# Summer Course

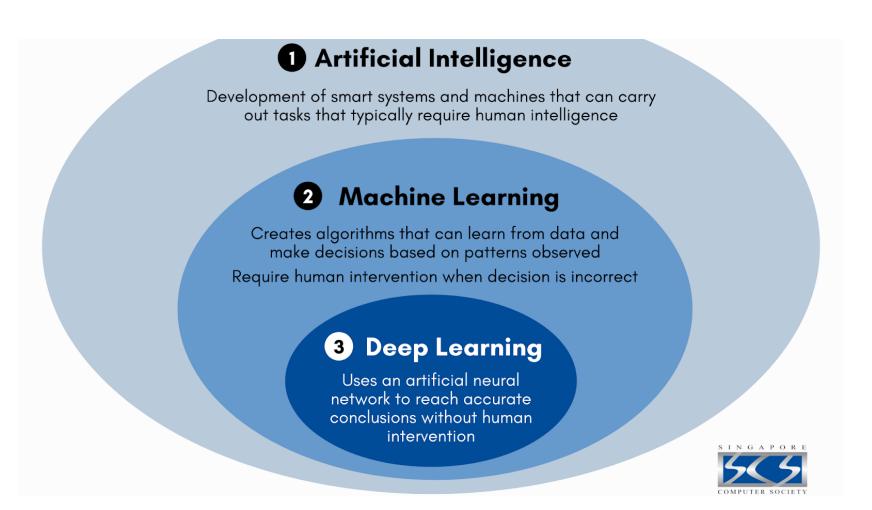
Deep Learning (DL)

Lu, HsinLing – 8/7

# Agenda

- Machine Learning & Deep Learning
- Neural Networks
- Object Recognition and Detection

Al vs. ML vs. DL



What is Machine Learning?

- What is "learning"?
  - Human learns from observations (experience)
  - 三折肱而成良醫 learning from past experience.
  - 類推適用 from 1 + 1 = 2 to 1 + 1 + 1 = 3
- How could machine "learn" something?
  - Traditional artificial intelligent: Expert system, Case-based Reasoning
  - Statistics: Probability Estimation (Classification), Regression

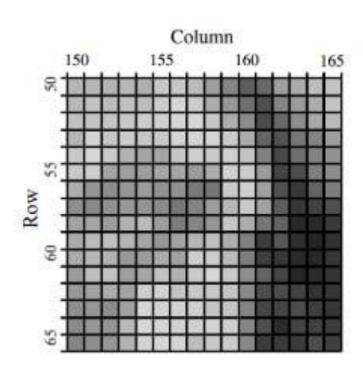
### How do we recognize things?

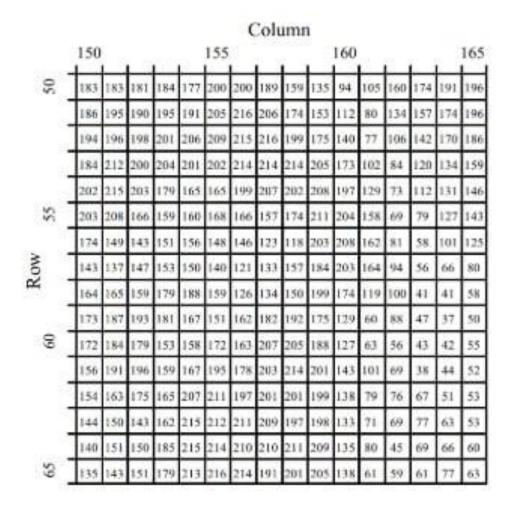
- Some visual clues (features)
  - Two standing ears
  - Brown fur
  - Curl tail

```
def is_shiba(dog: Image) -> bool:
 if not has_standing_ears(dog):
     return False
 if not has_brown_fur(dog):
     return False
 if not has_curl_tail(dog):
     return False
 ...
 return True
```

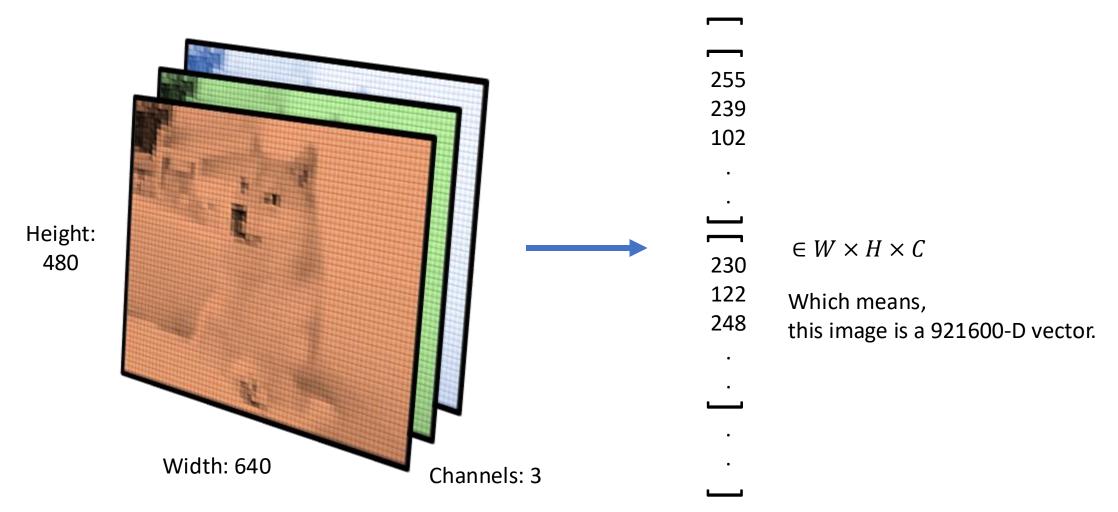


Digital images are just numbers





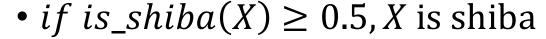
Digital images are just numbers



#### Binary classification

• 
$$is\_shiba(X) = \sigma(w_1x_1 + w_2x_2 + \dots + w_{921600}x_{92600})$$

•  $is\_shiba(X) \in [0,1]$ 



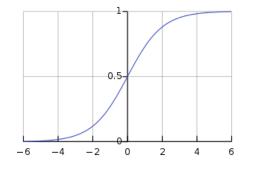
•  $if is\_shiba(X) < 0.5, X is not shiba$ 

Maybe a more complex model?

• 
$$is\_shiba(X) = \sigma(w_{1.1}x_1 + w_{1.2}x_1^2 + w_{1.3}x_3^3 + \cdots)$$

#### Sigmoid function

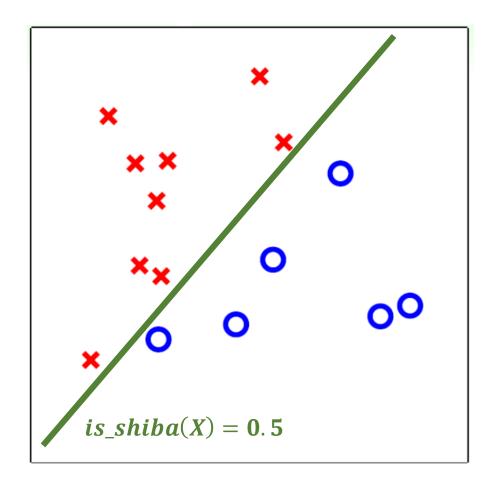
$$\sigma(x) = \frac{1}{1 + e^{-x}} \in [0, 1]$$



#### Binary classification

- Say we have n random dog images
  - Some of them are Shiba.
  - All images are 640x480 res.
    (Which means all of them are 921600-D vectors)

- We can plot these n vectors.
- $is\_shiba(X) = 0.5$  is the decision boundary.



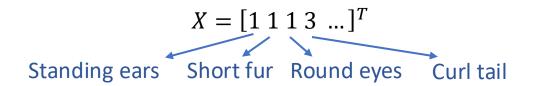
# Machine Learning & Deep Learning Binary classification

- How do we find the coefficient  $w? \rightarrow$  Learn from existing data
- Some algorithm to find w
  - Perceptron Learning Algorithm (PLA)
  - Support Vector Machine (SVM)
  - Adaptive Boosting (Adaboosting)
  - Decision Tree, Random Forest
  - Neural Network (NN)
- However, this approach is not good enough (using a 921600-D vectors)

#### Data preprocessing & feature extraction

- Representing images with 921600-D vectors is not useful
  - Maybe not every pixel matters.
  - Pixel values (intensities) are very low-level features.
  - The computation cost is to high.

- Can we represent the content (the dog) in better way?
  - Down sampling
  - Even some semantic information provided by human?



#### Data preprocessing & feature extraction

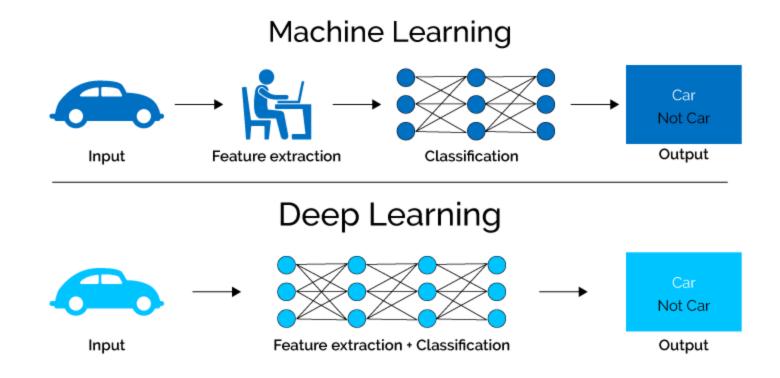
- Data Preprocessing
  - Dimensionality Reduction
  - Normalization
  - Data Cleaning
  - Data Augmentation
- Feature Extraction
  - Relatively low-level features: Gradient, Edge, Texture intensity, etc.
  - Relatively higher-level features: Average Semantic intensity, etc.

How to perform Machine Learning?

- 1. Prepare a dataset
  - Labeling
  - Data preprocessing
- 2. Choose a model
  - Perceptron, SVM, Neural Network, etc.

- 3. Apply to a learning algorithm
  - PLA, Linear Regression, Gradient Descending, etc.

What is Deep Learning?

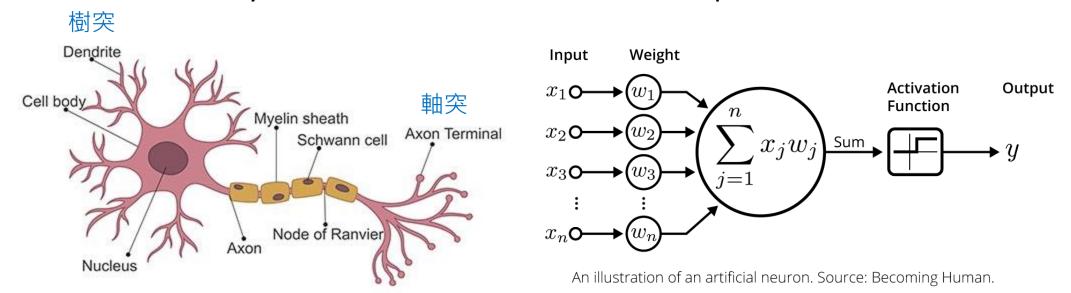


How to perform Deep Learning?

- 1. Prepare a dataset
  - Labeling
  - Data preprocessing The machine also learns to perform data preprocessing.
- 2. Choose a model
  - Neural Network (NN, CNN, RNN, LSTM, GAN, Transformer, diffusion model)
- 3. Apply to a learning algorithm
  - loss function(s)
  - Gradient Descending (Backpropagation)

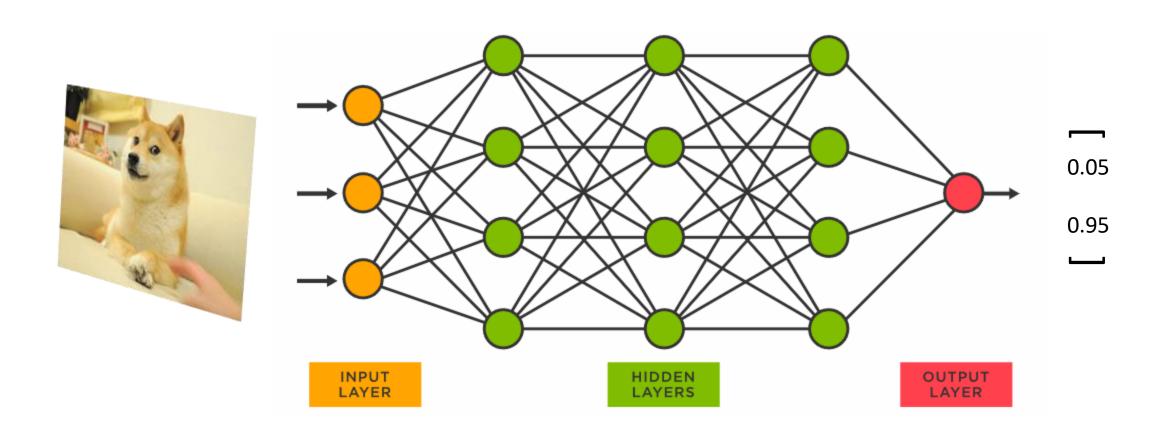
#### What is Neural Network?

- Human brain has 8.6 x 10<sup>10</sup> (eighty six billion) neurons (神經元).
- Neuron receives information and pass to others if needed (activated).
- Some scientists try to simulate human brain with computer.

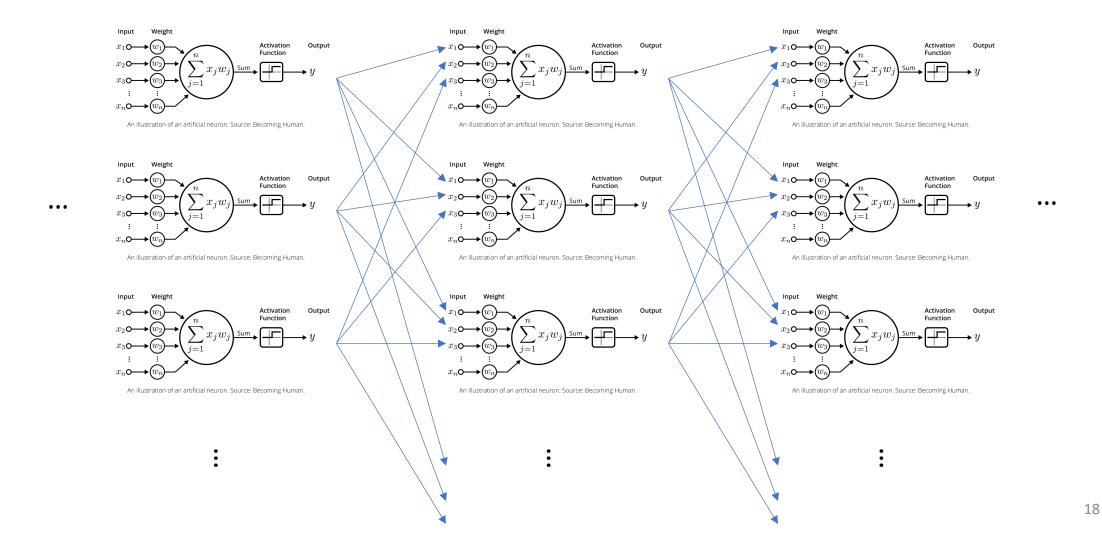


Artificial neurons are only a weighted sum followed by activation function!

#### What is Neural Network?



#### How neural networks learn?



#### What is Neural Netw

### Neural Network

#### How neural networks learn?

- Forward Propagation: The input data starts at the input layer and passes through each layer's weighted computation, ultimately reaching the output layer.
- Compute Loss: The difference between the model's predictions and the true labels is called the loss. A loss function measures this difference.
- Backpropagation: Based on the value of the loss function, each weight's contribution to the loss is calculated. The backpropagation algorithm computes gradients to update weights, reducing the loss function gradually.
- Weight Update: Using the gradient descent algorithm, the weights are updated based on the computed gradients, making the model's predictions more accurate.

#### How neural networks learn?

- Neurons are just weighted sum with activation function, so a neural network can be represented by a mathematical function. And, this function is differentiable.
- Loss function: A way to evaluate the performance of neural networks.
  - Loss (Error): The distance between prediction and ground truth
  - Mean Absolute Error (MAE)
  - Mean Squared Error (MSE)
  - Cross Entropy (CE)
  - Focal Loss
  - Dice Loss



#### How neural networks learn?

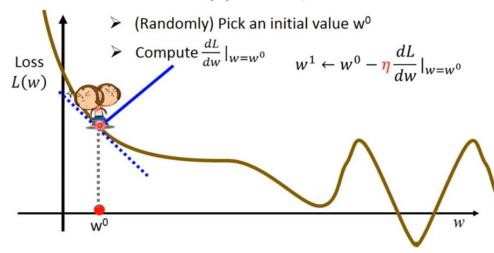
- We can plot the parameter space with a simple curve.
- All we want is to find the global minimum of loss.
- Because neural networks are differentiable, we can calculate the gradient of current parameters with given loss.
- We modify the weights toward negative gradient direction, so the loss will decrease ideally.

http://chico386.pixnet.net/al bum/photo/171572850

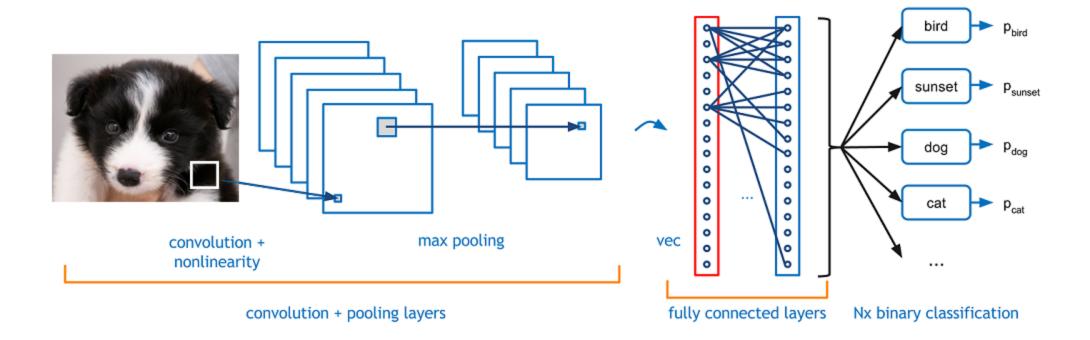
#### Step 3: Gradient Descent

$$w^* = arg \min_{w} L(w)$$

• Consider loss function L(w) with one parameter w:



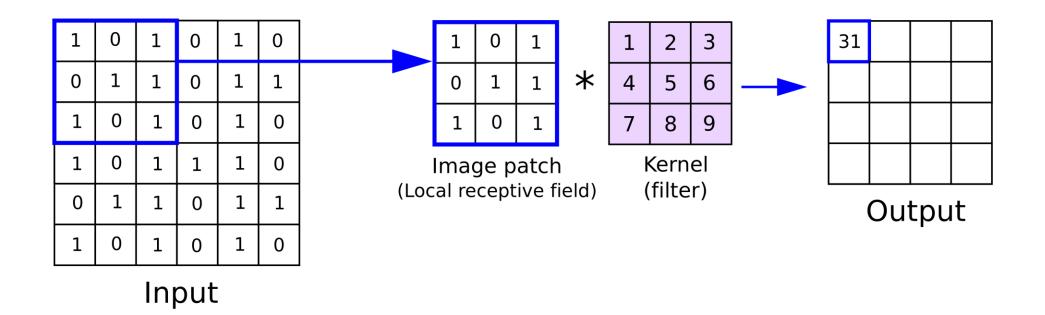
### Convolutional Neural Network (CNN)



https://medium.com/%E9%9B%9E%E9%9B%9E%E8%88%87%E5%85%94%E5%85%944E7%9A%84%E5%B7%A5%E7%A8%8B%E4%B8%96%E7%95%8C/%E6%A9%9F%E5%99%A8%E5%AD%B8%E7%BF%92-ml-note-convolution-neural-network-%E5%8D%B7%E7%A9%8D%E7%A5%9E%E7%B6%93%E7%B6%B2%E8%B7%AF-bfa8566744e9

#### Convolutional Neural Network (CNN)

#### Convolutional Layer



#### Convolutional Neural Network (CNN)

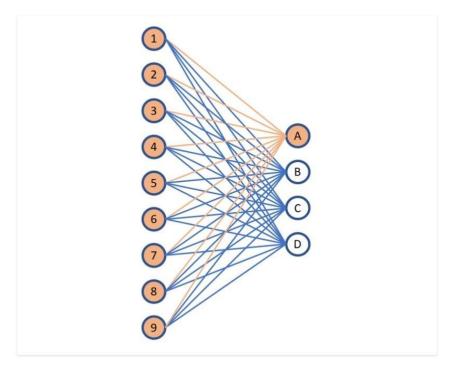
**Pooling Layer** 

#### **Max Pooling**

2	3	1	4
5	6	7	8
9	10	11	12
13	14	15	16

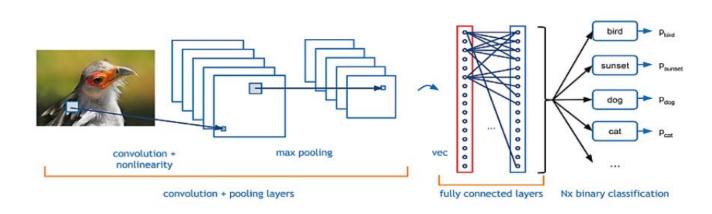
Select the maximum value from each window.

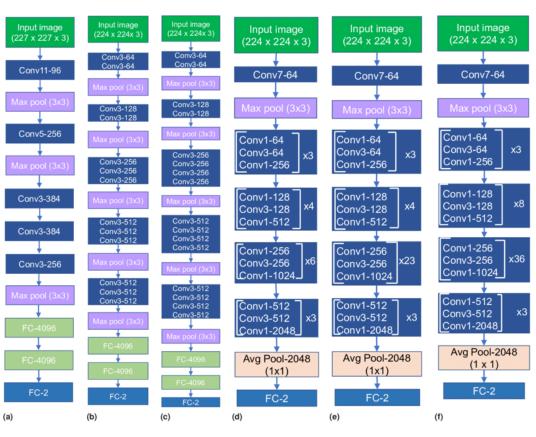
**Fully Connected Layer** 



https://builtin.com/machine-learning/fully-connected-layer

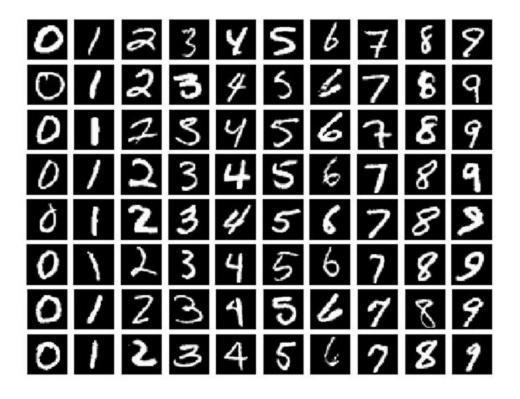
images recognition



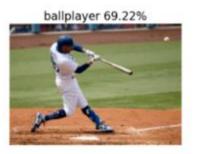


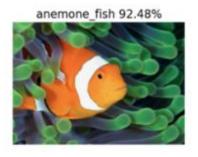
#### images recognition

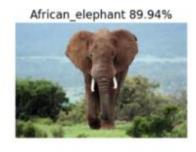




### images recognition









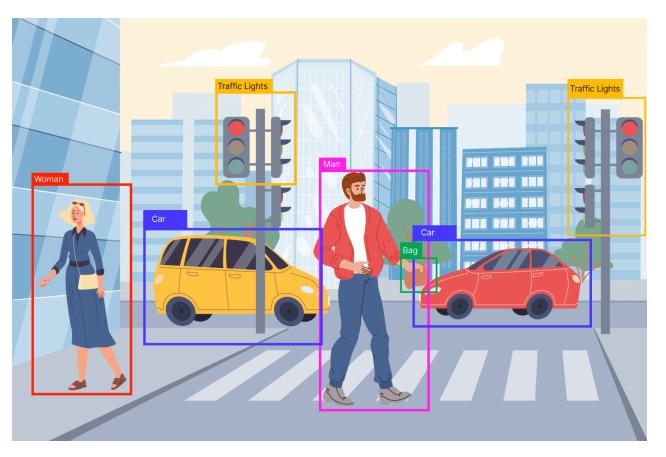








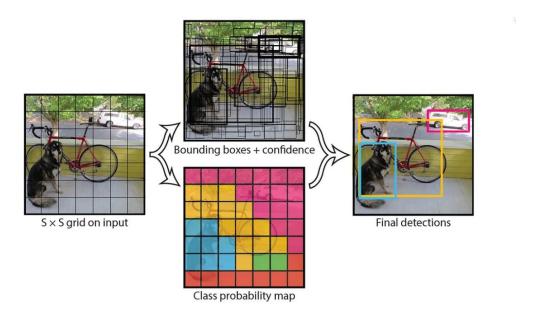
### Object detection

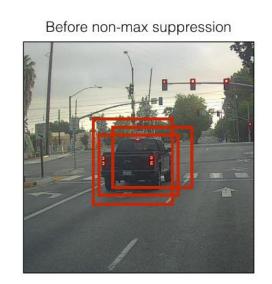


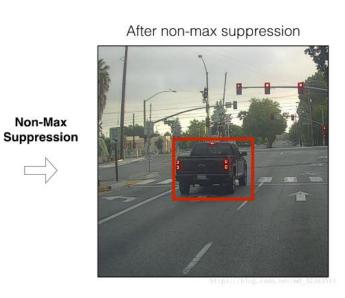
- Bounding boxes: Bounding boxes
   are a commonly used annotation
   type for object detection. They are
   used to mark the rectangular area
   of an object within an image.
- Points: Points can be used to mark a specific location within an image. This annotation type is often used for facial recognition or keypoint detection.

#### Object detection

• One stage object detection : ssd \ yolo



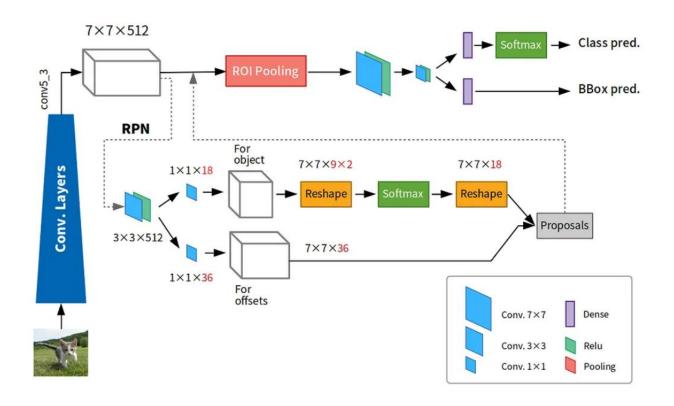


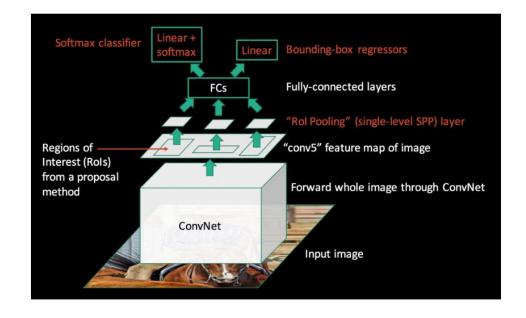


Non-Max

#### Object detection

Two stage object detection: RCNN \ faster-RCNN \ fpn \ mask-RCNN





# THANK YOU:))))