

## 8 Exercise: Stresses

### 8.1 Stress vectors

Consider the motion of the tetrahedron from the previous exercise:

$$[\underline{\underline{\mathbf{R}}}(t)] = \begin{bmatrix} \cos\left(\frac{2\pi t}{t_{max}}\right) & -\sin\left(\frac{2\pi t}{t_{max}}\right) & 0 \\ \sin\left(\frac{2\pi t}{t_{max}}\right) & \cos\left(\frac{2\pi t}{t_{max}}\right) & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad [\underline{\mathbf{b}}(t)] = \begin{bmatrix} 0 \\ 0 \\ \frac{3}{20} \frac{t}{t_{max}} \end{bmatrix}$$

with  $t_{max} = 1/2$ .

Anticipating a global equilibrium, the resulting contact forces and moments acting on the tetrahedron are given by the inertial minus the volume forces and moments calculated in exercise 7:

$$\begin{aligned} {}^{con}\underline{\underline{\mathbf{f}}}(t) &= {}^{ine}\underline{\underline{\mathbf{f}}}(t) - {}^{vol}\underline{\underline{\mathbf{f}}}(t) & [{}^{con}\underline{\underline{\mathbf{f}}}] &= \begin{bmatrix} -\frac{\pi^2}{15}(\cos(4\pi t) - \sin(4\pi t)) \\ -\frac{\pi^2}{15}(\cos(4\pi t) + \sin(4\pi t)) \\ \frac{5}{3} \end{bmatrix} \\ {}^{con}\hat{\underline{\underline{\mathbf{f}}}}_0(t) &= {}^{ine}\hat{\underline{\underline{\mathbf{f}}}}_0(t) - {}^{vol}\hat{\underline{\underline{\mathbf{f}}}}_0(t) & [{}^{con}\hat{\underline{\underline{\mathbf{f}}}}_0] &= \frac{125 + \pi^2(4 + 60t)}{3000} \begin{bmatrix} \sin(4\pi t) + \cos(4\pi t) \\ \sin(4\pi t) - \cos(4\pi t) \\ 0 \end{bmatrix} \end{aligned}$$

By analogy with a homogeneous small strain motion of the nodes

$${}^i\underline{\mathbf{u}}(t) = \underline{\underline{\mathbf{H}}}(t){}^i\underline{\mathbf{x}} + \underline{\mathbf{b}}(t) = (\underline{\underline{\epsilon}}(t) + \underline{\underline{\mathbf{A}}}(t)){}^i\underline{\mathbf{x}} + \underline{\mathbf{b}}(t)$$

we write a linear form for the force vectors  ${}^i\underline{\mathbf{f}}$  acting on the vertices  $i$  in the actual configuration

$${}^i\underline{\mathbf{f}}(t) = -\frac{1}{3}(\underline{\underline{\mathbf{T}}}(t) + \underline{\underline{\mathbf{W}}}(t)){}^iA_t(t){}^i\underline{\mathbf{n}}_t(t) + \frac{1}{4}{}^{con}\underline{\underline{\mathbf{f}}}(t)$$

where  ${}^iA_t{}^i\underline{\mathbf{n}}$  is the actual face normal weighted by the actual area,  ${}^{con}\underline{\underline{\mathbf{f}}}(t)$  corresponds to the sum of the contact forces acting on the tetrahedron and  $\underline{\underline{\mathbf{T}}}(t)$ ,  $\underline{\underline{\mathbf{W}}}(t)$  are symmetric, respectively antisymmetric second order stress tensors.

Using the usual relation for antisymmetric tensors

$$\underline{\underline{\mathbf{W}}}(t){}^iA_t{}^i\underline{\mathbf{n}}_t(t) = -\frac{1}{2}\underline{\mathbf{w}}(t) \wedge {}^iA_t{}^i\underline{\mathbf{n}}_t(t)$$

and the following definition

$$\underline{\mathbf{w}}(t) = -4(({}^{cfi}\underline{\mathbf{y}} \cdot {}^iA_t{}^i\underline{\mathbf{n}}_t)\underline{\mathbf{I}} + ({}^{cfi}\underline{\mathbf{y}} \otimes {}^iA_t{}^i\underline{\mathbf{n}}_t))^{-1}({}^{con}\hat{\underline{\underline{\mathbf{f}}}}_0 - {}^c\underline{\mathbf{y}} \wedge {}^{con}\underline{\underline{\mathbf{f}}}(t))$$

with summation over  $i$  and  ${}^{con}\hat{\underline{\mathbf{f}}}_0$  being the sum of the contact moments acting on the tetrahedron with respect to the origin.

Show that

$$\sum_{i=1}^4 {}^i\underline{\mathbf{f}}(t) = {}^{con}\hat{\underline{\mathbf{f}}}(t) \quad \forall \underline{\underline{\mathbf{T}}} = \underline{\underline{\mathbf{T}}}^T \quad (1)$$

$$\sum_{i=1}^4 {}^i\underline{\mathbf{y}}(t) \wedge {}^i\underline{\mathbf{f}}(t) = {}^{con}\hat{\underline{\mathbf{f}}}_0(t) \quad \forall \underline{\underline{\mathbf{T}}} = \underline{\underline{\mathbf{T}}}^T \quad (2)$$

In fact, the nodal forces can be converted to stress vectors  ${}^i\underline{\mathbf{t}}$  applied on the opposed face:

$${}^i\underline{\mathbf{t}}(t) = \frac{{}^{con}\hat{\underline{\mathbf{f}}}(t) - 3 {}^i\underline{\mathbf{f}}(t)}{{}^iA} \quad i = 1, 4$$

The stress vectors become a superposition of a homogeneous Cauchy stress and an external contribution that balances forces and moments

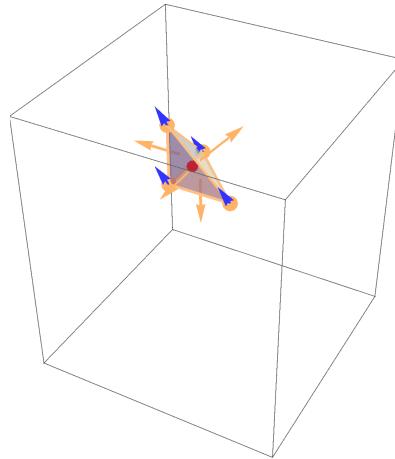
$${}^i\underline{\mathbf{t}}(t) = \underline{\underline{\mathbf{T}}}(t) {}^i\underline{\mathbf{n}}_t(t) - \frac{1}{2} \underline{\mathbf{w}}(t) \wedge {}^i\underline{\mathbf{n}}_t(t) + \frac{1}{4} {}^iA_t(t) {}^{con}\hat{\underline{\mathbf{f}}}(t)$$

Show that

$$\sum_{i=1}^4 {}^iA_t {}^i\underline{\mathbf{t}}(t) = {}^{con}\hat{\underline{\mathbf{f}}}(t) \quad \forall \underline{\underline{\mathbf{T}}} = \underline{\underline{\mathbf{T}}}^T \quad (3)$$

$$\sum_{i=1}^4 {}^{cfi} \underline{\mathbf{y}}(t) \wedge {}^iA_t {}^i\underline{\mathbf{t}}(t) = {}^{con,0}\hat{\underline{\mathbf{f}}}(t) \quad \forall \underline{\underline{\mathbf{T}}} = \underline{\underline{\mathbf{T}}}^T \quad (4)$$

Plot the nodal forces  ${}^i\underline{\mathbf{f}}$  at  $t = t_{max}$  in the case  $\underline{\underline{\mathbf{T}}} = 0$



When inertial and body forces and moments vanish, the Cauchy stress vector is recovered

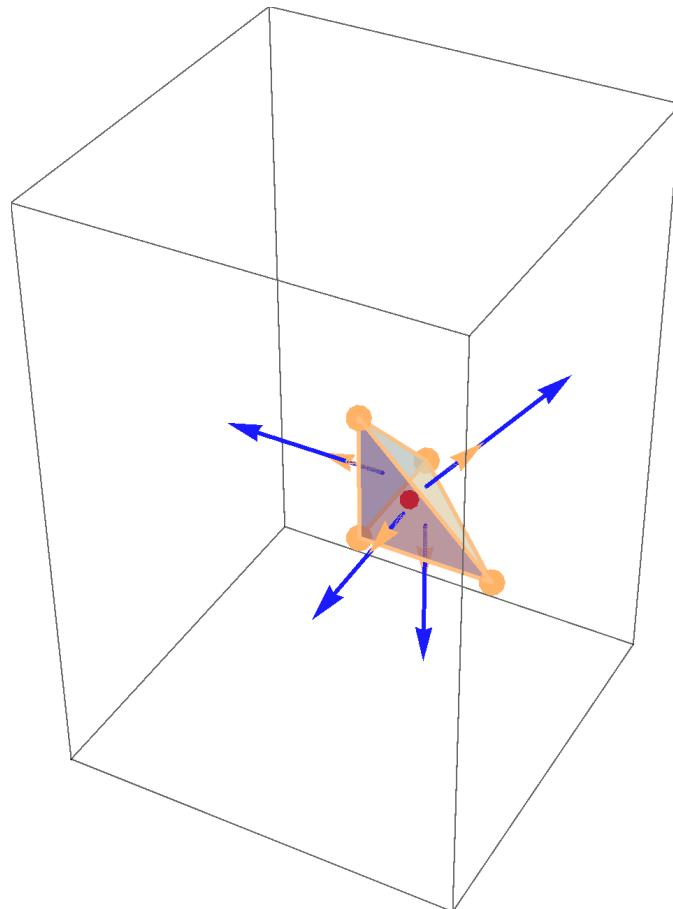
$${}^i \underline{\mathbf{t}}(t) = \underline{\underline{\mathbf{T}}}(t) {}^i \underline{\mathbf{n}}_t(t)$$

## 8.2 Hydrostatic stress

In the absence of rotation, translation and volume forces, plot the stress vectors on the original face centroids of the tetrahedron for a hydrostatic stress

$$\underline{\underline{\mathbf{T}}} = -\pi \underline{\underline{\mathbf{I}}} \quad (5)$$

with  $\pi = 25$  kPa.

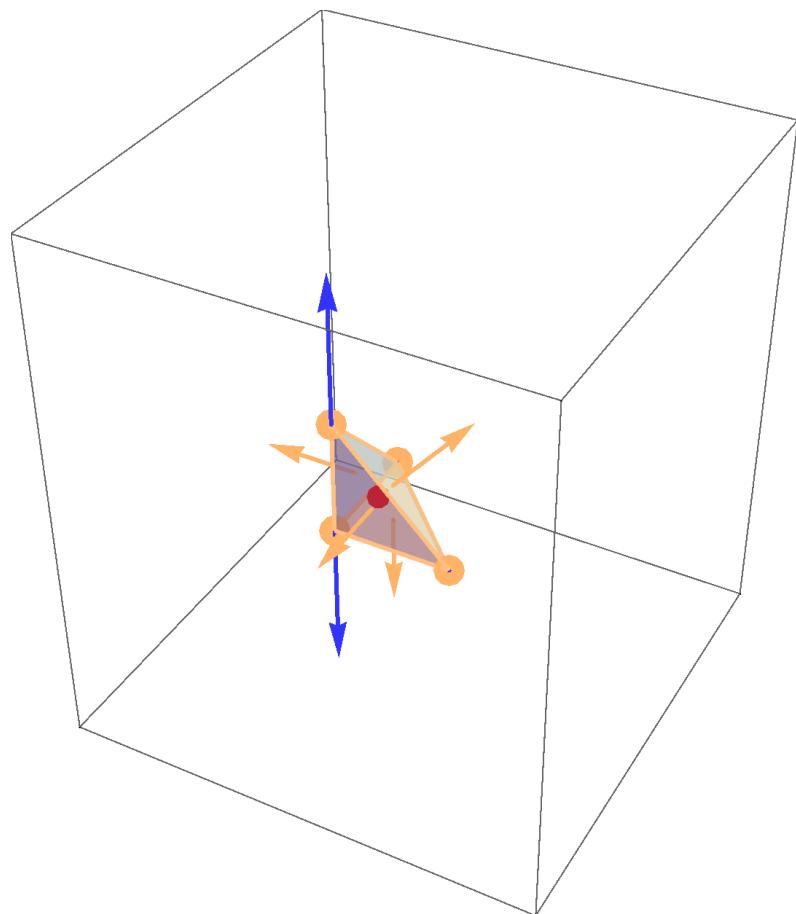


### 8.3 Uniaxial stress

In the absence of rotation, translation and volume forces, plot the nodal force vectors on the original vertices of the same tetrahedron for a uniaxial stress

$$\underline{\underline{T}} = \sigma ({}^3\mathbf{e} \otimes {}^3\mathbf{e}) \quad (6)$$

with  $\sigma = 10$  kPa.

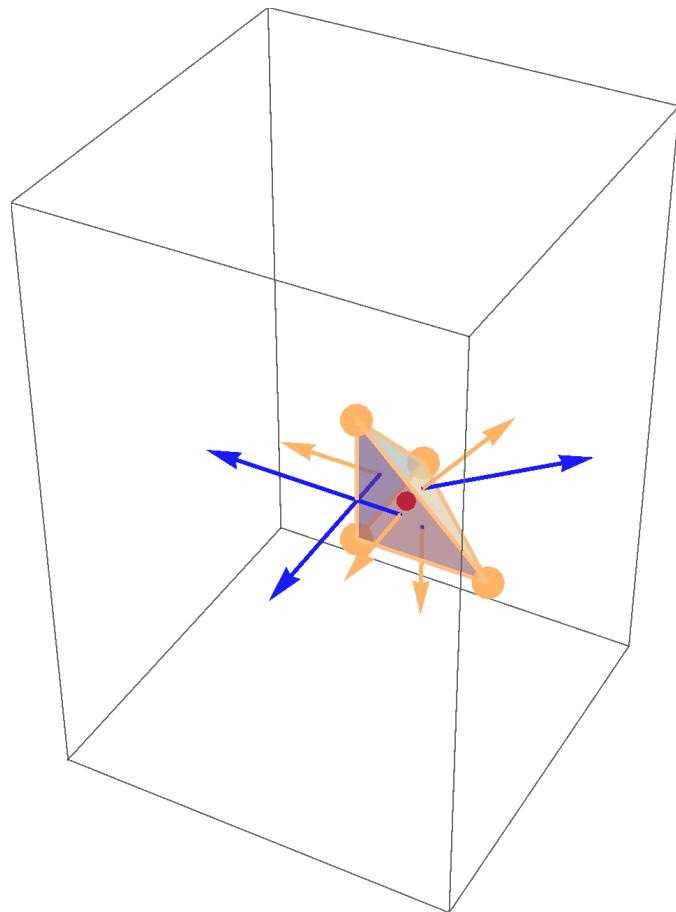


## 8.4 Shear stress

In the absence of rotation, translation and volume forces, plot the stress vectors on the face centroids of the same tetrahedron for a shear stress

$$\underline{\underline{T}} = \tau (\underline{^1e} \otimes \underline{^2e} + \underline{^2e} \otimes \underline{^1e}) \quad (7)$$

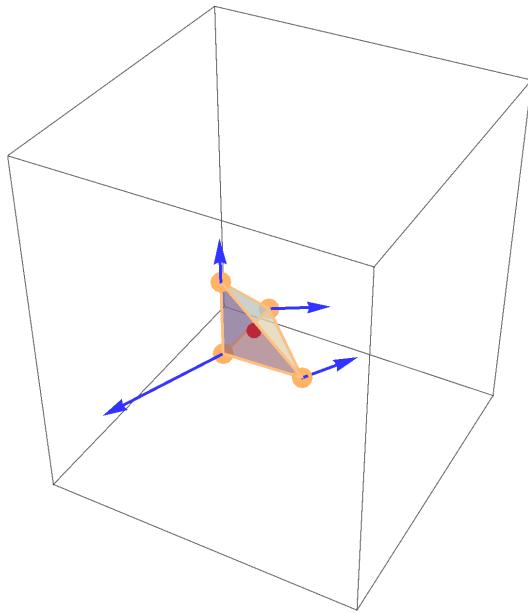
with  $\tau = 3.85$  kPa.



## 8.5 Option: Multiaxial stress

Plot the nodal force vectors on the original vertices for the superposition of the above stresses

$$\underline{\underline{\mathbf{T}}} = -\pi \underline{\underline{\mathbf{I}}} + \sigma (\underline{\underline{\mathbf{e}}}^3 \otimes \underline{\underline{\mathbf{e}}}^3) + \tau (\underline{\underline{\mathbf{e}}}^1 \otimes \underline{\underline{\mathbf{e}}}^2 + \underline{\underline{\mathbf{e}}}^2 \otimes \underline{\underline{\mathbf{e}}}^1)$$



Compute hydrostatic pressure and von Mises stress

$$\pi = -\frac{1}{3} \text{tr} \underline{\underline{\mathbf{T}}} = 28333.3 \text{ MPa}$$

$${}^{vM}T = \sqrt{\frac{3}{2} \underline{\underline{\mathbf{T}}}': \underline{\underline{\mathbf{T}}}' } = 55002.2 \text{ MPa}$$

with

$$\underline{\underline{\mathbf{T}}}' = \underline{\underline{\mathbf{T}}} + \pi \underline{\underline{\mathbf{I}}}$$