```
In [1]: %%capture
# This snipped of code will download the data file
!wget https://www.dropbox.com/s/ms5p2hqqhlaago7/replay_buffer.npy?dl=1
!mv replay_buffer.npy?dl=1 replay_buffer.npy
```

The code below solves the Bellman equation using TD with neural networks function approximation.

```
In [2]: from tensorflow.keras import Sequential
         from tensorflow.keras.layers import Dense, Activation
         import numpy as np
         {\color{red} \textbf{import}} \ {\color{blue} \textbf{matplotlib.pyplot}} \ {\color{blue} \textbf{as}} \ {\color{blue} \textbf{plt}}
         \gamma = 0.95
         batch_size = 128
         replay_buffer = np.load('replay_buffer.npy')
         replay_buffer
[1.4697709 , 1.3415053 , 0.4629144 , 0.55566776],
                 [2.2108552 , 2.2101867 , 0.20458762, 0.20471142],
                 [1.322186 , 1.2165726 , 0.5720248 , 0.67565334]], dtype=float32)
In [3]: model = Sequential([Dense(20, activation='relu'), Dense(1, activation='linear')])
         model.compile(optimizer='Adam', loss='mse')
In [4]: # This function will select a random sample of the replay buffer.
         def sample_from_buffer():
              idx = np.random.choice(len(replay_buffer), batch_size, replace=False) # A vector of random indexes,
              # where the indexes can vary from 0 to len(replay_buffer).
# The size of the sample is 'batch_size'
             mini_batch = replay_buffer[idx]
             Dt, D_{tp1}, \pi_{t}, \pi_{tp1} = np.split(mini_batch, 4, axis=1) R = \gamma * \pi_{tp1} * D_{tp1}
             return Dt, R, D_tp1
         # This function implements one step of the TD update
         def update():
             D, R, D_tp1 = sample_from_buffer() # get a sample from the replay buffer
             V_tp1 = model.predict(D_tp1) # Evaluate the network at y_tp1
             \texttt{TD\_target} = \texttt{R} + \gamma * \texttt{V\_tp1}
              model.fit(D, TD_target, validation_split=0.1, verbose=False, batch_size=batch_size)
```

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In [9]: for iteration in range(10000):
     update()
```

```
In [10]: # Show your results
Dt, D_tpl, \( \pi_\tau, \pi_\tau, \pi_\tau \text{pl} = \text{np.split(replay_buffer, 4, axis=1)} \)
V = model.predict(Dt)
Pt = V / \( \pi_\tau \text{plt.figure(figsize=(7,6), dpi=100)} \)
plt.scatter(Dt, Pt, s=1)
plt.show()
plt.pause(le-6)
# P.S: you figure should be similar to this one: https://www.dropbox.com/s/6992cmfatiu3wkj/PD.png?dl=0
```

