

p6_cnn.py

March 19, 2018

```
In [10]: # Import all relevant libraries
import warnings
def fxn():
    warnings.warn("deprecated", DeprecationWarning)

with warnings.catch_warnings( ):
    warnings.simplefilter("ignore")
    fxn( )

# Keras imports
import keras
from keras.models import Sequential
from keras.layers import BatchNormalization, MaxPooling2D, Permute, Flatten, Softmax,
from keras.utils import np_utils
from keras.optimizers import Adam

# Other
import numpy as np
import h5py
import sklearn
from sklearn import preprocessing
from sklearn.model_selection import StratifiedKFold
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
from keras import regularizers
import random

In [11]: # Load data from specific trial
def get_trial(trial_num):
    trial = h5py.File('data/A0' + str(trial_num) + 'T_slice.mat', 'r')
    X = np.copy(trial['image'])
    y = np.copy(trial['type'])
    y = y[0,0:X.shape[0]:1]
    y = np.asarray(y, dtype=np.int32)
    y -= 769 # shift class labels to [0-3]
    X = np.nan_to_num(X)[:,:22,:] # remove EOG channels
    return X, y
```

```

def get_all_trials():
    X_total = np.concatenate([get_trial(trial_num)[0] for trial_num in range(1, 9)], a
    y_total = np.concatenate([get_trial(trial_num)[1] for trial_num in range(1, 9)], a
    return X_total, y_total

def stratified_train_test_split(X, y, k):
    ''' Returns a stratified train/test split, for k number of splits.
    Return value is in the form [(train indices, test indices), ... for k folds ]
    '''
    skf = StratifiedKFold(n_splits=k)
    return skf.split(X, y)

```

In [12]: *# Get the data from one person*

```
num_folds = 5
```

```
# X, y = get_trial(1)
```

```
# num_trials = 1
```

```
def get_normalized_data():
```

```
# Get the data from all the people
```

```
X, y = get_all_trials()
```

```
num_trials = 9
```

```
X = np.transpose(X, (0,2,1))
```

```
# 0 mean and unit variance
```

```
temp = np.reshape(X, (X.shape[0], -1))
```

```
X = np.reshape(preprocessing.scale(temp), X.shape)
```

```
# Generate train/test split
```

```
y_cat = keras.utils.to_categorical(y, num_classes=4)
```

```
X_train, X_test, y_train, y_test = train_test_split(X, y)
```

```
tt_splits = stratified_train_test_split(X_train, y_train, num_folds)
```

```
one_hot_train = keras.utils.to_categorical(y_train)
```

```
one_hot_test = keras.utils.to_categorical(y_test)
```

```
return X_train, X_test, one_hot_train, one_hot_test, tt_splits
```

```
# The data for each trial is of the shape (288, 22, 1000)
```

```
# There are 288 samples per trial (12 of each class per "run", 4 classes, 6 "runs"  
# at different time periods of the day)
```

```
# There are 22 electrodes from the EEG (represents spatial aspect of the signals)
```

```
# There are 1000 time units (4 seconds of data, sampled at 250Hz). The first 250 un  
# are when no movement occurs (but the cue is heard,
```

```
# the next 750 units are when the movement occurs
```

```
# The labels for each trial belong in one of 4 classes
```

```
# 0 - left
```

```
# 1 - right
```

```
# 2 - foot
```

```

# 3 - tongue
# print(X_train.shape)
# print(X_test.shape)
# print(one_hot_train.shape)
# print(one_hot_test.shape)

```

```

In [67]: # more accurate version of 1D NN
# def CNN_1D(nl=2):
#     # Naive implementation
#     num_layers = nl
#     model = Sequential()
#     for _ in np.arange(num_layers):
#         model.add(Conv1D(filters = 25, kernel_size = 10, activation = 'elu', input_shape=(X_train.shape[1], X_train.shape[2])))
#         model.add(BatchNormalization())
#         model.add(Dropout(0.4))
#     model.add(AveragePooling1D(pool_size=(75), strides=(15)))
#     model.add(Dropout(0.5))
#     model.add(Flatten())
#     model.add(Dense(units=4, kernel_initializer='glorot_normal', activity_regularizer=keras.regularizers.l2(0.01)))

#     adam = Adam(lr=0.0007, decay=0.005)
#     sgd = keras.optimizers.SGD(lr=0.01, momentum=0.7, decay=0.001, nesterov=True)
#     model.compile(optimizer=adam,
#                   loss='categorical_crossentropy',
#                   metrics=['accuracy'])
#     return model

```

```

In [82]: # grid search for number of layers
batch_size = 32
num_epochs = 40
history = []
for l2 in [0.0005, 0.0001, 0.005, 0.001, 0.05]:
    X_tr, X_te, y_tr, y_te, tt_splits = get_normalized_data()
    print("l2_norm", l2)
    nl_histories = []
    for i, (train, test) in enumerate(tt_splits):
        print("running fold", i)
        model = CNN_1D(l2=l2)
        nl_histories.append(model.fit(X_tr[train], y_tr[train], validation_data=(X_tr[test], y_te[test]),
                                     num_epochs=num_epochs))
    history.append(np.average(nl_histories, axis=0))

for hist_tuple in history:
    plt.plot(hist_tuple)

plt.title('validation accuracy for different L2 norms')
plt.ylabel('accuracy')
plt.xlabel('epoch')

```

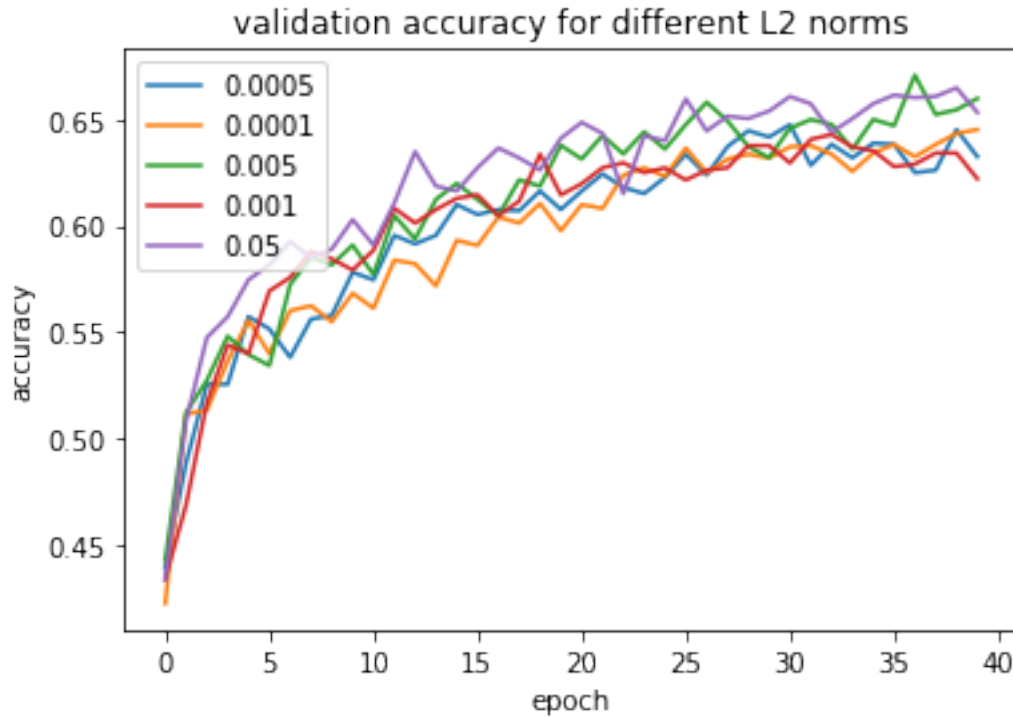
```

plt.legend(['0.0005', '0.0001', '0.005', '0.001', '0.05'], loc='upper left')
plt.show()
plt.savefig('l2_norm.pdf')

for hist_tuple in history:
    print(sum(hist_tuple[-10:])/len(hist_tuple[-10:]))

l2_norm 0.0005
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4
l2_norm 0.0001
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4
l2_norm 0.005
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4
l2_norm 0.001
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4
l2_norm 0.05
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4

```



0.6352318688295282
0.636594899038365
0.6514149575248166
0.6332849951630579
0.6570739652386945

<matplotlib.figure.Figure at 0x146858198>

```
In [87]: def CNN_1D(nl=2, optimizer='adam', filters=30, lr=0.001, ld=0.0001, dp1=0.3, dp2=0.4,
# Naive implementation
num_layers = nl
model = Sequential()
for _ in np.arange(num_layers):
    model.add(Conv1D(filters = filters, kernel_size = 10, activation = 'elu', input_shape=(1, 100)))
    model.add(BatchNormalization())
    model.add(Dropout(dp1))

model.add(AveragePooling1D(pool_size=(75), strides=(15)))
model.add(Dropout(dp2))
model.add(Flatten())
model.add(Dense(units=4, kernel_initializer='glorot_normal', activity_regularizer=
```

```

optimizer = Adam(lr=lr, decay=ld)
#     sgd = keras.optimizers.SGD(lr=0.01, momentum=0.7, decay=0.001, nesterov=True)
model.compile(optimizer=optimizer,
              loss='categorical_crossentropy',
              metrics=['accuracy'])
return model

```

In [78]: CNN_1D()

(None, 991, 25)

(None, 982, 25)

Out[78]: <keras.models.Sequential at 0x14e3b3470>

In [76]: # grid search for number of layers

```

batch_size = 32
num_epochs = 40
history = []
for nl in [1,2,3,5,7,9]:
    X_tr, X_te, y_tr, y_te, tt_splits = get_normalized_data()
    print("running number of layers", nl)
    nl_histories = []
    for i, (train,test) in enumerate(tt_splits):
        print("running fold", i)
        model = CNN_1D(nl)
        nl_histories.append(model.fit(X_tr[train], y_tr[train], validation_data=(X_tr[
            history.append(np.average(nl_histories, axis=0))

for hist_tuple in history:
    plt.plot(hist_tuple)

plt.title('validation accuracy for different layers')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['One layer', 'Two layers', 'Three layers', 'Five layers', 'Seven layers',
# plt.legend(['One layer', 'Two layers'], loc='upper left')
plt.show()
plt.savefig('layers.pdf')

for hist_tuple in history:
    print(sum(hist_tuple[-10:])/len(hist_tuple[-10:]))

```

running number of layers 1

running fold 0

running fold 1

running fold 2

running fold 3

running fold 4

```

running number of layers 2
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4
running number of layers 3
running fold 0
running fold 1
running fold 2
running fold 3
running fold 4
running number of layers 5
running fold 0

```

KeyboardInterrupt

Traceback (most recent call last)

```

<ipython-input-76-9e2a98c44712> in <module>()
    10         print("running fold", i)
    11         model = CNN_1D(nl)
---> 12         nl_histories.append(model.fit(X_tr[train], y_tr[train], validation_data=(X_
    13         history.append(np.average(nl_histories, axis=0))
    14

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/keras/models.py in fit
    961         initial_epoch=initial_epoch,
    962         steps_per_epoch=steps_per_epoch,
--> 963         validation_steps=validation_steps)
    964
    965     def evaluate(self, x=None, y=None,

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/keras/engine/training.py
1703         initial_epoch=initial_epoch,
1704         steps_per_epoch=steps_per_epoch,
-> 1705         validation_steps=validation_steps)
1706
1707     def evaluate(self, x=None, y=None,

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/keras/engine/training.py
1247         val_outs = self._test_loop(val_f, val_ins,
1248                                     batch_size=batch_size,

```

```

-> 1249                                     verbose=0)
1250                                     if not isinstance(val_outs, list):
1251                                     val_outs = [val_outs]

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/keras/engine/training.py
1424                                     ins_batch[i] = ins_batch[i].toarray()
1425
-> 1426                                     batch_outs = f(ins_batch)
1427                                     if isinstance(batch_outs, list):
1428                                     if batch_index == 0:

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/keras/backend/tensorflow_backend.py
2476                                     session = get_session()
2477                                     updated = session.run(fetches=fetches, feed_dict=feed_dict,
-> 2478                                     **self.session_kwargs)
2479                                     return updated[:len(self.outputs)]
2480

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/tensorflow/python/client/tensor_client.py
903                                     try:
904                                     result = self._run(None, fetches, feed_dict, options_ptr,
--> 905                                     run_metadata_ptr)
906                                     if run_metadata:
907                                     proto_data = tf_session.TF_GetBuffer(run_metadata_ptr)

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/tensorflow/python/client/tensor_client.py
1135                                     if final_fetches or final_targets or (handle and feed_dict_tensor):
1136                                     results = self._do_run(handle, final_targets, final_fetches,
-> 1137                                     feed_dict_tensor, options, run_metadata)
1138                                     else:
1139                                     results = []

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/tensorflow/python/client/tensor_client.py
1353                                     if handle is None:
1354                                     return self._do_call(_run_fn, self._session, feeds, fetches, targets,
-> 1355                                     options, run_metadata)
1356                                     else:
1357                                     return self._do_call(_prun_fn, self._session, handle, feeds, fetches)

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/tensorflow/python/client/tensor_client.py
1359                                     def _do_call(self, fn, *args):
1360                                     try:

```



```

-> 1361         return fn(*args)
    1362     except errors.OpError as e:
    1363         message = compat.as_text(e.message)

~/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/tensorflow/python/client
1338         else:
1339             return tf_session.TF_Run(session, options, feed_dict, fetch_list,
-> 1340                                     target_list, status, run_metadata)
1341
1342     def _prun_fn(session, handle, feed_dict, fetch_list):

```

KeyboardInterrupt:

```

In [ ]: # batch_size = 32
        num_epochs = 40
        X_tr, X_te, y_tr, y_te, tt_splits = get_normalized_data()
        history = []
        for batch_size in [32, 64, 128]:
            for nl in [1,2]:
                print("running number of layers", nl)
                nl_histories = []
                for i, (train,test) in enumerate(tt_splits):
                    print("running fold", i)
                    model = CNN_1D(nl)
                    nl_histories.append(model.fit(X_tr[train], y_tr[train], validation_data=(X
                    history.append(np.average(nl_histories, axis=0))
        for hist_tuple in history:
            plt.plot(hist_tuple)
        plt.title('validation accuracy for different layers')
        plt.ylabel('accuracy')
        plt.xlabel('epoch')
        # plt.legend(['One layer', 'Two layers', 'Three layers', 'Five layers', 'Seven layers
        plt.legend(['One layer', 'Two layers'], loc='upper left')
        plt.show()
        savefig('layers.pdf')

```

```

In [88]: batch_size = 32
        num_epochs = 40
        val_split = 0.2
        X_tr, X_te, y_tr, y_te, tt_splits = get_normalized_data()
        avg_acc = 0
        # for train_idx, test_idx in tt_splits:
        #     print(train_idx, X_tr.shape)
        #     X_train = X_tr[train_idx]
        #     y_train = y_tr[train_idx]

```

```

#     X_test = X_tr[test_idx]
#     y_test = y_tr[test_idx]

#     print(X_train.shape)
model = CNN_1D()
history = model.fit(X_tr, y_tr, validation_split=val_split, epochs=num_epochs, batch_size=batch_size)
plt.plot(history.history['acc'])
plt.plot(history.history['val_acc'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
metrics = model.evaluate(X_test, y_test, batch_size=batch_size)
avg_acc += metrics[0]

print(metrics)

metrics = model.evaluate(X_te, y_te, batch_size=batch_size)
print('testing', metrics)

```

Train on 1382 samples, validate on 346 samples

```

Epoch 1/40
1382/1382 [=====] - 14s 10ms/step - loss: 2.7161 - acc: 0.3459 - val_loss: 2.7161
Epoch 2/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.3723 - acc: 0.4624 - val_loss: 2.3723
Epoch 3/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.2231 - acc: 0.5195 - val_loss: 2.2231
Epoch 4/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.1472 - acc: 0.5637 - val_loss: 2.1472
Epoch 5/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.1084 - acc: 0.5948 - val_loss: 2.1084
Epoch 6/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0944 - acc: 0.6107 - val_loss: 2.0944
Epoch 7/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0823 - acc: 0.6165 - val_loss: 2.0823
Epoch 8/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0731 - acc: 0.6187 - val_loss: 2.0731
Epoch 9/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0638 - acc: 0.6462 - val_loss: 2.0638
Epoch 10/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0657 - acc: 0.6324 - val_loss: 2.0657
Epoch 11/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0523 - acc: 0.6773 - val_loss: 2.0523
Epoch 12/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0469 - acc: 0.6751 - val_loss: 2.0469
Epoch 13/40

```

```

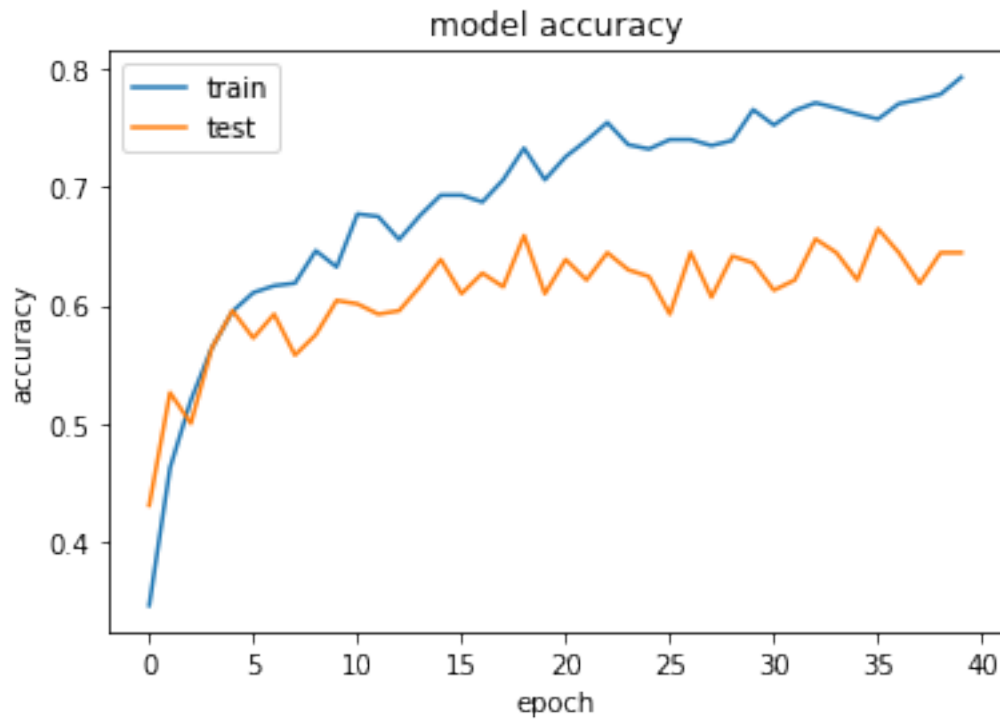
1382/1382 [=====] - 5s 4ms/step - loss: 2.0527 - acc: 0.6556 - val_loss: 2.0527
Epoch 14/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0463 - acc: 0.6758 - val_loss: 2.0463
Epoch 15/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0376 - acc: 0.6932 - val_loss: 2.0376
Epoch 16/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0381 - acc: 0.6932 - val_loss: 2.0381
Epoch 17/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0479 - acc: 0.6874 - val_loss: 2.0479
Epoch 18/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0321 - acc: 0.7062 - val_loss: 2.0321
Epoch 19/40
1382/1382 [=====] - 7s 5ms/step - loss: 2.0161 - acc: 0.7330 - val_loss: 2.0161
Epoch 20/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0259 - acc: 0.7062 - val_loss: 2.0259
Epoch 21/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0138 - acc: 0.7258 - val_loss: 2.0138
Epoch 22/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0172 - acc: 0.7395 - val_loss: 2.0172
Epoch 23/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0111 - acc: 0.7547 - val_loss: 2.0111
Epoch 24/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0168 - acc: 0.7359 - val_loss: 2.0168
Epoch 25/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0090 - acc: 0.7323 - val_loss: 2.0090
Epoch 26/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0051 - acc: 0.7402 - val_loss: 2.0051
Epoch 27/40
1382/1382 [=====] - 6s 4ms/step - loss: 2.0079 - acc: 0.7402 - val_loss: 2.0079
Epoch 28/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0069 - acc: 0.7352 - val_loss: 2.0069
Epoch 29/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0075 - acc: 0.7395 - val_loss: 2.0075
Epoch 30/40
1382/1382 [=====] - 5s 4ms/step - loss: 2.0008 - acc: 0.7656 - val_loss: 2.0008
Epoch 31/40
1382/1382 [=====] - 5s 4ms/step - loss: 1.9984 - acc: 0.7525 - val_loss: 1.9984
Epoch 32/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9978 - acc: 0.7648 - val_loss: 1.9978
Epoch 33/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9922 - acc: 0.7713 - val_loss: 1.9922
Epoch 34/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9940 - acc: 0.7670 - val_loss: 1.9940
Epoch 35/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9895 - acc: 0.7619 - val_loss: 1.9895
Epoch 36/40
1382/1382 [=====] - 7s 5ms/step - loss: 1.9945 - acc: 0.7576 - val_loss: 1.9945
Epoch 37/40

```

```

1382/1382 [=====] - 6s 4ms/step - loss: 1.9962 - acc: 0.7706 - val_loss: 2.0753
Epoch 38/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9880 - acc: 0.7742 - val_loss: 2.0753
Epoch 39/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9866 - acc: 0.7786 - val_loss: 2.0753
Epoch 40/40
1382/1382 [=====] - 6s 4ms/step - loss: 1.9860 - acc: 0.7931 - val_loss: 2.0753

```



```

346/346 [=====] - 1s 2ms/step
[1.9914478477025996, 0.7543352590820004]
576/576 [=====] - 1s 2ms/step
testing [2.075380047162374, 0.6458333333333334]

```

```
In [ ]: # Deep Implementation CNN
```

```
model = Sequential()
```

```
# Conv Pool Block 1
```

```
model.add(Conv2D(filters=25, kernel_size=(10,1), input_shape=(1000, 22, 1), strides=1,
```

```
model.add(Conv2D(filters = 25, kernel_size = (1,22), activation = 'elu'))
```

```
model.add(Permute((1,3,2)))
```

```
model.add(BatchNormalization())
```

```

model.add(MaxPooling2D(pool_size = (3,1), strides = (3,1)))
model.add(Dropout(0.5))
print(model.output_shape)

# Conv Pool Block 2
model.add(Conv2D(filters = 50, kernel_size = (10,25), activation = 'elu'))
model.add(Permute((1,3,2)))
model.add(BatchNormalization())
model.add(MaxPooling2D(pool_size = (3,1), strides = (3,1)))
model.add(Dropout(0.5))
print(model.output_shape)

# Conv Pool Block 3
model.add(Conv2D(filters = 100, kernel_size = (10,50), activation = 'elu'))
model.add(Permute((1,3,2)))
model.add(BatchNormalization())
model.add(MaxPooling2D(pool_size = (3,1), strides = (3,1)))
model.add(Dropout(0.5))
print(model.output_shape)

# Conv Pool Block 4
model.add(Conv2D(filters = 200, kernel_size = (10,100), activation = 'elu'))
model.add(Permute((1,3,2)))
model.add(BatchNormalization())
model.add(MaxPooling2D(pool_size = (3,1), strides = (3,1)))
model.add(Dropout(0.5))
print(model.output_shape)

# Dense Layers
model.add(Flatten())
model.add(Dense(units=4, kernel_initializer='glorot_normal', activation = 'softmax'))
print(model.output_shape)

#Adam = Adam(lr=0.15)
model.compile(optimizer='adam',
              loss='categorical_crossentropy',
              metrics=['accuracy'])

X_train = X_train.transpose((0,2,1))
X_train = X_train[:, :, 0:22]

X_test = X_test.transpose((0,2,1))
X_test = X_test[:, :, 0:22]

```

```

model.fit(X_train[:, :, :, None] , one_hot_train, epochs=30, batch_size=32)
score = model.evaluate(X_test, one_hot_test, verbose=0)
print(score)

```

In []: *# Shallow CNN*

```

model = Sequential()
model.add(Conv2D(filters=40, kernel_size=(25,1), activation='elu', input_shape=(1000, 1, 1, 1)))
print(model.output_shape)
model.add(Permute((3, 2, 1)))
print(model.output_shape)
model.add(Conv2D(filters=40, kernel_size=(22, 40), activation='elu', data_format="channels_last"))
print(model.output_shape)
model.add(Permute((3, 2, 1)))
print(model.output_shape)
model.add(AveragePooling2D(pool_size=(75,1), strides=(15,1)))
print(model.output_shape)
model.add(Flatten())
model.add(Dense(units=4, kernel_initializer='glorot_normal', activation = 'softmax'))
print(model.output_shape)

```

```

Adam = Adam(lr=0.15)
model.compile(optimizer='adam',
              loss='categorical_crossentropy',
              metrics=['accuracy'])

```

```

X_train = X_train.transpose((0,2,1))
X_train = X_train[:, :, 0:22]

```

```

X_test = X_test.transpose((0,2,1))
X_test = X_test[:, :, 0:22]

```

```

model.fit(X_train[:, :, :, None] , one_hot_train, epochs=30, batch_size=32)
score = model.evaluate(X_test, one_hot_test, verbose=0)
print(score)

```

In [71]: `print(nl_histories)`
`np.average(nl_histories, axis=0)`

[]

```

/Users/jayendrajog/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/numpy/lib/function_base.py:2547: RuntimeWarning: Mean of empty slice.
  avg = a.mean(axis)
/Users/jayendrajog/code/EC239/p6/ece239_project/.env/lib/python3.6/site-packages/numpy/core/_methods.py:187: RuntimeWarning: invalid value encountered in divide
  _ufunc__rdivide__ = _ufunc__div__

```

```
ret = ret.dtype.type(ret / rcount)
```

```
Out[71]: nan
```