



Universidade Federal de Lavras

Engenharia de Controle e Automação

Robótica

Professor: Leonardo Paiva

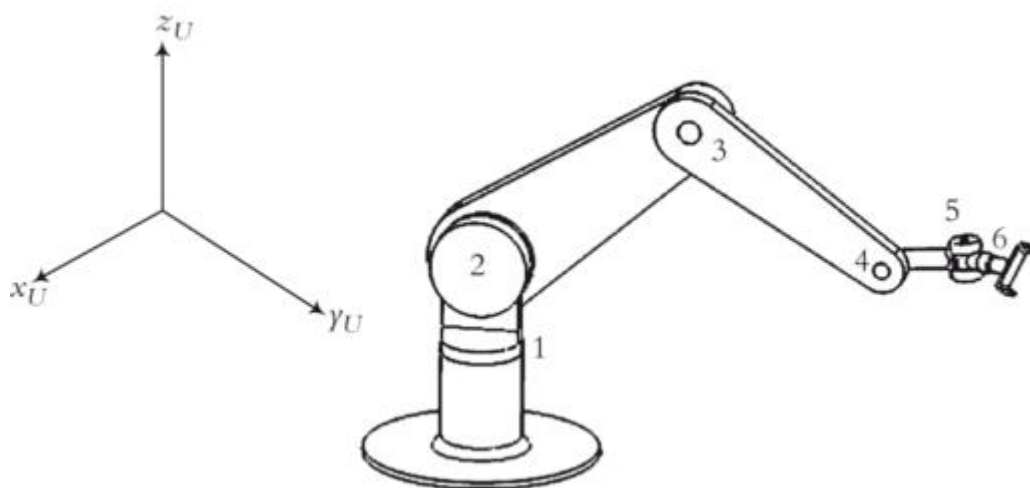
Data:

Exercício

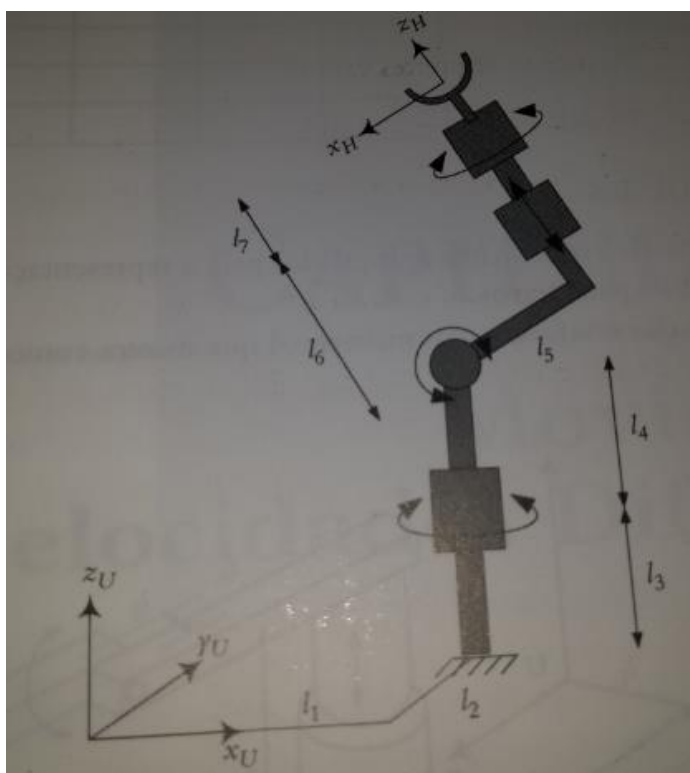
Aluno:

Dados as seguintes anatomias de manipuladores abaixo, determine os parâmetros de Denavit-hartenberg

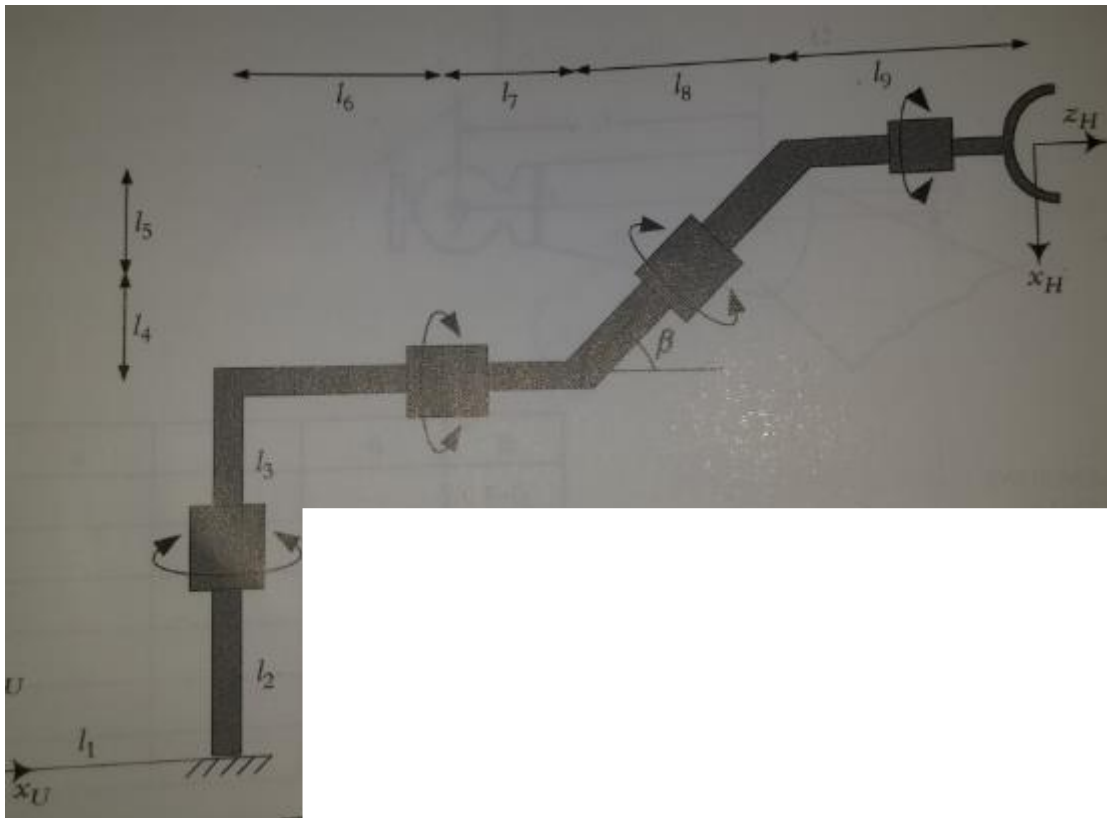
a)



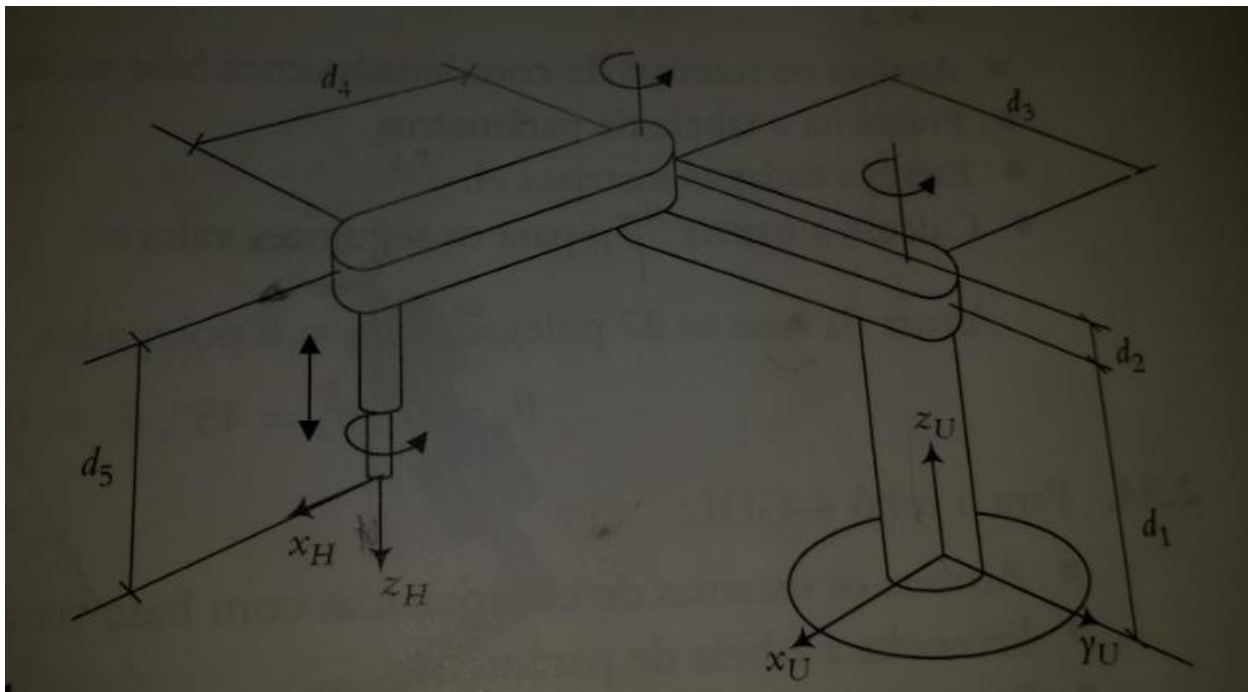
b)



c)



d)



e)

