# **Distributed Computing**

## **CS5320**

# **Programming Assignment-II**

**CS19MTECH11009** 

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## Assignment on Termination Detection

#### Approach:

We need to find the termination of all the processes in the distributed system. A distributed system is a collection of computers or components (processes) that are located at different locations and they communicate with each other through message passing to perform some particular task. As we don't have availability of distributed systems, we are asked to create a distributed environment using threads and processes. The distributed environment should contain the systems/processes which are connected to each other in the form of a connected graph topology. Each node communicates with every other node through messages.

In this distributed environment each process will maintain two threads. One thread for receiving messages and another thread will be responsible for internal computation of a process. In this system, each process will have its own unique identification number, color and socket descriptor as its attributes. Each process is considered to be running on a different system. We are having 'n' no.of processes which are communicating with each other in the distributed manner. The socket programming is used to make communication between the processes. As mentioned in the assignment description, each process will maintain color. Initially all processes will contain white as their color. If the process color is red then it is active. The process will be passive if it has blue color. If all the processes are blue then termination is occured. So we need to find the termination of processes in the given distributed system.

At the starting of the program, I have read input file for the information required for the distributed environment and information related to complete the required task. I have created a thread for each process. Each process is assigned a port number, which will be used in socket programming for communication. After creating 'n' processes, as a part of computation I have chosen some random processes which will turn their color to red and continue further communication with other processes. Each process will make communication by sending a message to its neighbours.

During the computation in the distributed system environment, one process will initiate termination detection algorithm by introducing some random processes that own blue color. We call such a node as initiator. This initiator node will detect the termination of all processes.

#### Dijkstra & Scholten Termination Detection Algorithm:

The computation initiated by a single initiator and spreading over to several other nodes in the network. There are two kinds of messages in the network: **signals** propagate along the direction of the edges, and **acks** propagate in the opposite direction. The initiator node will send a **signal** message towards its children to activate termination detection. If a child is idle then it sends **ack** message to its parent. So this process will be continued to know termination in the network.

Internal node which receives a signal message may propagate this message to its neighbours. The node will send an **acknowledgement** message to its parent only if all its children send him/her **ack** message and the node is idle. This **Dijkstra and Scholten** algorithm uses two **variables** called C and D. I have used the concept explained in the book by A. **Kshemkalyani and M. Singhal**. (7.5 A Spanning-Tree-Based Termination Detection Algorithm).

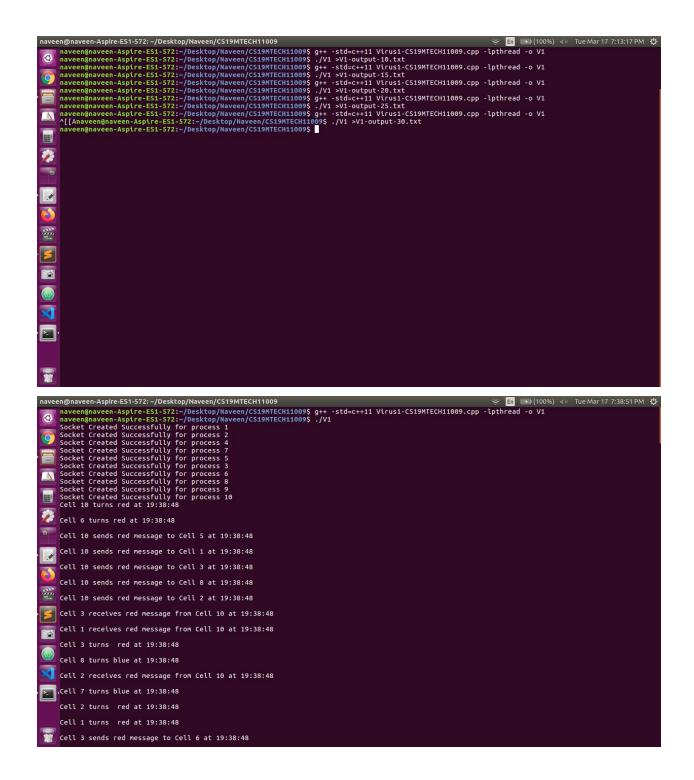
Note: So that I'm not writing the explanation of the Spanning - Tree algorithm

#### **Programming Approach:**

I'm solving this assignment using cpp language. In this assignment I have created a Class which is responsible for send, receive, socket creation and internal computation of the process. Each process will have all these functions. Sending and receiving the messages is the way in which processes will communicate with each other. I performed some computations in each of the send and receive functions mentioned in Process class inorder to get information to detect the termination.

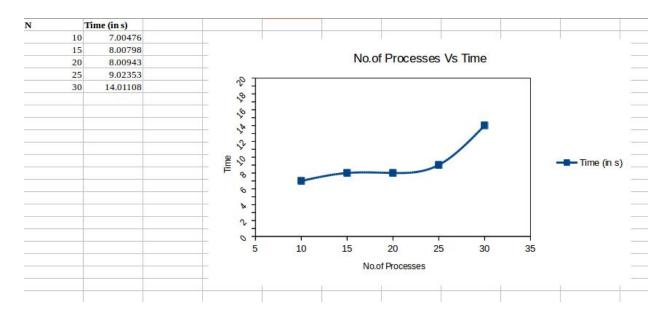
I also created a main file, called CS19MTECH11009\_TD\_1.cpp, in which we start with the main function. In the main function, I have taken the text file as input to read all the required data to move forward with the computations. After reading a text file, I have created **n** processes using thread, during the process creation the sockets and constructor of Process class will be created for each process. After creating all the processes, I have chosen the red process as mentioned in the assignment description and started the computation. The communication will be happening between the processes, we will determine the termination if and only if all the processes are in blue color.

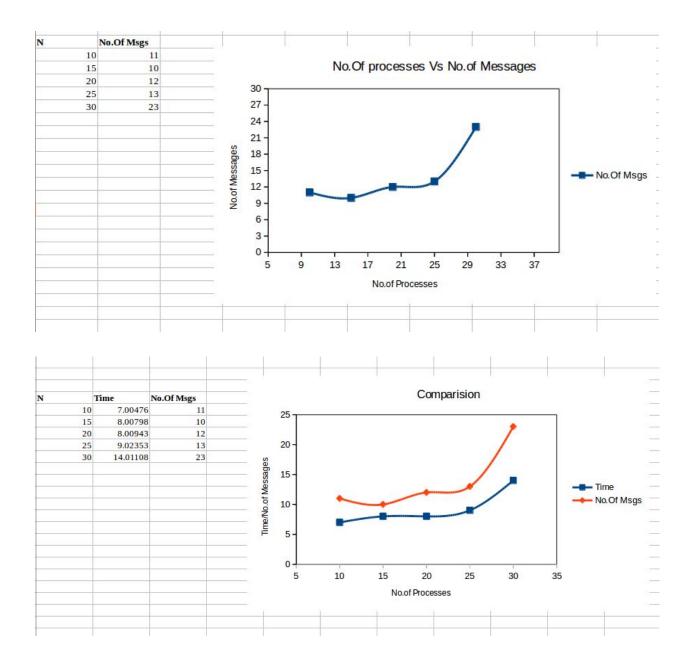
Below images show the running the code for multiple times and the output sample for the code.



```
naveen@naveen-Aspire-ES1-572:~/Desktop/Naveen/CS19MTECH11009
    Cell 5 receives blue message from Cell 6 at 19:40:12
    Cell 5 turns blue at 19:40:12
    Cell 5 sends blue message to Cell 6 at 19:40:12
    Cell 10 receives blue message from Cell 8 at 19:40:13
    Cell 10 turns blue at 19:40:13
    Cell 10 sends blue message to Cell 8 at 19:40:13
    Cell 10 sends blue message to Cell 5 at 19:40:13
     Time taken by * Dijkstra Termination Detection * Algorithm is: (in seconds) 5.00598
                                    parentNode
            color
blue
            blue
            blue
            blue
            blue
            blue
            blue
            blue
    8 is number of messages sent to detect Termination
    naveen@naveen-Aspire-ES1-572:~/Desktop/Naveen/CS19MTECH11009$
```

#### The graphs related to the Dijkstra-Scholten Algorithm:





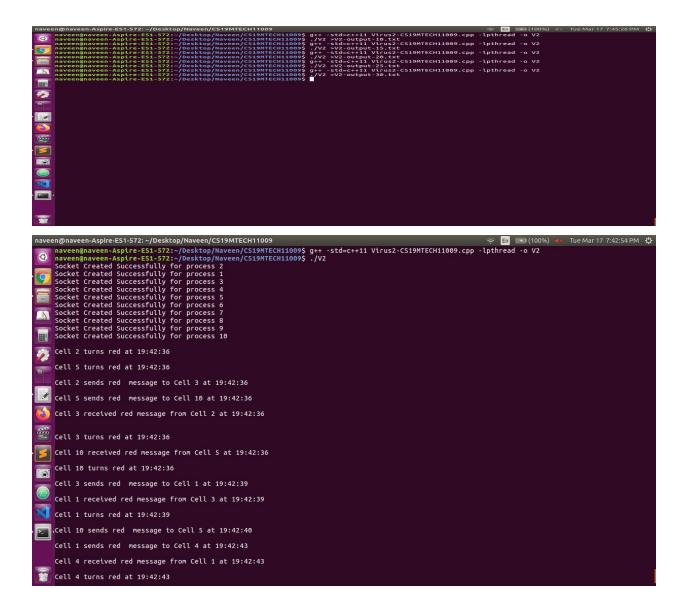
### A spanning-tree-based Termination Detection Algorithm:

This algorithm is explained in book A&M section 7.5. In this algorithm we will have a fixed spanning tree. We use this spanning tree to detect the termination. I have used the same concept explained in the book.

#### **Programming Approach:**

I'm solving this assignment using cpp language. In this assignment I have created a Class which is responsible for send, receive, socket creation and internal computation of the process. Each process will have all these functions. Sending and receiving the messages is the way in which processes will communicate with each other. I performed some computations in each of the send and receive functions mentioned in Process class inorder to get information to detect the termination.

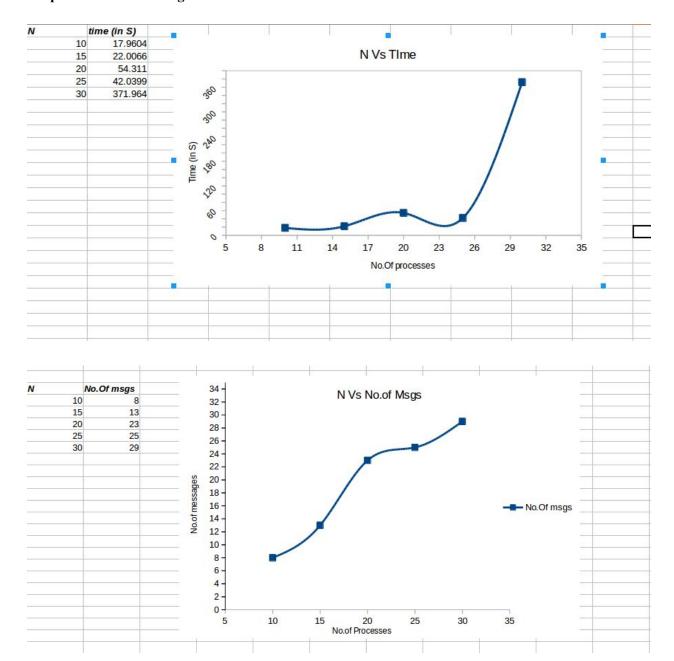
I also created a main file, called CS19MTECH11009\_TD\_2.cpp, in which we start with the main function. In the main function, I have taken the text file as input to read all the required data to move forward with the computations. After reading a text file, I have created **n** processes using thread, during the process creation the sockets and constructor of Process class will be created for each process. After creating all the processes, I have chosen the red process as mentioned in the assignment description and started the computation. The communication will be happening between the processes, we will determine the termination if and only if all the processes are in blue color. In this case, the root node has to get a token from its children and the token should not be black and the process should be passive.

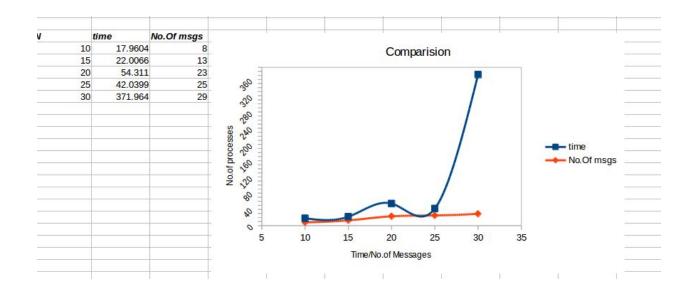


```
naveen@naveen-Aspire-ES1-572: ~/Desktop/Naveen/CS19MTECH11009
Cell 7 sends blue message to Cell 3 at 19:44:14
                                                                                                              🤶 En 🕟 (100%) ∢× Tue Mar 17 7:45:45 PM 🔱
Ø
    Cell 6 received red message from Cell 8 at 19:44:14
    Cell 7 sends blue message to Cell 4 at 19:44:14
Cell 6 turns red at 19:44:14
Cell 6 sends red message to Cell 1 at 19:44:14
    Cell 2 received red message from Cell 6 at 19:44:15
    Cell 2 turns red at 19:44:15
*
    Cell 6 sends red message to Cell 5 at 19:44:15
    Cell 5 received red message from Cell 6 at 19:44:15
    Cell 5 turns red at 19:44:15
    Cell 5 sends red message to Cell 3 at 19:44:15
    Cell 5 sends red message to Cell 6 at 19:44:15
Cell 2 sends red message to Cell 8 at 19:44:16
Cell 2 sends red message to Cell 5 at 19:44:16
    Cell 7 sends blue message to Cell 5 at 19:44:17
Cell 7 sends blue message to Cell 8 at 19:44:17
    Cell 7 sends blue message to Cell 1 at 19:44:17
Cell 4 sends blue message to Cell 1 at 19:44:17
Cell 4 sends blue message to Cell 3 at 19:44:18
     Cell 4 sends blue message to Cell 5 at 19:44:18
    Cell 4 sends blue message to Cell 2 at 19:44:19
   Cell 4 sends blue message to Cell 6 at 19:44:19
```

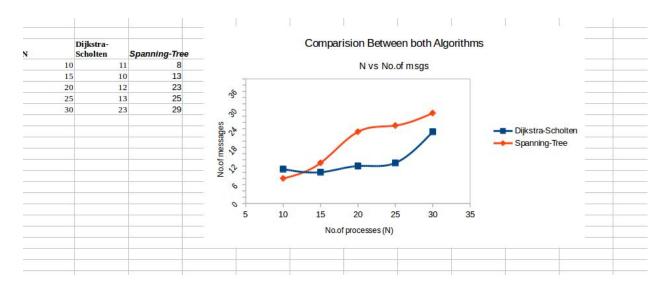
```
Cell 1 sends blue message to Cell 6 at 20:00:04
Cell 1 sends blue message to Cell 3 at 20:00:04
Cell 1 sends blue message to Cell 10 at 20:00:05
Cell 2 sends blue message to Cell 8 at 20:00:05
Cell 3 sends blue message to Cell 6 at 20:00:07
Cell 4 sends blue message to Cell 2 at 20:00:07
Cell 5 sends blue message to Cell 10 at 20:00:08
Cell 5 sends blue message to Cell 1 at 20:00:08
Cell 5 sends blue message to Cell 6 at 20:00:09
Cell 5 sends blue message to Cell 4 at 20:00:10
Cell 4 sends blue message to Cell 1 at 20:00:11
Time taken by * Spanning-Tree Termination Detection * Algorithm is: 17.9607
is number of messages sent to detect Termination
 id
        color
                 isLeaf
                          hasToken
                                             tokenColor
                                                              No of children Parent Node
        blue
blue
                                            white
white
                 0
                          0
                                                               0
        blue
                 0
                                             white
        blue
blue
                 0
                          0
                                             white
                                                               0
                                             white
         blue
                          0 0 0
                                                               0 0 0
        blue
                                             white
         blue
        blue
blue
                          0
                                             white
                                                               0
```

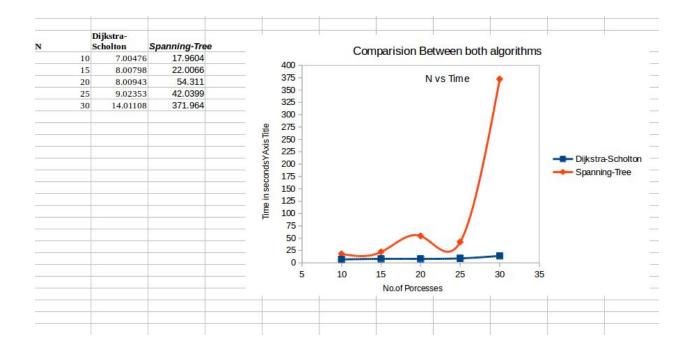
#### Graphs related to this algorithm:





#### Comparison between both algorithms:





#### **Observations:**

During the execution of programs I have observed few things. When a program is executed multiple times the time taken for detecting the termination may change. It is because of the processes we choose to make red , blue and it also depends on the threads behaviour in the system(Processor). In Dijkstra-Scholten algorithm , C and D values will be changed appropriately based on the acknowledgement received by the processes. We are choosing random processes, so due to this randomness the same processes will not be chosen every time. In the case of the Spanning-Tree algorithm , for the same input , time taken to determine the termination will not be the same. It may vary. It happens because of randomness and re-initiation of the termination detection when the root node has black token. Sometimes we may detect the termination at first go , sometimes we may re-initiate the process which will take some more time. If proper memory/RAM is not available for threads/processes that we create in the program we will get segmentation error.