

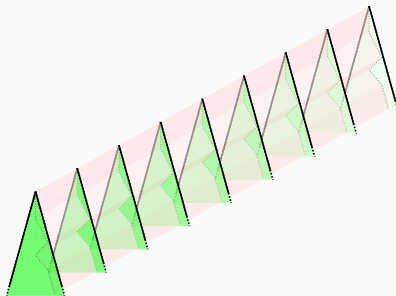
# Automata-theoretic Synthesis for Probabilistic Environments

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July 31, 2018

Informatik 7, RWTH Aachen



# **Word-Automata**

### Theorem

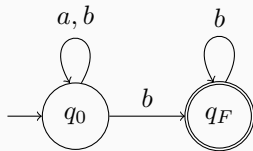
*The class of recognizable languages coincides for NBAs, NPAs and DPAs and is called  $\omega$ -regular languages. DBAs are strictly less expressive.*

$$\mathcal{L} = \{\alpha \in \{a, b\}^\omega \mid a \notin \text{Inf}(\alpha)\}$$

## Theorem

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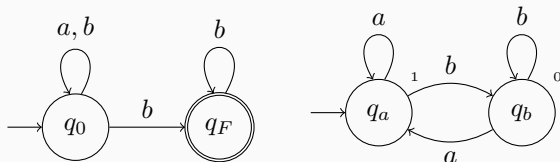


# $\omega$ -regular Languages

## Theorem

The class of recognizable languages coincides for NBAs, *NPAs* and *DPA*s and is called  $\omega$ -regular languages. DBAs are strictly less expressive. *However, NBA-determinisation is inherently costly ( $> n!$ ).*

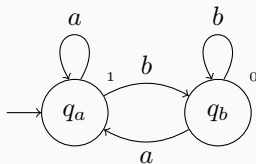
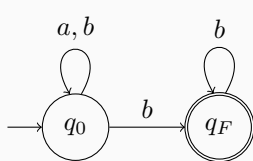
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## Theorem

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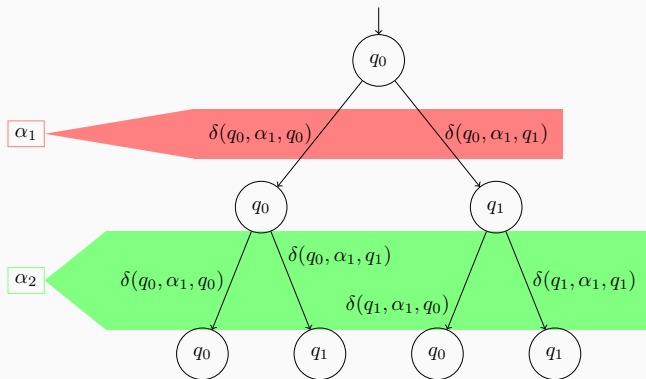
$b^\omega$ ,  
 $b^{n_0} ab^\omega$ ,  
 $b^{n_0} ab^{n_1} ab^\omega$ ,  
 $\vdots$

$$\mathcal{A} = (Q, \Sigma, \delta : Q \times \Sigma \times Q \rightarrow [0, 1], q_0, F)$$

- $Q$ : finite state set
- $\Sigma$ : finite alphabet
- $q_0 \in Q$ : initial state
- $\delta : Q \times \Sigma \times Q \rightarrow [0, 1]$ : transition probability function
- $F \subseteq Q$ : final states

# Probabilistic Büchi Automata

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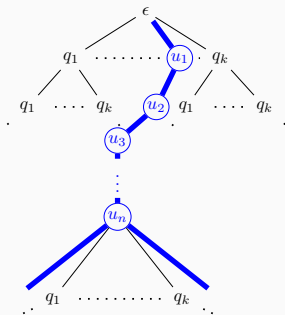


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$$\text{cyl}(u) = \{u \cdot \alpha : \alpha \in Q^\omega\}$$



# Probabilistic Büchi Automata

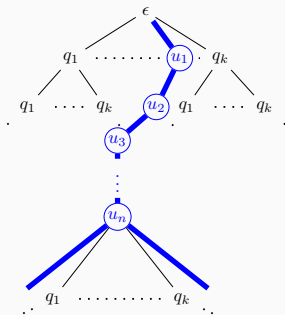
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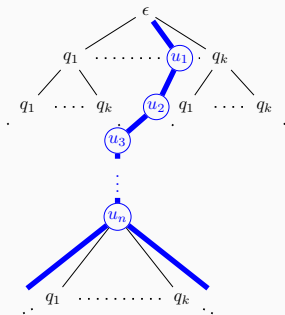


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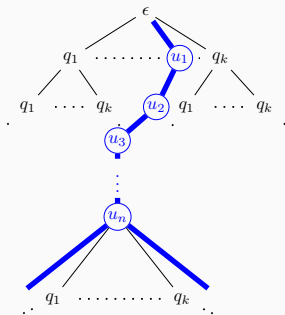
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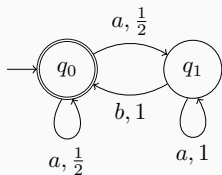
$$\mu_\alpha(\text{Acc}_{\text{Büchi}}(F)) > 0$$

- almost-sure:

$$\mu_\alpha(\text{Acc}_{\text{Büchi}}(F)) = 1$$

# Probabilistic Automata - Examples

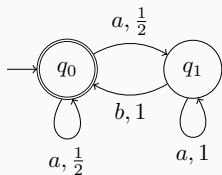
## Positive Acceptance



$$\underbrace{\left\{ a^{k_1} b a^{k_2} b \cdots : \begin{array}{l} k_i > 0 \text{ for all } i > 0, \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) > 0 \end{array} \right\}}_{\mathcal{L}_1}$$

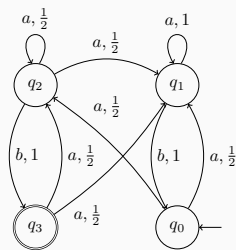
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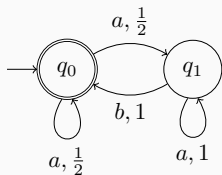
## Almost-Sure Acceptance



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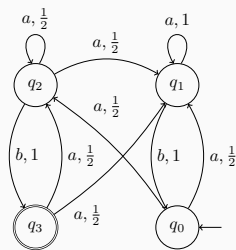
# Probabilistic Automata - Examples

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$$\overline{\mathcal{L}_1} = \mathcal{L}_2 \cup \underbrace{b\Sigma^\omega + \Sigma^*bb\Sigma^\omega + \Sigma^*a^\omega}_{\omega\text{-regular}}$$

# Probabilistic Automata - Properties

Positive Acceptance

Almost-Sure Acceptance



# Probabilistic Automata - Properties

## Positive Acceptance

- strictly subsumes  $\omega$ -regular

## Almost-Sure Acceptance

# Probabilistic Automata - Properties

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- **strictly** subsumes  $\omega$ -regular

## Almost-Sure Acceptance

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# Probabilistic Automata - Properties

## Positive Acceptance

- strictly subsumes  $\omega$ -regular
- recognizable languages form Boolean-algebra

## Almost-Sure Acceptance

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## Almost-Sure Acceptance

- incomparable with  $\omega$ -regular

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- undecidable emptiness

$$\{\alpha \in \{a, b\}^\omega \mid a \notin \text{Inf}(\alpha)\}$$

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$$\begin{aligned} & \overline{\left\{ a^{k_1} b a^{k_2} b \dots : \begin{array}{l} k_i > 0 \text{ for all } i > 0, \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) > 0 \end{array} \right\}} \\ &= \left\{ a^{k_1} b a^{k_2} b \dots : \begin{array}{l} k_i > 0 \text{ for all } i > 0 \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) = 0 \end{array} \right\} \\ & \cup b\Sigma^\omega + \Sigma^* b b \Sigma^\omega + \Sigma^* a^\omega \end{aligned}$$

# Probabilistic Automata - Properties

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## Positive Acceptance

- strictly subsumes  $\omega$ -regular
- recognizable languages form Boolean-algebra
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## Almost-Sure Acceptance

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- decidable emptiness
- **Parity**-condition coincides with positive acceptance of Büchi- or Parity-condition

# Tree-Automata

## Definition

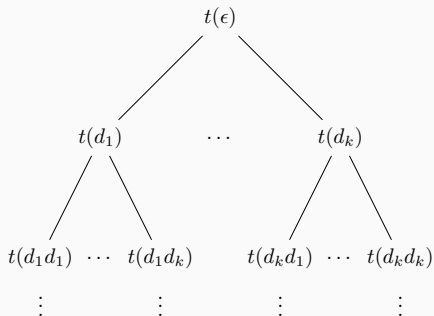
$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$

- $Q$ : finite state set
- $q_0 \in Q$ : initial state
- $D$ : finite set of directions
- $\Sigma$ : finite alphabet
- $\Delta$ : finite set of transitions
- $\text{Acc}$ : accepted language

# Definition

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$

$D$ -ary  $\Sigma$ -tree:  $t : D^* \rightarrow \Sigma$

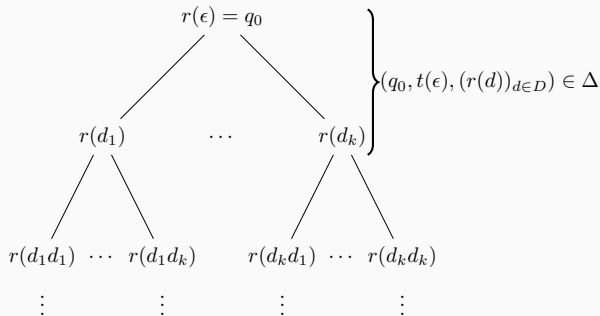


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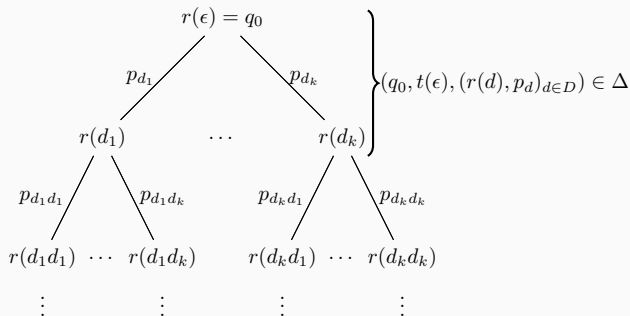


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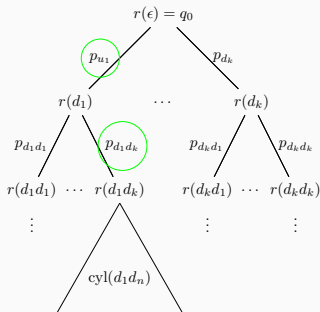


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$$(D^\omega, \mathcal{B}(D), \mu_r) \Rightarrow \mu_r(\{\rho \in D^\omega \mid r(\rho) \in \text{Acc}\})$$

## Tree Automata - Example

$$\mathcal{A} = (Q = \{q_a, q_b\}, q_a, D = \{0, 1\}, \Sigma = \{a, b\}, \Delta, F = \{q_a\})$$



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$$\Delta = \left\{ (q, \sigma, q_\sigma, q_\sigma) : \substack{q \in Q, \\ \sigma \in \{a, b\}} \right\} \text{ or } \left\{ \left( q, \sigma, q_\sigma, \frac{1}{2}, q_\sigma, \frac{1}{2} \right) : \substack{q \in Q, \\ \sigma \in \{a, b\}} \right\}$$

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$$\mathcal{L} = \left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} A_\infty^t = D^\omega \end{array} \right\} \text{ or } \left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} \mu_{\frac{1}{2}}(A_\infty^t) = 1 \ (\mu_{\frac{1}{2}}(A_\infty^t) > 0) \end{array} \right\}$$

where

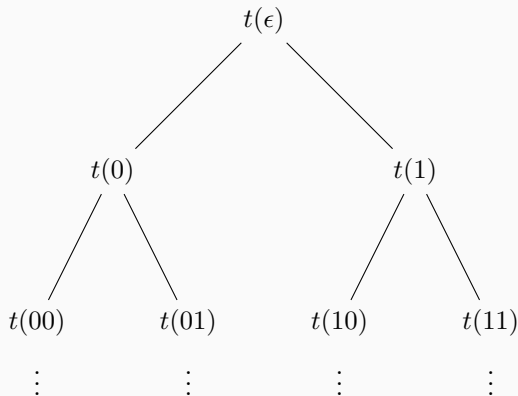
$$A_\infty^t = \{\alpha_1 \alpha_2 \cdots \in D^\omega \mid a \in \text{Inf}(t(\epsilon) t(\alpha_1) t(\alpha_1 \alpha_2) \dots)\}$$

## Alternating Tree Automata - Definition

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$

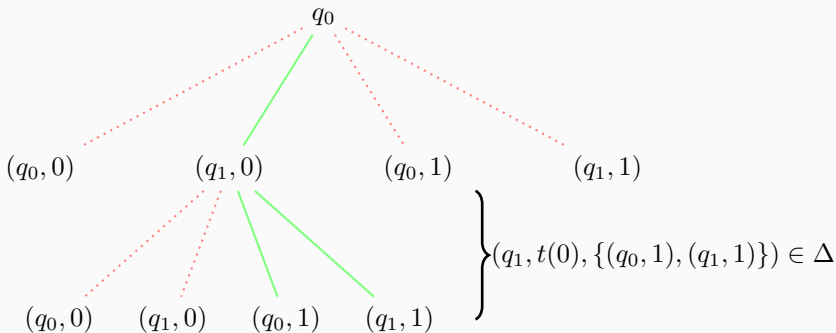
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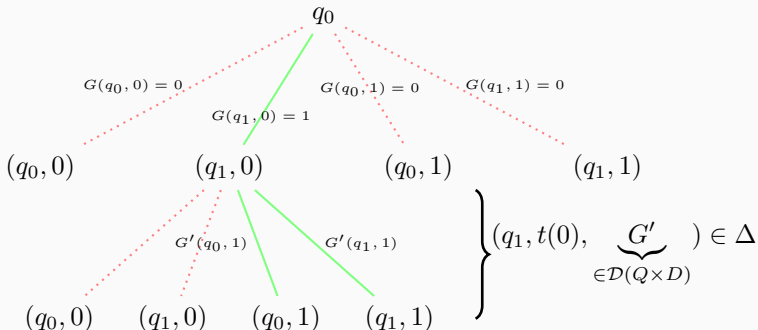
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$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$



$$\Rightarrow ((Q \times D)^\omega, \mathcal{B}(Q \times D), \mu_r)$$

## Alternating Tree Automaton - Example

$$\left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} \text{there is } u \in \{0, 1\}^* \\ \text{with } t(u) = a \end{array} \right\}$$

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$q_s, q_f$

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- non-deterministically move

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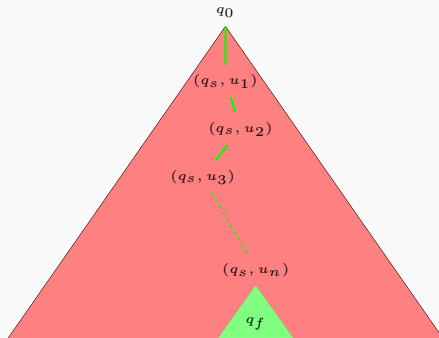
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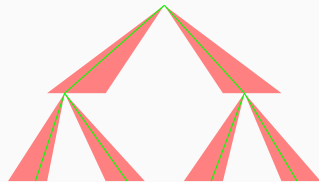
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# Weighted Descent Tree Automata - Structural Properties

choiceless (c.l.):  $|\{G:(q,\sigma,G)\in\Delta\}|=1$   
for all  $q\in Q, \sigma\in\Sigma$

uni-directional (u.d.):  
for every  $G\in\mathcal{G}(\mathcal{A}), d\in D$   
exists *at most one*  $p\in Q$   
with  $G(d,p)>0$



## **Theorem (Simulation Theorem)**

*There is an effective construction which, when given an APTA, produces an equivalent PTA. Furthermore, given an ABTA, there is a way to effectively construct an equivalent BTA.*

- recognizable languages form a Boolean-algebra
- decidable emptiness

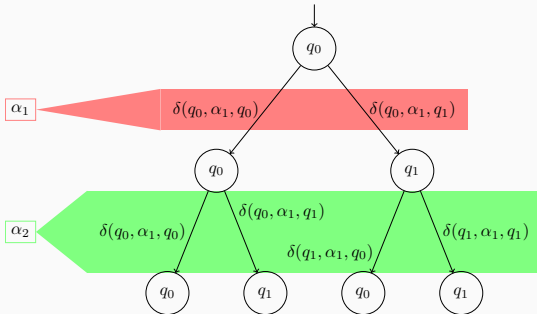
# Weighted Descent Tree Automata - Word-Automata

for unary trees:

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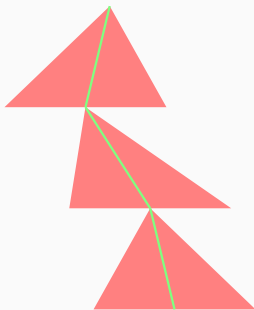
- c.l. WDTAs “equivalent” to PPAs



# Weighted Descent Tree Automata - Word-Automata

for unary trees:

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- u.d. WDTAs “equivalent” to  $\omega$ -regular





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- $\Rightarrow$  undecidable emptiness for (c.l.) WDTAs with positive Büchi-acceptance and almost-sure Parity-acceptance

# Weighted Descent Tree Automata - Word-Automata

for unary trees:

- c.l. WDTAs “equivalent” to PPAs
  - u.d. WDTAs “equivalent” to  $\omega$ -regular
- ⇒ undecidable emptiness for (c.l.) WDTAs with positive Büchi-acceptance and almost-sure Parity-acceptance
- ⇒ Simulation Theorem does not translate to WDTAs

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

# Partially Observable Markov Decision Processes

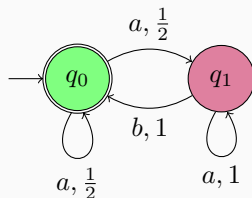
$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

- $S$ : finite state set
- $s_0 \in S$ : initial state
- $A$ : finite state of actions
- $\tau_a \in \mathcal{D}(S \times S)$ : transition probabilities
- $\sim$ : observable equivalence classes
- strategy  $f : [S]_{\sim}^* \rightarrow A$

$$\Rightarrow (S^{\omega}, \mathcal{B}(S), \mu_f)$$

# Partially Observable Markov Decision Processes

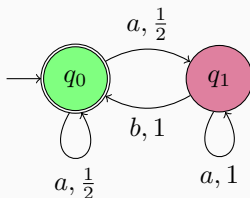
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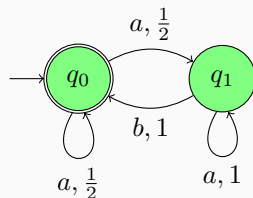
$$f(\epsilon) = a$$
$$f(p_1 \dots p_n) = \begin{cases} a & \text{if } p_n = q_0, \\ b & \text{otherwise.} \end{cases}$$



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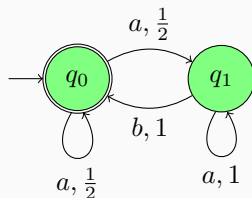
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# Partially Observable Markov Decision Processes

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

$\mu_f(\text{Acc}_{\text{Büchi}}(F)) > 0$  if and only if  $f \in \mathcal{L}(\mathcal{P})$ .





# Partially Observable Markov Decision Processes

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

Computing Strategies	Fully observable	Partially observable
Positive Büchi	PTIME	Undecidable
Almost-Sure Büchi	PTIME	EXPTIME
Positive Parity	PTIME	Undecidable
Almost-Sure Parity	PTIME	Undecidable

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{par}) \text{ and } \mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

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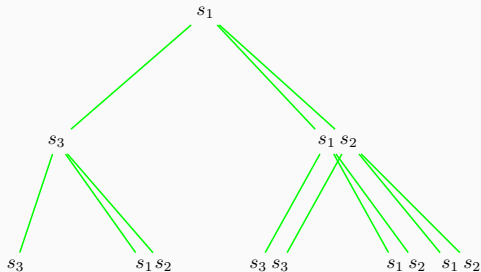
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# WDTAs and POMDPs

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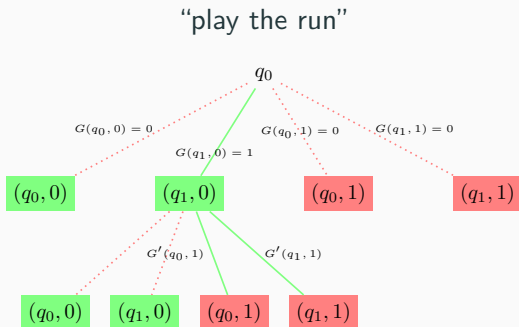
“directions are observations”



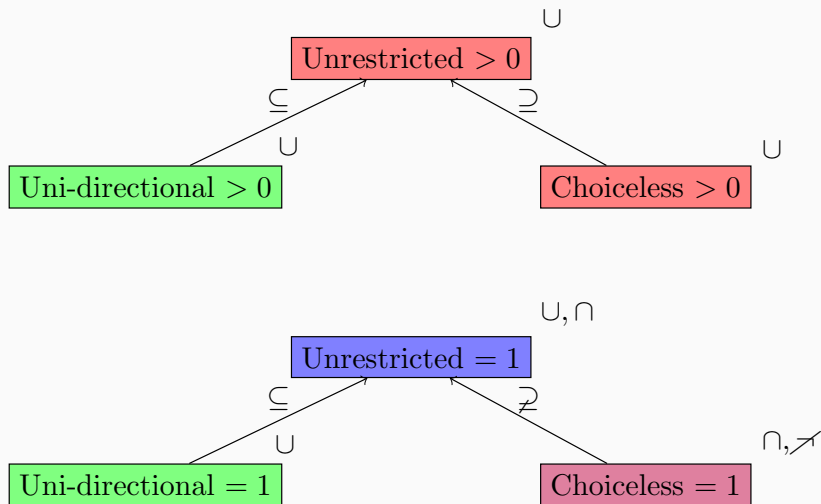
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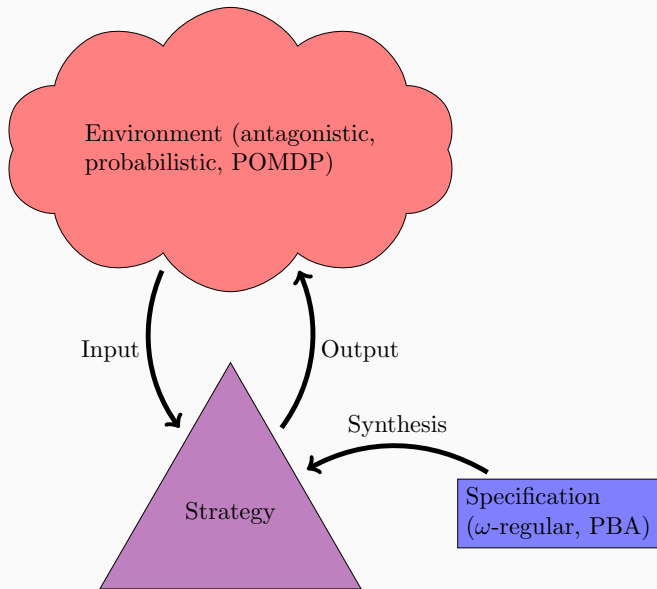


# Weighted Descent Tree Automata - Overview



# Synthesis

# Setting





## Definition (Synthesis Problem)

Given a logic  $\mathbb{L}$ . Compute for every formula  $\phi(\cdot, \cdot) \in \mathbb{L}$  over inputs  $I$  and outputs  $J$  an algorithm  $S : I^+ \rightarrow J$  such that  $\phi(\alpha, S(\alpha_1)S(\alpha_1\alpha_2)\dots)$  is true for all  $\alpha_1\alpha_2\dots \in I^\omega$  or prove that such an  $S$  cannot exist.

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$$(j_0, i_0) (j_1, i_1) \dots \in \mathcal{L}_\phi \text{ iff } \phi(i_0 i_1 \dots, j_1 j_2 \dots) \text{ is true.}$$

## Antagonistic Environment - $\omega$ -regular Specification

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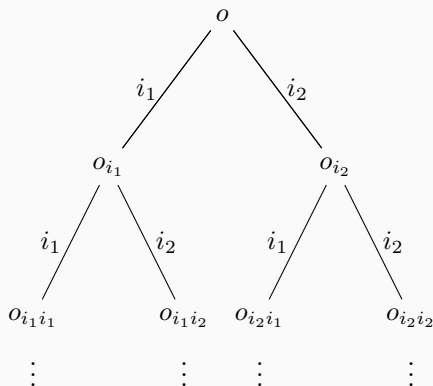
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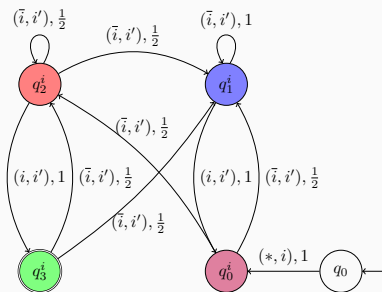
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$a$ : last input differs from current output  
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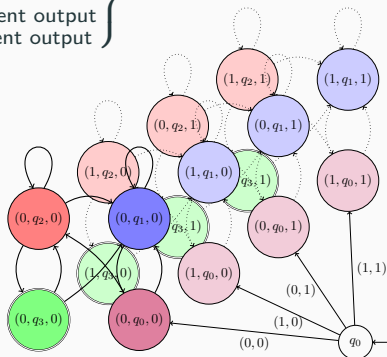
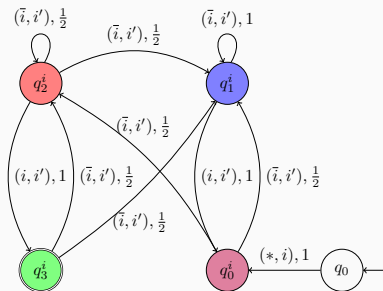


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## Definition

Given a POMDP  $\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$  and a specification  $\phi \subseteq S^\omega$  such that  $\phi \in \mathcal{B}(S)$ . The qualitative synthesis problem  $(\mathcal{S}, \phi)$  demands the computation of a strategy  $s : [S]_\sim^* \rightarrow A$  such that  $\mu_s(\phi) = 1$ .



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Computing Strategies	Fully observable	Partially observable
Positive Büchi	PTIME	Undecidable
Almost-Sure Büchi	PTIME	EXPTIME
Positive Parity	PTIME	Undecidable
Almost-Sure Parity	PTIME	Undecidable

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## Definition

Given  $(\Omega_1, \mathcal{F}_1)$ ,  $(\Omega_2, \mathcal{F}_2)$ , then  $K : \Omega_1 \times \mathcal{F}_2 \rightarrow [0, 1]$  is a Markov-kernel if

1.  $K(\cdot, A)$  is measurable in  $\mathcal{F}_1$  for all  $A \in \mathcal{F}_2$ ,
2.  $K(\omega, \cdot)$  is a probability measure on  $(\Omega_2, \mathcal{F}_2)$  for every  $\omega \in \Omega_1$ .



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- for a strategy  $s$ :  $\int_{\alpha \in S^\omega} K(\alpha, \text{Acc}_{\text{Büchi}}(F)) d\mu_s = 1$  iff  $\mu_\alpha(\text{Acc}_{\text{Büchi}}(F)) = 1$  for almost all  $\alpha$

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- $\Rightarrow$  induces product construction for  $\mathcal{S}$  and  $\mathcal{P}$

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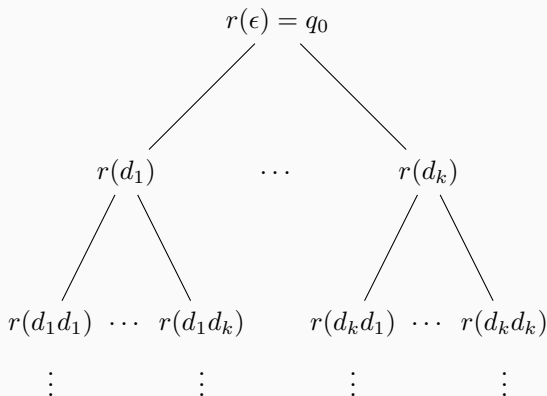
$\Rightarrow$  almost-surely accepting strategy in  $\mathcal{S} \otimes \mathcal{P}$  is qualitatively “good” for  $\mathcal{S}$  with specification  $\mathcal{P}$

## **Conclusion**

- Introduction of WDTAs
- Synthesis for antagonistic environment for almost-sure accepting PBAs in doubly exponential time
- Synthesis for POMDP for almost-sure accepting PBAs in exponential time
- \* Co-operative POSG as emptiness games for unrestricted WDTAs
- \* Strategy computation for  $EVE$  in equally informed POSG

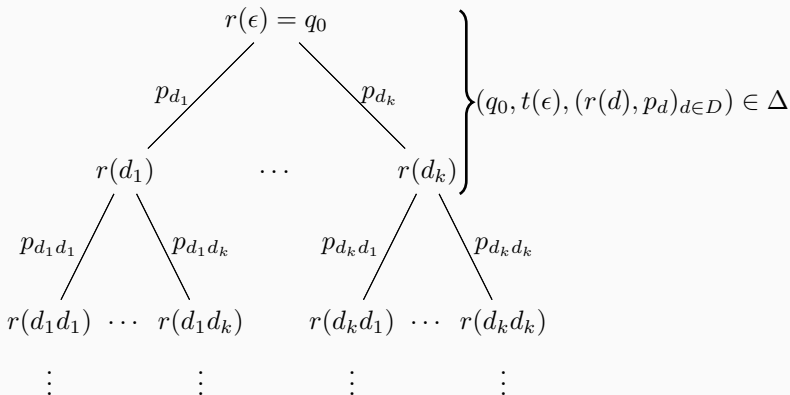
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- non-deterministically construct run
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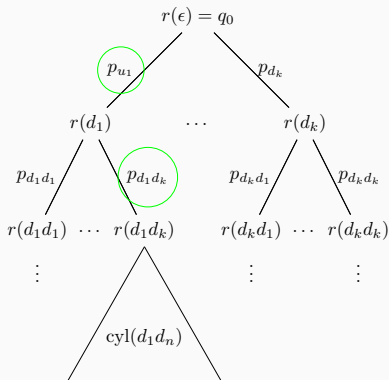
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$$\mu_r(\text{cyl}(u_1 \dots u_n)) = \prod_{1 \leq i \leq n} p_{u_1 \dots u_i}$$

$$\Rightarrow (D^\omega, \mathcal{B}(D), \mu_r)$$

with

$$\mu_r(\{\rho \in D^\omega \mid r(\rho) \in \text{Acc}\})$$





## Weighted Descent Tree Automata - Definition

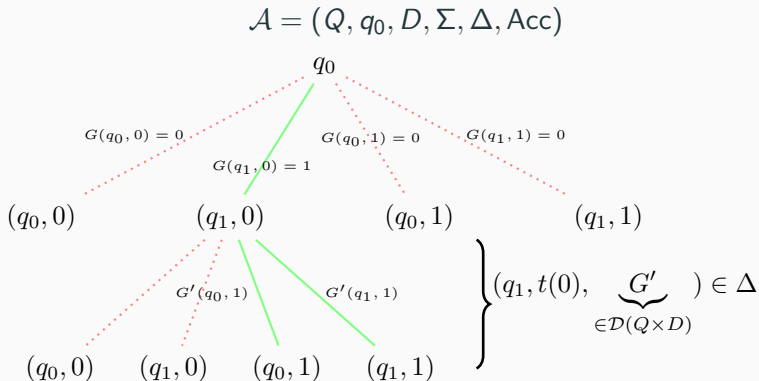
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- $Q$ : finite state set
- $q_0 \in Q$ : initial state
- $D$ : finite set of directions
- $\Sigma$ : finite alphabet
- $\Delta$ : transitions of the form  $(q, \sigma, G)$
- $\text{Acc}$ : accepted language

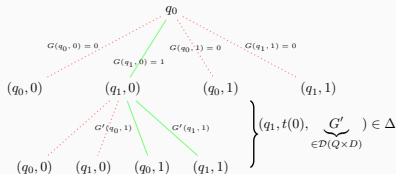
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$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc})$$

- run:  $Q \times D$ -ary  $\mathcal{G}(\mathcal{A})$ -tree
- $\Rightarrow ((Q \times D)^\omega, \mathcal{B}(Q \times D), \mu_r)$



$$\text{Acc}[Q] = \{(d_1, q_1)(d_2, q_2) \cdots \in (D \times Q)^\omega \mid q_1 q_2 \cdots \in \text{Acc}\}$$

and

$$\mu_r(\text{Acc}[Q]) > 0 \text{ or } \mu_r(\text{Acc}[Q]) = 1$$

# Tree Automata - Example

$$\mathcal{L} = \left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} a \notin \text{Inf}(t(\epsilon)t(\alpha_1)t(\alpha_1\alpha_2)\dots) \\ \text{for all } \alpha_1\alpha_2\dots \in \{0, 1\}^\omega \end{array} \right\}$$

- Parity-condition ✓
- Büchi-condition ✗

$$\mathcal{A} = (\{q_a, q_b\}, q_a, \{0, 1\}, \{a, b\}, \\ \Delta, \{q_a \mapsto 1, q_b \mapsto 0\})$$

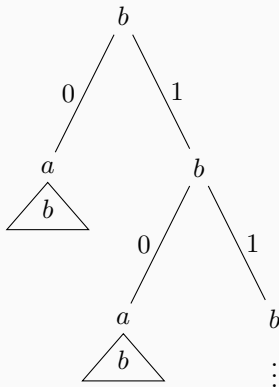
with

$$\Delta = \left\{ (q, \sigma, q_\sigma, q_\sigma) : \begin{array}{l} q \in Q, \\ \sigma \in \{a, b\} \end{array} \right\}$$

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$$(Q, J \times I, \delta, q_0, F) \Rightarrow (S, s_0, E, A, (\tau_{e,a})_{e \in E, a \in A}, \sim_E, \sim_A, F')$$

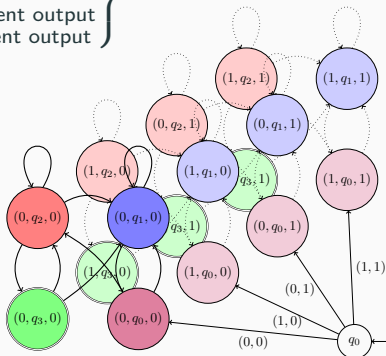
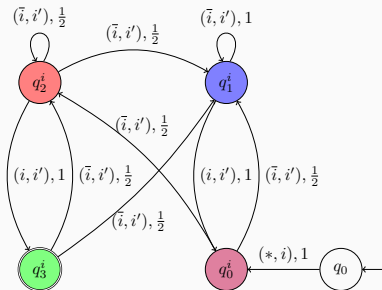
- “input-/output-game with unobservable stochastic background”
- $S = I \times Q \times J \cup \{q_0\}$  with  $s_0 = q_0$
- $E = J, A = I$
- $\tau_{j,i}((a, q, e), (i', p, j')) = \begin{cases} \delta(q, (i, j), p) & \text{if } i' = i, j' = j, \\ 0 & \text{otherwise.} \end{cases}$
- $\sim_E = \sim_A = \left\{ ((i, q, j), (i, p, j)) : \begin{array}{l} i \in I, j \in J, q, p \in Q \end{array} \right\}$
- $F' = I \times F \times J$



# Antagonistic Environment - PBA Specification

$$(Q, J \times I, \delta, q_0, F) \Rightarrow (S, s_0, E, A, (\tau_{e,a})_{e \in E, a \in A}, \sim_E, \sim_A, F')$$

$$\left\{ \begin{array}{l} a^{k_1} b a^{k_2} b \dots : \\ \begin{array}{l} k_i > 0 \text{ for all } i > 0 \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) = 0 \\ a: \text{last input differs from current output} \\ b: \text{last input is equal to current output} \end{array} \end{array} \right\}$$



# POMDP - PBA Specification

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim) \text{ and } \mathcal{P} = (Q, S, \delta, q_0, F)$$

$$\alpha \in S^\omega \Rightarrow (Q, \mathcal{B}(Q), \mu_s)$$

## Definition

Given  $(\Omega_1, \mathcal{F}_1)$ ,  $(\Omega_2, \mathcal{F}_2)$ , then  $K : \Omega_1 \times \mathcal{F}_2 \rightarrow [0, 1]$  is a Markov-kernel if

1.  $K(\cdot, A)$  is measurable in  $\mathcal{F}_1$  for all  $A \in \mathcal{F}_2$ ,
2.  $K(\omega, \cdot)$  is a probability measure on  $(\Omega_2, \mathcal{F}_2)$  for every  $\omega \in \Omega_1$ .

# POMDP - PBA Specification

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim) \text{ and } \mathcal{P} = (Q, S, \delta, q_0, F)$$

$$K : S^\omega \times \mathcal{B}(Q) \rightarrow [0, 1] \text{ with } K(\alpha, A) = \mu_\alpha(A)$$

- for a strategy  $s$ :  $\int_{\alpha \in S^\omega} K(\alpha, \text{Acc}_{\text{Büchi}}(Q)) d\mu_s = 1$  iff  
 $\mu_\alpha(\text{Acc}_{\text{Büchi}}(Q)) = 1$  for almost all  $\alpha$ .
  - measure  $\mu_s \otimes K$  on  $(S^\omega \times Q^\omega, \mathcal{B}(S) \otimes \mathcal{B}(Q))$  uniquely determined by  $\int_{\text{cyl}(u)} K(\cdot, \text{cyl}(v)) d\mu_s$
  - $\int_{\text{cyl}(u)} K(\cdot, \text{cyl}(v)) d\mu_s = \mu_s(\text{cyl}(u)) \cdot \mu_u(\text{cyl}(v))$  for  $|u| = |v|$
- $\Rightarrow$  induces product construction for  $\mathcal{S}$  and  $\mathcal{P}$

# POMDP - PBA Specification

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim) \text{ and } \mathcal{P} = (Q, S, \delta, q_0, F)$$

$$\mathcal{S} \otimes \mathcal{P} = (S \times Q, (q_0, s_0), A, (\tau'_a)_{a \in A}, \sim')$$

- $\tau'_a((s, q), (z, p)) = \tau_a(s, z) \cdot \delta(p, s, q)$
- $(s, q) \sim' (z, p)$  iff  $s \sim z$

$\Rightarrow$  strategies can be translated from  $\mathcal{S}$  to  $\mathcal{S} \otimes \mathcal{P}$

$$\Rightarrow \mu_s(\text{AccBüchi}(S \times F)) = \int_{S^\omega} K(\cdot, \text{AccBüchi}(F)) d\mu_s$$

$\Rightarrow$  almost-surely accepting strategy in  $\mathcal{S} \otimes \mathcal{P}$  is qualitatively “good” for  $\mathcal{S}$  with specification  $\mathcal{P}$