- WWDG

Analog

- ⚠ ADC1
- ⚠ ADC2
- ADC3
- ✓ DAC

Timers

Connectivity

- CAN1
- CAN2
- CAN3
- ⚠ ETH
- FMC
- I2C1
- I2C2

ADC1 Mode and Configuration

Mode

- ☒ IN3
- ☐ IN4
- ☐ IN5
- ☐ IN6
- ☐ IN7
- ☐ IN8
- ☐ IN9
- ☐ IN10
- ☐ IN11
- ☐ IN12
- ☐ IN13
- ☐ IN14
- ☐ IN15
- ☐ Temperature Sensor Channel

(one channel only)

Configuration

Reset Configuration

✓ NVIC Settings | ✓ DMA Settings | ✓ GPIO Settings

✓ Parameter Settings | ✓ User Constants

NVIC Interrupt Table	Enabled	Preemption Priority	Sub ...
ADC1, ADC2 and ADC3 global interrupts	<input checked="" type="checkbox"/>	0	0

Pinout view

PC2, PC3, VDD, VSSA, VREF+, VDDA, PA0/..., PA1, PA2, PA3, VSS, VDD, PA4, PA5

ADC1_IN3, DAC_OUT1

1

2

Need to set this value higher than 0

Interrupt mode

STM32CubeIDE – DAC ADC

Set Pre-emption Priority for ADC Interrupt

MX *Hands-On_03_DAC_ADC_INT.ioc

Pinout & Configuration | Clock Configuration | Project Manager | Tools

Software Packs | Pinout

NVIC Mode and Configuration

Configuration

System Core

- CORTEX_M7
- DMA
- GPIO
- IWDG
- NVIC
- RCC
- SYS
- WWDG

Analog

- ADC1
- ADC2
- ADC3
- DAC

Timers

Connectivity

NVIC

Code generation

Priority Group: 4 bits for pre-emption priority 0 bits for subpriority

Sort by Preemption Priority and Sub Priority

Sort by interrupts names

Search: Search (Ctrl+F)

Show: available interrupts

Force DMA channels Interrupts

NVIC Interrupt Table	Enabled	Preemption Priority	Sub Priority
Non maskable interrupt	<input checked="" type="checkbox"/>	0	0
Hard fault interrupt	<input checked="" type="checkbox"/>	0	0
Memory management fault	<input checked="" type="checkbox"/>	0	0
Pre-fetch fault, memory access fault	<input checked="" type="checkbox"/>	0	0
Undefined instruction or illegal state	<input checked="" type="checkbox"/>	0	0
System service call via SWI instruction	<input checked="" type="checkbox"/>	0	0
Debug monitor	<input checked="" type="checkbox"/>	0	0
Pendable request for system service	<input checked="" type="checkbox"/>	0	0
Time base: System tick timer	<input checked="" type="checkbox"/>	0	0
PVD interrupt through EXTI line 16	<input type="checkbox"/>	0	0
Flash global interrupt	<input type="checkbox"/>	0	0
RCC global interrupt	<input type="checkbox"/>	0	0
ADC1, ADC2 and ADC3 global interrupts	<input checked="" type="checkbox"/>	1	0
USART3 global interrupt	<input type="checkbox"/>	0	0
EXTI line[15:10] interrupts	<input checked="" type="checkbox"/>	0	0
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	<input type="checkbox"/>	0	0
FPU global interrupt	<input type="checkbox"/>	0	0

Set ADC interrupt priority lower than the System tick timer due to **HAL_Delay()** in ADC interrupt routine.

Interrupt mode

STM32CubeIDE – DAC ADC

ADC Settings: Enable Scan Conversion Mode, and take note of other settings

The screenshot displays the STM32CubeIDE interface for configuring the ADC1. The 'Pinout & Configuration' tab is active, showing the 'ADC1 Mode and Configuration' settings. The left sidebar shows the 'System Core' tree with 'ADC1' selected under 'Analog'. The main panel shows the 'ADC1 Mode and Configuration' settings, including 'Mode' (IN3), 'Configuration' (Reset Configuration), and 'Parameter Settings' (Parameter Settings, User Constants, NVIC Settings, DMA Settings, GPIO Settings). The 'ADCs_Common_Settings' section shows 'Mode' (Independent mode). The 'ADC_Settings' section shows 'Clock Prescaler' (PCLK2 divided by 4), 'Resolution' (12 bits (15 ADC Clock cycles)), 'Data Alignment' (Right alignment), 'Scan Conversion Mode' (Enabled), 'Continuous Conversion Mode' (Disabled), 'Discontinuous Conversion Mode' (Disabled), 'DMA Continuous Requests' (Disabled), and 'End Of Conversion Selection' (EOC flag at the end of single channel conversion). The 'ADC_Regular_ConversionMode' section shows 'Number Of Conversion' (1), 'External Trigger Conversion Source' (Regular Conversion launched by software), 'External Trigger Conversion Edge' (None), 'Rank' (1), 'Channel' (Channel 3), and 'Sampling Time' (480 Cycles). The 'ADC_Injected_ConversionMode' section shows 'Number Of Conversions' (0). The 'WatchDog' section shows 'Enable Analog WatchDog Mode' (unchecked).

Section	Parameter	Value
ADCs_Common_Settings	Mode	Independent mode
	Scan Conversion Mode	Enabled
ADC_Settings	Clock Prescaler	PCLK2 divided by 4
	Resolution	12 bits (15 ADC Clock cycles)
	Data Alignment	Right alignment
	Continuous Conversion Mode	Disabled
	Discontinuous Conversion Mode	Disabled
	DMA Continuous Requests	Disabled
	End Of Conversion Selection	EOC flag at the end of single channel conversion
ADC_Regular_ConversionMode	Number Of Conversion	1
	External Trigger Conversion Source	Regular Conversion launched by software
	External Trigger Conversion Edge	None
	Rank	1
	Channel	Channel 3
	Sampling Time	480 Cycles
ADC_Injected_ConversionMode	Number Of Conversions	0
WatchDog	Enable Analog WatchDog Mode	<input type="checkbox"/>

Interrupt mode

STM32CubeIDE – DAC ADC

Add code to **main.c**,

```
/* main.c */
/* Includes */
#include "main.h"
#include "adc.h"
#include "dac.h"
#include "usart.h"
#include "gpio.h"

/* Private includes */
/* USER CODE BEGIN Includes */
#include <stdio.h>
/* USER CODE END Includes */

/* Private variables */
/* USER CODE BEGIN PV */
uint32_t adc = 0;
uint32_t dac = 0;
float vsense = 3.3 / 4096.0;
float temperature = 0.0;
/* USER CODE END PV */

/* Private function prototypes */
void SystemClock_Config(void);
```

```
int main(void)
{
    /* MCU Configuration */
    /* Reset of all peripherals, Initializes ... */
    HAL_Init();
    /* Configure the system clock */
    SystemClock_Config();
    /* Initialize all configured peripherals */
    MX_GPIO_Init();
    MX_USART3_UART_Init();
    MX_ADC1_Init();
    MX_DAC_Init();

    /* USER CODE BEGIN 2 */
    HAL_DAC_Start(&hdac, DAC_CHANNEL_1);
    HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);
    HAL_ADC_Start_IT(&hadc1);
    /* USER CODE END 2 */

    /* Infinite loop */
    /* USER CODE BEGIN WHILE */
    while (1)
    {
        HAL_GPIO_TogglePin(GPIOB, LD3_Pin);
        printf("DAC ADC vales = %ld %ld \n\r", dac, adc);
        HAL_Delay(1000);
    }
    /* USER CODE END WHILE */
```

Interrupt mode

STM32CubeIDE – DAC ADC



Add code to **main.c**, USER CODE 4

```
/* USER CODE BEGIN 4 */
void HAL_ADC_ConvCpltCallback(ADC_HandleTypeDef* hadc)
{
    adc = HAL_ADC_GetValue(&hadc1);
    HAL_DAC_SetValue(&hdac, DAC_CHANNEL_1, DAC_ALIGN_12B_R, dac);

    ++dac;
    if(dac > 4095) dac = 0;
    HAL_Delay(10);
    HAL_ADC_Start_IT(&hadc1);
}

void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
{
    if(GPIO_Pin == GPIO_PIN_13)
    {
        HAL_GPIO_TogglePin(GPIOB, LD2_Pin);
    }
}

int __io_putchar(int ch)
{
    uint8_t c[1];
    c[0] = ch & 0x00FF;
    HAL_UART_Transmit(&huart3, &c, 1, 10);
    return ch;
}
/* USER CODE END 4 */
```



```
/*
int _write(int file, char *ptr, int len)
{
    int DataIdx;
    for(DataIdx= 0; DataIdx < len; DataIdx++)
    {
        __io_putchar(*ptr++);
    }
    return len;
}
*/
```