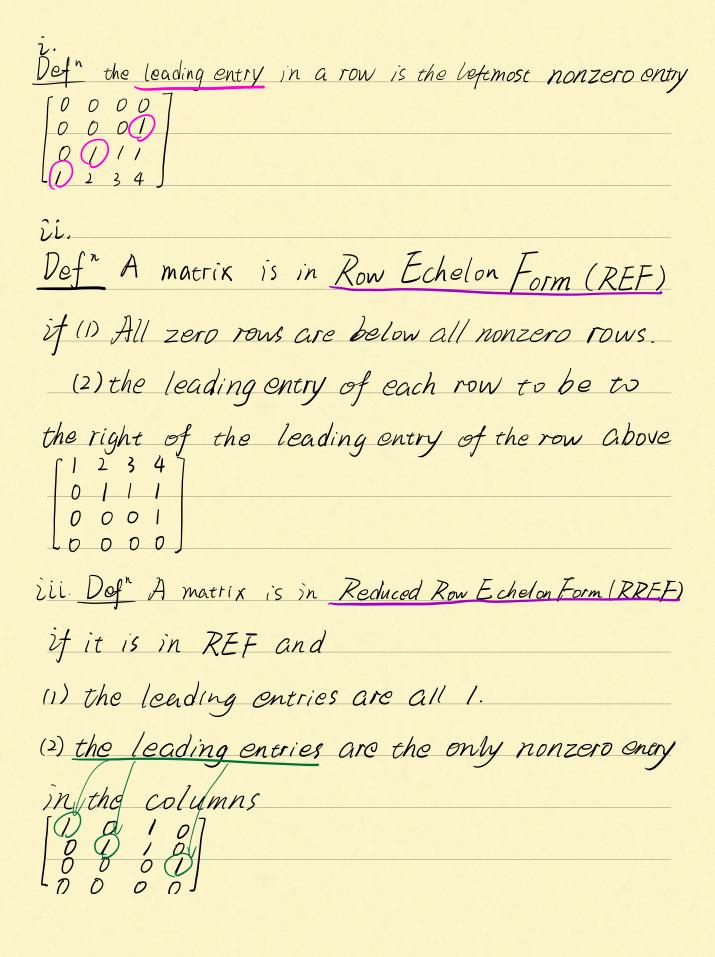
1. Vector Space example
/ addition
multiplication
CO(R) = { continuous function}.
$f(x) = x^2$, $g(x) = \sin x$.
$(f+g)(x) = x^2 sin x$
$(Cf)(x) = Cx^{2}$
2. Linear maps. example
$0.\mathbb{R} \to C^{\circ}(\mathbb{R}) y \to f_{y}(x) = y$
(real number) produces (a function)
$3C'(R) \rightarrow C'(R) f \rightarrow f'$
$C'(R) = \{ continous functions with continous derivatives \}.$
3 An m×n matrix A defines a linear map
from IR" to IR".
example: $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ or $A : \mathbb{R}^2 - \mathbb{R}^2 \begin{bmatrix} x \\ y \end{bmatrix} - \mathbb{R}^2 \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$ maps like La are used to study linear equations.
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3. Systems of linear equations.
Variables X1, X2 Xn
Equations (linear) m of them.
$a_{ii} x_i + a_{i2} x_2 + a_{in} x_n = b_i$
$a_{2i} X_i + a_{2i} X_2 + a_{2n} X_n = b_2$
$a_{m_1} x_1 + a_{m_2} x_2 + \cdots - a_{m_n} x_n = b_m$
find all solutions.
Strategy:
Manipulate equations to get to simpler system. elementary row operations. $0 E_i \longleftrightarrow E_j @E_i \longleftrightarrow CE_i \ (c \neq 0) @E_i \hookleftarrow E_i \ t E_j$
$\begin{bmatrix} a_{11} & a_{12} & -a_{1n} \\ a_{21} & & \\ a_{m_1} & & a_{m_n} \end{bmatrix} R_m$ Theorem 1: None of these Change the Set of Solutions
$[a_{m_1} a_{m_n}] R_m$
Row Echelon Form:



Theorem 2: Every matrix can be put in RREF
by a finite sequence of elementary row operations.
Theorem 3: The RREF of a matrix is unique.
Theorem 4: The solution set of a linear system
with augmented matrix in RREF is easily
described in a standard way.
example: Consider the system with augmented matrix.
$ \begin{vmatrix} $
00000 0=1
This system has no Solutions. (It is inconsistent).
(Moral: A leading entry in the rightmost colum
of REF => system is inconsistent.)
example:
$ \begin{bmatrix} 10 & 70 \\ 01 & 00 \end{bmatrix} \underbrace{15}_{3} & \chi_{1} & -\chi_{3} &= 0 \\ \chi_{2} &= 0 & infinitely solutions. \\ 0 &= 0 $
(Convention: USE variable corresponding to columns

l

J

in RREF with no leading entries to parameterize Solution Set) Set X3=t => X1=t X2=0. $(X_1, X_2, X_3) = \{(t, 0, t) | t \in \mathbb{R}\}$ example. 0000303 Set $\chi_2 = t$, $\chi_4 = t_2$ $\chi_1 = 2 - 2t_1 - t_2 \qquad \chi_3 = 3 - 3t_2$ 0000004 The rank of a matrix. Ciet a k parameter solutions, where k equals to the number of columns (besides befores) without bending entries. n-k is the rank of the matrix. Corallary: Any system have Dinfinitely many solutions: $\begin{bmatrix} 1/2 & 0/1 & 0/2 \\ 0 & 1/3 & 0/3 \end{bmatrix} =$ Q. exacely one solution: $\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} =$

Theorem 2: Every matrix can be put in RREF by a finite sequence of elementary row operations. O. Ri CRi QRi CRi (C+0) @Rj CRi+CRj Proof: by conseruction (Gaussian Elimination) (A) forward pass to REF Lignore row with and repeat (2) (ii)

Repeat until at bottom row. Now in RBF A

13) Backward Pass from RET to RRET

12).

Using © makes rightmost leading entry 1. $\begin{bmatrix}
1 & 1 & 1 & 1 \\
0 & 1 & 2 & 3
\end{bmatrix}
\xrightarrow{R_3 \rightarrow \frac{1}{2}R_3}, \begin{bmatrix}
1 & 1 & 1 & 1 \\
0 & 1 & 2 & 3
\end{bmatrix}$ $\begin{bmatrix}
0 & 0 & 0 & 2
\end{bmatrix}$

(ii) Use 3) to put zeros above this 1. $\frac{R_1 \rightarrow R_1 - R_3}{R_2 \rightarrow R_2 - 3R_1} \begin{bmatrix}
1 & 1 & 1 & 0 \\
0 & 1 & 2 & 0 \\
0 & 0 & 0 & 1
\end{bmatrix}$

(iii) Repent for the next leading entry.