Data Science 2

Loss Functions

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Maximum Likelihood Estimation

Given a network architecture (i.e., the computation graph with specified activation functions), we aim to find a set of weights W^{j} and biases w_{0}^{j} to represent the underlying data.

Putting all the weights and biases together into a single parameter vector:

$$\theta = (\text{vector}(W^1), w_0^1, \text{vector}(W^2), w_0^2, \dots) \in \Theta,$$

where Θ denotes the parameter space and vector(A) denotes the vectorization of matrix A. We shall write $f_{\theta}(x) \in \mathbb{R}^n$ for the output of the network given the input $x \in \mathbb{R}^m$.

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We identify the network output $f_{\theta}(x) \in \mathbb{R}^n$ with a probability density $p_{\theta}(\cdot|x)$ in the label space \mathbb{R}^n , e.g. in the case of a continuous labels we shall put

$$p_{\theta}(\cdot|x) = \mathcal{N}(f_{\theta}(x), \sigma^{2}I_{n\times n})$$

for some unknown $\sigma^2 > 0$.

By means of Maximum Likelihood Estimation we find $\hat{\theta} \in \Theta$ so that $p_{\hat{\theta}}(\cdot|x)$ is *close* to the true label distribution given input $x \in \mathbb{R}^m$.

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Definition (Maximum Likelihood Estimation for Neural Networks)¹

Let $x_1,\ldots,x_N\in\mathbb{R}^m$ be training examples of input data with labels drawn independently from some (unknown) conditional probability density, that is we have $y_j\sim p_{model}\left(\cdot|x_j\right), j=1,\ldots N$. The Maximum Likelihood Estimation of $\theta\in\Theta$ is given by

$$\hat{\theta} = \arg \max_{\theta \in \Theta} \prod_{j=1}^{N} p_{\theta} (y_{j}|x_{j})$$

 $^{^{1}}$ We use a simplified formulation where the empirical distribution for x coincides with the true one. See Sec.2.2 in [1] for the general case.

Assume there exists unique $\theta_{TRUE} \in \Theta$ so that the true conditional distribution $p_{model}(\cdot|x)$ is equal to $p_{\theta_{TRUE}}(\cdot|x)$.

The theory gives us important asymptotical properties with growing sample size $N \to \infty$

- · Consistency: The estimator converges to $\theta_{\textit{TRUE}} \in \Theta$ in probability,
- Efficiency: The estimator achieves the Cramér–Rao lower bound, i.e. no consistent estimator has lower asymptotic mean squared error.

Regression task

In the regression task, with continuous labels $y_1, \ldots, y_N \in \mathbb{R}^n$, we represent (as above) the distribution $p_{\theta}(\cdot|x) = \mathcal{N}\left(f_{\theta}(x), \sigma^2 I_{n \times n}\right)$, for some unknown $\sigma^2 > 0$. Then we have

$$\begin{split} \hat{\theta} &= \arg \max_{\theta \in \Theta} \prod_{j=1}^{N} p_{\theta} \left(y_{j} | x_{j} \right) \\ &= \arg \min_{\theta \in \Theta} - \sum_{j=1}^{N} \log \left(p_{\theta} \left(y_{j} | x_{j} \right) \right) \\ &= \arg \min_{\theta \in \Theta} - \sum_{j=1}^{N} \log \left(\frac{1}{\sqrt{2\pi\sigma^{2n}}} \exp \left[-\frac{\left(y_{j} - f_{\theta} \left(x_{j} \right) \right)^{T} \left(y_{j} - f_{\theta} \left(x_{j} \right) \right)}{2\sigma^{2}} \right] \right) \\ &= \arg \min_{\theta \in \Theta} \sum_{j=1}^{N} \left[\frac{1}{2\sigma^{2}} \left(y_{j} - f_{\theta} \left(x_{j} \right) \right)^{T} \left(y_{j} - f_{\theta} \left(x_{j} \right) \right) \right] + const \\ &= \arg \min_{\theta \in \Theta} \frac{1}{N} \sum_{i=1}^{N} \left[\left(y_{j} - f_{\theta} \left(x_{j} \right) \right)^{T} \left(y_{j} - f_{\theta} \left(x_{j} \right) \right) \right] + const \end{split}$$

Regression task

Thus, Maximum Likelihood Estimation in the regression task is equivalent to minimization of the mean squared error loss function

$$\mathcal{L}(\theta) = \frac{1}{N} \sum_{j=1}^{N} (y_j - f_{\theta}(x_j))^{\mathsf{T}} (y_j - f_{\theta}(x_j))$$

over the training data.

Regression task

Consider a multilayer perceptron with single matrix multiplication

$$f(x) = \varphi(Wx + W_0),$$

where φ is the identity, $W \in \mathbb{R}^m$ and $w_0 \in \mathbb{R}$.

From the correspondence of mean squared error minimization and Maximum Likelihood Estimation, the problem of the W, w_0 estimation is equivalent to the problem of least-squares estimation in the linear regression model

$$y_j = Wx_j + w_0 + \epsilon_j,$$

where the error terms $\epsilon_{j} \sim \mathcal{N}\left(0, \sigma^{2}\right)$ are independent.

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Intermezzo: Information Theory

Definition (Self-Information)

For an event with probability *p*, we define the amount *self-information* (or amount surprise) as

$$I(p) = -\log p$$

We motivate the definition by the requirements

- an almost sure event has no self-information as when it occurs no additional information is brought,
- less likely events bring more self-information as when they occur we learn more about the system,
- self-information is additive on the system of independent events (for algebraic simplicity).

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Definition (Entropy)

For a discrete random variable X with a distribution p_X we define its entropy as the expected self-information

$$H(X) = \mathbb{E}[I(p_X)] = \mathbb{E}[-\log(p_X(X))],$$

The entropy of a distribution is the entropy of a random variable following this distribution.

If p_X is supported on a countable set X we have

$$H(X) = -\sum_{x \in \mathcal{X}} p_X(x) \log p_X(x),$$

where $0 \cdot \log 0$ is defined via the limit $0 \log 0 = \lim_{p \to 0+} (p \log p) = 0$.

Among the discrete random variables on $\{1, \dots, N\}$

- the one-hot distribution, which is equal to one for some $j \in \{1, ..., N\}$ and zero else elsewhere, has the lowest entropy and is equal to zero,
- · the uniform distribution has the highest entropy and is equal to

$$-\sum_{j=1}^{N} \frac{1}{N} \log \frac{1}{N} = \log N$$

Entropy can be also defined for continuous random variables and a well-known fact is that among the distributions with fixed finite variance, normal distribution is the one with the highest entropy.

As a measure of a deviation from the mean, variance could also be used to measure the amount of *surprise* or *self-information*. However, entropy, unlike variance does not depend on the actual values but only on the probabilities which is often desirable².

²A nice account on the applications may be found in [2]

Cross-Entropy

Definition (Cross-Entropy)

For two discrete probability distributions P and Q, we define the cross-entropy as the expected self-information of P given Q

$$H(P,Q) = \mathbb{E}_{P}[I(Q)] = \mathbb{E}[-\log(Q(X))],$$

where $X \sim P$.

If P, Q are supported on a countable set \mathcal{X} we have

$$H(P,Q) = -\sum_{x \in \mathcal{X}} P(x) \log Q(x),$$

again with the convention $0 \log 0 = 0$.

Cross-Entropy

H is not symmetric.

In H(P,Q) the distribution P plays the role a of a prior.

Theorem (Gibbs' inequality, proof on p.56 in [2])

For two discrete probability distributions P and Q, we have

$$H(P,Q) \geq H(P)$$

with equality if and only if P = Q.

Using Gibb's inequality we can standardize the cross-entropy to be zero for identical distributions.

Definition (Kullback-Leibler Divergence)

For two discrete probability distributions *P* and *Q*, we define the *Kullback-Leibler Divergence*

$$D_{KL}(P||Q) = H(P,Q) - H(P) = \mathbb{E}\left[\log\frac{P(X)}{Q(X)}\right]$$

where $X \sim P$.

Compares amount of surprise of *Q* given *P* to the amount of surprise in *P* itself and thus is a good candidate for measuring distances between distributions.

However, D_{KL} is not symmetric (as already H is not) and thus it is not a proper distance.

We could symmetrize the divergence

$$D_{KL}^{S}(P,Q) = D_{KL}(P,Q) + D_{KL}(Q,P)$$

but it is not desirable as can be seen from the example below.

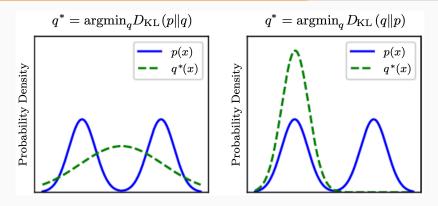


Figure 1: Comparison of what happens to the divergence minimization problem when the two distributions are swapped. Here *p* denotes the target distribution, *q* denotes the approximation distribution when chosen from a set of distributions with one peak.

From the above example we see that symmetricity is not a desirable property and we will minimize D_{KL} directly when training the network.

Revisited

Maximum Likelihood Estimation

In the classification task³, with categorical labels $y_1, ..., y_N \in \{0, 1\}$, we represent the distribution using the sigmoid function

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

$$p_{\theta}(\{1\}|x) = \sigma(f_{\theta}(x)) = \frac{1}{1 + e^{-f_{\theta}(x)}}$$

$$p_{\theta}(\{0\}|x) = 1 - \sigma(f_{\theta}(x)) = \frac{1}{1 + e^{f_{\theta}(x)}} = \sigma(-f_{\theta}(x)).$$

For the label distribution we have

$$p_{model}(\{1\}|x_j) = \mathbf{1}_{[y_j=1]}$$

 $p_{model}(\{0\}|x_j) = \mathbf{1}_{[y_j\neq 1]}$

³We use two classes for simplicity, but the following can be adjusted to multiple-classes problem.

Then we have

$$\begin{split} \hat{\theta} &= \arg \max_{\theta \in \Theta} \prod_{j=1}^{N} p_{\theta} \left(y_{j} | x_{j} \right) \\ &= \arg \min - \sum_{j=1}^{N} \log \left(p_{\theta} \left(y_{j} | x_{j} \right) \right) \\ &= - \arg \min \sum_{j=1}^{N} \left[\mathbf{1}_{\left[y_{j} = 1 \right]} \log \left(\sigma \left(f_{\theta} \left(x \right) \right) \right) + \mathbf{1}_{\left[y_{j} = 0 \right]} \log \left(\sigma \left(- f_{\theta} \left(x \right) \right) \right) \right] \\ &= - \arg \min \sum_{j=1}^{N} \left[p_{model} \left(\left\{ 1 \right\} | x_{j} \right) \log \left(p_{\theta} \left(\left\{ 1 \right\} | x \right) \right) \right. \\ &\left. + p_{model} \left(\left\{ 0 \right\} | x_{j} \right) \log \left(p_{\theta} \left(\left\{ 0 \right\} | x \right) \right) \right] \\ &= \arg \min_{\theta \in \Theta} \sum_{j=1}^{N} H \left(p_{model} \left(\cdot | x_{j} \right), p_{\theta} \left(\cdot | x_{j} \right) \right) \end{split}$$

Thus, Maximum Likelihood Estimation in the classification task is equivalent to minimizing the cross-entropy loss function:

$$\frac{1}{N} \sum_{j=1}^{N} H\left(p_{\text{model}}\left(\cdot \mid x_{j}\right), p_{\theta}\left(\cdot \mid x_{j}\right)\right)$$

over the training data. Since $H(p_{model}(\cdot \mid x))$ does not depend on θ , this is also equivalent to minimizing the Kullback-Leibler divergence:

$$\arg \min_{\theta \in \Theta} \frac{1}{N} \sum_{j=1}^{N} H\left(p_{\text{model}}\left(\cdot \mid x_{j}\right), p_{\theta}\left(\cdot \mid x_{j}\right)\right)$$

$$= \arg \min_{\theta \in \Theta} \frac{1}{N} \sum_{j=1}^{N} D_{\text{KL}}\left(p_{\text{model}}\left(\cdot \mid x_{j}\right) \parallel p_{\theta}\left(\cdot \mid x_{j}\right)\right)$$

Consider a multilayer perceptron with single matrix multiplication

$$f(x) = \varphi(Wx + W_0),$$

where $\varphi = \sigma$ is the sigmoid function, $W \in \mathbb{R}^m$ and $w_0 \in \mathbb{R}$.

From the correspondence of the cross-entropy minimization and Maximum Likelihood Estimation, the problem of the W, w_0 estimation is equivalent to the problem of logistic regression⁴ with the model

$$p(x) = \frac{1}{1 + e^{-(Wx + w_0)}}.$$

⁴Recall the logistic loss from the previous lectures which is the same as our cross-entropy loss

In the case of a multi-class classification, we represent the labels $y_1, \ldots, y_N \in \{1, \ldots, K\}$ for some $K \in \mathbb{N}$ and use a network architecture so that $f_{\theta}(x) \in \mathbb{R}^K$ represents the logits.

Instead of applying the sigmoid function σ we create an output vector that represents a probability distribution:

$$p_{\theta}(x) = \operatorname{softmax}(f_{\theta}(x)),$$

where

$$\operatorname{softmax}(v) = \left(\frac{e^{v_1}}{\sum_{j=1}^m e^{v_j}}, \dots, \frac{e^{v_m}}{\sum_{j=1}^m e^{v_j}}\right), \quad v \in \mathbb{R}^m$$

so that the image of softmax has always positive values that sum to one.

Similar correspondence to cross-entropy minimization is then obtained. Another good reason to use softmax is also the simple form of the derivatives with respect to the network output f_{θ} (x) which will be important in the training procedure.

Zapomněnka⁵: A nice motivation for the choice of the softmax function for classification task is explained here: link.⁶

⁵to-be-forgotten

⁶Loosely speaking, softmax function should be used to model probabilities, if we want to obtain a distribution with maximum entropy under some constraints.

References i



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