

Math 416 Practice Final

1. Solve

$$\begin{aligned}x_1 + x_2 + x_4 &= 2 \\2x_1 - x_2 + x_3 + 3x_4 &= 1 \\x_1 - 2x_2 + x_3 + 2x_4 &= -1 \\x_1 + 2x_2 + 3x_3 + 4x_4 &= 3.\end{aligned}$$

$$\left[\begin{array}{cccc|c} 1 & 1 & 0 & 1 & 2 \\ 2 & -1 & 1 & 3 & 1 \\ 1 & -2 & 1 & 2 & -1 \\ 1 & 2 & 3 & 4 & 3 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cccc|c} 1 & 1 & 0 & 1 & 2 \\ 0 & -3 & 1 & 1 & -3 \\ 0 & -3 & 1 & 1 & -3 \\ 0 & 1 & 3 & 3 & 1 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cccc|c} 1 & 1 & 0 & 1 & 2 \\ 0 & 1 & 3 & 3 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{cases} x_1 = 1-t \\ x_2 = 1 \\ x_3 = -t \\ x_4 = t \end{cases}$$

2. Consider the linear map $T : P_2(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ defined by

$$T(a + bx + cx^2) = \begin{pmatrix} a & c \\ b - a & a \end{pmatrix}.$$

Let $\alpha = \{1 + x, x + x^2, 1 + x + x^2\}$ and $\beta = \{E_{11}, E_{12}, E_{21}, E_{22}\}$ be the bases for $P_2(\mathbb{R}), M_{2 \times 2}(\mathbb{R})$, respectively, where $E_{11} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, E_{12} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, E_{21} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, E_{22} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}.$

- (1) Compute the coordinate vector $[f]_\alpha$ for $f(x) = 1 - x + 2x^2$.
- (2) Compute the matrix representation $[T]_\alpha^\beta$ with respect to α, β .
- (3) Is T injective?

$$(1) [f]_{\alpha} =$$

$$\begin{cases} x_1 + x_3 = 1 \\ x_1 + x_2 + x_3 = -1 \\ x_2 + x_3 = 2 \end{cases} \Rightarrow \begin{cases} x_1 = -3 \\ x_2 = -2 \\ x_3 = 4 \end{cases}$$

$$[f]_{\alpha} = (-3, -2, 4)$$

$$(2) [T]_{\alpha}^{\beta} = \begin{bmatrix} ([\begin{smallmatrix} 1 & 0 \\ 0 & 1 \end{smallmatrix}])_{\beta} & ([\begin{smallmatrix} 0 & 1 \\ 1 & 0 \end{smallmatrix}])_{\beta} & ([\begin{smallmatrix} 1 & 1 \\ 0 & 1 \end{smallmatrix}])_{\beta} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$(3) T(a+bx+cx^2) = 0_{2 \times 2} \Rightarrow \begin{cases} a=0 \\ b=0 \\ c=0 \end{cases}$$

$$\Rightarrow N(T) = \{\vec{0}\}$$

$$\Rightarrow T \text{ is injective.}$$

3. Consider a 3×4 matrix $A = \begin{pmatrix} 1 & -1 & 2 & 1 \\ 3 & 1 & 1 & 0 \\ -2 & -2 & 1 & 1 \end{pmatrix}$. Let $T = L_A : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

(1) Find a basis β of the null space $N(T)$ so that $N(T) = \text{span}(\beta)$.

(2) Find a basis γ of the range $R(T)$ so that $R(T) = \text{span}(\gamma)$.

(3) Verify the dimension theorem (the rank-nullity theorem).

$$(1) \quad T(x) = \begin{bmatrix} 1 & -1 & 2 & 1 \\ 3 & 1 & 1 & 0 \\ -2 & -2 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \vec{0}$$

$$\begin{bmatrix} 1 & -1 & 2 & 1 \\ 0 & 4 & -5 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 = -\frac{3}{4}t_1 - \frac{1}{4}t_2 \\ x_2 = \frac{5}{4}t_1 + \frac{3}{4}t_2 \\ x_3 = t_1 \\ x_4 = t_2 \end{cases}$$

$$\beta = \left\{ \left(-\frac{3}{4}, \frac{5}{4}, 1, 0\right), \left(-\frac{1}{4}, \frac{3}{4}, 0, 1\right) \right\}.$$

$$(2) \quad \gamma = \{ (2, 1, 1), (1, 0, 1) \}.$$

$$(3) \quad \dim N(T) = 2 \quad \dim R(T) = 2$$

$$\dim N(T) + \dim R(T) = 4 = \dim \mathbb{R}^4$$

4.

$$(1) \text{ Compute the determinant of } \begin{pmatrix} 3 & 2 & -1 & 0 \\ 2 & -1 & 0 & 1 \\ 2 & -2 & 0 & 2 \\ 1 & 0 & -1 & 1 \end{pmatrix} \text{ and verify that } \det(A) \neq 0.$$

(2) Compute the inverse of A .

$$(1). \quad \begin{vmatrix} 0 & 0 & 0 & 1 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 1 \\ 1 & 0 & -1 & 1 \end{vmatrix} = - \begin{vmatrix} 1 & 0 & -1 & 1 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{vmatrix} = -2 \neq 0.$$

$$\left| \begin{array}{cccc} 0 & 0 & -2 & 2 \\ 1 & 0 & -1 & 1 \end{array} \right| \quad \left| \begin{array}{cccc} 0 & 0 & -2 & 2 \\ 0 & 0 & 0 & 1 \end{array} \right|$$

$$b). [A | I] = \left[\begin{array}{cccc|cccc} 3 & 2 & -1 & 0 & 1 & 0 & 0 & 0 \\ 2 & -1 & 0 & 1 & 0 & 1 & 0 & 0 \\ 2 & -2 & 0 & 2 & 0 & 0 & 1 & 0 \\ 1 & 0 & -1 & 1 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cccc|cccc} 0 & 2 & 2 & -3 & 1 & 0 & 0 & -3 \\ 0 & -1 & 2 & -1 & 0 & 1 & 0 & -2 \\ 0 & -2 & 2 & 0 & 0 & 0 & 1 & -2 \\ 1 & 0 & -1 & 1 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cccc|cccc} 0 & 0 & 6 & -5 & 1 & 2 & 0 & -7 \\ 0 & -1 & 2 & -1 & 0 & 1 & 0 & -2 \\ 0 & 0 & -2 & 2 & 0 & -2 & 1 & 2 \\ 1 & 0 & -1 & 1 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cccc|cccc} 0 & 0 & 0 & 1 & 1 & -4 & 3 & -1 \\ 0 & 1 & 0 & 0 & 1 & -3 & \sqrt{2} & -1 \\ 0 & 0 & 1 & 0 & 1 & -3 & \frac{5}{2} & -2 \\ 1 & 0 & 0 & 0 & 0 & 1 & -\frac{1}{2} & 0 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 1 & -\frac{1}{2} & 0 \\ 0 & 1 & 0 & 0 & 1 & -3 & \sqrt{2} & -1 \\ 0 & 0 & 1 & 0 & 1 & -3 & \frac{5}{2} & -2 \\ 0 & 0 & 0 & 1 & 1 & -4 & 3 & -1 \end{array} \right]$$

5. True / False. Justify your answer.

- (a) Every square matrix over the complex numbers \mathbb{C} has a Jordan Form.
- (b) Every nonzero finite dimensional inner product space has an orthonormal basis.
- (c) If S is an orthogonal set of nonzero vectors, then S is linearly independent.
- (d) A linear operator T on a finite dimensional inner product space V over \mathbb{R} is self-adjoint if and only if there exists an orthonormal basis for V consisting of eigenvectors of T .
- (e) Every symmetric matrix over \mathbb{R} is diagonalizable.
- (f) Every symmetric matrix over \mathbb{C} is diagonalizable. $\begin{bmatrix} i & 1 \\ 1 & -i \end{bmatrix}$ $(i-\tau)(-i-\tau) = -1$
 $\tau^2 = 0, \tau = 0$
- (g) If a linear operator T on a finite dimensional inner product space V over \mathbb{R} is normal, then V admits an orthonormal basis which consists of the eigenvectors of T . $T = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$
- (h) If a linear operator T on a finite dimensional inner product space V is self-adjoint, then it is normal.
- (i) If T is a linear operator on a finite dimensional vector space V whose characteristic polynomial splits, then the dimension of the generalized eigenspace K_λ corresponding to an eigenvalue λ is equal to the algebraic multiplicity of λ .

(a) Every square matrix A over the complex numbers

$\Rightarrow \det A$ splits. $\Rightarrow A$ has a Jordan Form.

(b) Use Gram-Schmidt Process.

(c) Assume not $S_1 = a_2 S_2 + \dots + a_n S_n$, $a_i \neq 0$.

$$\langle S_1, S_i \rangle = a_i \|S_i\|^2 \neq 0$$

(d) self-adjoint \Leftrightarrow matrix is symmetric in \mathbb{R} \Leftrightarrow

matrix have an orthonormal basis for \mathbb{R}^n consisting of eigenvectors.