



Classification Models Lecture 02

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Content

1. Decision Trees

- How it works
- CART and ID3
- Prunning

2. Support Vector Machines (SVM)

- Linear SVM
- Nonlinear SVM





Objectives

Upon completion of this lecture, you will be able to:

- Understand the main concepts of Decision Trees and Support Vector Machines;
- Understand how these models perform classification and regression;
- Build these models with scikit-learn and use them for classification or regression.





Decision Trees





Decision Trees

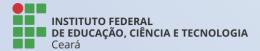
- Decision Trees are versatile Machine Learning algorithms that can perform both classification and regression tasks.
- They are probably one of the most intuitive and frequently used data science techniques.
- Decision Trees are also easy to set up and easy to interpret.





How it works

- A decision tree model takes a form of decision flowchart where an attribute is tested in each node.
- At end of the decision tree path is a *leaf node* where a prediction is made about the target variable based on conditions set forth by the decision path.
- The nodes split the dataset into subsets.
- These splits are based on the "purity" of the data.





Measures of impurity

- The most common measures of impurity used in Decision Trees are the Gini index and entropy.
- These measures of impurity must satisfy the following conditions:
 - Maximum impurity is reached when all possible classes are equally represented.
 - When only one class is represented, the measure of impurity must be zero.





Evaluating Gini and Entropy

• Entropy:

$$H = -\sum_{k=1}^{K} p_k \log_2(p_k)$$

• Gini:

$$G = 1 - \sum_{k=1}^{K} p_k^2$$

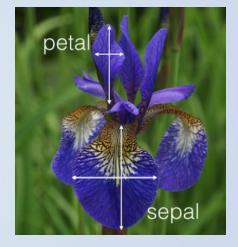
- \circ $k = 1, \dots, K$ represents the classes of the target variable; and
- \circ p_k represents the proportion of samples that belong to class k

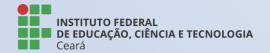




Example

- Let's build a Decision Tree and see how it makes predictions.
- For this example, we will use the "iris dataset".
- There are 150 samples in this dataset, 50 in each of the three classes.
- There are four numeric features:
 - sepal length in cm
 - sepal width in cm
 - petal length in cm
 - o petal width in cm
- The classes are: Iris-Setosa, Iris-Versicolour and Iris-Virginica



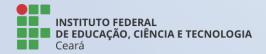




Example

```
import numpy as np
from sklearn.datasets import load iris
from sklearn.tree import DecisionTreeClassifier
from sklearn.tree import export graphviz
import graphviz
np.random.seed(7)
iris = load iris()
X = iris.data[:, 2:] # petal length and width
y = iris.target
tree clf = DecisionTreeClassifier(max depth=2)
tree clf.fit(X, y)
dot = export graphviz(tree clf,
                feature names=iris.feature names[2:],
                class names=iris.target names,
                rounded=True, filled=True)
graph = graphviz.Source(dot)
graph
```

```
petal width (cm) <= 0.8
               gini = 0.667
              samples = 150
            value = [50, 50, 50]
              class = setosa
                             False
         True
                       petal width (cm) <= 1.75
   gini = 0.0
                              gini = 0.5
 samples = 50
                            samples = 100
value = [50, 0, 0]
                          value = [0, 50, 50]
 class = setosa
                          class = versicolor
                 gini = 0.168
                                         aini = 0.043
                                        samples = 46
                samples = 54
               value = [0, 49, 5]
                                       value = [0, 1, 45]
               class = versicolor
                                       class = virginica
```





The CART Training Algorithm

- Scikit-Learn uses the Classification and Regression Tree (CART) algorithm to train Decision Trees.
- The algorithm works by first splitting the training set into two subsets using a single feature k and a threshold t_k .
- To select the feature and threshold, it searches for the pair (k, t_k) that produces the purest subsets (weighted by their size).
- Once the CART algorithm has successfully split the training set in two, it splits the subsets using the same logic, then the sub-subsets, and so on, recursively.





The ID3 Training Algorithm

- Another common training algorithm in Decision Trees is the ID3 (Iterative Dichotomiser 3).
- It works similarly to CART. Here are the steps in ID3:
 - 1. Calculate the entropy of every feature of the training set;
 - 2. Split the training set into subsets using the feature for which the resulting entropy after splitting is minimized;
 - 3. Make a node containing that attribute;
 - 4. Recurse on subsets using the remaining attributes.





Overfitting

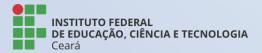
- Decision Trees make very few assumptions about the training data.
- If left unconstrained, the tree structure will adapt itself to the training data, fitting it very closely.
- To avoid overfitting, the tree's growth may need to be restricted or reduced, using a process called *pruning*.
- The tree can be pruned before/during training (pre-pruning) or after it (post-pruning).





Prunning

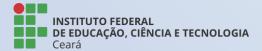
- Pre-pruning can be done by, for example:
 - setting a maximum depth for the tree;
 - setting the minimum number of samples a node must have before it can be split;
 - setting the maximum number of leaf nodes;
- Post-pruning methods do not restrict the tree and allow it to grow as deep as the data will allow.
 Then, after training, the unnecessary nodes are pruned.
- A node whose children are all leaf nodes is considered unnecessary if the purity improvement it provides is not statistically significant.





Regression

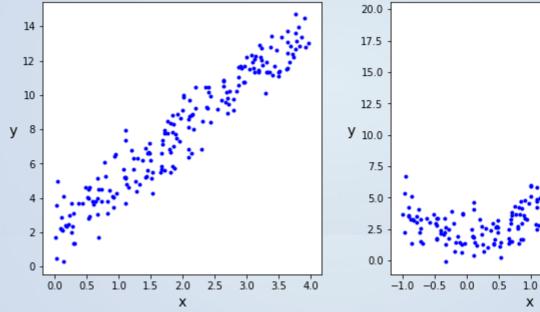
- Decisions Trees are also capable of performing regression.
- For regression problems, instead of predicting a class in each leaf node, it predicts a value.
- For training, the training algorithm will try to split the training set in order to minimize the Mean Squared Error (MSE), instead of impurity.
- We also must be careful when performing regression with Decision Trees, as it is prone to overfitting.
- Regularization can be done in the same way as in Classification.





Example

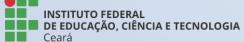
• For the regression examples, we will consider the following datasets:

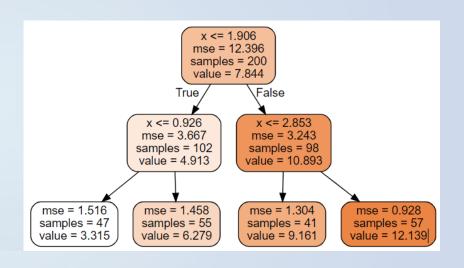




2.0 2.5 3.0

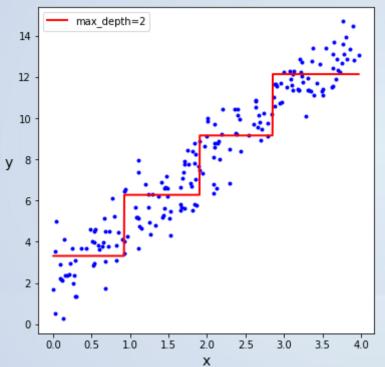
1.5

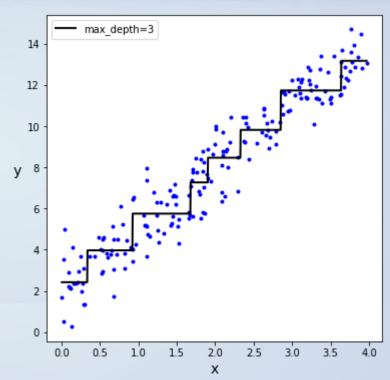






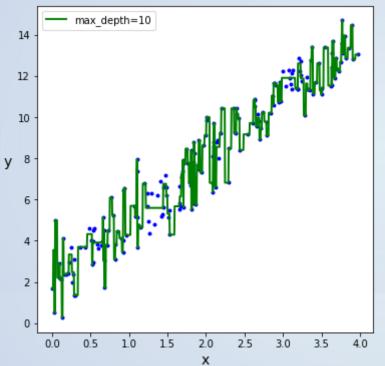


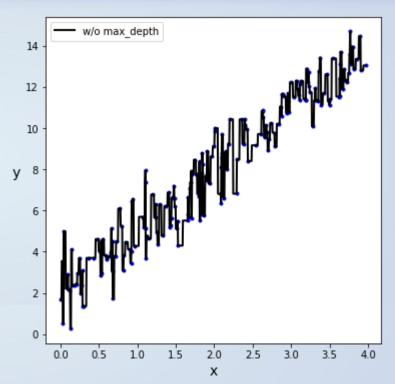






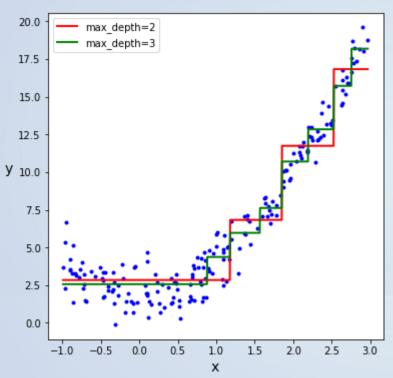


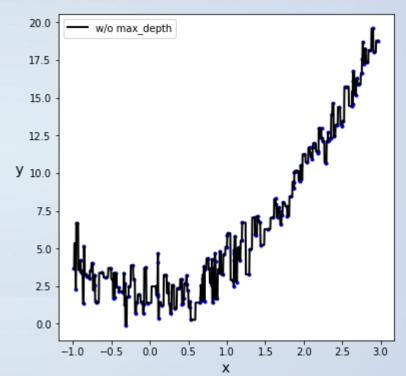


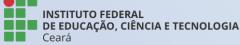














Support Vector Machines





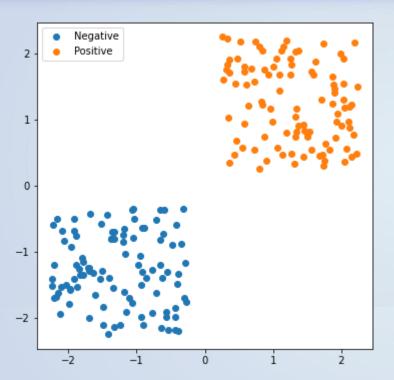
Support Vector Machines

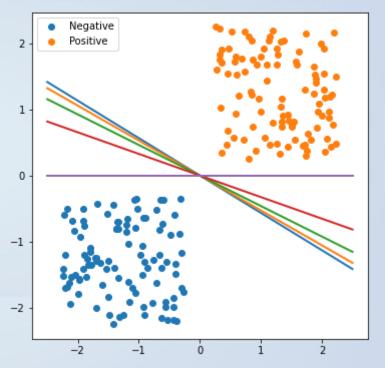
- A **Support Vector Machine (SVM)** is a powerful and versatile Machine Learning model, capable of performing linear or nonlinear classification, regression, and even outlier detection.
- Briefly, for binary classification, a SVM performs an implicit nonlinear mapping of the input data to a very high-dimension feature space.
- In this space, a linear decision surface is constructed with special properties that ensure a high generalization ability.





Linear SVM





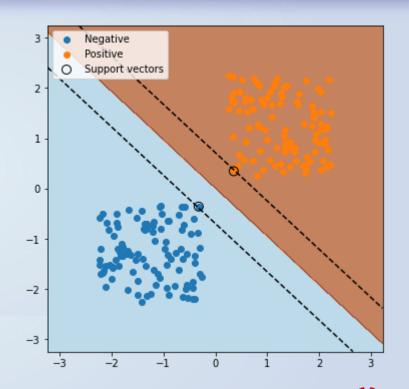


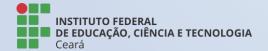


Hard Margin SVM

- For a linearly separable dataset, a SVM will look for the hyperplane ($\mathbf{w}^T \mathbf{x} + b = 0$) that separates the classes with maximum margin.
- Margin is the sum of the distance between the hyperplane and the closest elements of each class, and is given by:

$$\rho = \frac{2}{\|w\|}$$







Hard Margin SVM

- Therefore, the optimal hyperplane is the one that minimizes ||w||.
- To find it, we need to solve the following quadratic programming problem (QPP):

$$\min_{(\mathbf{w},b)} \frac{1}{2} \mathbf{w}^T \mathbf{w}$$
s.t. $y_i(\mathbf{w}^T \mathbf{x}_i + b) \ge 1$, $i = 1, \dots, m$

- This version of SVM has two main problems:
 - It only works with linearly separable data;
 - It is sensible to outliers.





Soft Margin SVM

• To avoid these problems, the addition of slack variables (ξ_i) was proprosed:

$$\min_{(w,b)} \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^m \xi_i$$
s.t. $y_i (\mathbf{w}^T \mathbf{x}_i + b) \ge 1 - \xi_i$, $i = 1, \dots, m$

$$\xi_i \ge 0, \qquad i = 1, \dots, m$$

• This formulation describes, for a sufficiently large C the problem constructing a separating hyperplane that minimizes the sum of deviations ξ (for training errors) and maximizes the margin for the correctly classified instances.





Dual problem

- Given a constrained optimization problem, known as the *primal problem*, it is possible to express a different but closely related problem, called its *dual problem*.
- For the SVM problem, the solutions of the primal and dual problems is the same.
- Therefore, we can choose to solve either of them.
- The Lagrange dual problem is:

$$\max_{\alpha} \sum_{i=1}^{m} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{m} \sum_{i=1}^{m} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{i}^{T} x_{j}$$

$$s.t. \sum_{i=1}^{m} \alpha_{i} y_{i} = 0$$

$$0 \le \alpha_{i} \le C, \qquad i = 1, \dots, m$$

 \circ $\alpha_i \ge 0$, $i = 1, \dots, m$ are the Lagrange multipliers and each is related to one constraint of the primal problem.





Dual problem

When dealing with the dual problem, we derive

$$w_0 = \sum_{i=1}^m \alpha_i^0 y_i x_i$$

 According to the Karush-Kuhn-Tucker conditions, each Lagrange multiplier and its corresponding constraint are connected by the equation:

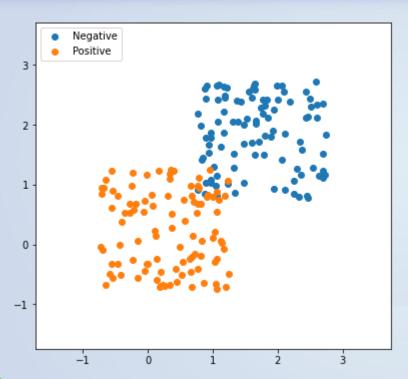
$$\alpha_i^0[y_i(w_0^Tx_i+b_0)-1]=0, \qquad i=1,\cdots,m$$

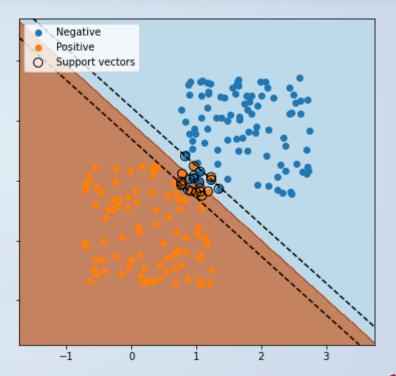
• That means that $\alpha_i^0 \neq 0$ only when $y_i(w_0^T x_i + b_0) - 1 = 0$. The training instances (x_i, y_i) that satisfy this last equation are called *support vectors*.





Soft Margin SVM



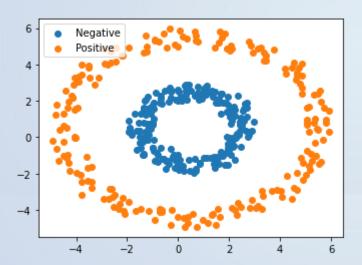


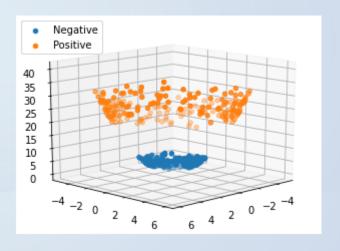




Nonlinear SVM

- Now, how to deal with data that is not linearly separable?
- One possibility would be to explictly map the data to a higher dimension and find the optimal separating hyperplane there.



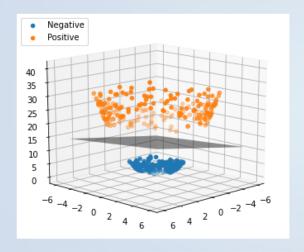


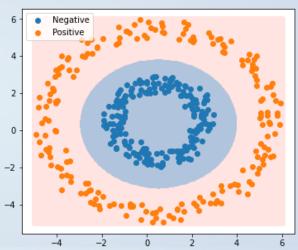




Nonlinear SVM

• Note that the decision surface is nonlinear when projected to the original data space.





• However, this approach has a few drawbacks. One of them is the computational cost, which can be absurdly high depending on them number of features and the choosen transformation.





Kernel trick

- Fortunately, by using *kernel functions*, SVMs can find the optimal separating hyperplane in a high dimension feature space **without** explicitly mapping the data into this space.
- A *kernel* K(a, b) is a function capable of computing the inner product $\langle \phi(a), \phi(b) \rangle$, based only on the input vectors a and b, without having to compute the transformation ϕ .

Commonly used kernels	
Linear	$K(\boldsymbol{a},\boldsymbol{b}) = \boldsymbol{a}^T \boldsymbol{b}$
Polynomial	$K(\boldsymbol{a},\boldsymbol{b}) = (\boldsymbol{a}^T\boldsymbol{b} + c)^d$
Gaussian RBF	$K(\boldsymbol{a}, \boldsymbol{b}) = \exp(-\gamma \ \boldsymbol{a} - \boldsymbol{b}\ ^2)$
Sigmoid	$K(\boldsymbol{a}, \boldsymbol{b}) = \tanh(\gamma \boldsymbol{a}^T \boldsymbol{b} + c)$





Regression

• In ε -SV regression, our goal is to find a function f(x) that has at most ε deviation from the targets y_i for all the training data, and at the same time is as flat as possible.

$$\min_{(w,b)} \frac{1}{2} w^{T} w + C \sum_{i=1}^{m} (\xi_{i} + \xi_{i}^{*})$$

$$s.t. \quad y_{i} - w^{T} x_{i} - b \le \epsilon + \xi_{i}, \qquad i = 1, \dots, m$$

$$w^{T} x_{i} + b - y_{i} \le \epsilon + \xi_{i}^{*}, \qquad i = 1, \dots, m$$

$$\xi_{i}, \xi_{i}^{*} \ge 0, \qquad i = 1, \dots, m$$

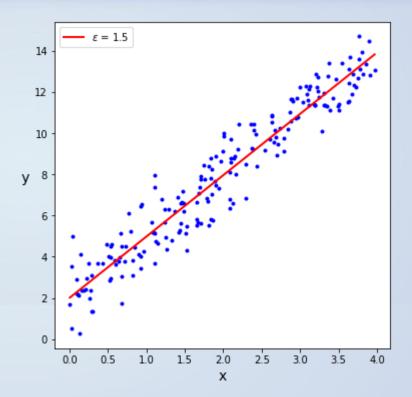
• It is also possible to use kernel functions with this model. All we need to do is consider the dual problem of the one above.

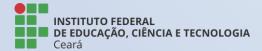




from sklearn.svm import LinearSVR

svm_reg = LinearSVR(epsilon=1.5)
svm reg.fit(x, y.ravel())

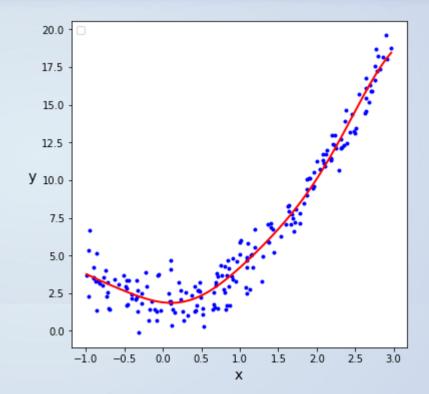


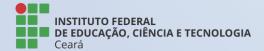




```
from sklearn.svm import SVR

svm_reg2 = SVR(kernel='rbf', C=10)
svm reg2.fit(x2, y2)
```







Decision Trees and SVMs with scikit-learn





Decision Trees and SVMs with scikit-learn

Decision Tree:

- Classification: <u>sklearn.tree.DecisionTreeClassifier</u>
- Regression: <u>sklearn.tree.DecisionTreeRegressor</u>
- Use sklearn.tree.export graphviz and graphviz to visualize the model.

SVM:

Classification: sklearn.svm.SVC

Regression: <u>sklearn.svm.SVR</u>





References

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- 3. Kotu, Vijay, and Bala Deshpande. Data science: concepts and practice. Morgan Kaufmann, 2018.
- 4. Smola, Alex J., and Bernhard Schölkopf. *A tutorial on support vector regression*. Statistics and computing 14.3 (2004): 199-222.





