Polynomial Parity Arguments on Directed Graphs (PPAD)

■ End of a Line (EOL)

(liven a directed greeph G = (V, E) S.t. every Vortex has in-degree at most I and out-degree at most 1. (Total degree ?!)

if you are given a vertex with in-degree or then there is another vertex with in-degree or (find it) out degree O. can't make a cycle.

PPAD-hard

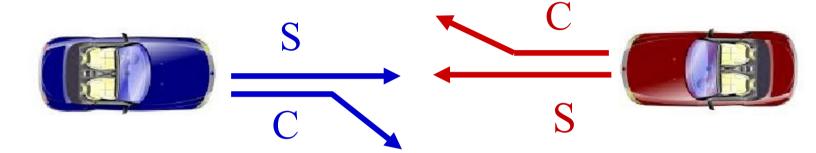
Any problem that can be reduced to EOL is in PPAD

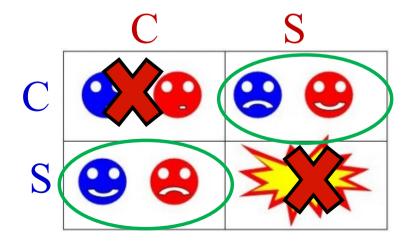
If <u>EOL</u> reduce to problem A, then A is <u>PPAD-Hard</u>.

Claim: Sperner's Lemma is PPAD-Hand.

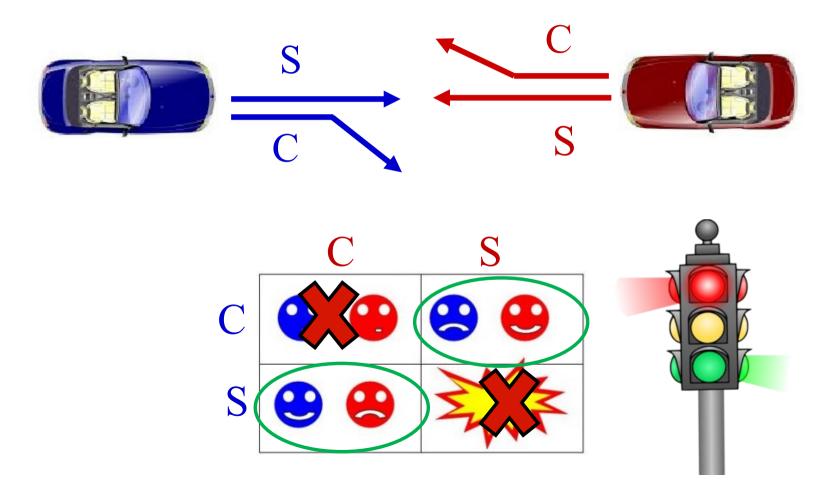
Norsh equilibrium is PPAD-Hard.

Chicken





Chicken (Traffic Light)



Game of Chicken

■ What are all NE?

mixed:
$$4P + (1-P) = 5P = P = \frac{1}{2}$$
.
 $4q + (1-q) = 5q = 9q = \frac{1}{2}$.
 $\left[\left(\frac{1}{2}C, \frac{1}{2}S\right), \left(\frac{1}{2}C, \frac{1}{2}S\right)\right]$.

Game of Chicken

C S
C 4, 4 1, 5
S 5, 1 0, 0

- What are all NE?
- What are the issues with NE?

Trusted Game Coordinator

- In NE, each player choose their strategy independently
- Suppose there is an external correlation device (a game coordinator such as traffic light) that advices each player to play (i, j) with probability p_{ij}
- The probabilities $p'_{ij}s$ are known to both the players, but not necessarily the advice given to the other player
- Players may choose to not follow the advice given to them

• $\{p_{ij}\}$ is a <u>correlated equilibrium (CE)</u> if it is <u>best for each</u> player to follow the advice assuming that the other player is following the advice

Given Player | played i. the prob Player 2 plays is: Pij
Flayer I's expected payoff:
$$\sum_{j} A_{ij} \cdot \frac{P_{ij}}{\sum_{j} P_{ik}}$$

CE: \(\frac{\rightarrow}{2}\rightarrow\) \(\frac
∑Bij Pij ≥ ∑Bij' Pij ∑Pij ∑Pij , J' ∈ Sz.
$Pij \geq 0, \forall i, j. \qquad \sum_{i,j} Pij = 1.$ $CE : \{Pij\} . S.t.$
=> Polyhedron => Convex Set.

• $\{p_{ij}\}$ is a correlated equilibrium (CE) if it is best for each player to follow the advice assuming that the other player is following the advice

- Set of CE is a polyhedral set and hence, convex
- Complexity of finding a CE? = linear feasible program.

polynominal time

■ How to find the best CE (which maximizes the total payoff)?

Example

S.t.
$$4P_{11} + P_{12} \ge 5P_{11} + O_1P_{12}$$

$$5P_{21} + 0P_{22} \ge 4R_{21} + 1P_{22}$$

 $4P_{11} + P_{21} \ge 5P_{11} + 0.P_{21}$

$$P_{11}, P_{12}, P_{21}, P_{11} \geq 0$$

$$\geq P_{13} = 1.$$

P12 2 P11

Pal & Par

Pu > Pi

 $P_{12} \gg P_{22}$

$$P_{11} = P_{12} = P_{24} = \frac{1}{3}$$

$$P_{22} = 0$$

Claim: NE ⊆ CE

Suppose
$$(x,y)$$
 is a NE. Set $Pij = x_iy_j$
 $\sum_{i} A_{ij} Pij > \sum_{i} A_{ij} Pij$

$$\Rightarrow \sum_{j} A_{ij} \times y_{j} \geqslant \sum_{j} A_{i'j} \times y_{j}$$

$$\Longrightarrow \sum_{j} A_{ij} y_{j} \geqslant \sum_{j} A_{i'j} y_{j}$$

4, 4	1, 5
5, 1	0, 0

■ What are the problems with CE?

1. not unique, but we can choose particular one.

2) it is not achieve the optimal payoff.