

Analysis of Image Transforms for Sketch-based Retrieval

Diploma Thesis

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Outline

Introduction and Background

- Motivation and Challenges of CBIR

- Prior Work

- Anatomy of a CBIR System

Proposed Solution

- Proposed Retrieval Pipelines

- Acquisition

- The Curvelet Transform

- Feature Extraction

- Ranking

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- Intra-Domain Benchmark

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Motivation

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Challenges of CBIR

The Semantic Gap

*“The semantic gap is the **lack of coincidence** between the information that one can extract from the **visual data** and the **interpretation** that the same data have for a user in a given situation.” – Smeulders et al.*

The Sensory Gap

*“The sensory gap is the gap between the **object in the world** and the information in a (computational) description derived from a **recording of that scene**.” – Smeulders et al.*

Prior Work on Human Recognition

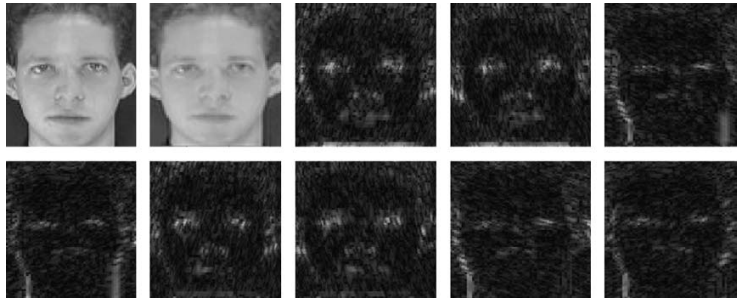


Figure: “Face recognition using curvelet based PCA.”, T. Mandal and Q. M.J Wu, ICPR 2008

Prior Work on Human Recognition



Figure: “Histograms of oriented gradients for human detection”, Dalal and Triggs, CVPR 2005

Prior Work on Visual Codebooks

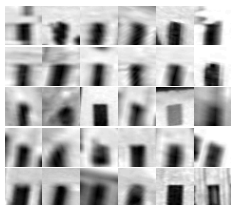
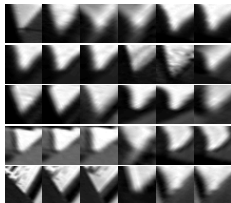


Figure: “Video Google: A text retrieval approach to object matching in videos”, Sivic and Zisserman, ICCV 2003

Prior Work on Scene Classification

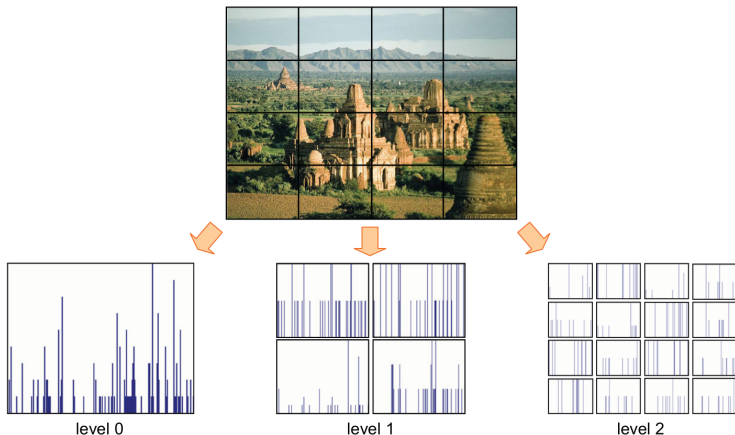


Figure: “Spatial pyramid matching”, Lazebnik et al., 2009

Anatomy of a CBIR System

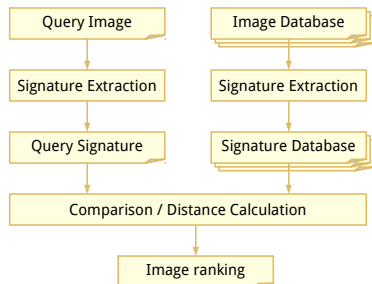


Figure: Global Descriptors

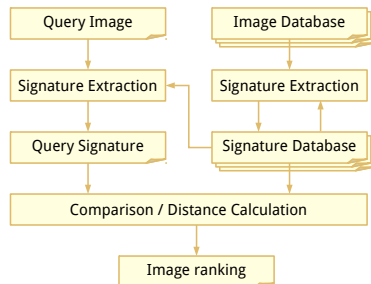


Figure: Local Descriptors

Proposed Retrieval Pipelines (Global)

Proposed Retrieval Pipelines (Local)

Acquisition

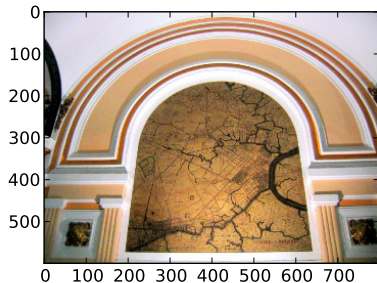


Figure: Original Image

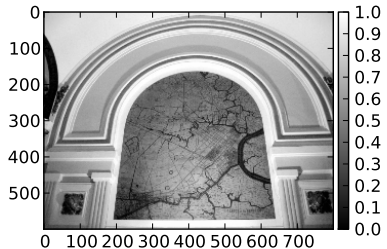


Figure: Luma Conversion

Acquisition

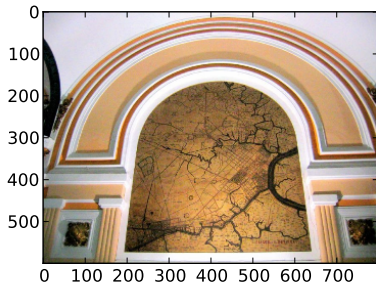


Figure: Original Image

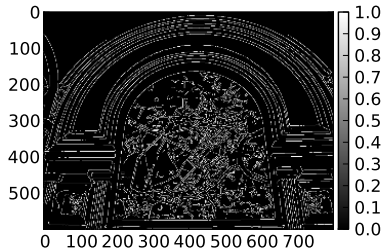


Figure: Canny Operator

Acquisition

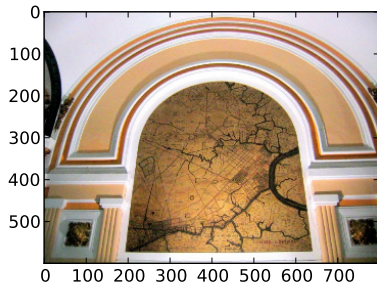


Figure: Original Image

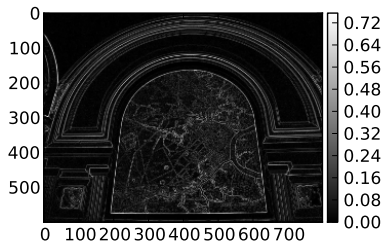


Figure: Sobel Operator

Acquisition

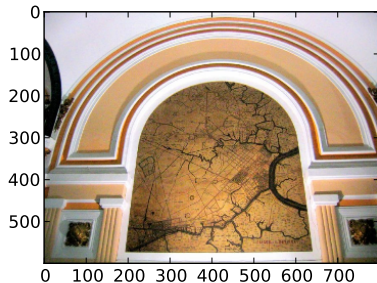


Figure: Original Image

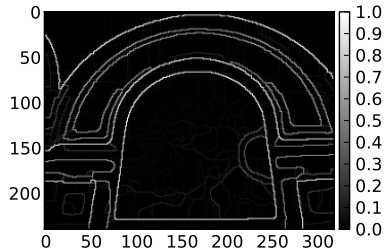


Figure: gPb-owt-ucm Transform

Properties of the Curvelet Transform

- ▶ An extension of the wavelet transform
- ▶ Localized in *position*, *scale* and *orientation*
- ▶ Curvelets obey parabolic scaling: $width \approx length^2$
- ▶ Approximation error along edges using m largest coefficients decays with $\frac{\log(m)^3}{m^2}$ (compare $\frac{1}{m}$ for wavelets)
- ▶ Defined in frequency domain using

Constructing the Curvelets

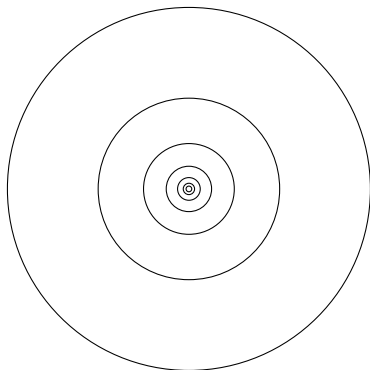


Figure: Frequency Domain

Figure: Spatial Domain

Constructing the Curvelets

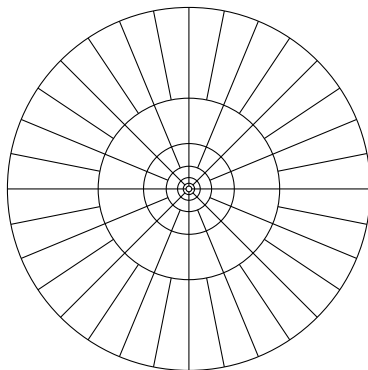


Figure: Frequency Domain

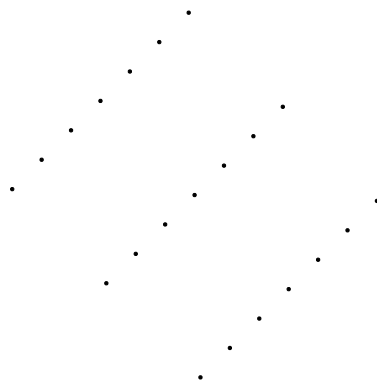


Figure: Spatial Domain

Constructing the Curvelets

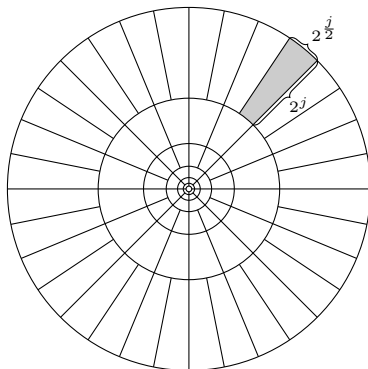


Figure: Frequency Domain

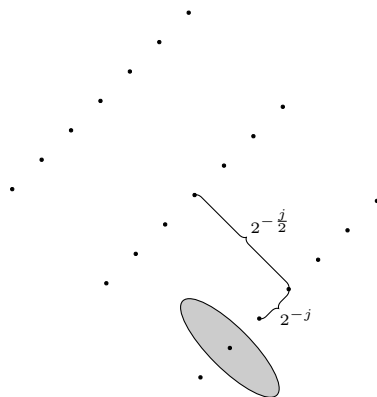


Figure: Spatial Domain

Constructing the Curvelets

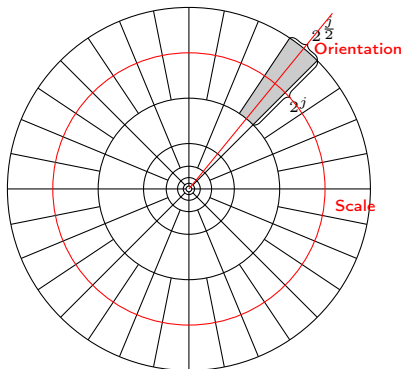


Figure: Frequency Domain

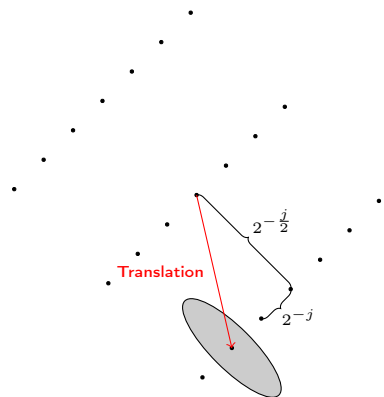


Figure: Spatial Domain

Example Curvelets



Figure: Frequency Domain

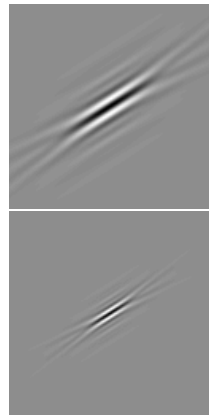


Figure: Spatial Domain

The Fast Discrete Curvelet Transform

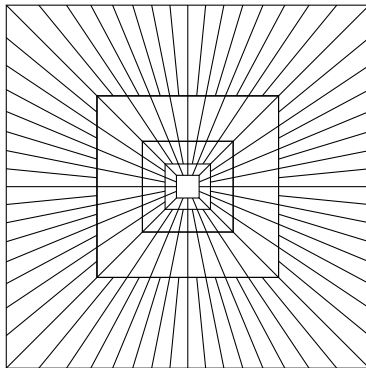


Figure: Frequency Domain

Figure: Parallelogram Support

The Fast Discrete Curvelet Transform

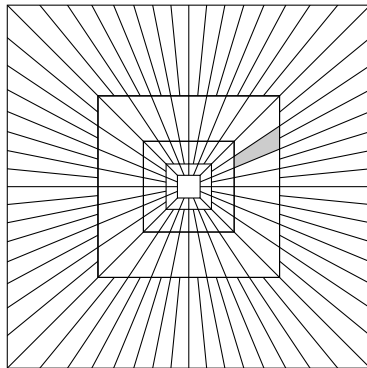


Figure: Frequency Domain



Figure: Parallelogram Support

The Fast Discrete Curvelet Transform

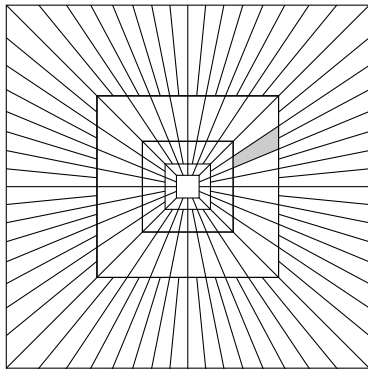


Figure: Frequency Domain

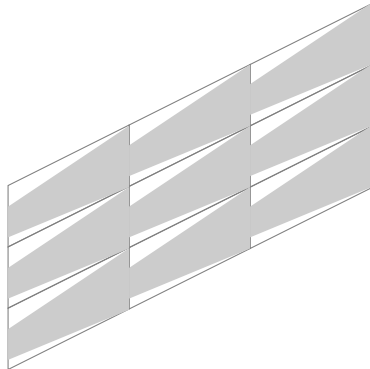


Figure: Parallelogram Support

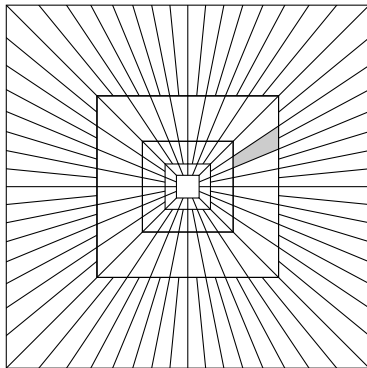


Figure: Frequency Domain

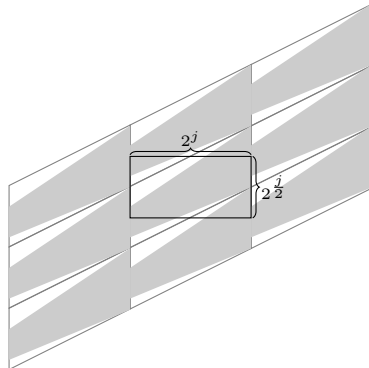


Figure: Parallelogram Support

Global Feature Extraction

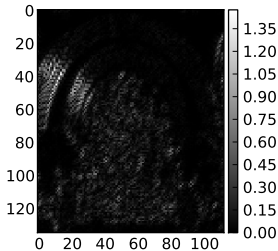


Figure: Curvelet coefficients at a specific scale and angle

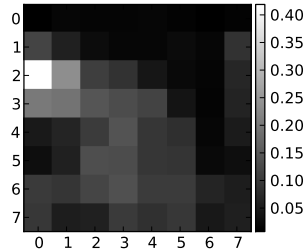


Figure: Mean values on an 8×8 grid

Local Feature Extraction (Clustering)

- ▶ k-means clustering
- ▶ Codebook size $k = 1000$
- ▶ Each sample vector is assigned to the cluster S_i , $i = 1, \dots, k$ the center of which it is closest to
- ▶ Image signature is the number of occurrences of each “visual word” in the image:

$$\tilde{I} = [|S_1|, |S_2|, \dots, |S_k|]$$

Distance Metrics

$$L_2 \quad d_{EUC L}(p, q) = \sqrt{\sum_{i=1}^n (q_i - p_i)^2}$$

$$\text{Cosine} \quad d_{COS}(p, q) = 1 - \frac{p \cdot q}{\|p\| \|q\|}$$

$$\text{Histogram Intersection (HI)} \quad d_{HI}(P, Q) = 1 - \frac{\sum_{i=1}^n \min(p_i, q_i)}{\sum_{i=1}^n q_i}$$

$$\text{Earth Mover's Distance (EMD)} \quad d_{EMD}(P, Q) = \frac{\sum_{i=1}^n \sum_{j=1}^m d_{i,j} f_{i,j}}{\sum_{i=1}^n \sum_{j=1}^m f_{i,j}}$$

TF-IDF Weighting

Term t_i occurs $tc_{i,j}$ times in document $d_j \in D$ with length n_j and is present in m_i documents overall.

Term Frequency $tf_{i,j} = \frac{tc_{i,j}}{n_j}$

Inverse Document Frequency $idf_i = \log \frac{|D|}{m_i}$

Total Term Weight $w_{i,j} = tf_{i,j} \cdot idf_i = \frac{tc_{i,j}}{n_j} \cdot \log \frac{|D|}{m_i}$

Cross-Domain Dataset



Figure: Example images from “Sketch-based image retrieval: benchmark and bag-of-features descriptors”, Eitz et al., 2011

Cross-Domain Benchmark

- ▶ 31 user study-based ground-truth rankings of 40 images with corresponding query sketches (Eitz et al., 2011)
- ▶ Kendall rank correlation coefficient $-1 \leq \tau_B \leq 1$
- ▶ τ_B is based on the number of similarly ordered pairs of measurements between two distributions
- ▶ $\tau_B = 1$ means same ordering, $\tau_B = -1$ means inverted ordering
- ▶ independent of the scaling differences between the two distributions

Cross-Domain Results

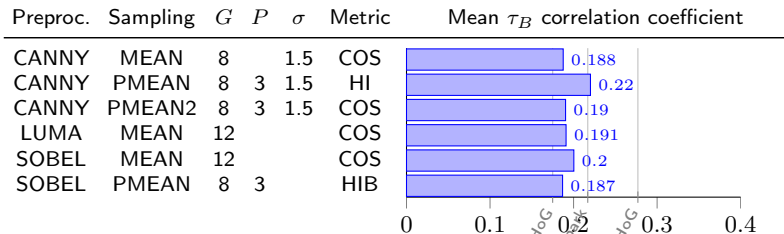
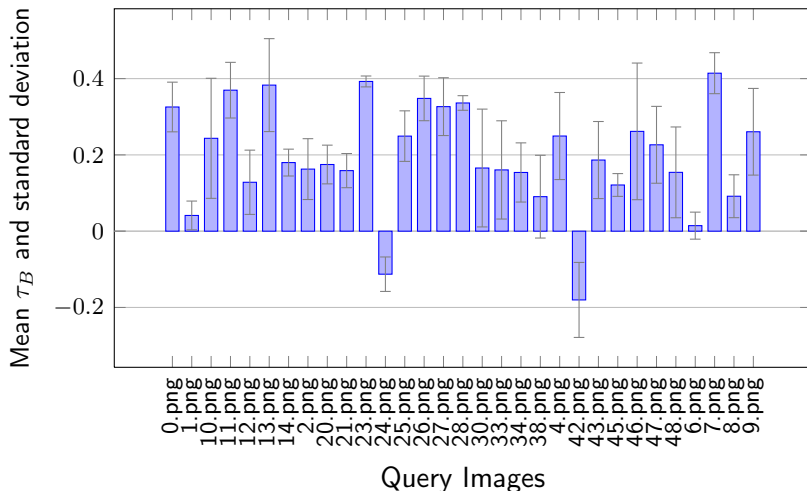


Table: Best performing pipeline configurations

Cross-Domain Distribution



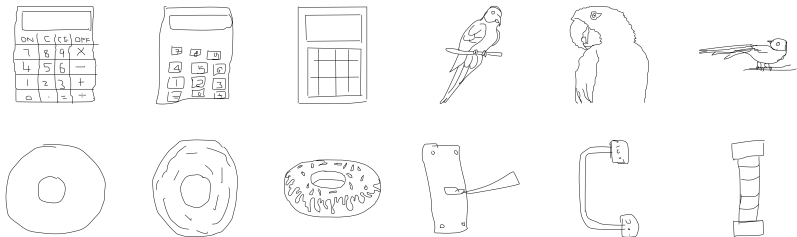


Figure: Example sketches from four categories from “How do humans sketch objects?”, Eitz et al., 2012

Intra-Domain Benchmark

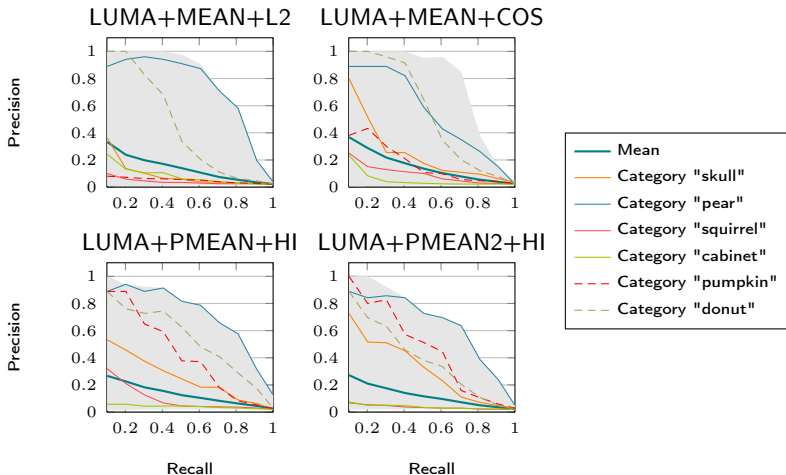
- ▶ 50 categories with 80 hand-drawn sketches each (Eitz et al., 2012)
- ▶ Precision-recall statistics

$$recall = \frac{\text{number of correct positive results}}{\text{total number of positives}}$$

$$precision = \frac{\text{number of correct positive results}}{\text{total number of results}}$$

- ▶ no edge-detecting preprocessing

Intra-Domain Results



Discussion and Conclusions

- ▶ Retrieval performance comparable to other descriptors
 - ▶ For cross-domain retrieval, local LUMA+CANNY+HI performs best
 - ▶ For intra-domain retrieval, global descriptors work better
 - ▶ Large performance differences between queries
- ⇒ Possibly much better results for narrower problem statements and specialized applications