



MINIMUM SPANNING TREE

AN MANAGEMENT AND MAN

Outline

17.1 Definitions and Greedy Property

17.2 Prim Algorithm

17.3 Kruskal Algorithm
-- with disjoint set

17.1 Definitions and Greedy Property

Minimum spanning trees

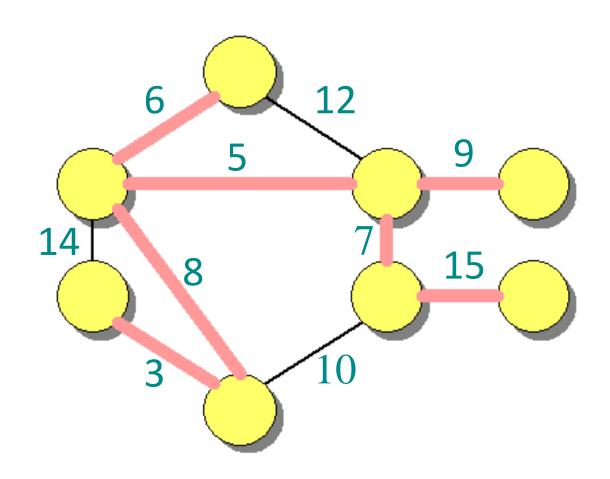
Input:

- -G = (V, E) A connected, undirected graph
- -Weight function w: $E \rightarrow R$.
- For simplicity, assume that all edge weights are distinct. (CLRS covers the general case.)

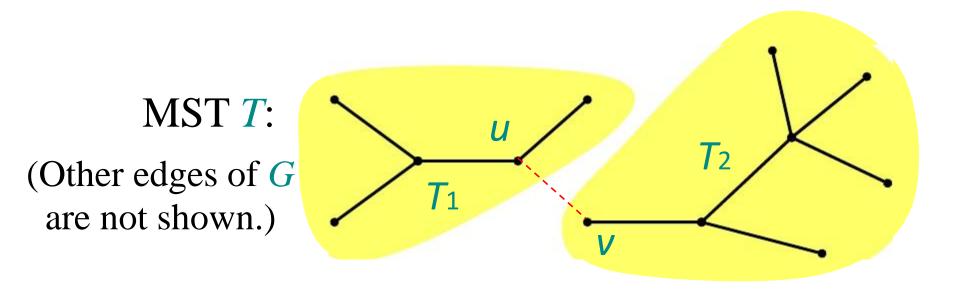
Output: A *spanning tree* T— a tree that connects all vertices — of minimum weight:

$$w(T) = \sum_{(u,v)\in T} w(u,v)$$

Example of MST



Optimal substructure

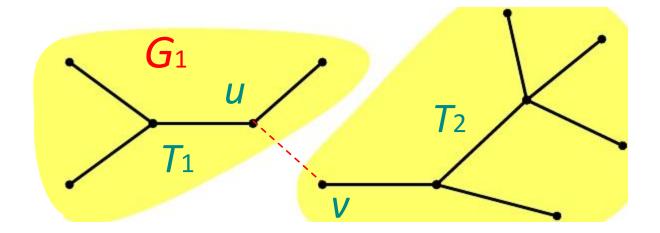


Remove any edge $(u, v) \in T$. Then, T is partitioned into two subtrees T1 and T2.

optimal substructure

Theorem.

The subtree T_1 is an MST of $G_1 = (V_1, E_1)$, where $V_1 = \text{vertices of } T_1$, $E_1 = \{(x, y) \in E \mid x, y \in V_1\}$.



optimal substructure

Proof. $w(T) = w(u, v) + w(T_1) + w(T_2)$. If T^1 a lower-weight spanning tree than T_1 for G_1 , then $T' = \{(u, v)\} \cup T^1 \cup T_2$ would be a lower-weight spanning tree than T for G.

Do we also have overlapping subproblems?

- Yes. Great, then dynamic programming may work!
- but MST leads to an even more efficient algorithm.

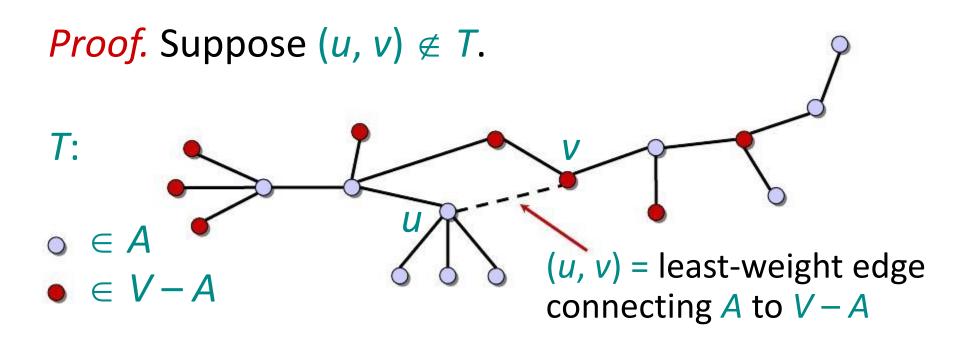
Greedy-choice property

A locally optimal choice is globally optimal.

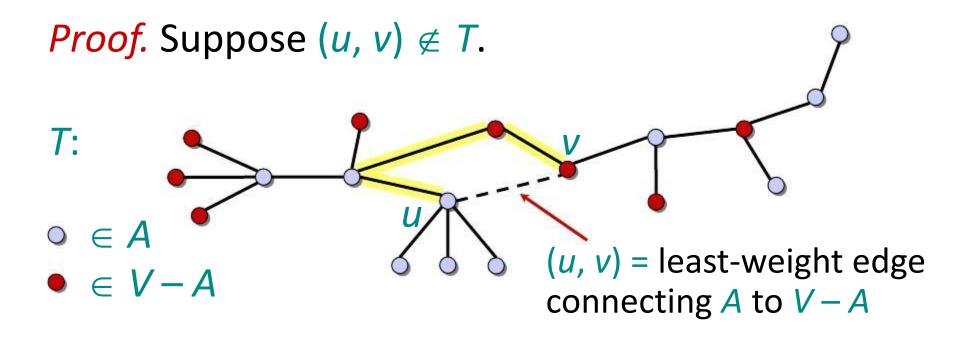
Theorem.

Let T be the MST of G = (V, E) and let $A \subseteq V$. Suppose that $(u, v) \in E$ is the least-weight edge connecting A to V - A. Then, $(u, v) \in T$.

Proof of theorem

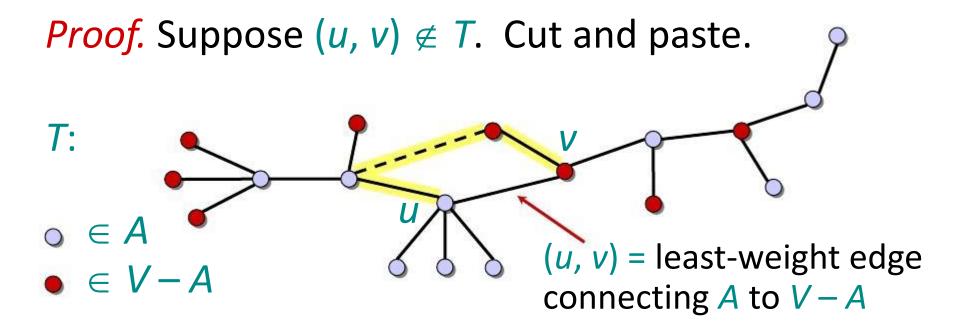


Proof of theorem



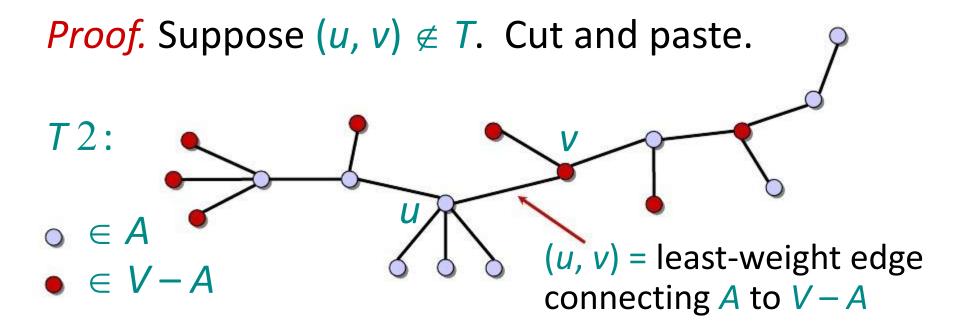
Consider the unique simple path from u to v in T.

Proof of theorem



Swap (u, v) with the first edge on this path that connects a vertex in A to a vertex in V - A.

Proof of theorem



A lighter-weight spanning tree than T results.

17.2 Prim Algorithm

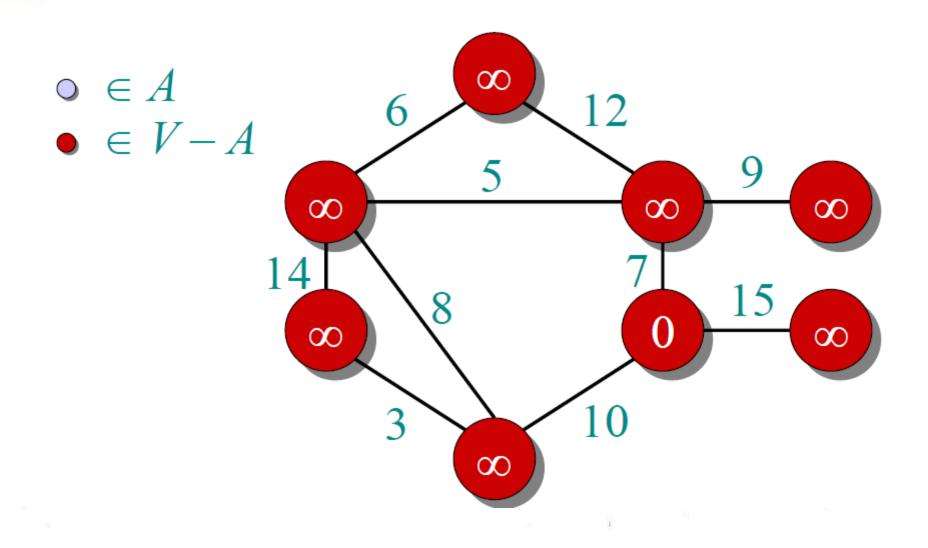
Prim's algorithm

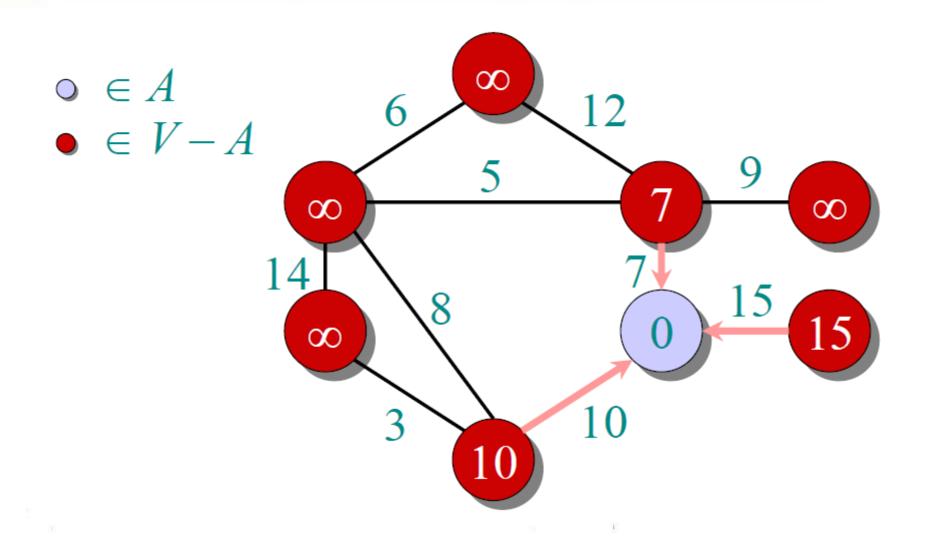
IDEA:

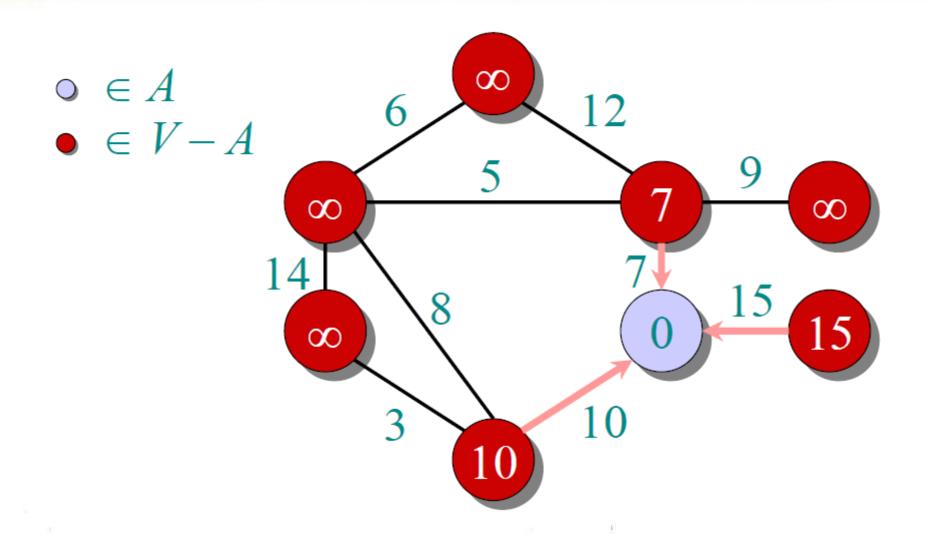
- Maintain V-A as a priority queue Q.
- Key each vertex in *Q* with the weight of the least-weight edge connecting it to a vertex in *A*.

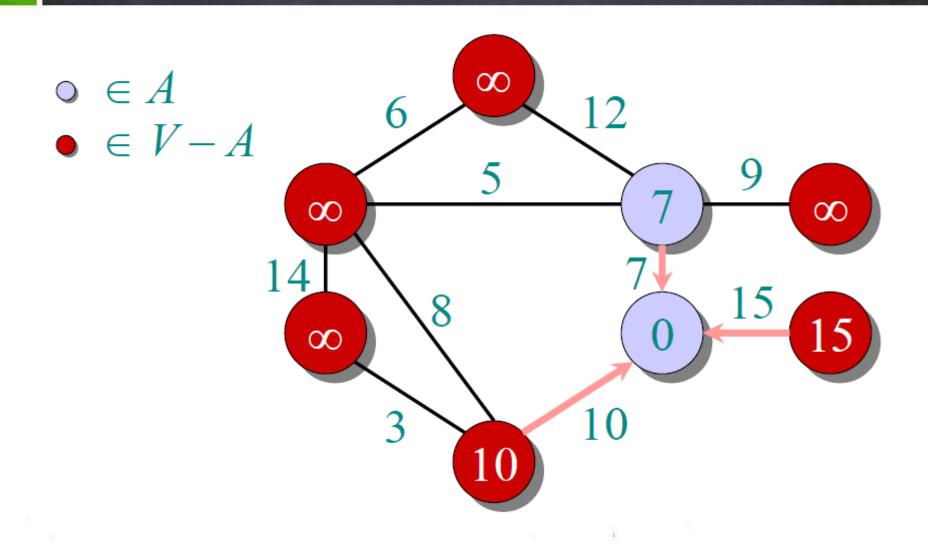
Prim's algorithm

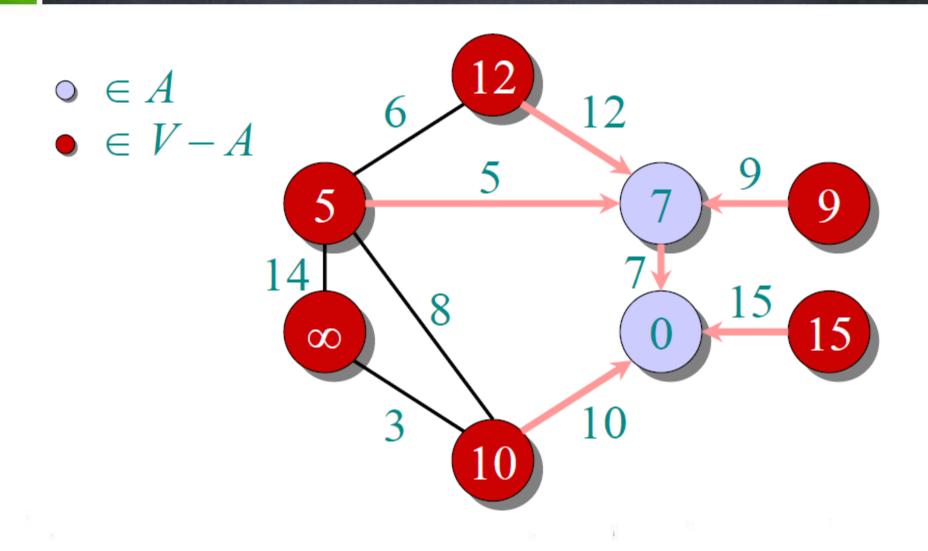
```
Q \leftarrow V
key[v] \leftarrow \infty for all v \in V
key[s] \leftarrow 0 for some arbitrary s \in V
while Q \neq \emptyset
    do u \leftarrow \text{EXTRACT-MIN}(Q)
         for each v \in Adj[u]
             do if v \in Q and w(u, v) < key[v]
                                                      ▶ Decrease-Key
                      then key[v] \leftarrow w(u, v)
                             \pi[v] \leftarrow u
At the end, \{(v, \pi[v])\} forms the MST.
```

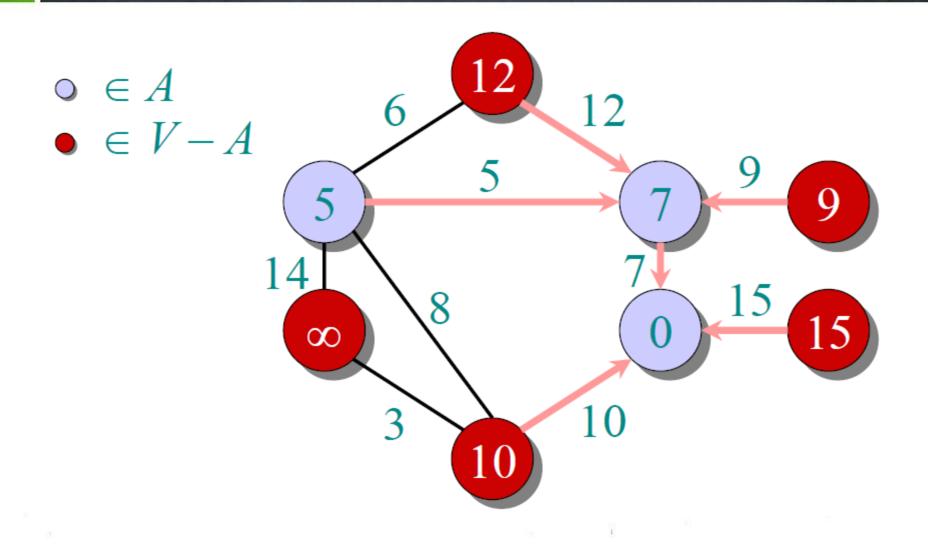


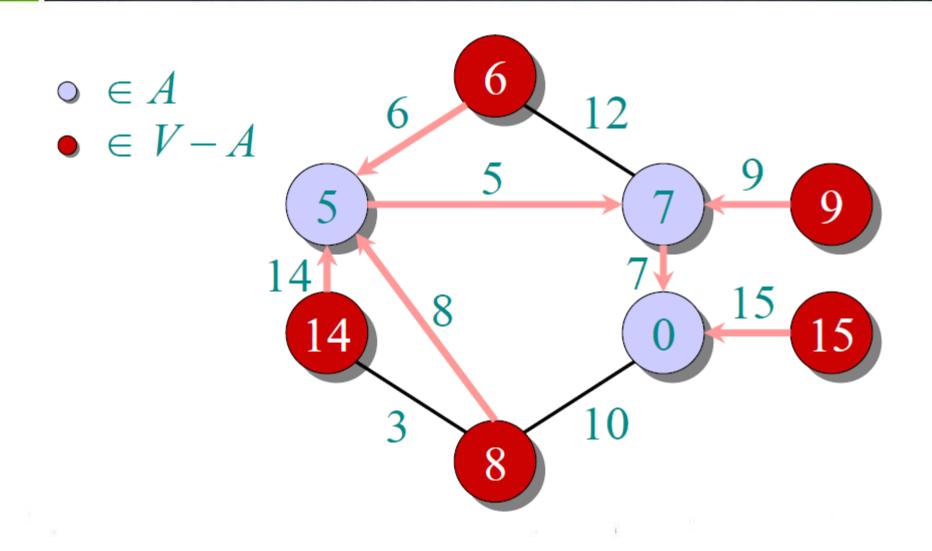


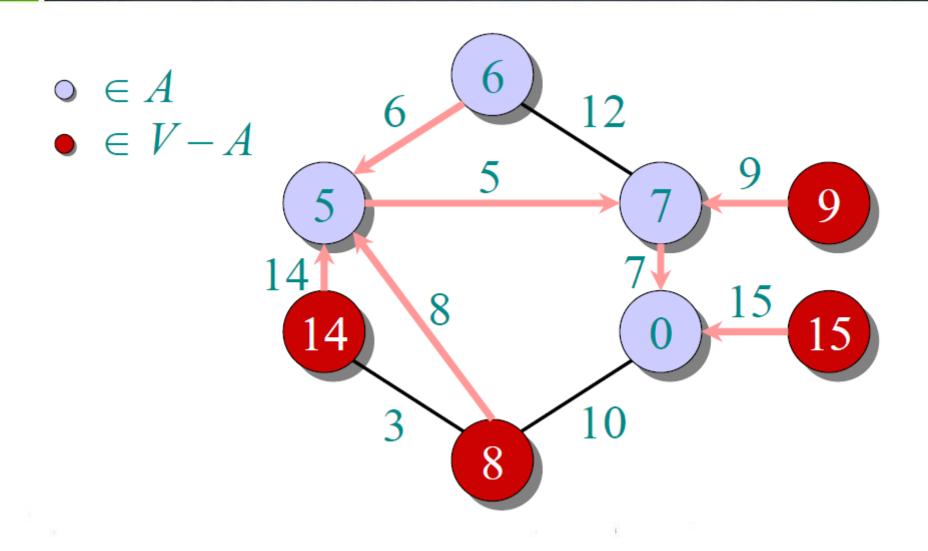


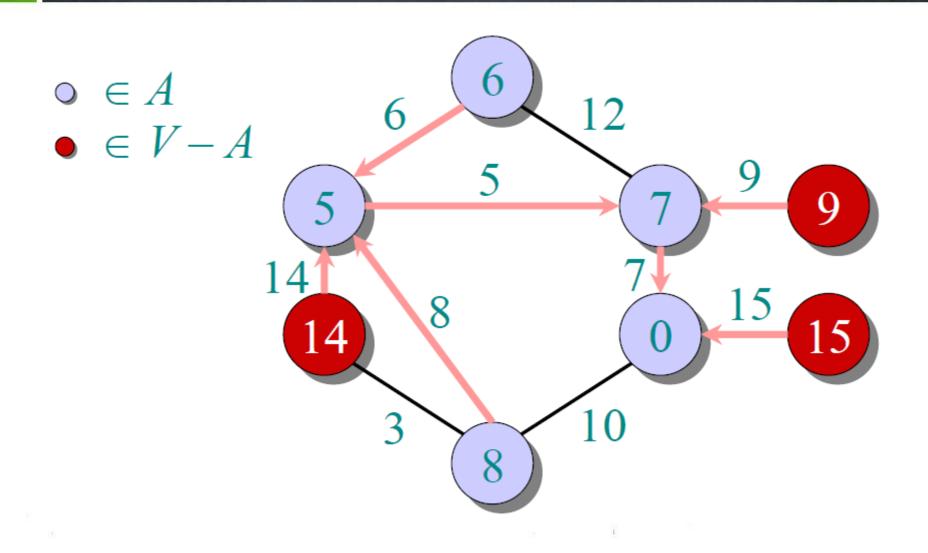


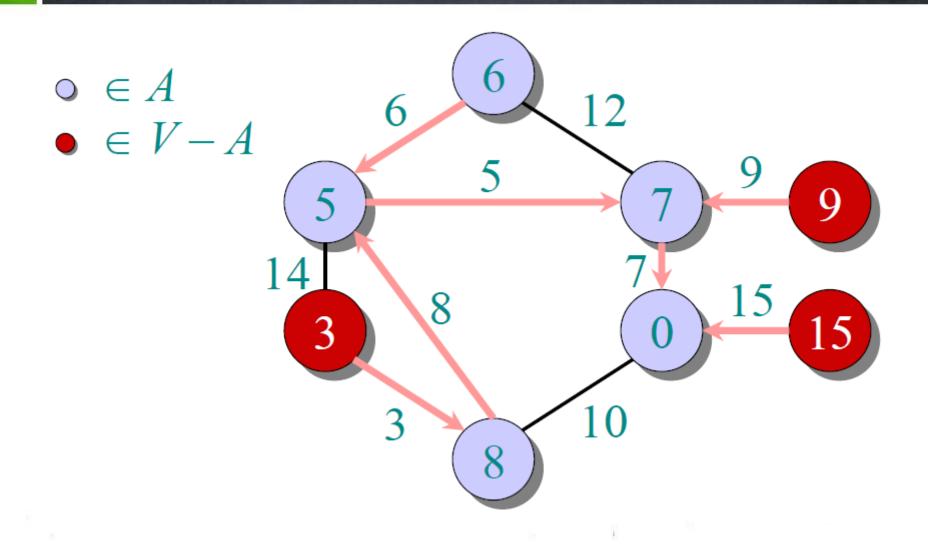


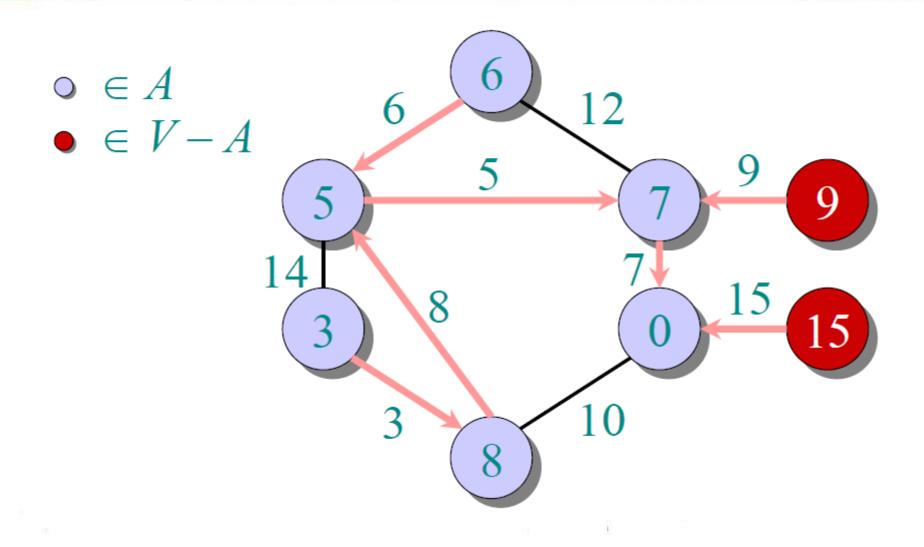


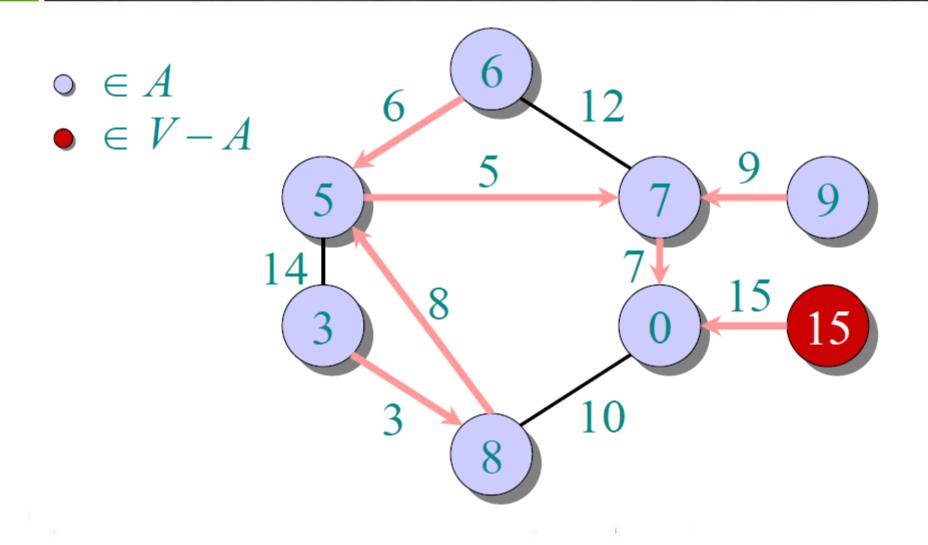


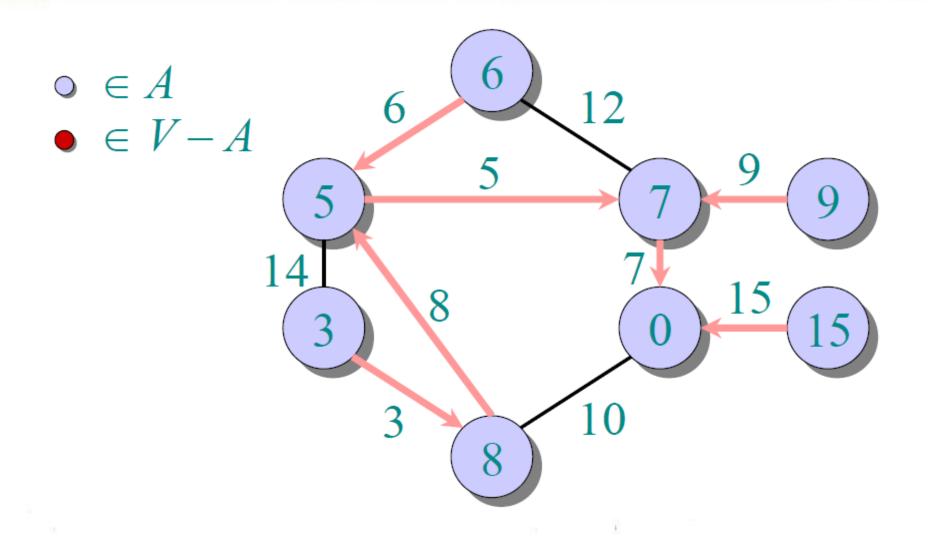




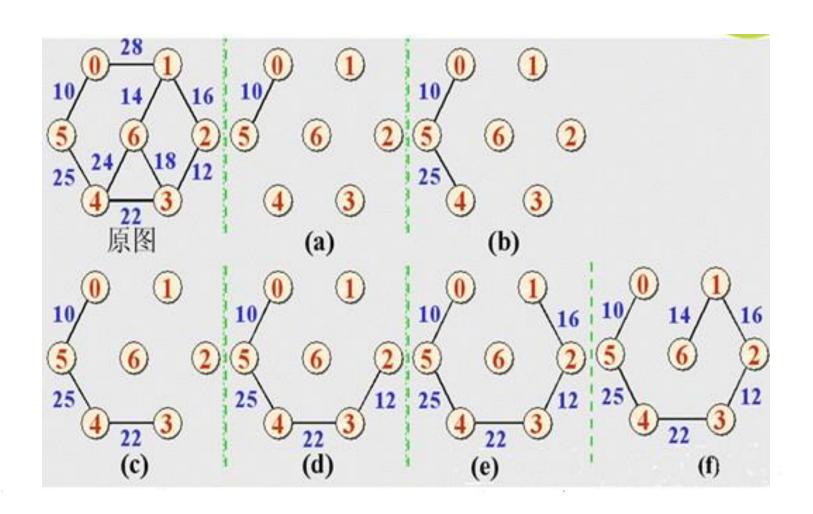








Another Example



Analysis of Prim

```
\Theta(V) \begin{cases} Q \leftarrow V \\ key[v] \leftarrow \infty \text{ for all } v \in V \\ key[s] \leftarrow 0 \text{ for some arbitrary } s \in V \end{cases}
                  while Q \neq \emptyset
                        \mathbf{do} \ u \leftarrow \text{EXTRACT-MIN}(Q)
                             for each v \in Adj[u]
   do if v \in Q and w(u, v) < key[v]
times then key[v] \leftarrow w(u, v)
                                   then key[v] \leftarrow w(u, v)
                                                        \pi[v] \leftarrow u
```

Handshaking Lemma $\Rightarrow \Theta(E)$ implicit Decrease-Key's.

Time =
$$\Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

Analysis of Prim

Time =
$$\Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

Q	T _{EXTRACT-MIN}	T _{DECREASE-KEY}	Y Total
array	O(V)	<i>O</i> (1)	$O(V^2)$
binary heap	$O(\lg V)$	$O(\lg V)$	$O(E \lg V)$
Fibonacci heap	$O(\lg V)$ amortized	O(1) amortized	$O(E + V \lg V)$ worst case

17.3 Kruskal Algorithm

Disjoint Set (Union-Find Set)

并查集(Disjoint-Set)是一种可以动态维护的数据结构,由不想交的集合构成,主要用于元素分组。基本运算有

•合并(Union): 把两个不相交的集合合并为一个集合

•查询(Find): 查询两个元素是否在同一个集合中

基本数据结构:

- 每个集合由其中的一个元素代表
- 集合中的所有元素都在以代表元素为根的树上(逻辑结构)
- 数组parent[x]指向元素x在树中的父节点,如果x为根,则parent[x] = x
- 每个元素x都可以沿parent[x]在树中向上移动,直至根元素

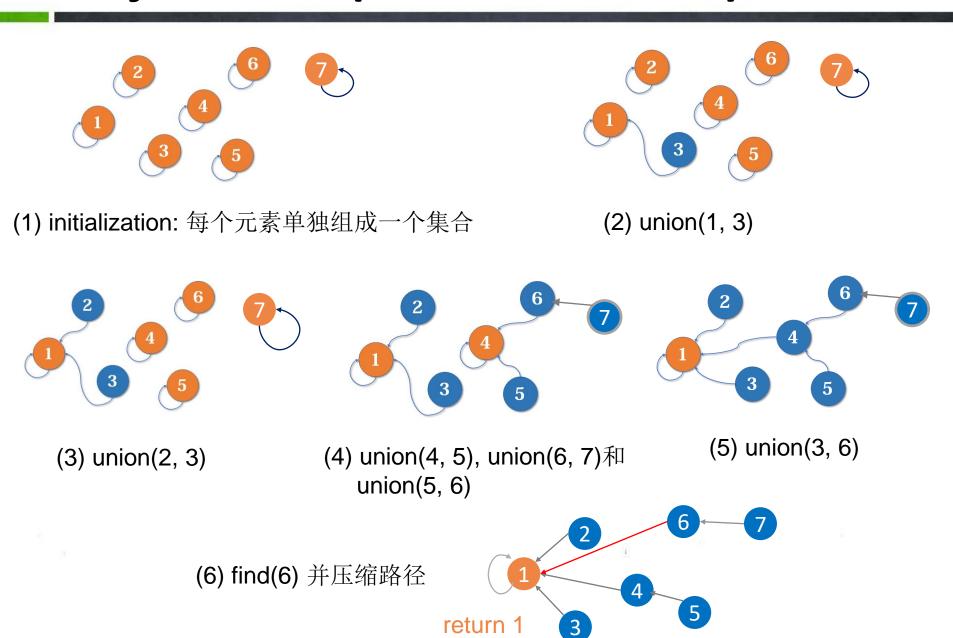
基本算法:

- 判断两个元素是否属于同一集合,只需要看它们的根节点是否相同
- 合并两个集合,只需要把根元素合并,即把其中一个根元素设置为另一个根元素的父节点

路径压缩:

• 把元素x到达根的路径上的所有元素的parent设为根节点

Disjoint Set (Union-Find Set)



Implementations

- 1. //initialization
- **2.** for each $i \in \{1, ... n\}$
- 3. **do** $parent[i] \leftarrow i$

```
find(a)
1.
       root \leftarrow a
       while parent[root] \neq root
3.
             \mathbf{do} \ root \leftarrow parent[root]
          //路径压缩
       while parent[a] \neq root
5.
             do temp \leftarrow parent[a]
                parent[a] \leftarrow root
7.
8.
                 a \leftarrow temp
9.
       return root
```

union(a, b)

- 1. $root_a \leftarrow find(a)$
- 2. $root_b \leftarrow find(b)$
- 3. if $root_a \neq root_b$
- 4. **then** $parent[root_b] \leftarrow root_a$

1. 某市调查城镇交通状况,得到现有城镇道路统计表。表中列出了每条道路直接连通的城镇。市政府 "村村通工程" 的目标是使全市任何两个城镇间都可以实现交通(但不一定有直接的道路相连,只要相互之间可达即可)。请你计算出最少还需要建设多少条道路?

解题思路: 把已有道路连通的城镇进行合并,合并后的集合数量减去1就是需要建设的道路的最少数量

2. 把正整数区间[a,b]($1 \le a < b < 10^6$)分割成若干个不想交的集合,各集合中的任一整数满足以下条件: 所有与该整数有不小于p(1 的公共质因数的整数都在同一个集合中。问最终能分成多少个集合?

解题思路: (1) 枚举 $\geq p$ 且 $\leq b$ 的所有质数: $P[1] = p < P[2] < \dots < P[m] \leq b$

(2) for each $k \in \{1, ..., m\}$, 合并区间[a, b]中所有P[k]的倍数

比如分割 [11,22],p=3

2. 把正整数区间[a,b]($1 \le a < b < 10^6$)分割成若干个集合,各集合中的任一整数满足以下条件:所有与该整数有<mark>不小于p(1)的公共质因数</mark>的整数都在同一个集合中。问最终能分成多少个集合?



3. 无向图G = (V, E), 从中依次删除k个节点 $n_1, n_2, ..., n_k$, 求去掉每个节点后的连通成分数量。

解题思路:并查集适合合并,不适合分离,所以倒序求解。先把k个节点及节点链接的边全部去掉,用并查集计算连通成分数量,再依次加入节点 n_k , n_{k-1} ,..., n_2 以及与图中其它节点链接的边,求每次添加后的连通成分数量。

Kruskal's Algorithm

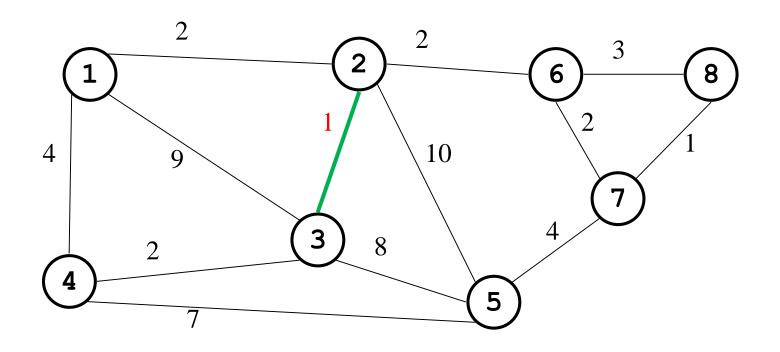
- Yet another greedy algorithm
- Initialize all vertices to unconnected
- While there are still unmarked edges
 - Pick the lowest cost edge e = (u, v) and mark it
 - If u and v are not already connected, add e to the minimum spanning tree and connect u and v
- How is this like maze generation?
- How is it different?

Kruskal's Algorithm

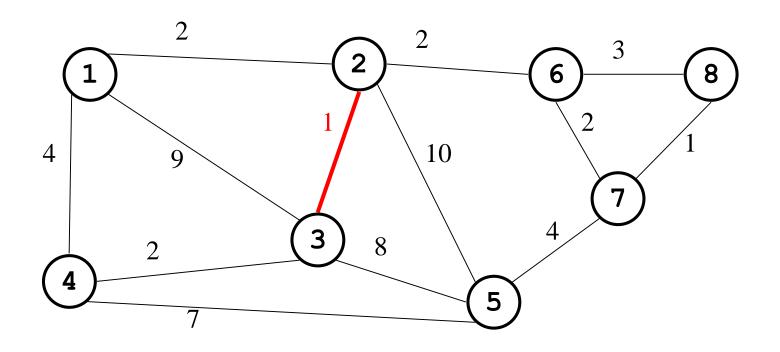
```
Algorithm:
  T=\{\};
   while (T contains less than n-1 edges &&
             E is not empty ){
        Choose a least cost edge (v,w) from E;
        delete (v,w) from E;
         if ((v,w) does not create a cycle in T)
            add (v,w) into T;
        else discard (v,w);
   if (T contains fewer than n-1 edges)
          print ("No spanning tree\n");
```

```
class KruskElem {
                           // An element for the heap
 public:
   int from, to, distance; // The edge being stored
   KruskElem() { from = -1; to = -1; distance = -1; }
   KruskElem(int f, int t, int d)
     { from = f; to = t; distance = d; }
void Kruskel(Graph* G) { // Kruskal's MST algorithm
 ParPtrTree A(G->n());
                          // Equivalence class array
 KruskElem E[G->e()]; // Array of edges for min-heap
  int i;
  int edgecnt = 0;
  for (i=0; i<G->n(); i++) // Put the edges on the array
    for (int w=G->first(i); w<G->n(); w = G->next(i,w)) {
     E[edgecnt].distance = G->weight(i, w);
     E[edgecnt].from = i;
     E[edgecnt++].to = w;
```

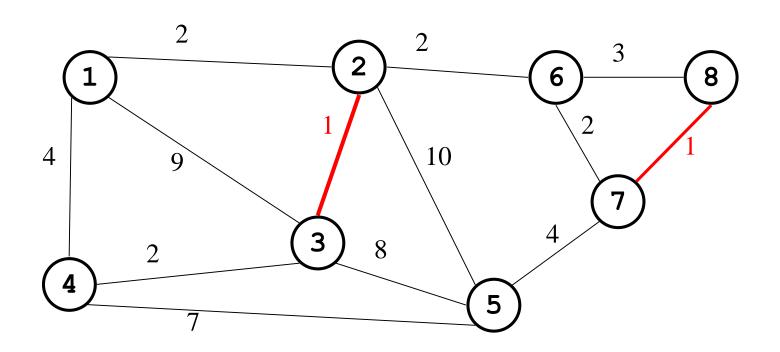
```
// Heapify the edges
heap<KruskElem, Comp> H(E, edgecnt, edgecnt);
int numMST = G->n(); // Initially n equiv classes
for (i=0; numMST>1; i++) { // Combine equiv classes
 KruskElem temp;
 temp = H.removefirst(); // Get next cheapest edge
 int v = temp.from; int u = temp.to;
 if (A.differ(v, u)) { // If in different equiv classes
   A.UNION(v, u); // Combine equiv classes
   AddEdgetoMST(temp.from, temp.to); // Add edge to MST
   numMST--; // One less MST
```



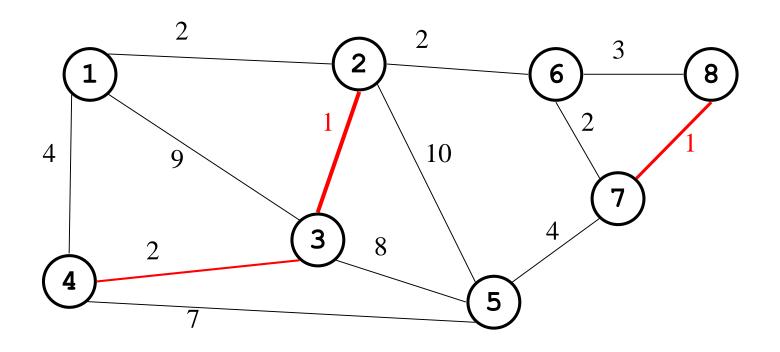
1	2	3	4	5	6	7	8
1	2	3	4	5	6	7	8



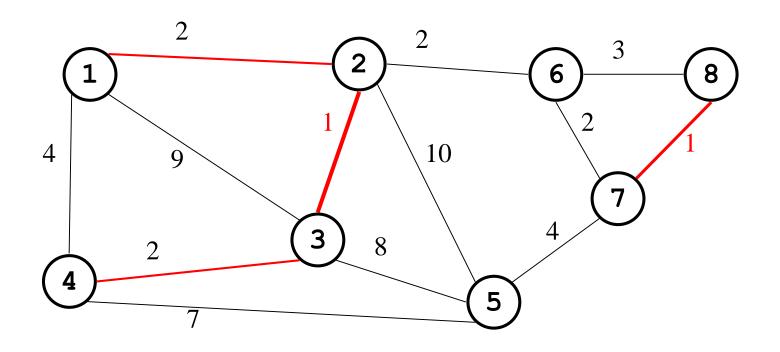
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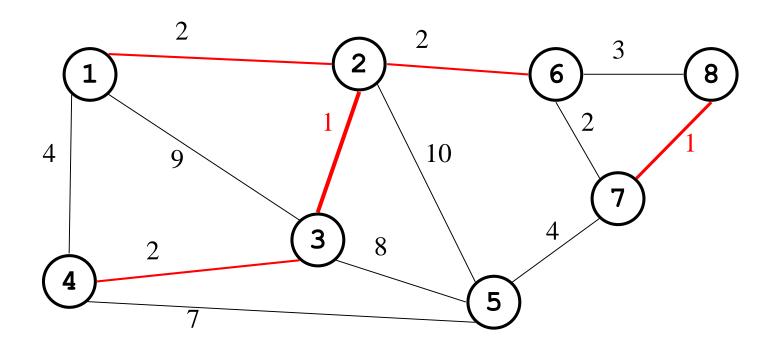
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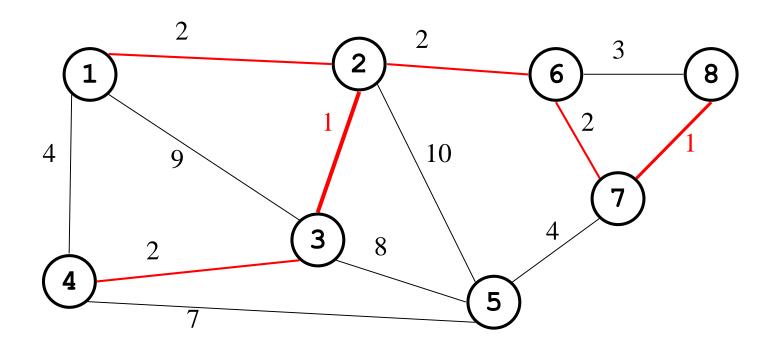
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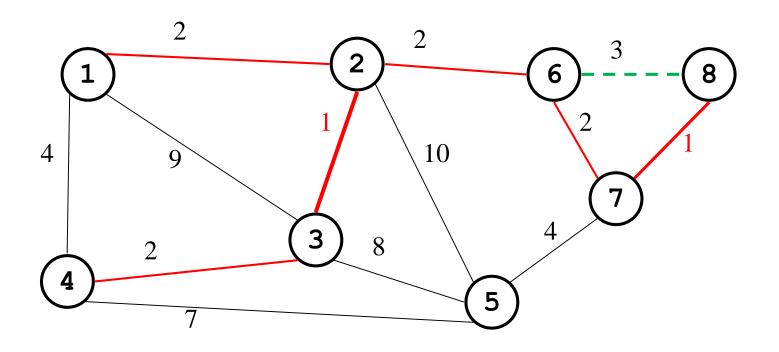
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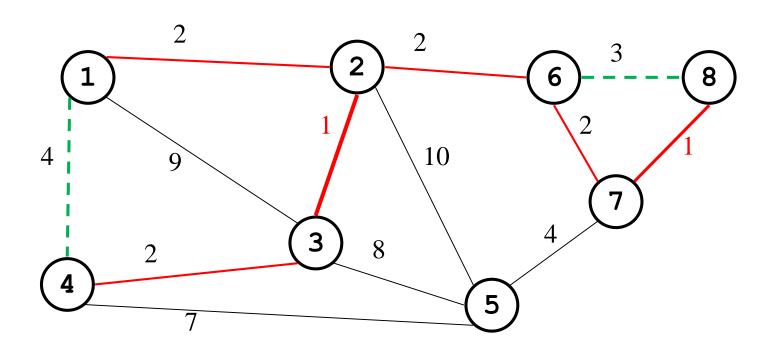
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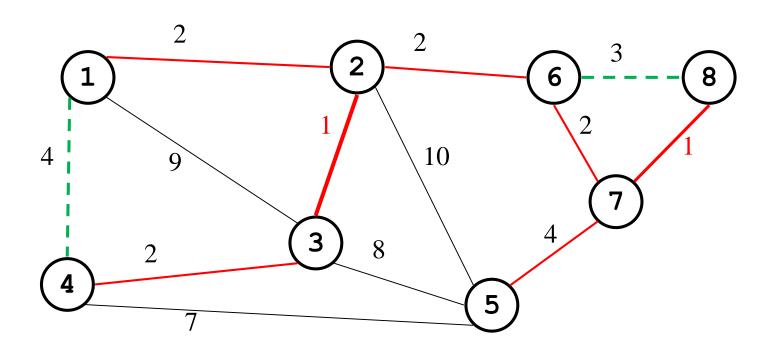
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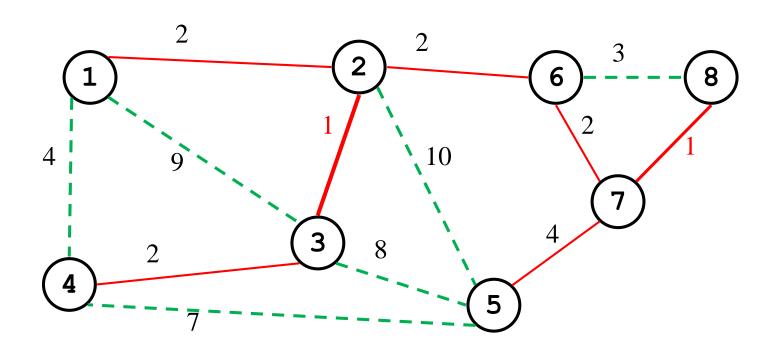
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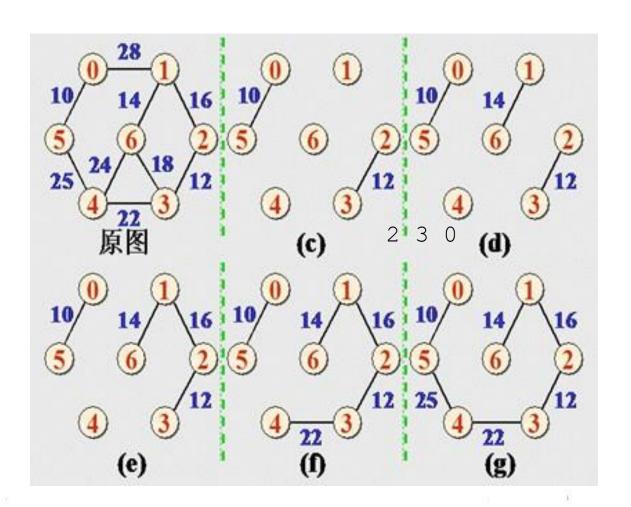
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1	2	3	4	5	6	7	8



1	1	2	2	1	1	1	7
1	2	3	4	5	6	7	8



Another Example



Fundamental features of MST

• 设G = (V,E)为连通无向图。G中的任意一条回路上 权重值最大的边,一定不在最小生成树上。

• 设G = (V,E)为连通无向图,如果G中所有边的权重 互异,则其MST唯一。

MST algorithms

Prim's algorithm

- Uses the priority queen.
- Running time = $O(E \lg V)$.

Kruskal's algorithm

- Uses the disjoint-set data structure.
- Running time = $O(E \lg V)$.

Best to date:

- Karger, Klein, and Tarjan [1993].
- Randomized algorithm.
- O(V + E) expected time.

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End of Section.