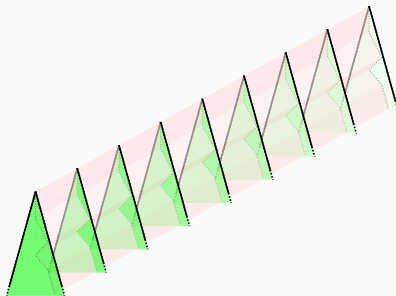


Automata-theoretic Synthesis for Probabilistic Environments

Christoph Welzel

July 31, 2018

Informatik 7, RWTH Aachen



Word-Automata

Theorem

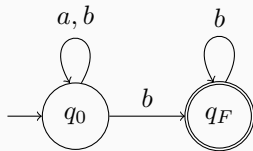
The class of recognizable languages coincides for NBAs, NPAs and DPAs and is called ω -regular languages. DBAs are strictly less expressive.

$$\mathcal{L} = \{\alpha \in \{a, b\}^\omega \mid a \notin \text{Inf}(\alpha)\}$$

Theorem

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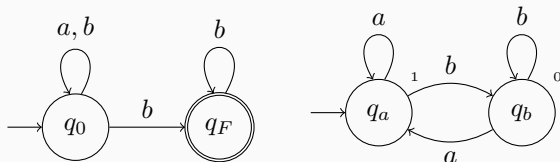


ω -regular Languages

Theorem

The class of recognizable languages coincides for NBAs, *NPA*s and *DPA*s and is called ω -regular languages. *DBA*s are strictly less expressive. *However, NBA-determinisation is inherently costly ($> n!$).*

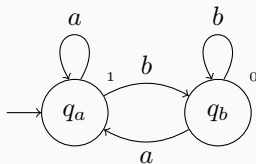
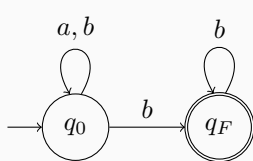
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Theorem

The class of recognizable languages coincides for NBAs, NPAs and DPAs and is called ω -regular languages. DBAs are strictly less expressive. However, NBA-determinisation is inherently costly ($> n!$).

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b^ω ,
 $b^{n_0}ab^\omega$,
 $b^{n_0}ab^{n_1}ab^\omega$,
 \vdots

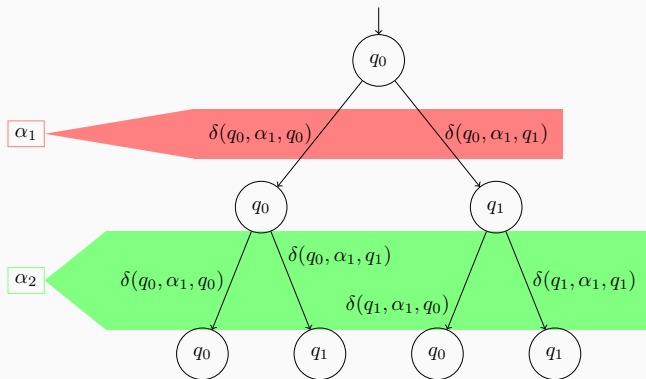
Probabilistic Büchi Automata

$$\mathcal{A} = (Q, \Sigma, \delta : Q \times \Sigma \times Q \rightarrow [0, 1], q_0, F)$$

- Q : finite state set
- Σ : finite alphabet
- $q_0 \in Q$: initial state
- $\delta : Q \times \Sigma \times Q \rightarrow [0, 1]$: transition probability function
- $F \subseteq Q$: final states

Probabilistic Büchi Automata

$$\mathcal{A} = (Q, \Sigma, \delta : Q \times \Sigma \times Q \rightarrow [0, 1], q_0, F)$$



Probabilistic Büchi Automata

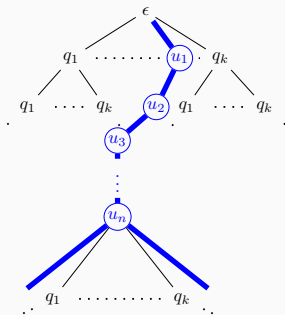
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- cylindric sets:

$$\text{cyl}(u) = \{u \cdot \alpha : \alpha \in Q^\omega\}$$

- α induces probability space

$$(Q^\omega, \mathcal{B}(Q), \mu_\alpha)$$

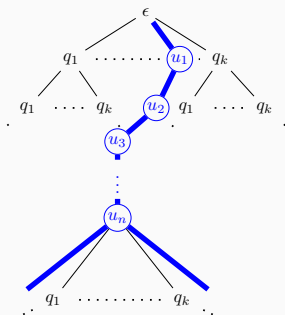


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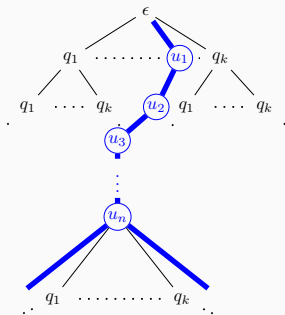
$$\mu_\alpha(\text{Acc}_{\text{Büchi}}(F)) > 0$$

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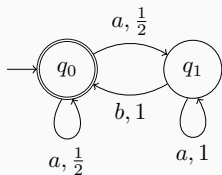
$$\mu_\alpha(\text{Acc}_{\text{Büchi}}(F)) > 0$$

- almost-sure:

$$\mu_\alpha(\text{Acc}_{\text{Büchi}}(F)) = 1$$

Probabilistic Automata - Examples

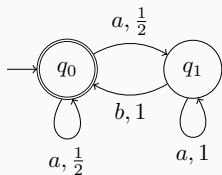
Positive Acceptance



$$\underbrace{\left\{ a^{k_1} b a^{k_2} b \cdots : \begin{array}{l} k_i > 0 \text{ for all } i > 0, \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) > 0 \end{array} \right\}}_{\mathcal{L}_1}$$

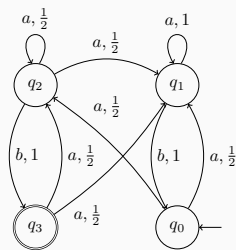
Probabilistic Automata - Examples

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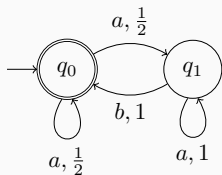
Almost-Sure Acceptance



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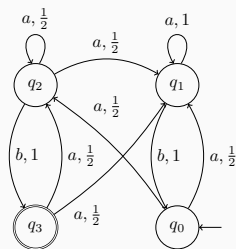
Probabilistic Automata - Examples

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$$\overline{\mathcal{L}_1} = \mathcal{L}_2 \cup \underbrace{b\Sigma^\omega + \Sigma^*bb\Sigma^\omega + \Sigma^*a^\omega}_{\omega\text{-regular}}$$

Probabilistic Automata - Properties

Positive Acceptance

Almost-Sure Acceptance

Probabilistic Automata - Properties

Positive Acceptance

- strictly subsumes ω -regular

Almost-Sure Acceptance

Probabilistic Automata - Properties

Positive Acceptance

- **strictly** subsumes ω -regular

Almost-Sure Acceptance

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Probabilistic Automata - Properties

Positive Acceptance

- strictly subsumes ω -regular
- recognizable languages form Boolean-algebra

Almost-Sure Acceptance

Probabilistic Automata - Properties

Positive Acceptance

- strictly subsumes ω -regular
- recognizable languages form Boolean-algebra
- undecidable emptiness

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Almost-Sure Acceptance

- incomparable with ω -regular

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$$\{\alpha \in \{a, b\}^\omega \mid a \notin \text{Inf}(\alpha)\}$$

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$$\begin{aligned} & \overline{\left\{ a^{k_1} b a^{k_2} b \dots : \begin{array}{l} k_i > 0 \text{ for all } i > 0, \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) > 0 \end{array} \right\}} \\ &= \left\{ a^{k_1} b a^{k_2} b \dots : \begin{array}{l} k_i > 0 \text{ for all } i > 0 \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) = 0 \end{array} \right\} \\ & \cup b\Sigma^\omega + \Sigma^* b b \Sigma^\omega + \Sigma^* a^\omega \end{aligned}$$

Probabilistic Automata - Properties

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Probabilistic Automata - Properties

Positive Acceptance

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- recognizable languages form Boolean-algebra
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Almost-Sure Acceptance

- incomparable with ω -regular
- decidable emptiness
- **Parity**-condition coincides with positive acceptance of Büchi- or Parity-condition

Tree-Automata

Definition

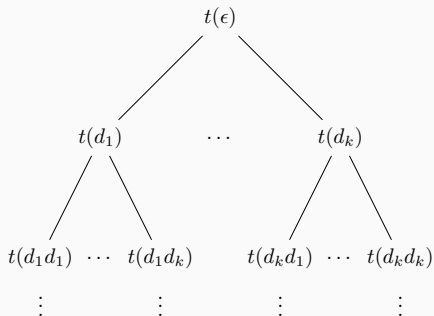
$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$

- Q : finite state set
- $q_0 \in Q$: initial state
- D : finite set of directions
- Σ : finite alphabet
- Δ : finite set of transitions
- Acc : accepted language

Definition

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$

D -ary Σ -tree: $t : D^* \rightarrow \Sigma$

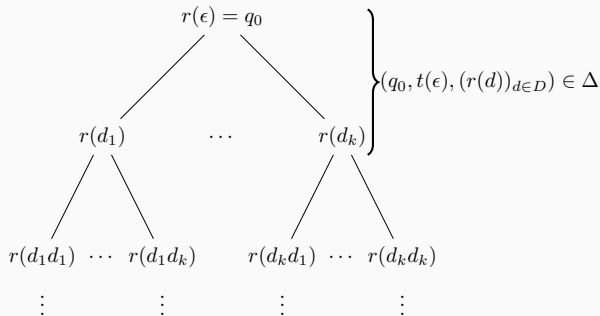


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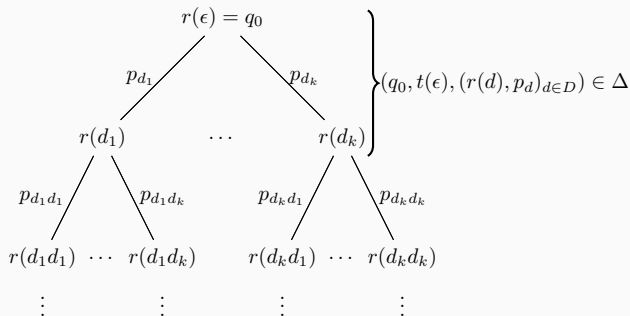


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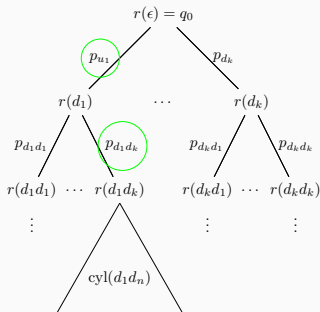


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D -ary Q -run: $r : D^* \rightarrow Q$



$$(D^\omega, \mathcal{B}(D), \mu_r) \Rightarrow \mu_r(\{\rho \in D^\omega \mid r(\rho) \in \text{Acc}\})$$

Tree Automata - Example

$$\mathcal{A} = (Q = \{q_a, q_b\}, q_a, D = \{0, 1\}, \Sigma = \{a, b\}, \Delta, F = \{q_a\})$$

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$$\Delta = \left\{ (q, \sigma, q_\sigma, q_\sigma) : \substack{q \in Q, \\ \sigma \in \{a, b\}} \right\} \text{ or } \left\{ \left(q, \sigma, q_\sigma, \frac{1}{2}, q_\sigma, \frac{1}{2} \right) : \substack{q \in Q, \\ \sigma \in \{a, b\}} \right\}$$

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$$\mathcal{L} = \left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} A_\infty^t = D^\omega \end{array} \right\} \text{ or } \left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} \mu_{\frac{1}{2}}(A_\infty^t) = 1 \ (\mu_{\frac{1}{2}}(A_\infty^t) > 0) \end{array} \right\}$$

where

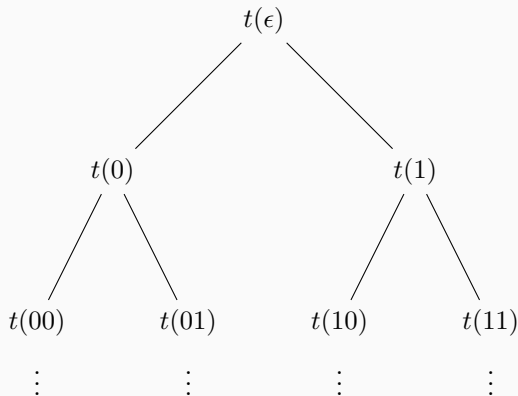
$$A_\infty^t = \{\alpha_1 \alpha_2 \cdots \in D^\omega \mid a \in \text{Inf}(t(\epsilon) t(\alpha_1) t(\alpha_1 \alpha_2) \dots)\}$$

Alternating Tree Automata - Definition

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$

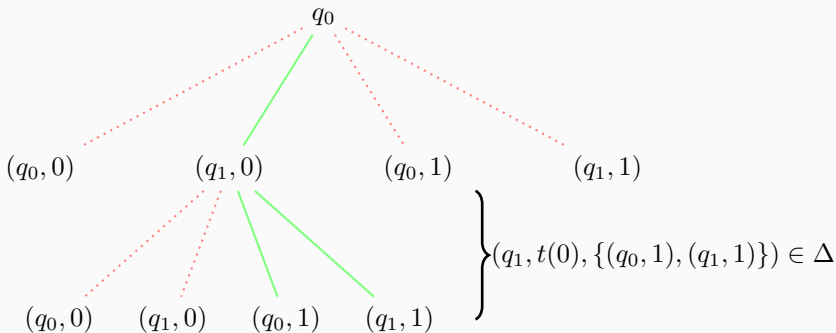
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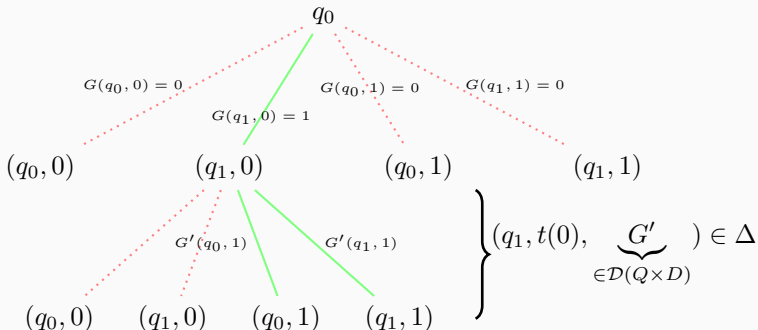
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Alternating Tree Automata - Definition

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc} \subseteq Q^\omega)$$



$$\Rightarrow ((Q \times D)^\omega, \mathcal{B}(Q \times D), \mu_r)$$

Alternating Tree Automaton - Example

$$\left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} \text{there is } u \in \{0, 1\}^* \\ \text{with } t(u) = a \end{array} \right\}$$

- search and found state:

q_s, q_f

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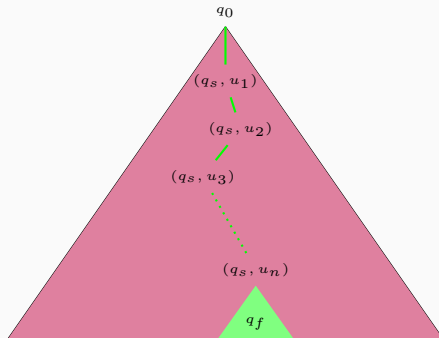
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- use $\{q_f\}$ as Büchi-condition

Alternating Tree Automaton - Example

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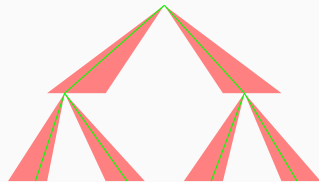
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Weighted Descent Tree Automata - Structural Properties

choiceless (c.l.): $|\{G:(q,\sigma,G)\in\Delta\}|=1$
for all $q\in Q, \sigma\in\Sigma$

uni-directional (u.d.):
for every $G\in\mathcal{G}(\mathcal{A}), d\in D$
exists *at most one* $p\in Q$
with $G(d,p)>0$



Theorem (Simulation Theorem)

There is an effective construction which, when given an APTA, produces an equivalent PTA. Furthermore, given an ABTA, there is a way to effectively construct an equivalent BTA.

- recognizable languages form a Boolean-algebra
- decidable emptiness

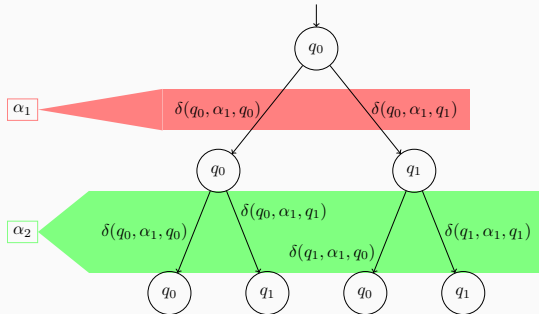
Weighted Descent Tree Automata - Word-Automata

for unary trees:

Weighted Descent Tree Automata - Word-Automata

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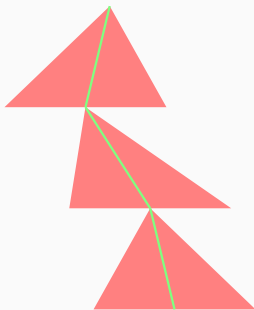
- c.l. WDTAs “equivalent” to PPAs



Weighted Descent Tree Automata - Word-Automata

for unary trees:

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Weighted Descent Tree Automata - Word-Automata

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- \Rightarrow undecidable emptiness for (c.l.) WDTAs with positive Büchi-acceptance and almost-sure Parity-acceptance

Weighted Descent Tree Automata - Word-Automata

for unary trees:

- c.l. WDTAs “equivalent” to PPAs
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- \Rightarrow undecidable emptiness for (c.l.) WDTAs with positive Büchi-acceptance and almost-sure Parity-acceptance
- \Rightarrow Simulation Theorem does not translate to WDTAs

Partially Observable Markov Decision Processes

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

Partially Observable Markov Decision Processes

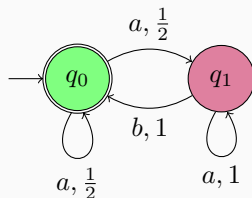
$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

- S : finite state set
- $s_0 \in S$: initial state
- A : finite state of actions
- $\tau_a \in \mathcal{D}(S \times S)$: transition probabilities
- \sim : observable equivalence classes
- strategy $f : [S]_{\sim}^* \rightarrow A$

$$\Rightarrow (S^\omega, \mathcal{B}(S), \mu_f)$$

Partially Observable Markov Decision Processes

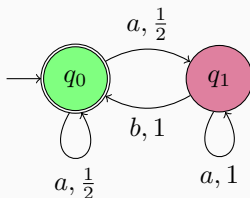
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Partially Observable Markov Decision Processes

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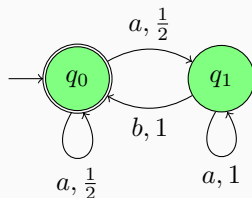
$$f(\epsilon) = a$$
$$f(p_1 \dots p_n) = \begin{cases} a & \text{if } p_n = q_0, \\ b & \text{otherwise.} \end{cases}$$



Partially Observable Markov Decision Processes

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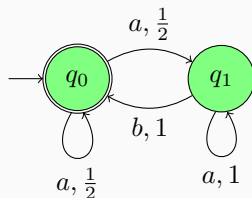
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Partially Observable Markov Decision Processes

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

$\mu_f(\text{Acc}_{\text{Büchi}}(F)) > 0$ if and only if $f \in \mathcal{L}(\mathcal{P})$.



Partially Observable Markov Decision Processes

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

Computing Strategies	Fully observable	Partially observable
Positive Büchi	PTIME	Undecidable
Almost-Sure Büchi	PTIME	EXPTIME
Positive Parity	PTIME	Undecidable
Almost-Sure Parity	PTIME	Undecidable

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{par}) \text{ and } \mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

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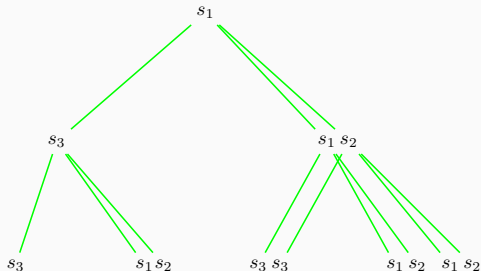
- strategies are
[S]_~-ary A-trees

WDTAs and POMDPs

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{par}) \text{ and } \mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$$

- strategies are $[S]_{\sim}$ -ary A -trees
- translate POMDP to c.l. WDTAs

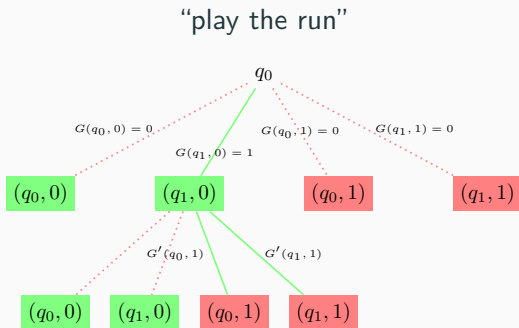
“directions are observations”



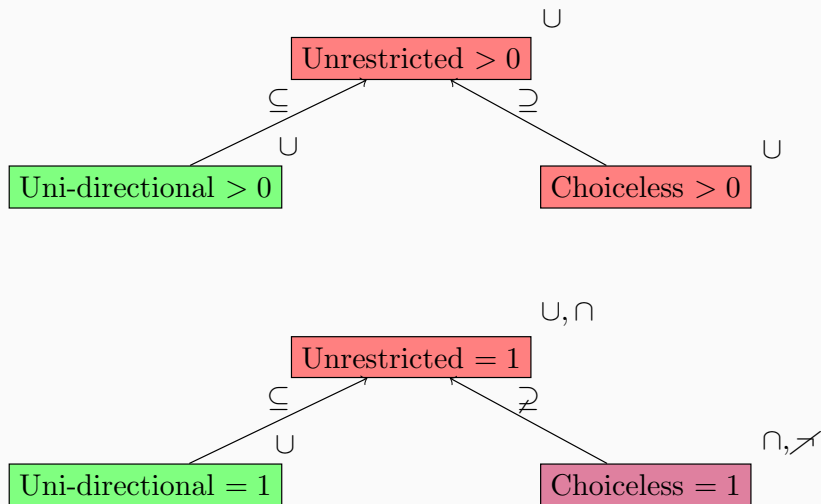
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- strategies are $[S]_{\sim}$ -ary A -trees
- translate POMDP to c.l. WDTAs
- use POMDPs as emptiness game for c.l. WDTAs

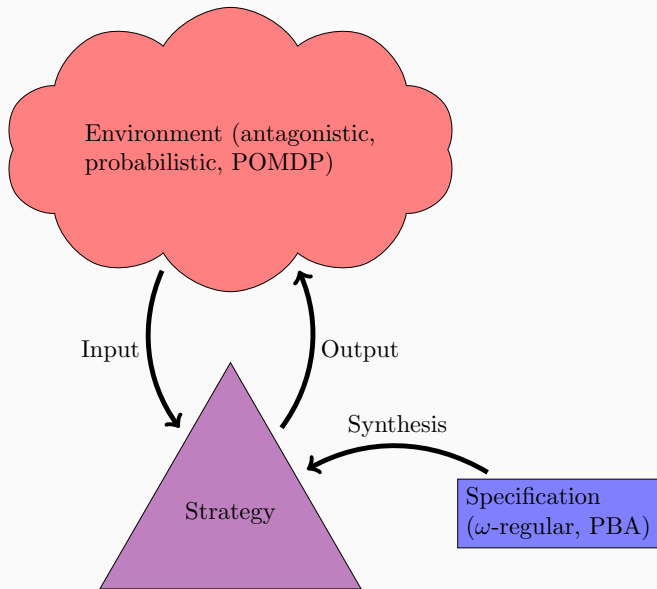


Weighted Descent Tree Automata - Overview



Synthesis

Setting



Definition (Synthesis Problem)

Given a logic \mathbb{L} . Compute for every formula $\phi(\cdot, \cdot) \in \mathbb{L}$ over inputs I and outputs J an algorithm $S : I^+ \rightarrow J$ such that $\phi(\alpha, S(\alpha_1)S(\alpha_1\alpha_2)\dots)$ is true for all $\alpha_1\alpha_2\dots \in I^\omega$ or prove that such an S cannot exist.

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$$(j_0, i_0) (j_1, i_1) \dots \in \mathcal{L}_\phi \text{ iff } \phi(i_0 i_1 \dots, j_1 j_2 \dots) \text{ is true.}$$

Antagonistic Environment - ω -regular Specification

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with

$$\Delta = \left\{ (q, i, (\delta(q, (i, j)))_{j \in J}) : \right. \\ \left. q \in Q, i \in I \right\}$$

Antagonistic Environment - ω -regular Specification

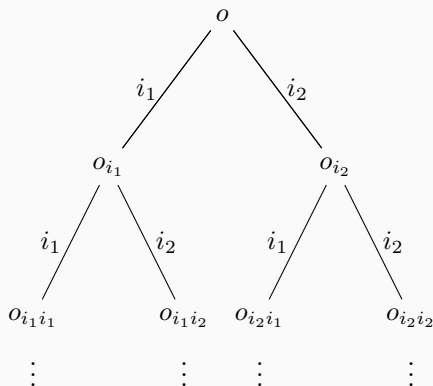
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Antagonistic Environment - PBA Specification

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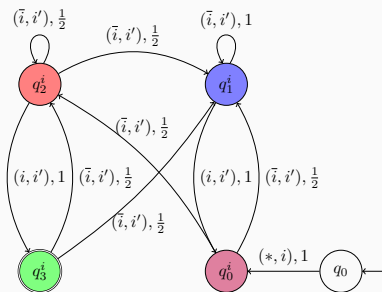
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“input-/output-game with unobservable stochastic background”

$$\left\{ \begin{array}{l} a^{k_1} b a^{k_2} b \dots : \\ \begin{array}{l} k_i > 0 \text{ for all } i > 0 \\ \prod_{i>0} \left(1 - \frac{1}{2} k_i\right) = 0 \end{array} \end{array} \right\}$$

a : last input differs from current output
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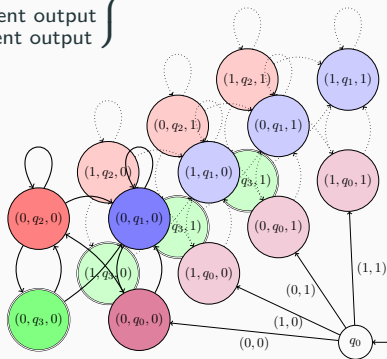
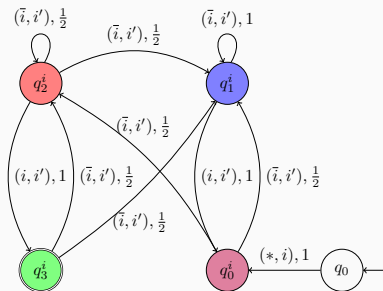


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Definition

Given a POMDP $\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim)$ and a specification $\phi \subseteq S^\omega$ such that $\phi \in \mathcal{B}(S)$. The qualitative synthesis problem (\mathcal{S}, ϕ) demands the computation of a strategy $s : [S]_\sim^* \rightarrow A$ such that $\mu_s(\phi) = 1$.

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Computing Strategies	Fully observable	Partially observable
Positive Büchi	PTIME	Undecidable
Almost-Sure Büchi	PTIME	EXPTIME
Positive Parity	PTIME	Undecidable
Almost-Sure Parity	PTIME	Undecidable

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim) \text{ and } \mathcal{P} = (Q, S, \delta, q_0, F)$$

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Definition

Given $(\Omega_1, \mathcal{F}_1)$, $(\Omega_2, \mathcal{F}_2)$, then $K : \Omega_1 \times \mathcal{F}_2 \rightarrow [0, 1]$ is a Markov-kernel if

1. $K(\cdot, A)$ is measurable in \mathcal{F}_1 for all $A \in \mathcal{F}_2$,
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POMDP - PBA Specification

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- \Rightarrow induces product construction for \mathcal{S} and \mathcal{P}

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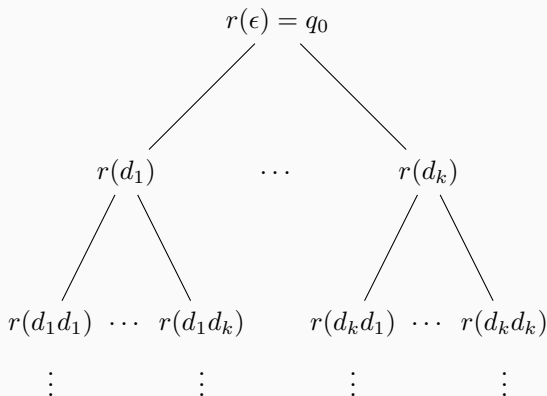
\Rightarrow almost-surely accepting strategy in $\mathcal{S} \otimes \mathcal{P}$ is qualitatively “good” for \mathcal{S} with specification \mathcal{P}

Conclusion

- Introduction of WDTAs
- Synthesis for antagonistic environment for almost-sure accepting PBAs in doubly exponential time
- Synthesis for POMDP for almost-sure accepting PBAs in exponential time
- * Co-operative POSG as emptiness games for unrestricted WDTAs
- * Strategy computation for EVE in equally informed POSG

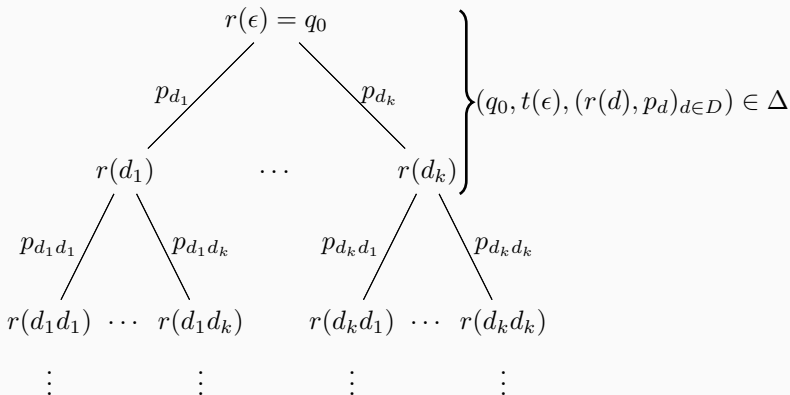
Weighted Descent Tree Automata - Idea

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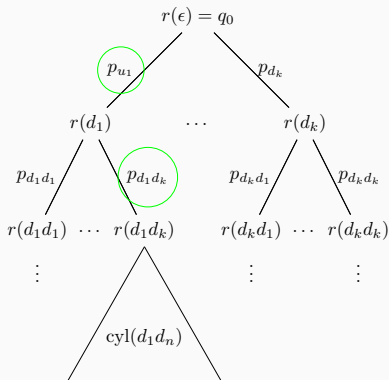
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$$\mu_r(\text{cyl}(u_1 \dots u_n)) = \prod_{1 \leq i \leq n} p_{u_1 \dots u_i}$$

$$\Rightarrow (D^\omega, \mathcal{B}(D), \mu_r)$$

with

$$\mu_r(\{\rho \in D^\omega \mid r(\rho) \in \text{Acc}\})$$



Weighted Descent Tree Automata - Definition

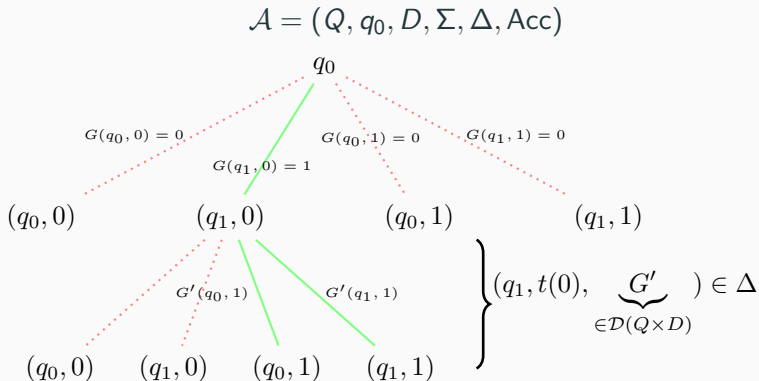
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Weighted Descent Tree Automata - Definition

$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc})$$

- Q : finite state set
- $q_0 \in Q$: initial state
- D : finite set of directions
- Σ : finite alphabet
- Δ : transitions of the form (q, σ, G)
- Acc : accepted language

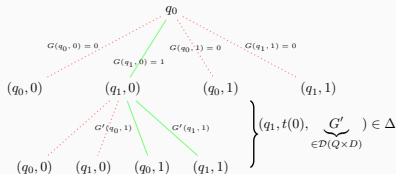
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$$\mathcal{A} = (Q, q_0, D, \Sigma, \Delta, \text{Acc})$$

- run: $Q \times D$ -ary $\mathcal{G}(\mathcal{A})$ -tree
 $\Rightarrow ((Q \times D)^\omega, \mathcal{B}(Q \times D), \mu_r)$



$$\text{Acc}[Q] = \{(d_1, q_1)(d_2, q_2) \cdots \in (D \times Q)^\omega \mid q_1 q_2 \cdots \in \text{Acc}\}$$

and

$$\mu_r(\text{Acc}[Q]) > 0 \text{ or } \mu_r(\text{Acc}[Q]) = 1$$

Tree Automata - Example

$$\mathcal{L} = \left\{ t : \{0, 1\}^* \rightarrow \{a, b\} \mid \begin{array}{l} a \notin \text{Inf}(t(\epsilon)t(\alpha_1)t(\alpha_1\alpha_2)\dots) \\ \text{for all } \alpha_1\alpha_2\dots \in \{0, 1\}^\omega \end{array} \right\}$$

- Parity-condition ✓
- Büchi-condition ✗

$$\mathcal{A} = (\{q_a, q_b\}, q_a, \{0, 1\}, \{a, b\}, \\ \Delta, \{q_a \mapsto 1, q_b \mapsto 0\})$$

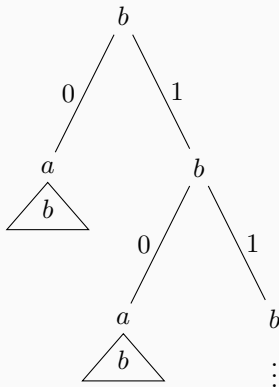
with

$$\Delta = \left\{ (q, \sigma, q_\sigma, q_\sigma) : \begin{array}{l} q \in Q, \\ \sigma \in \{a, b\} \end{array} \right\}$$

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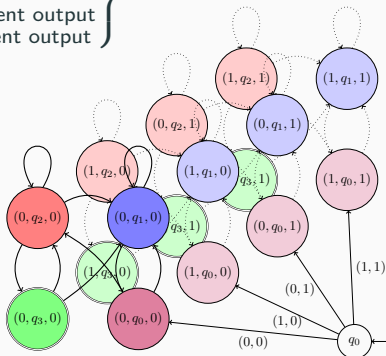
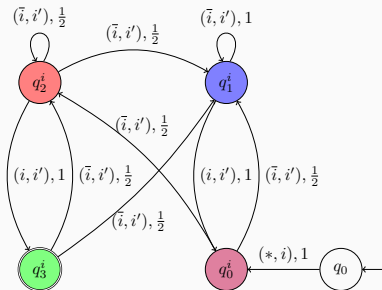
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- “input-/output-game with unobservable stochastic background”
- $S = I \times Q \times J \cup \{q_0\}$ with $s_0 = q_0$
- $E = J, A = I$
- $\tau_{j,i}((a, q, e), (i', p, j')) = \begin{cases} \delta(q, (i, j), p) & \text{if } i' = i, j' = j, \\ 0 & \text{otherwise.} \end{cases}$
- $\sim_E = \sim_A = \left\{ ((i, q, j), (i, p, j)) : \begin{matrix} i \in I, j \in J, q, p \in Q \end{matrix} \right\}$
- $F' = I \times F \times J$

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Definition

Given $(\Omega_1, \mathcal{F}_1)$, $(\Omega_2, \mathcal{F}_2)$, then $K : \Omega_1 \times \mathcal{F}_2 \rightarrow [0, 1]$ is a Markov-kernel if

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 $\mu_\alpha(\text{Acc}_{\text{Büchi}}(Q)) = 1$ for almost all α .
 - measure $\mu_s \otimes K$ on $(S^\omega \times Q^\omega, \mathcal{B}(S) \otimes \mathcal{B}(Q))$ uniquely determined by $\int_{\text{cyl}(u)} K(\cdot, \text{cyl}(v)) d\mu_s$
 - $\int_{\text{cyl}(u)} K(\cdot, \text{cyl}(v)) d\mu_s = \mu_s(\text{cyl}(u)) \cdot \mu_u(\text{cyl}(v))$ for $|u| = |v|$
- \Rightarrow induces product construction for \mathcal{S} and \mathcal{P}

POMDP - PBA Specification

$$\mathcal{S} = (S, s_0, A, (\tau_a)_{a \in A}, \sim) \text{ and } \mathcal{P} = (Q, S, \delta, q_0, F)$$

$$\mathcal{S} \otimes \mathcal{P} = (S \times Q, (q_0, s_0), A, (\tau'_a)_{a \in A}, \sim')$$

- $\tau'_a((s, q), (z, p)) = \tau_a(s, z) \cdot \delta(p, s, q)$
- $(s, q) \sim' (z, p)$ iff $s \sim z$

\Rightarrow strategies can be translated from \mathcal{S} to $\mathcal{S} \otimes \mathcal{P}$

$$\Rightarrow \mu_s(\text{AccBüchi}(S \times F)) = \int_{S^\omega} K(\cdot, \text{AccBüchi}(F)) d\mu_s$$

\Rightarrow almost-surely accepting strategy in $\mathcal{S} \otimes \mathcal{P}$ is qualitatively “good” for \mathcal{S} with specification \mathcal{P}