

Network Simulator

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Chapter 1

Data Structure Index

1.1 Data Structures

Here are the data structures with brief descriptions:

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EdgeNode	Node in the adjacency list linked list	7
EdgeRaw	Temporary structure for reading edges before graph construction	8
HeapNode	Single element in the priority queue	9
MinHeap	Binary min-heap structure for efficient priority queue operations for Dijkstra's algorithm during global spillover calculation	10
Node	Single entity in the simulation network	10
RankPair	Helper structure for sorting nodes by spillover weight	12

Chapter 2

File Index

2.1 File List

Here is a list of all files with brief descriptions:

simulator.c	A simulator of network using OpenMP for parallel implementation	13
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Chapter 3

Data Structure Documentation

3.1 AdjGraph Struct Reference

graph representation using an adjacency list.

Data Fields

- `int32_t n_nodes`
- `int32_t n_edges`
- `EdgeNode ** head`

3.1.1 Detailed Description

graph representation using an adjacency list.

3.1.2 Field Documentation

3.1.2.1 head

`EdgeNode** AdjGraph::head`

array of pointers to the head of the linked lists for each node

3.1.2.2 n_edges

`int32_t AdjGraph::n_edges`

num of edges in the graph

3.1.2.3 n_nodes

```
int32_t AdjGraph::n_nodes
```

num of nodes in the graph

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.2 CSRGraph Struct Reference

graph representation using compressed sparse row/CSR.

Data Fields

- int32_t [n_nodes](#)
- int32_t [n_edges](#)
- int32_t * [row_ptr](#)
- int32_t * [col_ind](#)
- double * [val](#)
- double * [val_unsigned](#)

3.2.1 Detailed Description

graph representation using compressed sparse row/CSR.

3.2.2 Field Documentation

3.2.2.1 col_ind

```
int32_t* CSRGraph::col_ind
```

column indices (size n_edges)

3.2.2.2 n_edges

```
int32_t CSRGraph::n_edges
```

num of edges

3.2.2.3 n_nodes

```
int32_t CSRGraph::n_nodes
```

num of nodes

3.2.2.4 row_ptr

```
int32_t* CSRGraph::row_ptr
```

row pointers (size n_nodes + 1)

3.2.2.5 val

```
double* CSRGraph::val
```

edge weights (size n_edges)

3.2.2.6 val_unsigned

```
double* CSRGraph::val_unsigned
```

unweighted (size n_edges)

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.3 EdgeNode Struct Reference

a node in the adjacency list linked list.

Data Fields

- int32_t [dst](#)
- double [w](#)
- double [uw](#)
- struct [EdgeNode](#) * [next](#)

3.3.1 Detailed Description

a node in the adjacency list linked list.

3.3.2 Field Documentation

3.3.2.1 dst

```
int32_t EdgeNode::dst
```

destination node id

3.3.2.2 next

```
struct EdgeNode* EdgeNode::next
```

pointer to the next edge in the list

3.3.2.3 uw

```
double EdgeNode::uw
```

unweighted value used for calculations

3.3.2.4 w

```
double EdgeNode::w
```

weighted value of the edge

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.4 EdgeRaw Struct Reference

temporary structure for reading edges before graph construction.

Data Fields

- int [src](#)
- int [dst](#)
- double [w](#)
- double [uw](#)

3.4.1 Detailed Description

temporary structure for reading edges before graph construction.

3.4.2 Field Documentation

3.4.2.1 dst

```
int EdgeRaw::dst
```

3.4.2.2 src

```
int EdgeRaw::src
```

3.4.2.3 uw

```
double EdgeRaw::uw
```

3.4.2.4 w

```
double EdgeRaw::w
```

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.5 HeapNode Struct Reference

represents a single element in the priority queue.

Data Fields

- `int32_t` [node](#)
- `double` [dist](#)

3.5.1 Detailed Description

represents a single element in the priority queue.

3.5.2 Field Documentation

3.5.2.1 dist

```
double HeapNode::dist
```

the priority value: distance/cost

3.5.2.2 node

```
int32_t HeapNode::node
```

node id

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.6 MinHeap Struct Reference

a binary min-heap structure for efficient priority queue operations for Dijkstra's algorithm during global spillover calculation.

Data Fields

- [HeapNode](#) * `data`
- `int32_t` `size`
- `int32_t` `capacity`

3.6.1 Detailed Description

a binary min-heap structure for efficient priority queue operations for Dijkstra's algorithm during global spillover calculation.

3.6.2 Field Documentation

3.6.2.1 `capacity`

```
int32_t MinHeap::capacity
```

maximum capacity of the heap

3.6.2.2 `data`

```
HeapNode* MinHeap::data
```

array of heap nodes

3.6.2.3 `size`

```
int32_t MinHeap::size
```

current number of elements in the heap

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.7 Node Struct Reference

represents a single entity in the simulation network.

Data Fields

- `int32_t id`
- `double initial`
- `double target`
- `double indicator`
- `double alloc`
- `double gap`
- `double spill_weight`

3.7.1 Detailed Description

represents a single entity in the simulation network.

3.7.2 Field Documentation

3.7.2.1 `alloc`

```
double Node::alloc
```

budget allocated to this node

3.7.2.2 `gap`

```
double Node::gap
```

difference between target and indicator

3.7.2.3 `id`

```
int32_t Node::id
```

unique node id

3.7.2.4 `indicator`

```
double Node::indicator
```

current state indicator

3.7.2.5 `initial`

```
double Node::initial
```

initial value

3.7.2.6 spill_weight

```
double Node::spill_weight
```

weight based on uniform, local, or global strategy

3.7.2.7 target

```
double Node::target
```

target value

The documentation for this struct was generated from the following file:

- [simulator.c](#)

3.8 RankPair Struct Reference

helper structure for sorting nodes by spillover weight.

Data Fields

- int [index](#)
- double [value](#)

3.8.1 Detailed Description

helper structure for sorting nodes by spillover weight.

3.8.2 Field Documentation

3.8.2.1 index

```
int RankPair::index
```

original index of the node

3.8.2.2 value

```
double RankPair::value
```

value to sort by spillover weight

The documentation for this struct was generated from the following file:

- [simulator.c](#)

Chapter 4

File Documentation

4.1 simulator.c File Reference

A simulator of network using OpenMP for parallel implementation.

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <math.h>
#include <stdbool.h>
#include <stdint.h>
#include <omp.h>
```

Data Structures

- struct [HeapNode](#)
represents a single element in the priority queue.
- struct [MinHeap](#)
a binary min-heap structure for efficient priority queue operations for Dijkstra's algorithm during global spillover calculation.
- struct [EdgeNode](#)
a node in the adjacency list linked list.
- struct [AdjGraph](#)
graph representation using an adjacency list.
- struct [CSRGraph](#)
graph representation using compressed sparse row/CSR.
- struct [Node](#)
represents a single entity in the simulation network.
- struct [RankPair](#)
helper structure for sorting nodes by spillover weight.
- struct [EdgeRaw](#)
temporary structure for reading edges before graph construction.

Macros

- #define [MAX_LINE_LEN](#) 4096
- #define [DIST_INF](#) 1e300

Typedefs

- typedef struct EdgeNode [EdgeNode](#)

Functions

- [MinHeap](#) * [heap_create](#) (int32_t capacity)
allocates and initializes a new [MinHeap](#).
- void [heap_free](#) ([MinHeap](#) *h)
frees the memory associated with a [MinHeap](#).
- void [heap_push](#) ([MinHeap](#) *h, int32_t node, double dist)
pushes a new node into the min-heap.
- [HeapNode](#) [heap_pop](#) ([MinHeap](#) *h)
pops the node with the smallest distance from the heap.
- [AdjGraph](#) * [create_adj_graph](#) (int32_t n_nodes)
creates an empty adjacency graph.
- void [add_edge_adj](#) ([AdjGraph](#) *g, int src, int dst, double w, double uw)
adds an edge to the adjacency graph.
- void [free_adj](#) ([AdjGraph](#) *g)
frees all memory associated with an adjacency graph.
- void [free_csr](#) ([CSRGraph](#) *g)
frees all memory associated with a csr graph.
- void [reset_nodes](#) ([Node](#) *nodes, int n)
resets node states for a new simulation run.
- int [compare_rank](#) (const void *a, const void *b)
comparator function for qsort to sort RankPairs descending.
- int [load_nodes](#) (const char *path, [Node](#) **out_nodes, int *out_n)
loads node data from a csv file.
- int [load_graphs](#) (const char *path, int n_nodes, [CSRGraph](#) **csr_f, [CSRGraph](#) **csr_b, [AdjGraph](#) **adj_f, [AdjGraph](#) **adj_b)
loads graph data and builds both csr and adjacency list representations.
- void [compute_local_spillover_csr](#) (const [CSRGraph](#) *g, [Node](#) *nodes, int n)
computes local spillover weights using csr representation.
- void [compute_global_spillover_csr](#) (const [CSRGraph](#) *g, [Node](#) *nodes, int n)
computes global spillover weights using CSR representation.
- void [compute_local_spillover_adj](#) (const [AdjGraph](#) *g, [Node](#) *nodes, int n)
computes local spillover weights using adj list representation.
- void [compute_global_spillover_adj](#) (const [AdjGraph](#) *g, [Node](#) *nodes, int n)
computes global spillover weights using adj list representation.
- double [compute_l2_gap](#) ([Node](#) *nodes, int n)
computes the l2/Euclidean dist of the gap.
- void [simulation_iteration](#) (int rep_type, const char *rep_name, const char *fac_name, const void *bwd_graph, [Node](#) *nodes, int n, double budget, double lambda, double gamma, int max_iter, double epsilon, int output_mode, const char *output_dir, int data_val, int num_candidates, int num_snapshots, int *out_steps, double *out_l2)
executes the simulation loop for budget allocation.
- int [main](#) (int argc, char **argv)
entry point of the simulation.

4.1.1 Detailed Description

A simulator of network using OpenMP for parallel implementation.

The main funtion contains spillover computation and iteration computation. It supports two graph representations: adjacency list and compressed sparse row. It uses three allocation strategies: uniform, local spillover, and global spillover.

Note

- Compile: `mpicc -fopenmp -fopenmp simulator.c -o simulator -lm`
- Usage: `srun -n #rank -c #thread ./simulator [gamma] [lambda] [budget] [output_mode] [nodes_file] [edges_file] ...`

4.1.2 Macro Definition Documentation

4.1.2.1 DIST_INF

```
#define DIST_INF 1e300
```

representation of infinity for distance calculation

4.1.2.2 MAX_LINE_LEN

```
#define MAX_LINE_LEN 4096
```

maximum length for line buffer reading

4.1.3 Typedef Documentation

4.1.3.1 EdgeNode

```
typedef struct EdgeNode EdgeNode
```

4.1.4 Function Documentation

4.1.4.1 add_edge_adj()

```
void add_edge_adj (  
    AdjGraph * g,  
    int src,  
    int dst,  
    double w,  
    double uw)
```

adds an edge to the adjacency graph.

Parameters

<i>g</i>	pointer to the graph.
<i>src</i>	source node id.
<i>dst</i>	destination node id.
<i>w</i>	edge weight.
<i>uw</i>	unweighted value.

4.1.4.2 compare_rank()

```
int compare_rank (
    const void * a,
    const void * b)
```

comparator function for qsort to sort RankPairs descending.

4.1.4.3 compute_global_spillover_adj()

```
void compute_global_spillover_adj (
    const AdjGraph * g,
    Node * nodes,
    int n)
```

computes global spillover weights using adj list representation.

Parameters

<i>g</i>	the adj graph.
<i>nodes</i>	the array of nodes to update.
<i>n</i>	num of nodes.

4.1.4.4 compute_global_spillover_csr()

```
void compute_global_spillover_csr (
    const CSRGraph * g,
    Node * nodes,
    int n)
```

computes global spillover weights using CSR representation.

Parameters

<i>g</i>	the csr graph.
<i>nodes</i>	the array of nodes to update.
<i>n</i>	num of nodes.

4.1.4.5 compute_l2_gap()

```
double compute_l2_gap (  
    Node * nodes,  
    int n)
```

computes the l2/Euclidean dist of the gap.

Parameters

<i>nodes</i>	array of nodes.
<i>n</i>	num of nodes.

Returns

the square root of the sum of squared gaps.

4.1.4.6 compute_local_spillover_adj()

```
void compute_local_spillover_adj (  
    const AdjGraph * g,  
    Node * nodes,  
    int n)
```

computes local spillover weights using adj list representation.

Parameters

<i>g</i>	the adjacency graph.
<i>nodes</i>	the array of nodes to update.
<i>n</i>	num of nodes.

4.1.4.7 compute_local_spillover_csr()

```
void compute_local_spillover_csr (  
    const CSRGraph * g,  
    Node * nodes,  
    int n)
```

computes local spillover weights using csr representation.

Parameters

<i>g</i>	the csr graph.
<i>nodes</i>	the array of nodes to update.
<i>n</i>	num of nodes.

4.1.4.8 create_adj_graph()

```
AdjGraph * create_adj_graph (  
    int32_t n_nodes)
```

creates an empty adjacency graph.

Parameters

<i>n_nodes</i>	number of nodes.
----------------	------------------

Returns

pointer to the new [AdjGraph](#).

4.1.4.9 free_adj()

```
void free_adj (  
    AdjGraph * g)
```

frees all memory associated with an adjacency graph.

Parameters

<i>g</i>	pointer to the graph.
----------	-----------------------

4.1.4.10 free_csr()

```
void free_csr (  
    CSRGraph * g)
```

frees all memory associated with a csr graph.

Parameters

<i>g</i>	pointer to the graph.
----------	-----------------------

4.1.4.11 heap_create()

```
MinHeap * heap_create (  
    int32_t capacity)
```

allocates and initializes a new [MinHeap](#).

Parameters

<i>capacity</i>	The maximum number of elements the heap can hold.
-----------------	---

Returns

pointer to the created [MinHeap](#).

4.1.4.12 heap_free()

```
void heap_free (  
    MinHeap * h)
```

frees the memory associated with a [MinHeap](#).

Parameters

<i>h</i>	pointer to the heap to free.
----------	------------------------------

4.1.4.13 heap_pop()

```
HeapNode heap_pop (  
    MinHeap * h)
```

pops the node with the smallest distance from the heap.

Parameters

<i>h</i>	pointer to the heap.
----------	----------------------

Returns

the [HeapNode](#) with the minimum distance.

4.1.4.14 heap_push()

```
void heap_push (  
    MinHeap * h,  
    int32_t node,  
    double dist)
```

pushes a new node into the min-heap.

Parameters

<i>h</i>	pointer to the heap.
<i>node</i>	the node identifier.
<i>dist</i>	the priority/distance value.

4.1.4.15 load_graphs()

```
int load_graphs (
    const char * path,
    int n_nodes,
    CSRGraph ** csr_f,
    CSRGraph ** csr_b,
    AdjGraph ** adj_f,
    AdjGraph ** adj_b)
```

loads graph data and builds both csr and adjacency list representations.

Parameters

	<i>path</i>	path to the edges csv file.
	<i>n_nodes</i>	total num of nodes.
out	<i>csr_f</i>	pointer to forward csv graph.
out	<i>csr_b</i>	pointer to backward csv graph.
out	<i>adj_f</i>	pointer to forward adjacency graph.
out	<i>adj_b</i>	pointer to backward adjacency graph.

Returns

0 on success, -1 on failure.

4.1.4.16 load_nodes()

```
int load_nodes (
    const char * path,
    Node ** out_nodes,
    int * out_n)
```

loads node data from a csv file.

Parameters

	<i>path</i>	path to the csv file.
out	<i>out_nodes</i>	pointer to the array of nodes.
out	<i>out_n</i>	pointer to the integer storing node count.

Returns

0 on success, -1 on failure.

4.1.4.17 main()

```
int main (  
    int argc,  
    char ** argv)
```

entry point of the simulation.

Parameters

<i>argc</i>	argument count.
<i>argv</i>	argument vector.

Returns

0 on success, 1 on error.

4.1.4.18 reset_nodes()

```
void reset_nodes (  
    Node * nodes,  
    int n)
```

resets node states for a new simulation run.

Parameters

<i>nodes</i>	array of nodes.
<i>n</i>	num of nodes.

4.1.4.19 simulation_iteration()

```
void simulation_iteration (
    int rep_type,
    const char * rep_name,
    const char * fac_name,
    const void * bwd_graph,
    Node * nodes,
    int n,
    double budget,
    double lambda,
    double gamma,
    int max_iter,
    double epsilon,
    int output_mode,
    const char * output_dir,
    int data_val,
    int num_candidates,
    int num_snapshots,
    int * out_steps,
    double * out_l2)
```

executes the simulation loop for budget allocation.

Parameters

	<i>rep_type</i>	the graph representation (0 for AdjList, 1 for CSR).
	<i>rep_name</i>	string name of representation for logging.
	<i>fac_name</i>	string name of the spillover factor strategy.
	<i>bwd_graph</i>	void pointer to the backward graph (cast based on rep_type).
	<i>nodes</i>	array of Node structures containing state.
	<i>n</i>	total number of nodes.
	<i>budget</i>	total budget to distribute per iteration.
	<i>lambda</i>	impact factor for spillover weights.
	<i>gamma</i>	step size for indicator updates.
	<i>max_iter</i>	max num of iterations allowed.
	<i>epsilon</i>	convergence threshold or tolerance for l2 gap.
	<i>output_mode</i>	if 1, writes detailed csv logs; if 0, runs silently.
	<i>output_dir</i>	directory path for output files.
	<i>data_val</i>	the dataset scale identifier.
	<i>num_candidates</i>	num of top candidates to track in logs.
	<i>num_snapshots</i>	num of snapshots to record in the log file.
out	<i>out_steps</i>	pointer to store the final iteration count.
out	<i>out_l2</i>	pointer to store the final l2 error.