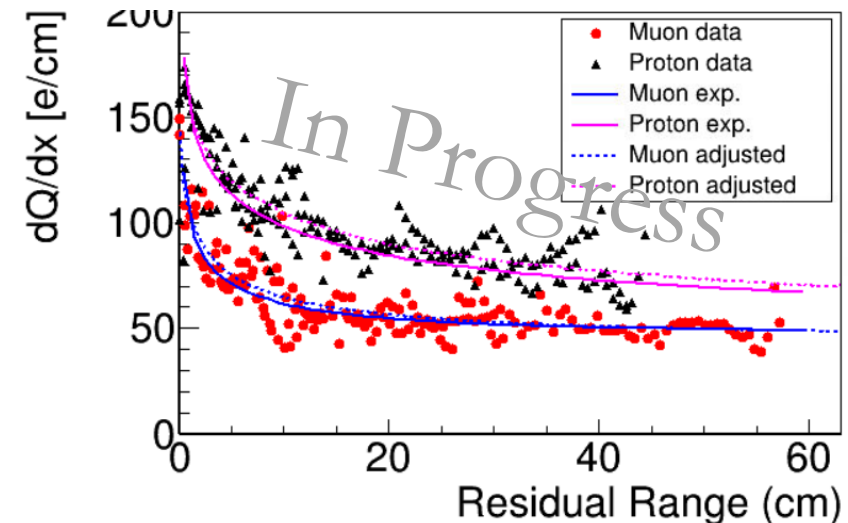
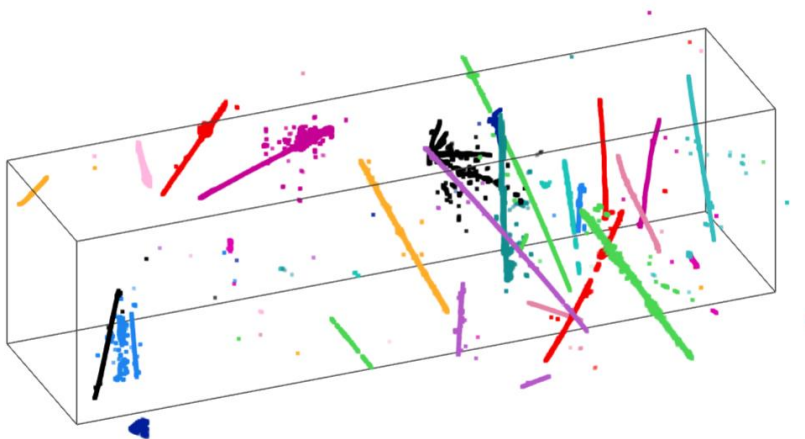


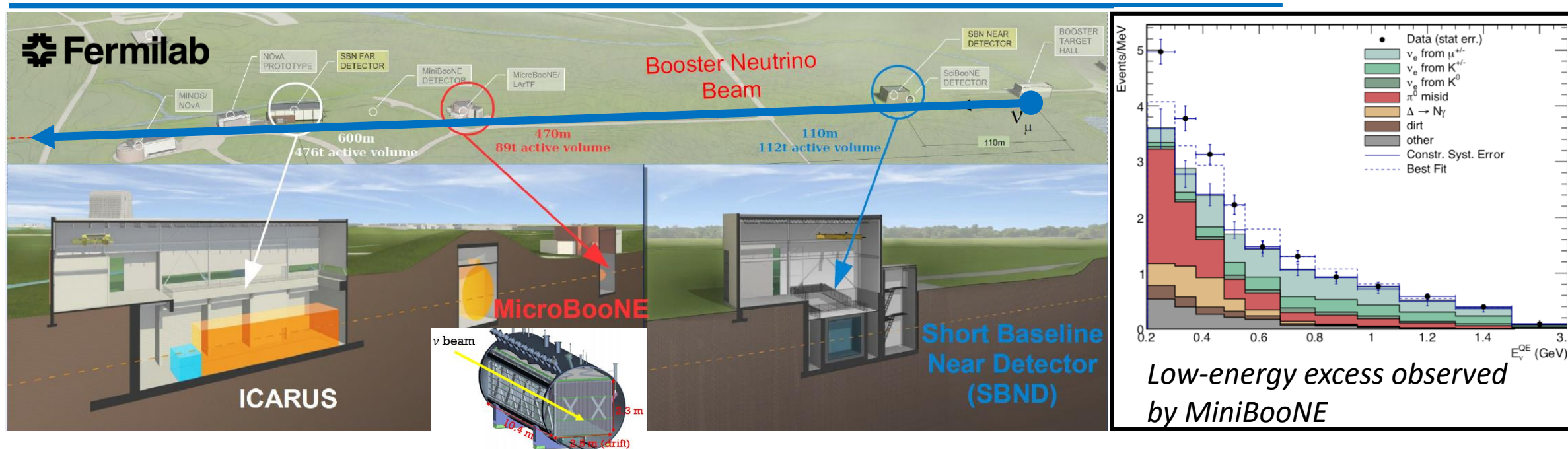
# Recent Progress on Wire-Cell 3D Event Reconstruction in MicroBooNE

Wenqiang Gu

Brookhaven National Laboratory



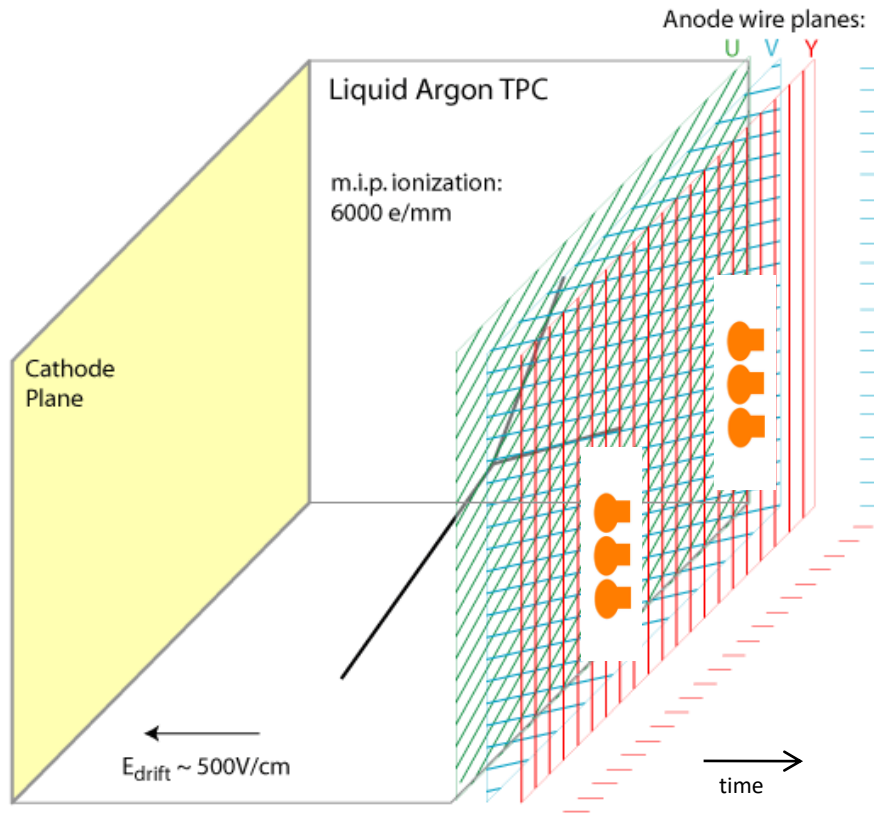
# The MicroBooNE Experiment



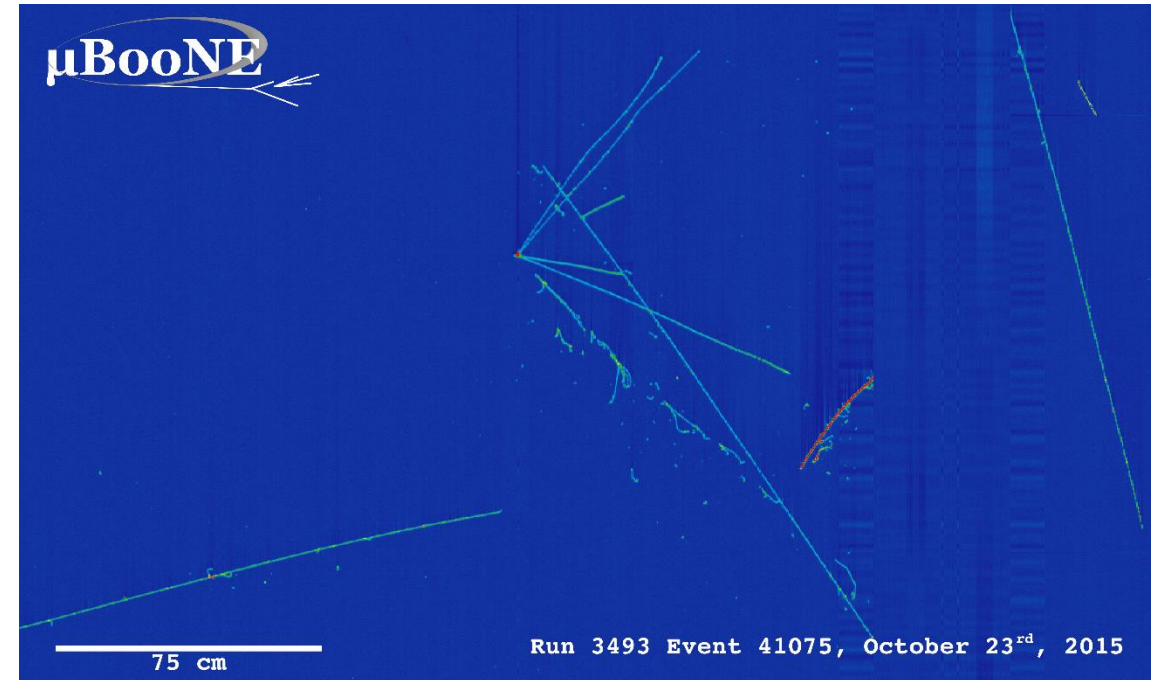
- Goals of the Short Baseline Neutrino Program
  - ▶ low-energy excess indicated by MiniBooNE
  - ▶ sterile neutrinos
  - ▶  $\nu$ -Ar interaction cross section

# Principle of Single-Phase LArTPC

Made by Bo Yu (BNL)

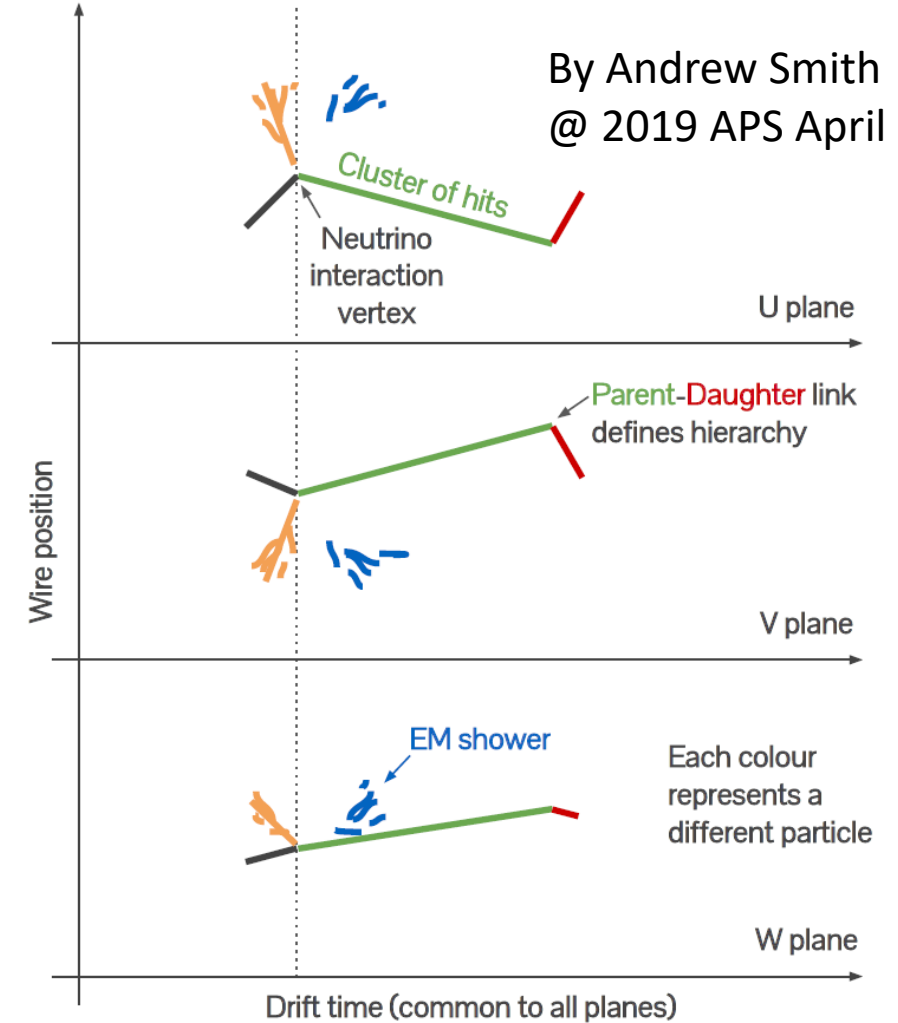
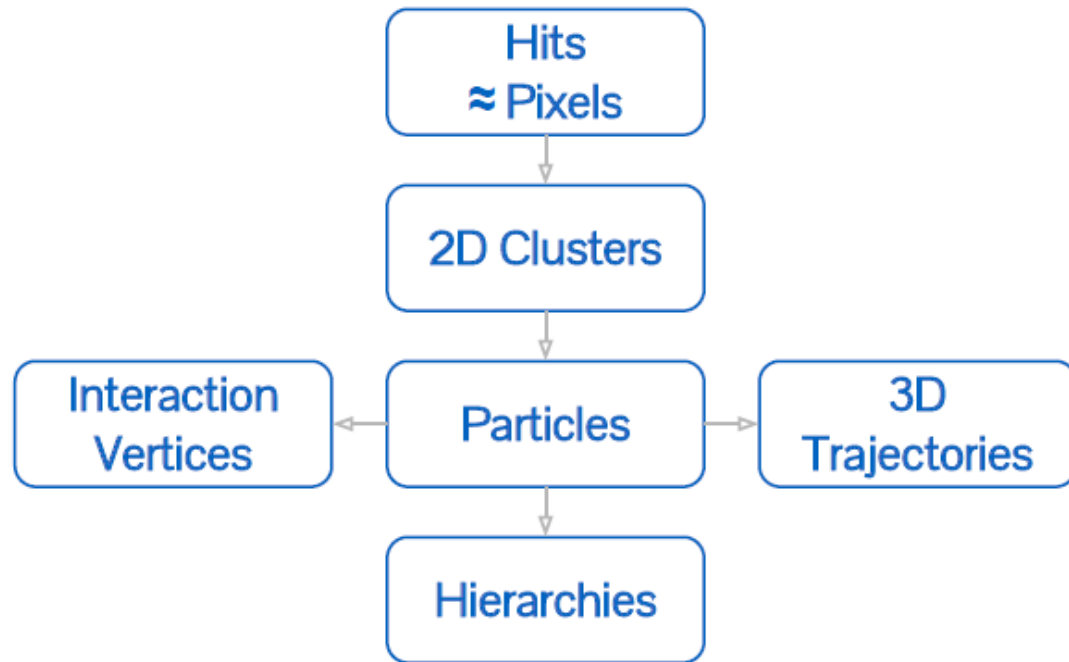
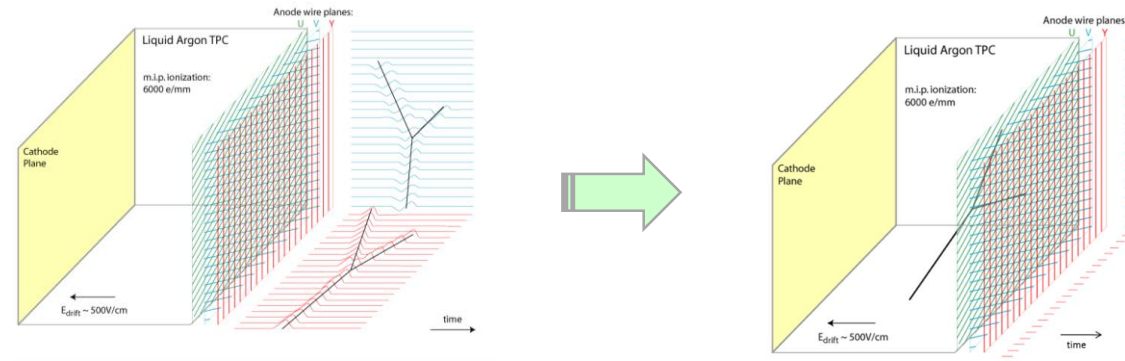


Drift velocity  $\sim O(1)$  km/s  $\Rightarrow$  a few ms drift time



- $\sim$  millimeter scale spatial resolution
- Excellent charge resolution
  - e/ $\gamma$  separation: bkg. rejection for  $\nu_e$  CC

# Traditional Reco. Approach: 2D matching $\Rightarrow$ 3D



*Illustration of LArTPC pattern recognition in the Pandora framework*



# Wire-Cell Tomographic Event Reconstruction

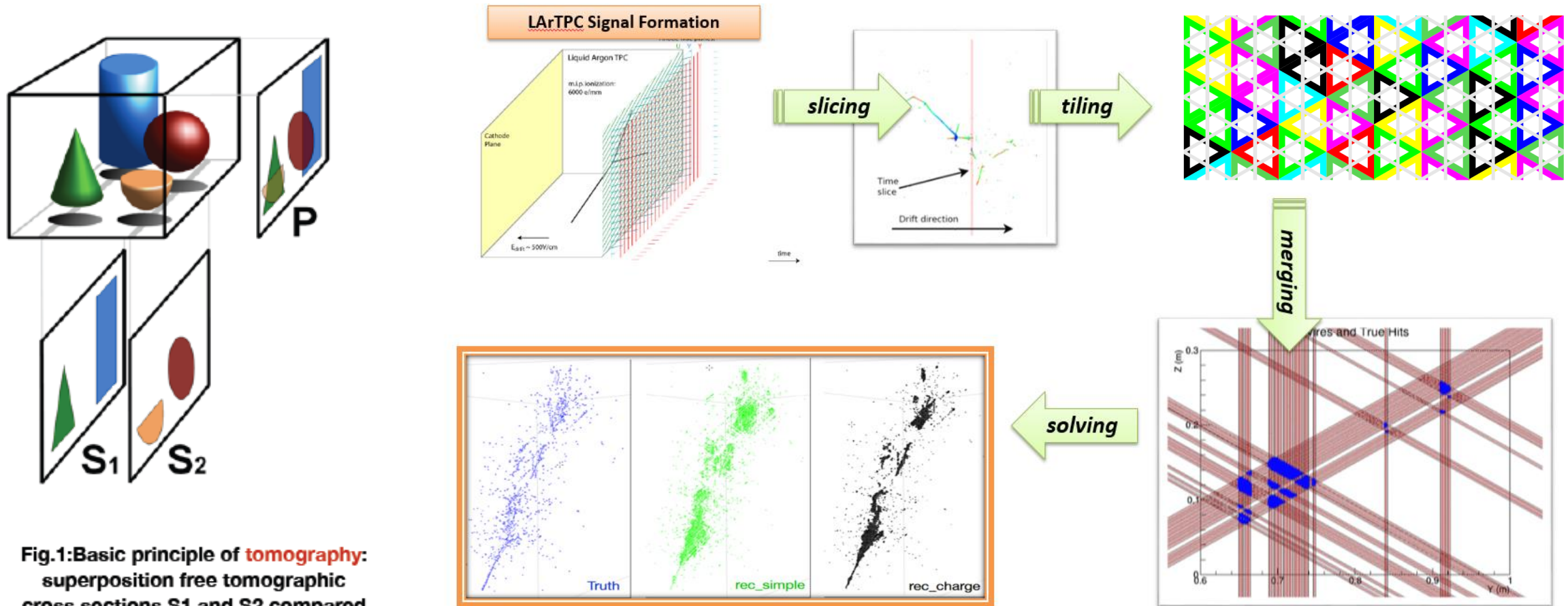
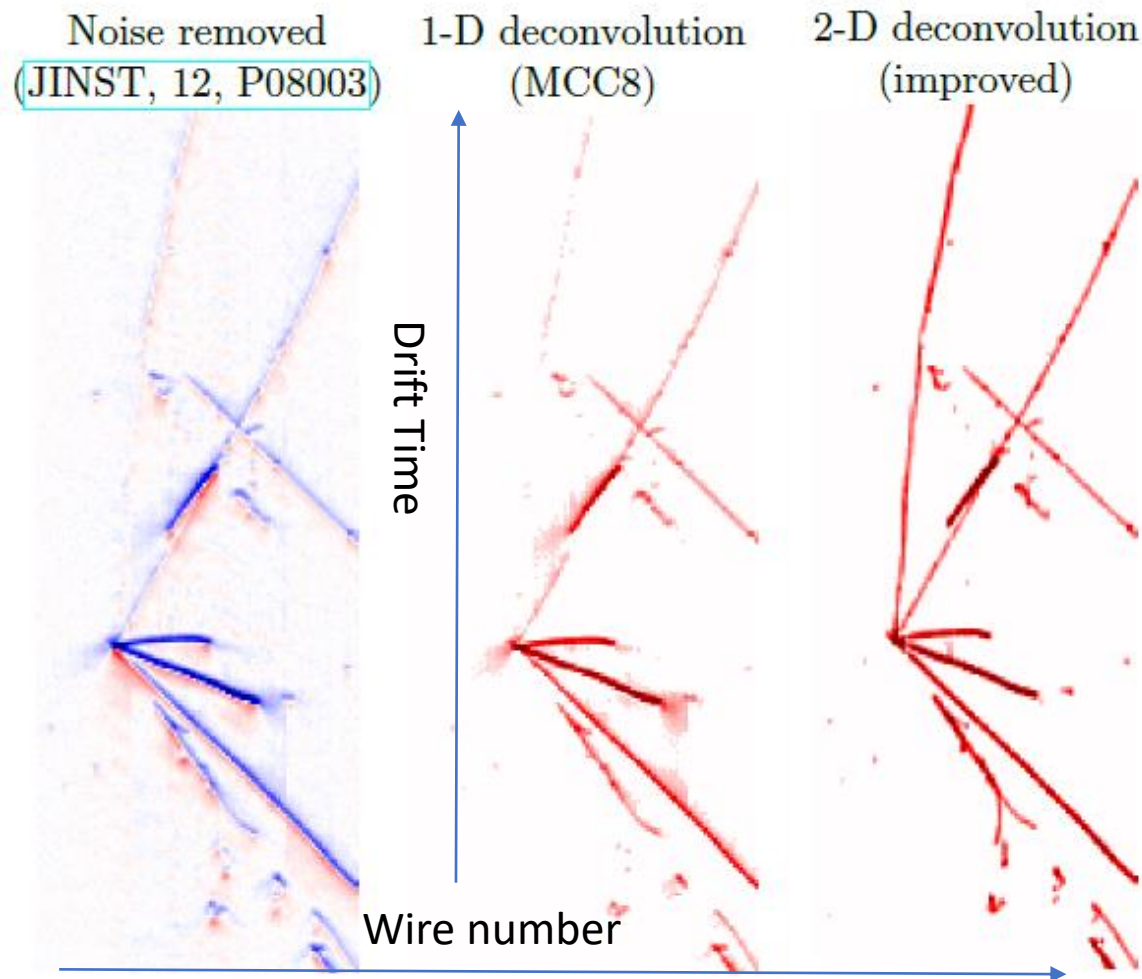


Fig.1: Basic principle of **tomography**: superposition free tomographic cross sections  $S_1$  and  $S_2$  compared with the projected image  $P$

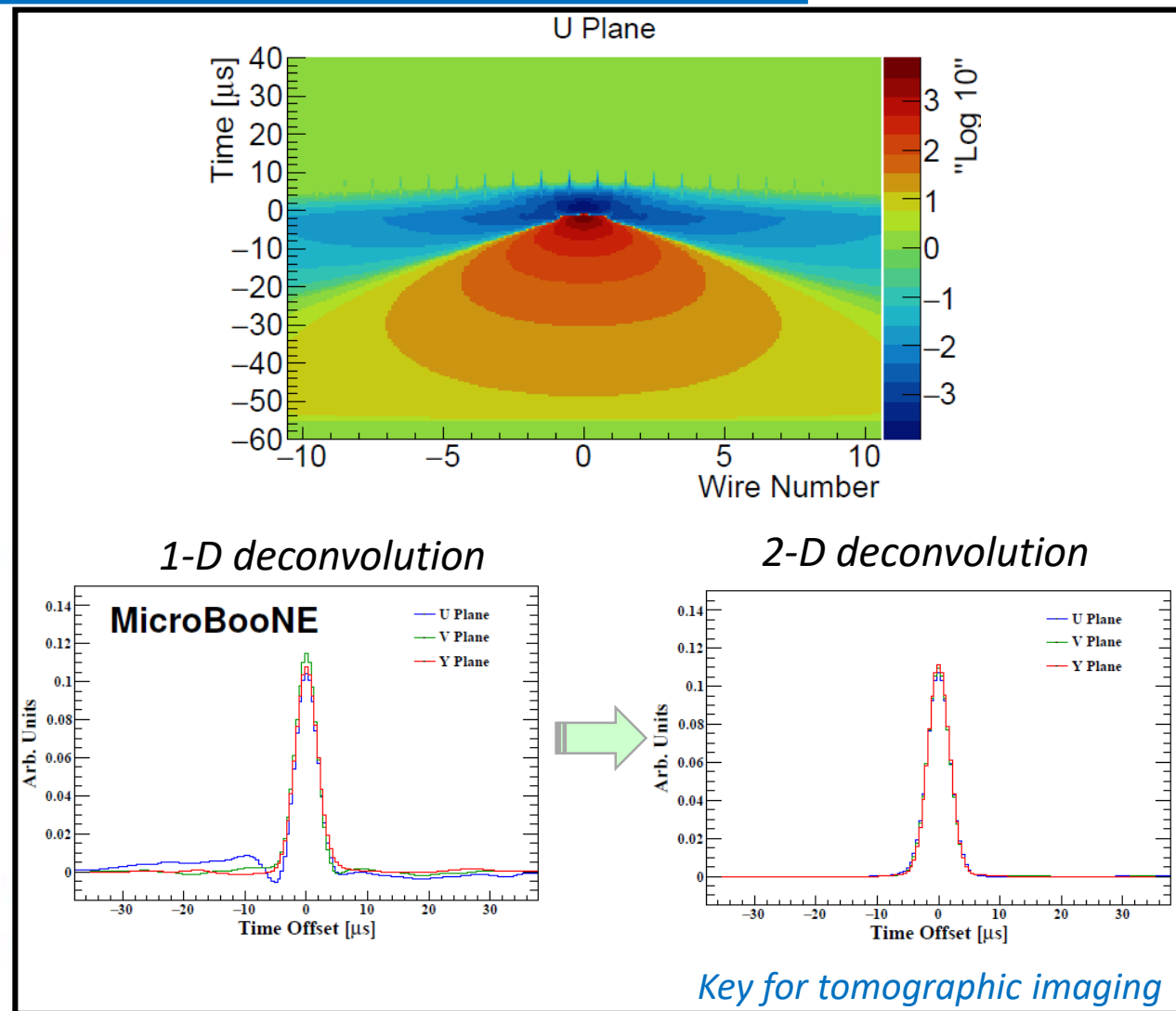
<https://en.wikipedia.org/wiki/Tomography>

Three-dimensional Imaging for Large LArTPCs  
Xin Qian *et al.* **JINST 13, P05032 (2018)**

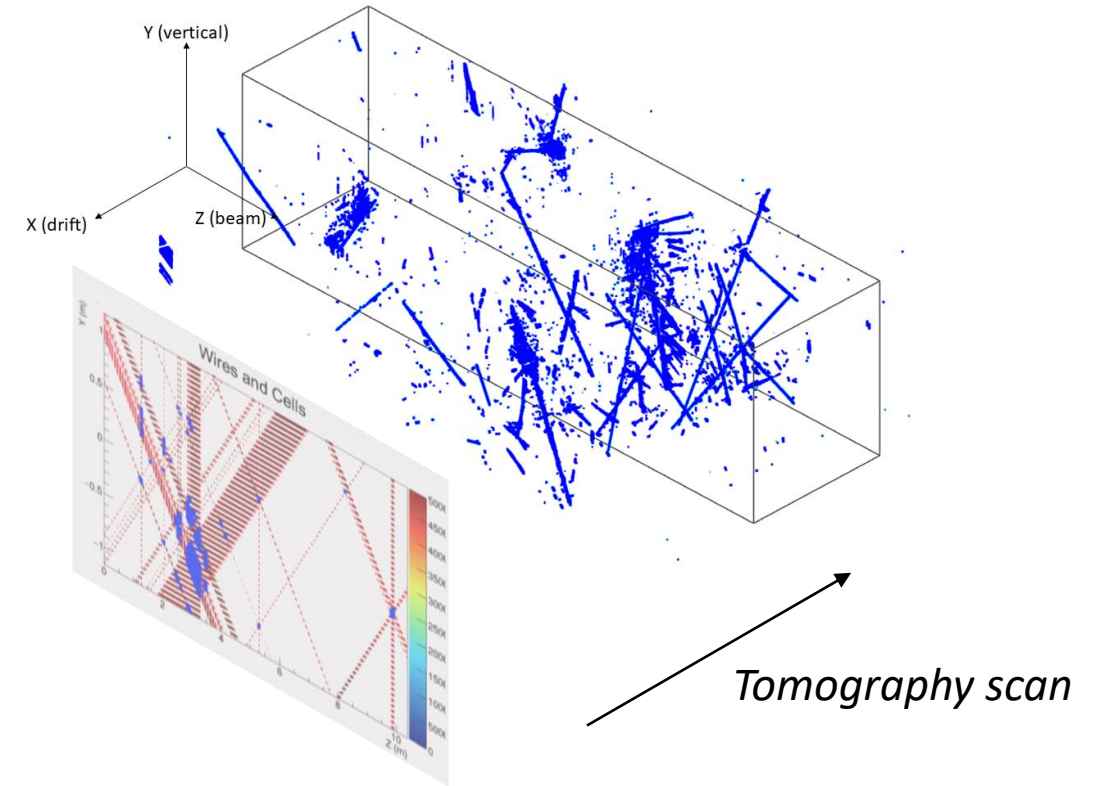
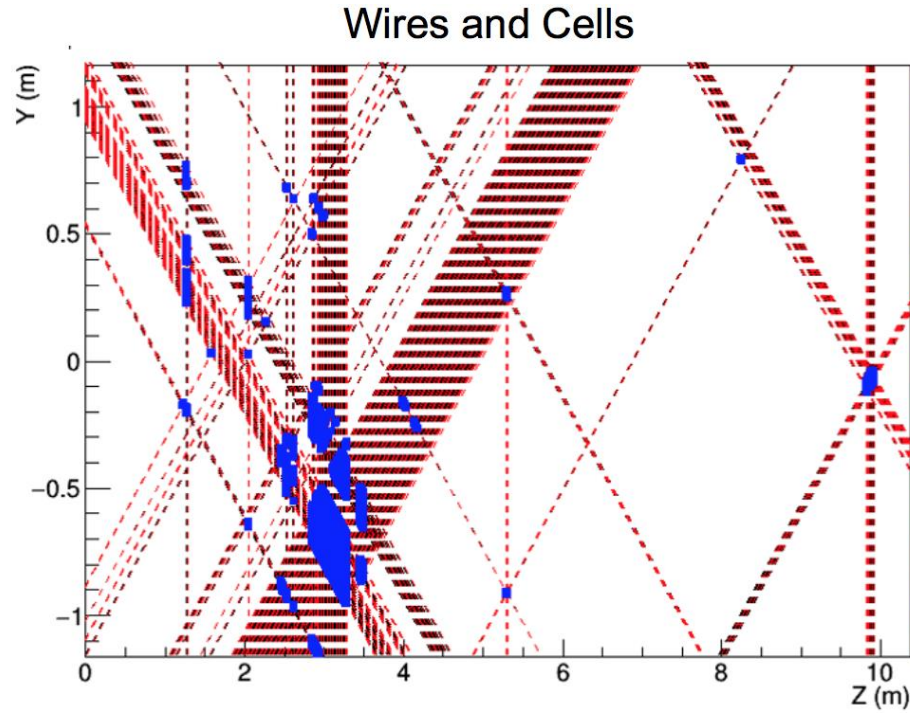
# Improved Signal Processing for Tomography



JINST 13 P07006/7 (2018)

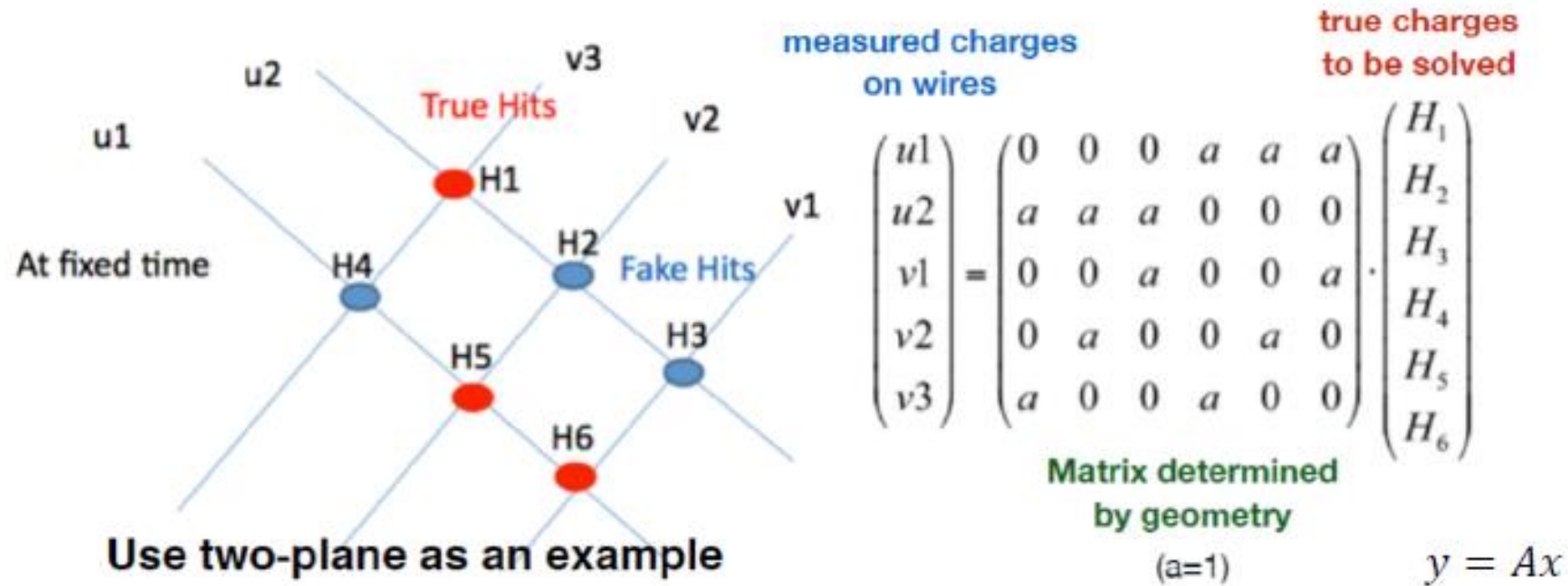


# Tomographic Reconstruction: Slicing and Tiling



- 2-plane tiling: at least two planes to be “fired” in a time slice

# Eliminate Fake Hits: Charge Solving



- **Fake hits** cannot be avoided when tiling the hit cells
- Instead, eliminated by solving a linear system with the wire geometry
  - ▶ However, this particular example, 6 unknowns with 5 equations. What to do??



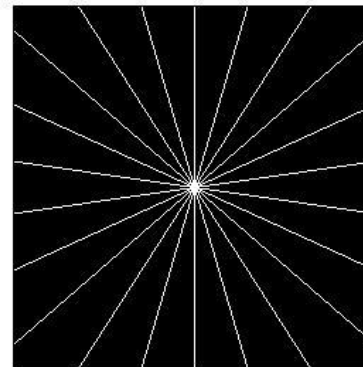
# Compressed Sensing

- Compressed sensing is a mathematical technique to recover **sparse signal** from under-determined (linear) system
  - ▶ However, very expensive in computing for a brute force solution
- A breakthrough comes from the proof that L0 problem can be well approximated by the L1 regularization

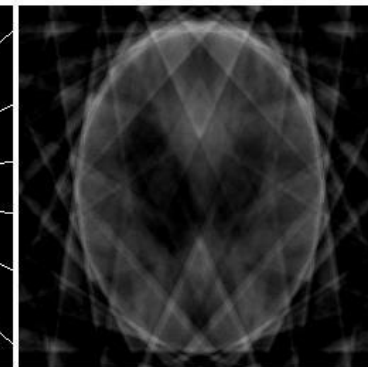
$$\text{minimize} \quad \chi^2 = (y - A \cdot x)^2 + \lambda \cdot \sum_i |x_i|$$

Hours of computing time with L0  
⇒ minutes of computing time with L1

- Sparse projections: 11 radial lines



available portion of the spectrum  
(11 radial lines)

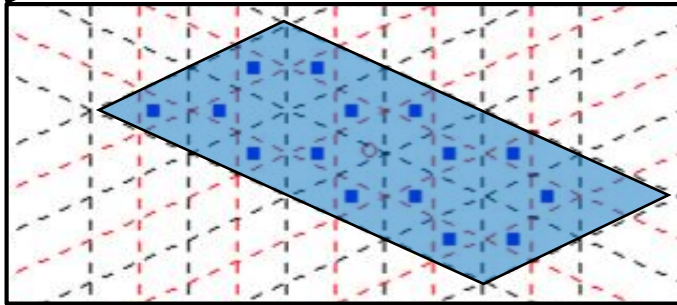
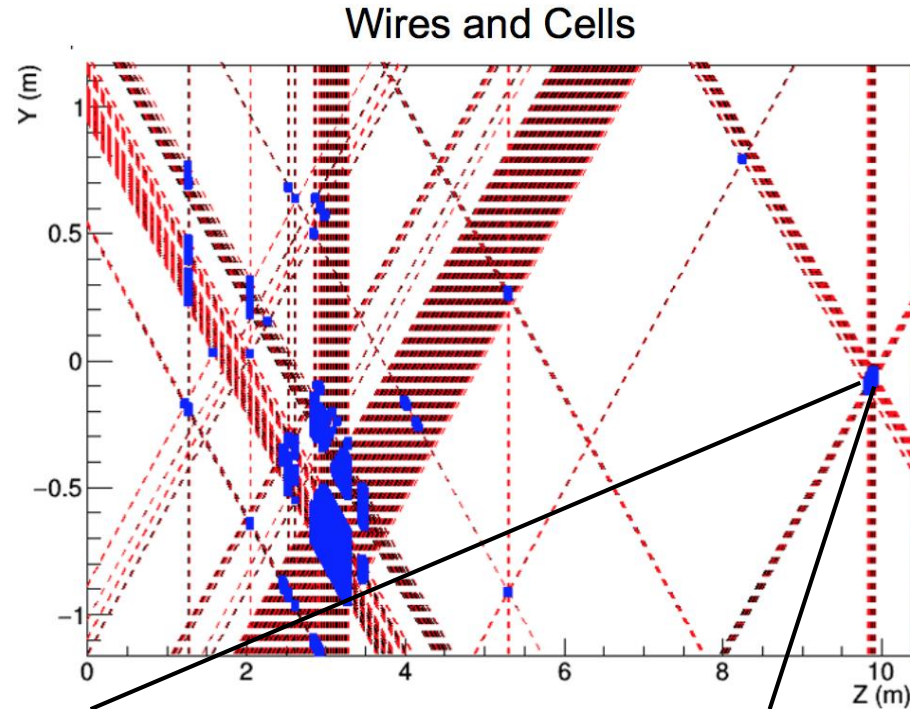


Back-projection estimate

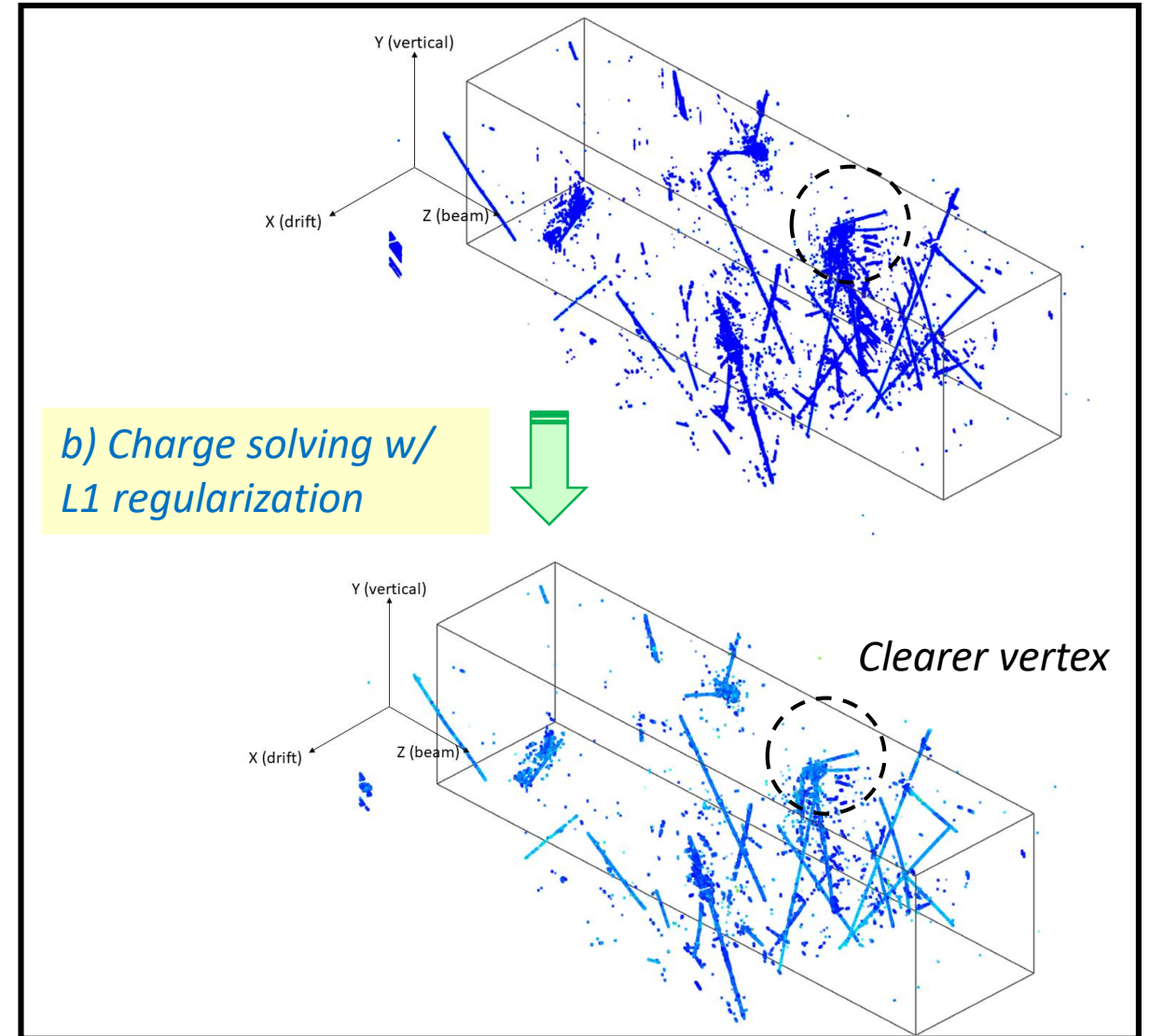


Estimate after convergence  
(exact reconstruction)

# Tomographic Reconstruction: Charge Solving



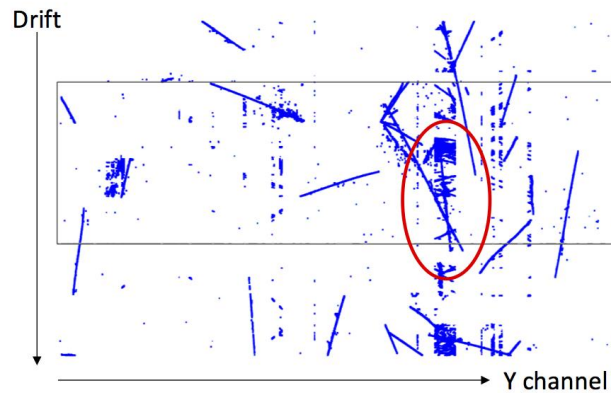
a) Merge the hit cells as **blob**  
⇒ further reduce unknowns



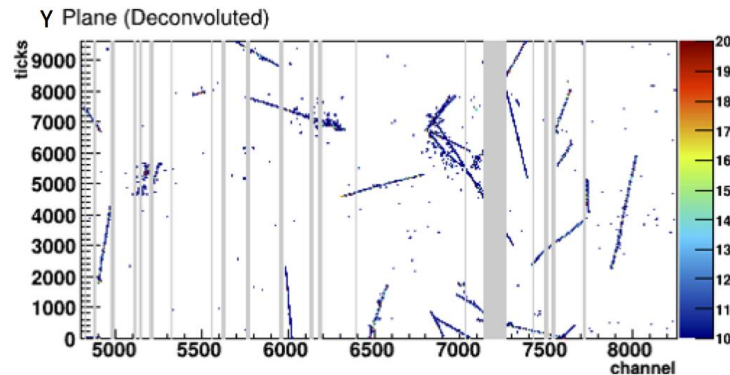
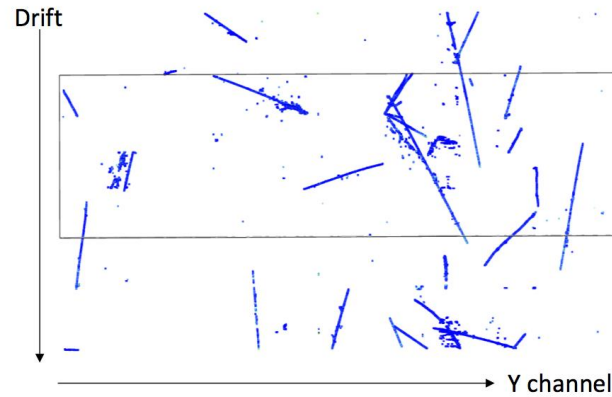
# Deghosting

- 10% nonfunctional channels add ambiguity
- Detach blobs mainly present in the nonfunctional region

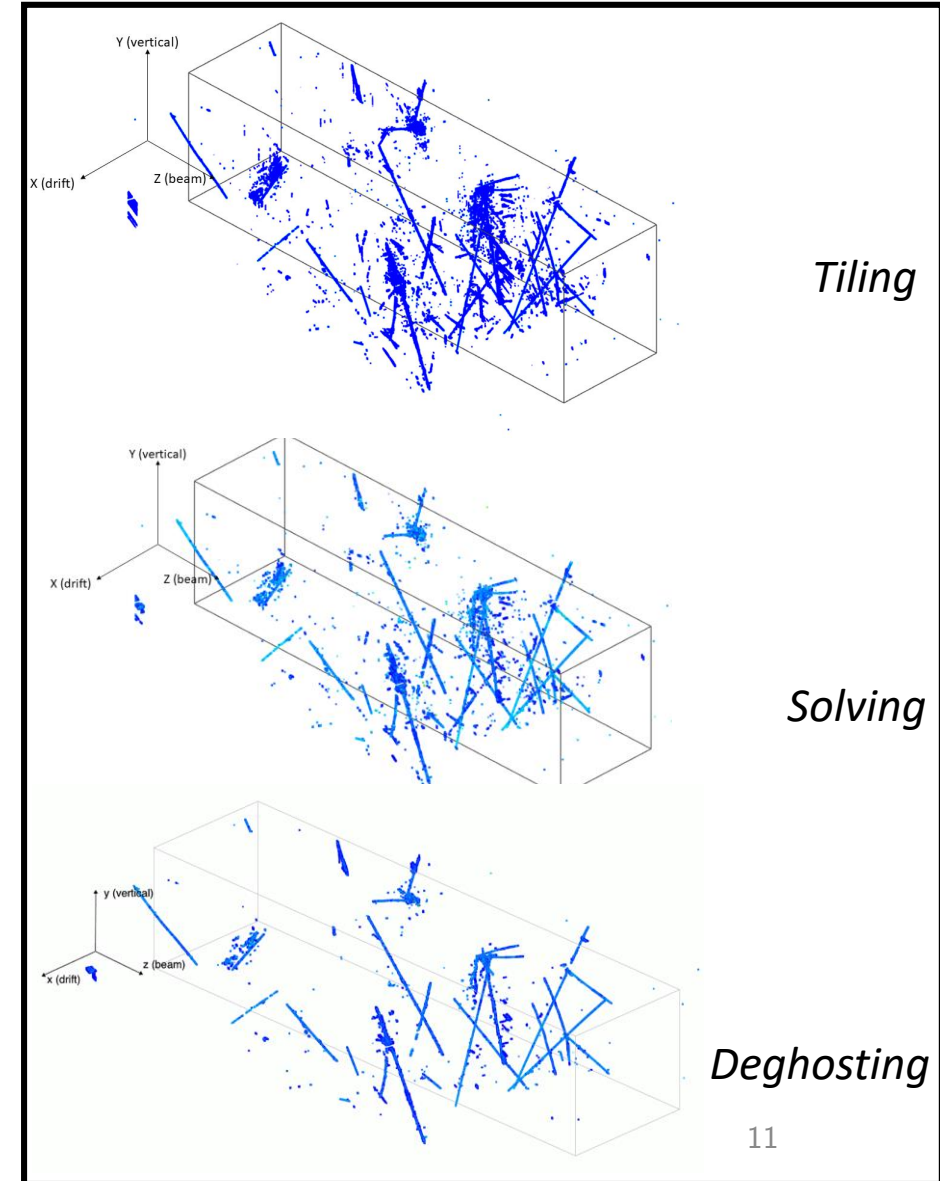
*Before deghosting*



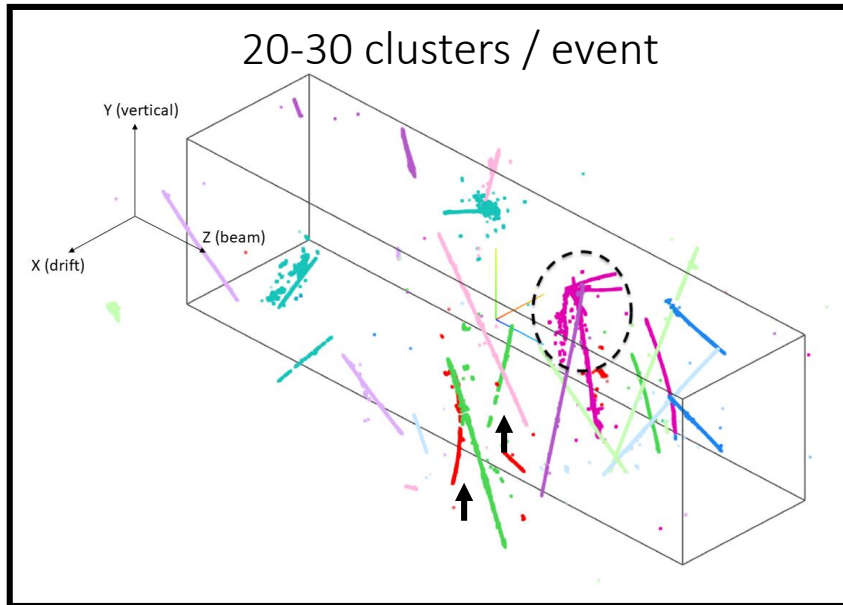
*After deghosting*



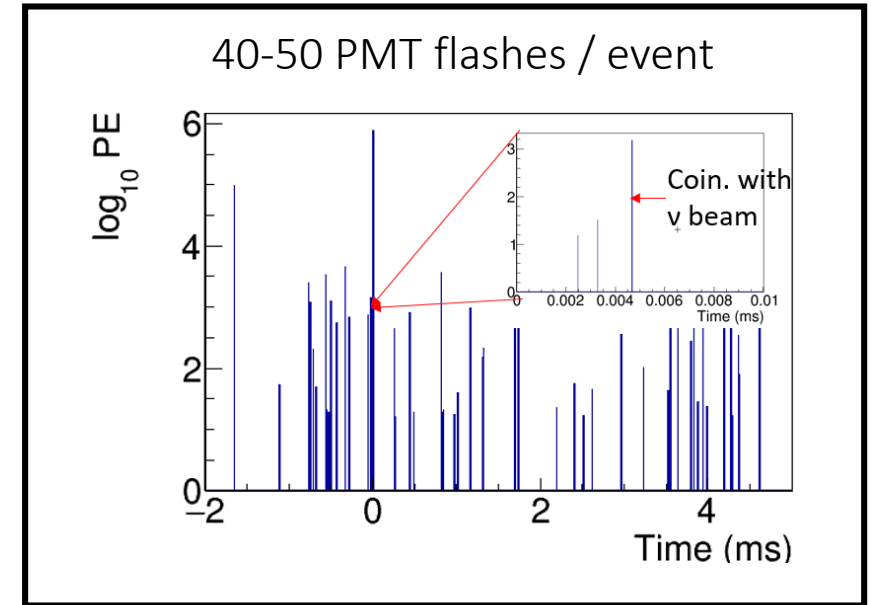
*Non-func. region*



# Clustering and “in-beam” flash matching



*Can we find the  $\nu$  cluster  
in coin. with beam flash?*

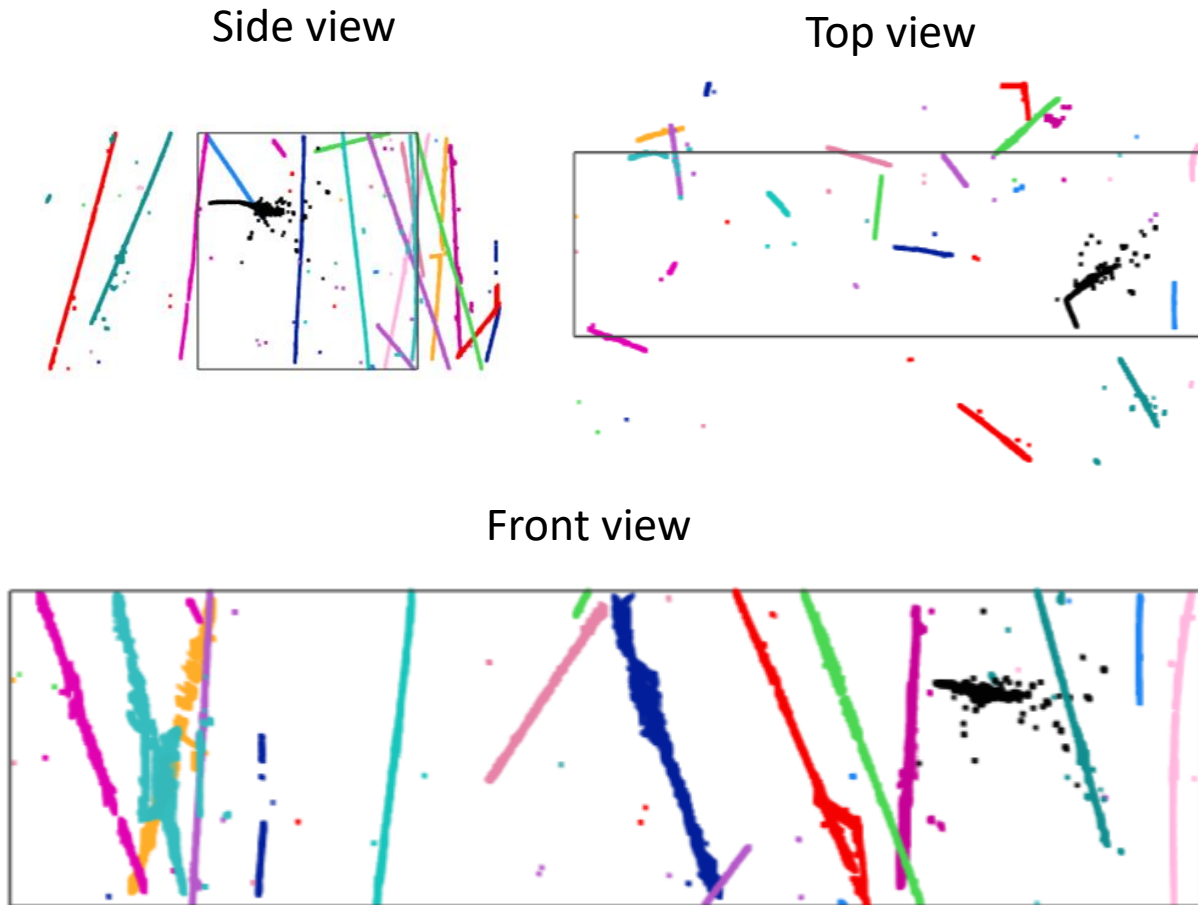


- Further clustering based on blob **distance** and **directionality**
  - ▶ gap bridging
  - ▶ primary track separation: PCA, Kalman-filter, etc.

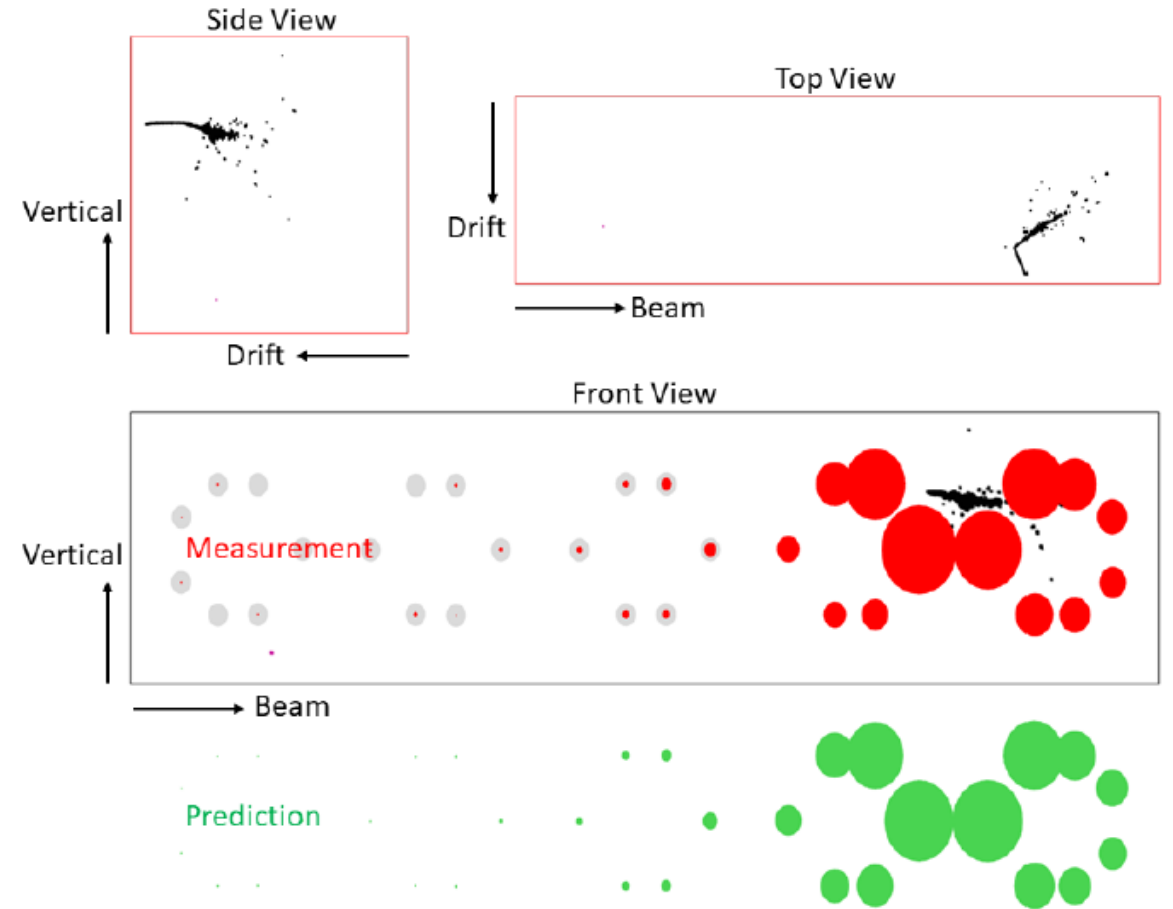
- PMT flash: key for calibrating T0
  - ▶ One cluster matches at most 1 flash
  - ▶ One flash can match any # of cluster (0,1,2, ...)
- Under-determined system
  - ▶ **compressed sensing** again!



# Before and After Flash Matching



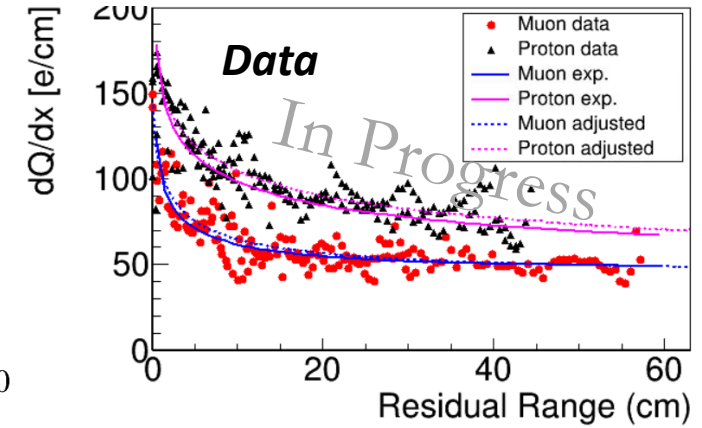
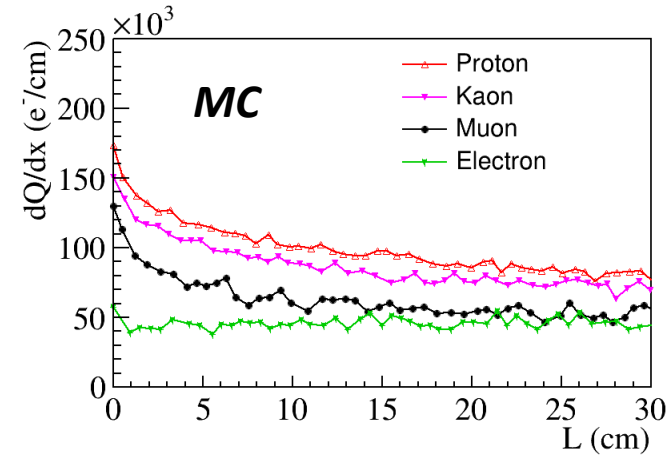
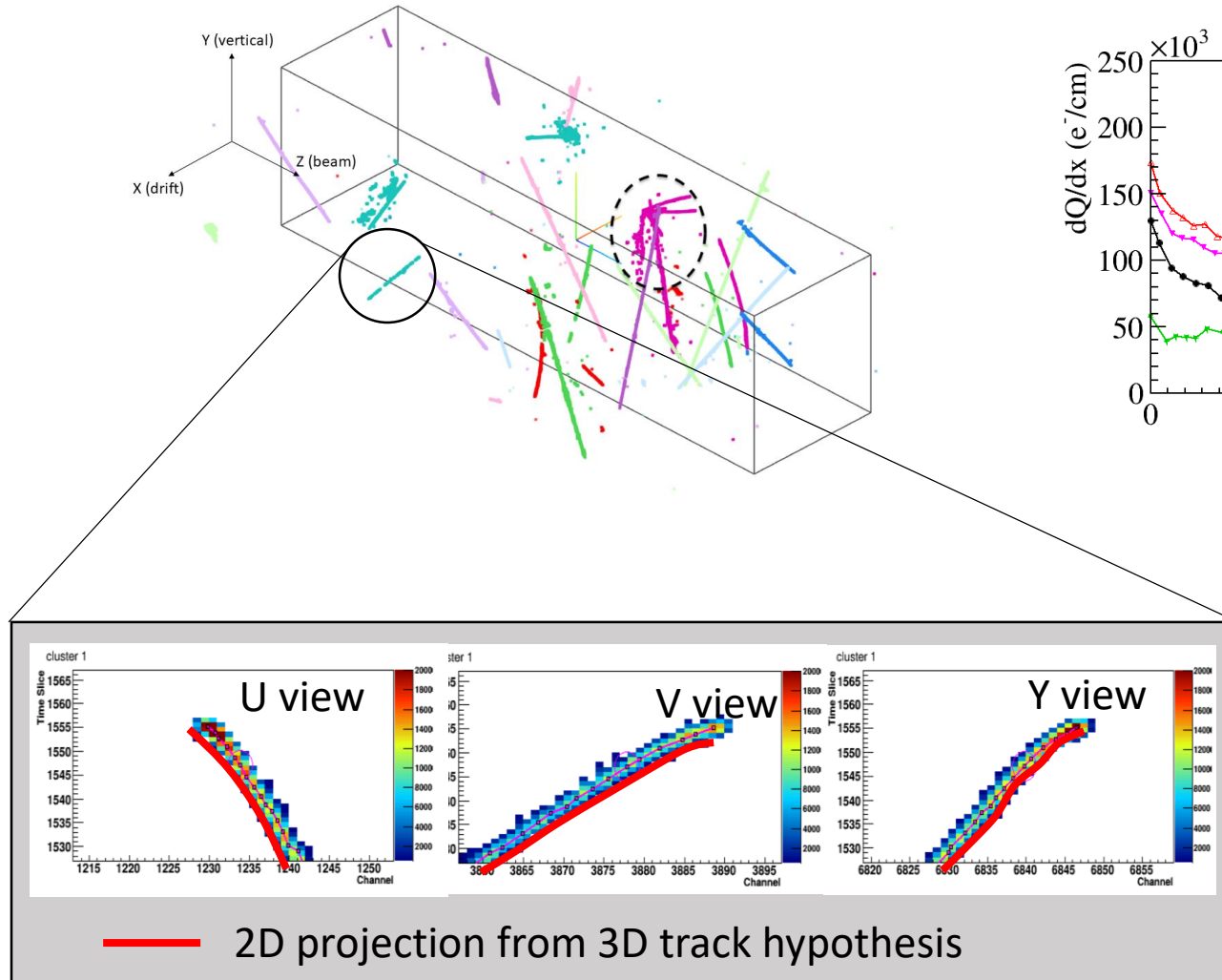
CC  $\nu_e$  candidate



MICROBOONE-NOTE-1040-PUB

Over 98% matching accuracy evaluated with cosmic muons

# Trajectory Fitting and Particle Identification



- Fine trajectory and  $dE/dx$  fitting
  - tomographic clusters as skeleton
- Trajectory and charge info matched to three views

# Summary

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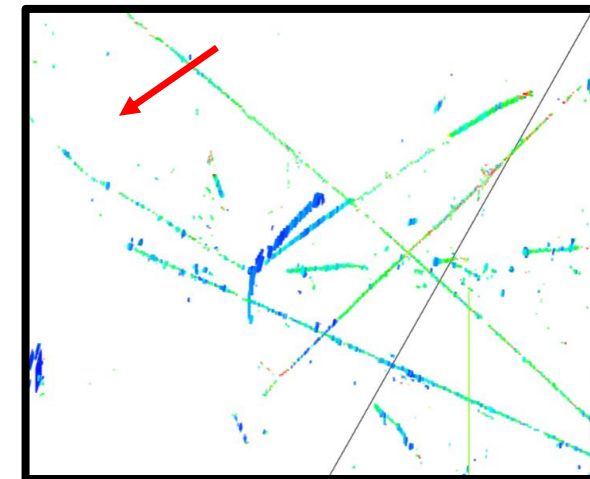
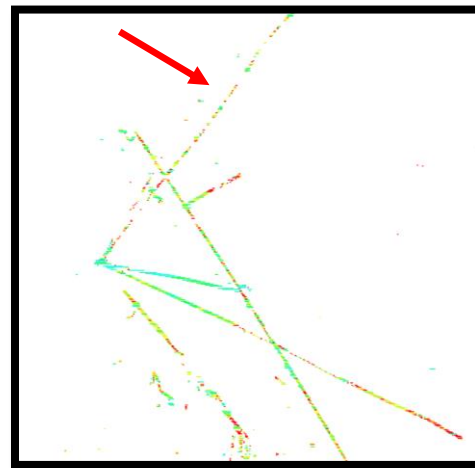
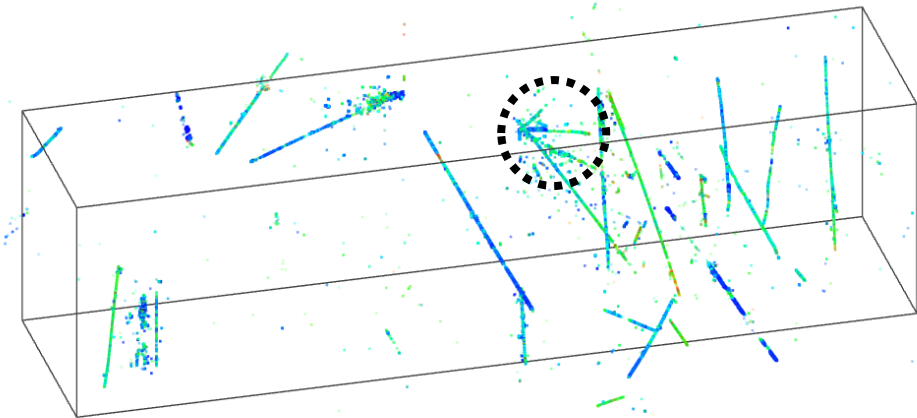
- MicroBooNE is a LArTPC capable of imaging neutrino interactions with very fine resolution
  - ▶ broad scope of physics topics – look out for the other MicroBooNE talks!
- Wire-Cell tomographic reconstruction is a new paradigm for LArTPC
  - ▶ topology-agnostic 3D space points by utilizing geometry, time, charge and sparseness to reduce ambiguity from individual 2D views
- Trajectory and calorimetry reconstruction is in good progress
  - ▶ particle identification
  - ▶ particle flow
  - ▶ ...

# Backup Slides



several hours of CPU running

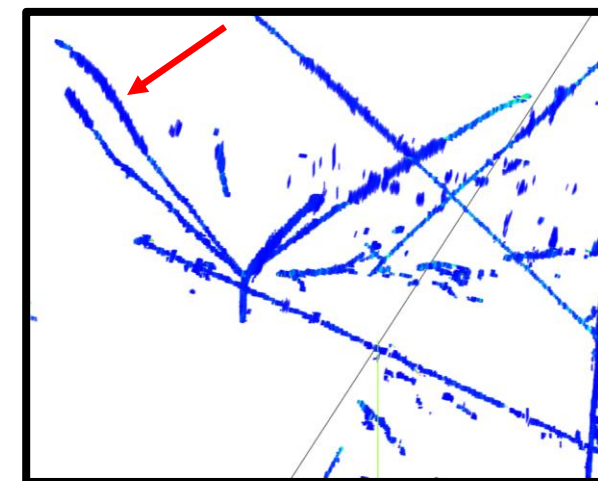
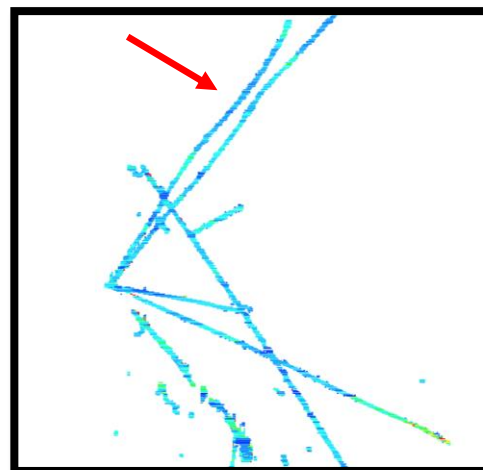
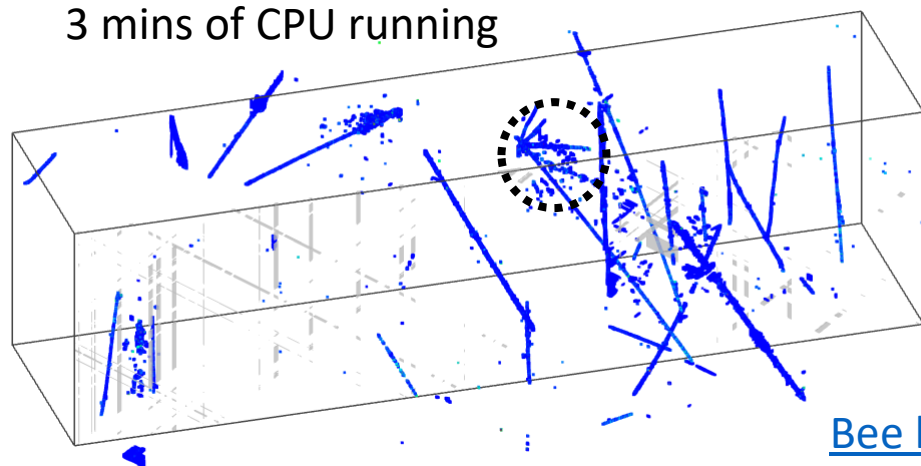
[Bee link](#)



- (upper) 1D deconvolution + L0 compressed sensing

3 mins of CPU running

[Bee link](#)



- (lower) 2D deconvolution + L1 regularization

[JINST 13, P05032 \(2018\)](#)

# Compressed Sensing

- Compressed sensing is a mathematical technique to **recover sparse signal from under-determined (linear) system**

Solve  $y = A \cdot x$   $n_x > n_y$

L0: minimize  $\|x\|_0$ , subject to  $y = A \cdot x$

- Example: Tomography with few projections:

Here  $\|x\|_0$  is the L0-norm of  $x$ , which counts the number of non-zero entries in  $x$

Find the sparsest solution approaching the true signal

Allow one to reconstruct the image with far less projections

Direct application to LArTPC problem

- Sparse projections: 11 radial lines

Candes, Romberg, and Tao,  
"Stable Signal Recovery  
from Incomplete and  
Inaccurate Measurements"

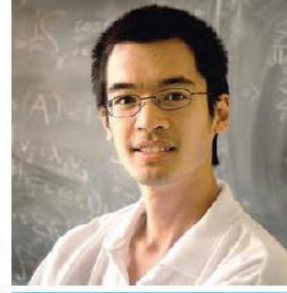
<https://arxiv.org/abs/math/0503066>



Emmanuel Candes. (Photo courtesy of Emmanuel Candes.)



Justin Romberg. (Photo courtesy of Justin Romberg.)



Terence Tao. (Photo courtesy of Reed Hutchinson/UCLA.)



available portion of the spectrum  
(11 radial lines)



Back-projection estimate



Estimate after convergence  
(exact reconstruction)

# 2D Deconvolution

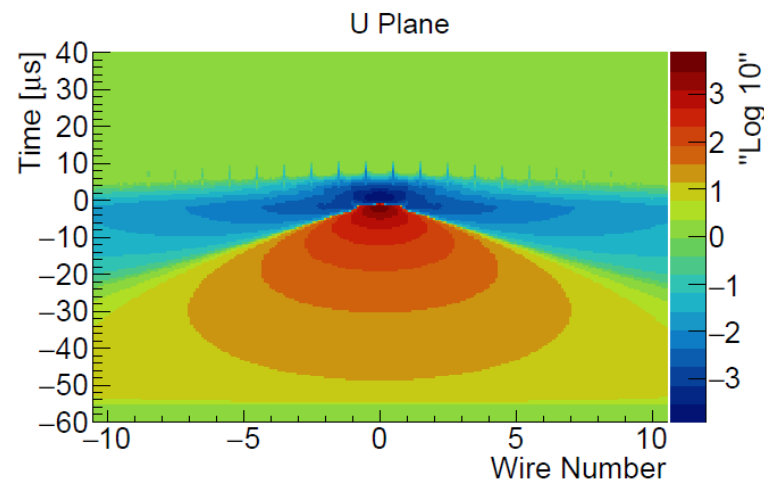
$$M_i(t_0) = \int_t (R_0(t_0 - t) \cdot S_i(t) + R_1(t_0 - t) \cdot S_{i+1}(t) + \dots) \cdot dt$$

$$M_i(\omega) = R_0(\omega) \cdot S_i(\omega) + R_1(\omega) \cdot S_{i+1}(\omega) + \dots$$

Measured  
waveform

1-D  
deconvolution

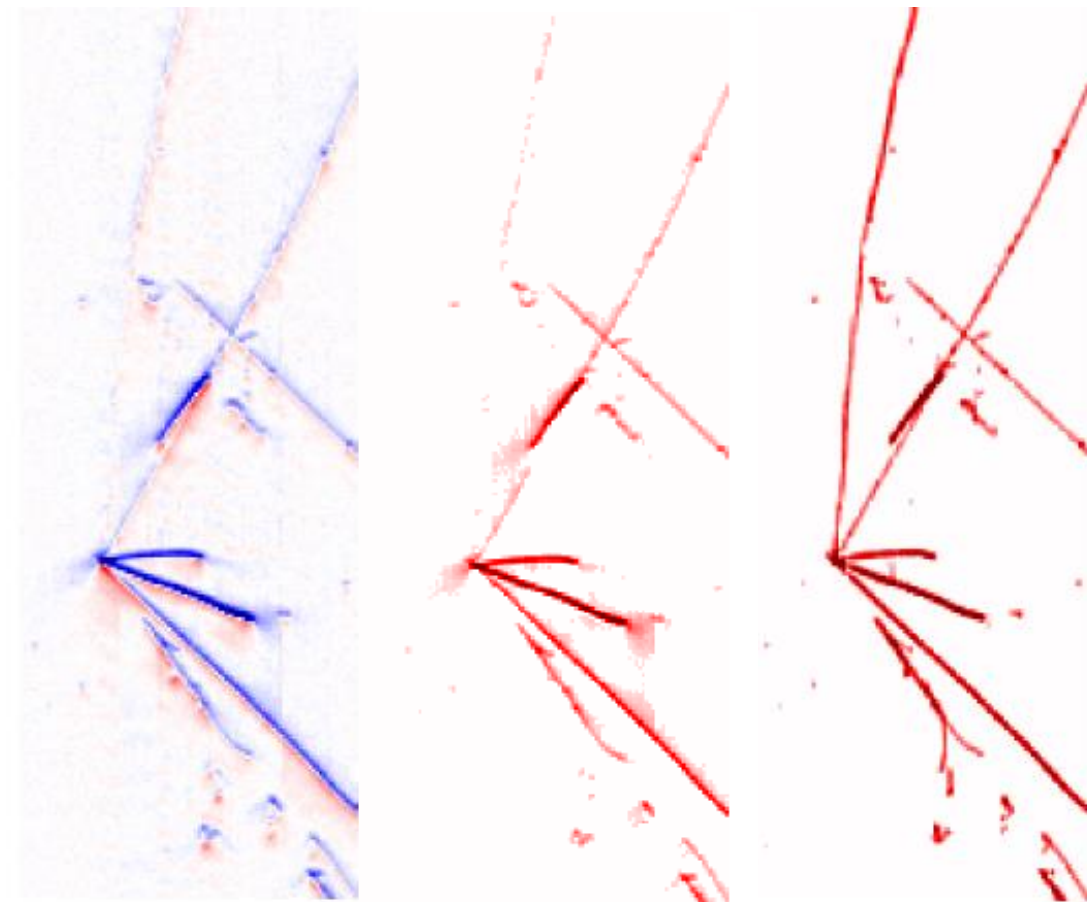
2-D  
deconvolution



$R_1$  represents the induced signal from (i+1)th wire signal to ith wire

$$\begin{pmatrix} M_1(\omega) \\ M_2(\omega) \\ \dots \\ M_{n-1}(\omega) \\ M_n(\omega) \end{pmatrix} = \begin{pmatrix} R_0(\omega) & R_1(\omega) & \dots & R_{n-2}(\omega) & R_{n-1}(\omega) \\ R_1(\omega) & R_0(\omega) & \dots & R_{n-3}(\omega) & R_{n-2}(\omega) \\ \dots & \dots & \dots & \dots & \dots \\ R_{n-2}(\omega) & R_{n-3}(\omega) & \dots & R_0(\omega) & R_1(\omega) \\ R_{n-1}(\omega) & R_{n-2}(\omega) & \dots & R_1(\omega) & R_0(\omega) \end{pmatrix} \cdot \begin{pmatrix} S_1(\omega) \\ S_2(\omega) \\ \dots \\ S_{n-1}(\omega) \\ S_n(\omega) \end{pmatrix}$$

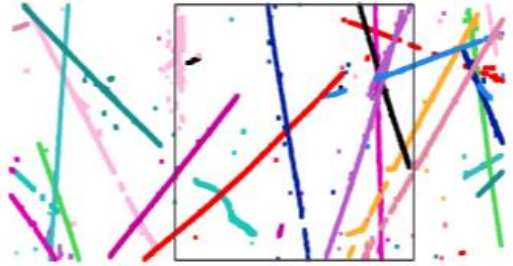
The inversion of matrix R can again  
be done with deconvolution →  
**2-D Fast Fourier Transformation**



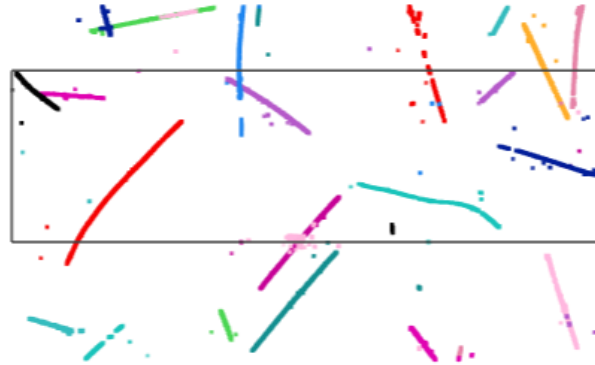
[JINST 13 P07006/7](#) (2018)

# Before and After L1 Matching

Side view



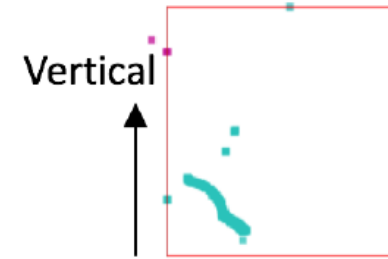
Top view



Front view



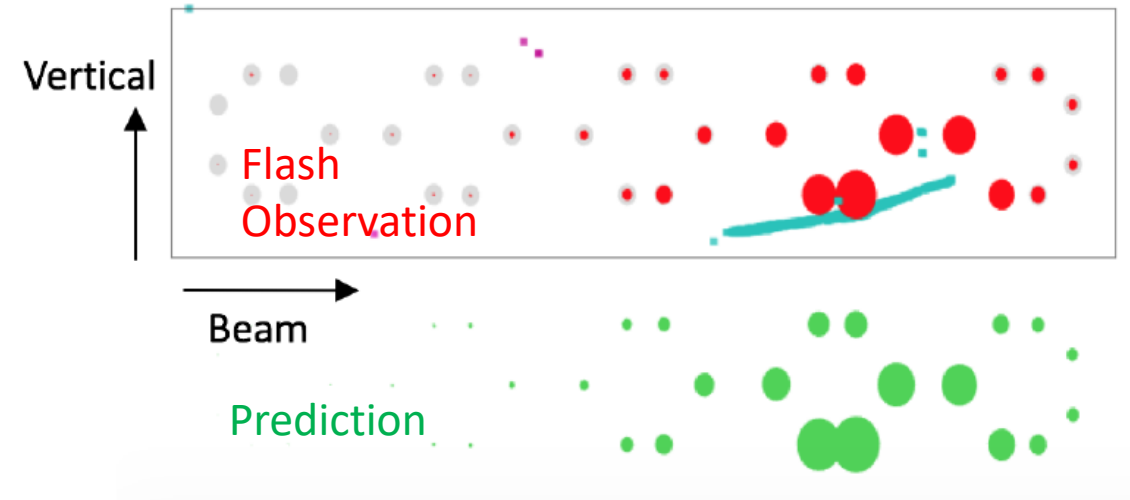
Side View



Top View



Front View



[Charged-Current  \$\nu\_\mu\$  candidate](#)

More details in [MICROBOONE-NOTE-1040-PUB](#)