# 逻辑回归

## 逻辑回归的概念:

逻辑回归也被称为广义线性回归模型,它与线性回归模型的形式基本上相同,都具有 ax+b,其中 a 和 b 是待求参数,其区别在于他们的因变量不同,多重线性回归直接将 ax+b 作为因变量,即 y=ax+b,而 logistic 回归则通过函数 S 将 ax+b 对应到一个隐状态 p,p=S(ax+b),然后根据 p 与 1-p 的大小决定因变量的值。这里的函数 S 就是 Sigmoid 函数。

$$S(t)=1/(1+e-t)$$

通过函数 S 的作用,我们可以将输出的值限制在区间[0, 1]上,p(x)则可以用来表示概率 p(y=1|x),即当一个 x 发生时,y 被分到 1 那一组的概率。

# 逻辑回归模型的代价函数:

逻辑回归一般使用交叉熵作为代价函数。关于代价函数的具体细节,请参考代价函数,这里只给出交叉熵公式:

$$J(\theta) = -1m \left[ \sum_{i=1m} (y_{(i)} logh_{\theta}(x_{(i)}) + (1-y_{(i)}) log(1-h_{\theta}(x_{(i)})) \right]$$

m: 训练样本的个数;

 $h_{\theta}(x)$ : 用参数 θ 和 x 预测出来的 y 值;

y: 原训练样本中的 y 值, 也就是标准答案

上角标(i): 第 i 个样本

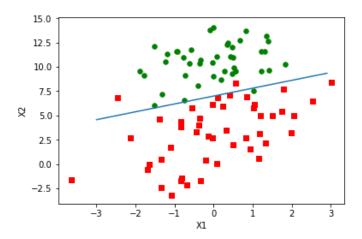
### 代码实现:

1.py

## 实验截图:

### 训练数据:

| [1.0, -0.017612, 14.053064], [1.0, -1.395634, 4.662541], [1.0, -0.752157, 6.53862], [1.0, -1.322371, 7.152853], [1.0, 0.423363, 11.054677], [1.0, 0.406704, 7.067335], [1.0, 0.667394, 12.741452], [1.0, -2.46015, 6.866805], [1.0, 0.569411, 9.548755], [1.0, -0.026632, 10.427743], [1.0, 0.850433, 6.920334], [1.0, 1.347183, 13.1755], [1.0, 0.931635, 1.589505], [1.0, -0.024205, 6.151823], [1.0, -0.036453, 2.690988], [1.0, -0.196949, 0.444165], [1.0, 1.014459, 5.754399], [1.0, 1.985298, 3.230619], [1.0, -1.693453, -0.55754], [1.0, -0.576525, 11.778922], [1.0, -0.346811, -1.67873], [1.0, -2.124484, 2.672471], [1.0, 1.217916, 9.597015], [1.0, -0.733928, 9.098687], [1.0, -3.642001, -1.618087], [1.0, 0.315985, 3.523953], [1.0, 1.416614, 9.619232], [1.0, -0.386323, 3.989286], [1.0, 1.956604, 4.951851], [1.0, 0.275221, 9.543647], [1.0, 0.470575, 9.332488], [1.0, -1.889567, 9.542662], [1.0, -1.527893, 12.150579], [1.0, -1.185247, 11.309318], [1.0, -0.445678, 3.297303], [1.0, 1.042222, 6.105155], [1.0, -1.185247, 11.309318], [1.0, -1.152083, 0.548467], [1.0, 0.828534, 2.676045], [1.0, -1.237728, 10.549033], [1.0, -0.683565, -2.166125], [1.0, 0.229456, 5.921938], [1.0, -0.95985, 11.555336], [1.0, 0.997822, 8.058397], [1.0, 0.824839, 13.730343], [1.0, 1.507278, 5.027866], [1.0, 0.099671, 6.835839], [1.0, -0.344008, 10.717485], [1.0, 1.785928, 7.718645], [1.0, -0.918801, 11.560217], [1.0, -0.364009, 4.7473], [1.0, -0.824839, 13.730343], [1.0, 1.507278, 5.027866], [1.0, 0.099671, 6.835839], [1.0, -0.344008, 10.717485], [1.0, 1.785928, 7.718645], [1.0, -0.9918801, 11.560217], [1.0, -0.364009, 4.7473], [1.0, -0.824839, 13.730343], [1.0, 0.490426, 1.960539], [1.0, -0.007194, -0.364009, 4.7473], [1.0, -0.841722, 4.119083], [1.0, 0.490426, 1.960539], [1.0, -0.007194, -0.364009, 4.7473], [1.0, -0.841722, 4.119083], [1.0, 0.490426, 1.960539], [1.0, -0.007194, -0.364009, 4.7473], [1.0, -0.841722, 4.119083], [1.0, 0.490426, 1.960539], [1.0, -0.007194, -0.364009, 4.7473], [1.0, -0.841722, 4.119083], [1.0, 0.490426, 1.960539], [1.0, -0.0 0.60847797] [-0.75168429]] [[0.00490753] [0.71262076] [0.47239538] [0.28512035]



### 测试数据:

```
[[0.99714035]
[0.04035907]
[0.12535895]
[0.99048731]
[0.98075409]
[0.97708653]
[0.9004989]
[0.97884487]
[0.28594188]
[0.00359693]]
```

