Multiple Linear Regression

Lecture 5

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Multiple Linear Regression (Part II)

Learning objectives

In this lecture we will:

- Review of Random Vectors' Mean and Variance.
- Properties of LS Estimators
- The Gauss-Markov Theorem
- Maximum Likelihood in MLR

Properties of the Least-Square estimates

Least-Square Estimates

– In MLR the LS estimate $\hat{\beta}$ is given by

$$\hat{\beta} = (\hat{\beta}_1, \hat{\beta}_2, \dots, \hat{\beta}_p)^T == (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

- $\hat{\beta}$ is a random vector, since it is a function of **y** (which is random).
- For hypothesis testing, we need to understand the obtain distribution of $\hat{\beta}$.

Mean & Variance of Random Vectors:

Review

Random Vectors Review

Random Vectors: Mean

Let **Z** a random vector of size $m \times 1$, with components Z_1, Z_2, \ldots, Z_m . The mean of **Z** is equal to vector μ defined as:

$$\mu = \mathbb{E}(\mathbf{Z}) = egin{pmatrix} \mathbb{E}(Z_1) \ \mathbb{E}(Z_2) \ \dots \ \mathbb{E}(Z_m) \end{pmatrix}$$



Variance of a Random Vector

The Variance of a random vector **Z** is a **matrix** – the Variance-Covariance matrix. This matrix is *symmetric* (why?) of size $m \times m$ with component (i,j) equal to the $Cov(Z_i, Z_j)$. Specifically,

$$\begin{split} \Sigma_{m \times m} &= \mathsf{Cov}(\boldsymbol{Z}) = \mathbb{E}\left((\boldsymbol{Z} - \boldsymbol{\mu})(\boldsymbol{Z} - \boldsymbol{\mu})^\mathsf{T}\right) \\ &= \begin{pmatrix} \mathsf{Var}(\mathsf{Z}_1) & \dots & \mathsf{Cov}(\mathsf{Z}_1, \mathsf{Z}_m) \\ \dots & \dots & \dots \\ \mathsf{Cov}(\mathsf{Z}_m, \mathsf{Z}_1) & \dots & \mathsf{Var}(\mathsf{Z}_m) \end{pmatrix} \end{split}$$

Affine Transformation of Random Vectors

Affine transformation **Z**

$$W = a_{n \times 1} + B_{n \times m} Z_{m \times 1}$$

Mean & Covariance Matrix of W

$$\mathbb{E}(\mathbf{W}) = \mathbf{a} + \mathbf{B}\mu, \quad Cov(\mathbf{W}) = \mathbf{B}\mathbf{\Sigma}\mathbf{B}^T$$

Another transformation of Z

$$W = \mathbf{v}^{\mathsf{T}} \mathbf{Z} = v_1 Z_1 + v_2 Z_2 + \ldots + v_m Z_m$$

Mean & Variance of W

$$\mathbb{E}(W) = \mathbf{v}^T \mu = \sum_{i=1}^m v_i \mu_i$$

$$Var(W) = \mathbf{v}^T \Sigma \mathbf{v} = \sum_{i=1}^m v_i^2 Var(Z_i) + 2 \sum_{i < j} v_i v_j Cov(Z_i, Z_j)$$

Mean & Covariance of the LS estimates

Linear Regression Model

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon},$$

with $\mathbb{E}(\varepsilon) = \mathbf{0}$, and $Cov(\varepsilon) = \sigma^2 \mathbf{I}_n$.

 These assumptions imply that the response has mean and variance equal to:

$$\mathbb{E}(\mathbf{y}) = \mathbf{X}\beta, \quad Cov(\mathbf{y}) = \sigma^2 \mathbf{I}_n$$

LS Estimators

The LS estimators $\hat{\beta}$ are *unbiased*.

Indeed,

$$\mathbb{E}(\hat{\beta}) = \mathbb{E}\left((\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}\right) = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbb{E}(\mathbf{y})$$
$$= (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{X}\beta = \beta$$

Mean & Covariance of the LS estimates (Cont.)

Variance-Covariance Matrix of $\hat{\beta}$

$$Cov(\hat{\beta}) = (\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{X}^{T}Cov(\mathbf{y}) \left((\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{X}^{T} \right)^{T}$$

$$= (\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{X}^{T} \sigma^{2} \mathbf{X} (\mathbf{X}^{T}\mathbf{X})^{-1}$$

$$= \sigma^{2}(\mathbf{X}^{T}\mathbf{X})^{-1}\mathbf{X}^{T}\mathbf{X} (\mathbf{X}^{T}\mathbf{X})^{-1}$$

$$= \sigma^{2}(\mathbf{X}^{T}\mathbf{X})^{-1}$$

Properties of \hat{y} and r

Using the previous results we can also show the following properties for the fitted values \hat{y} and the residuals r:

- (a) $\mathbb{E}(\hat{\mathbf{y}}) = \mathbf{X}\beta$
- (b) $Cov(\hat{\mathbf{y}}) = \sigma^2 \mathbf{H}$
- (c) $\mathbb{E}(\mathbf{r}) = \mathbf{0}$
- (d) $Cov(\mathbf{r}) = \sigma^2(\mathbf{I_n} \mathbf{H})$
- (e) $\mathbb{E}(\hat{\sigma}^2) = \frac{1}{n-p} \mathbb{E}(\mathbf{r}^\mathsf{T}\mathbf{r}) = \frac{1}{n-p} \sigma^2(n-p) = \sigma^2$

Remark: It can be shown that $\frac{\mathbf{r^Tr}}{\sigma^2} = \frac{RSS}{\sigma^2} \sim \chi^2_{n-p}$

Standard Error of \hat{eta}_1

- $\hat{\beta}$ and $\hat{\sigma}^2$ are unbiased estimators of β and σ^2 respectively.
- We can plug-in the variance estimator $\hat{\sigma}^2$ to get an estimator for the covariance of $\hat{\beta}$.
- The standard errors of the $\hat{\beta}_i$ are the square roots of the elements of the diagonal of the covariance matrix $Cov(\hat{\beta}) = \hat{\sigma}^2(\mathbf{X}^\mathsf{T}\mathbf{X})^{-1}$. For example:

$$se(\hat{\beta}_1) = \hat{\sigma}\sqrt{((\mathbf{X}^\mathsf{T}\mathbf{X})^{-1})_{11}}$$

The Gauss-Markov Theorem

If the errors are *uncorrelated*, have *equal variance* and *mean equal to zero*, the LS estimators have the lowest variance within the class of linear estimators.

– Suppose we are interested in estimating a linear combination of β of the form:

$$\theta = \mathbf{c}^T \beta = \sum_{j=1}^p c_j \beta_j$$

For example, estimating any element of β and estimating the mean response at a new value x^* are all special cases of this setup.

The Gauss-Markov Theorem (Cont.)

– Naturally, we can form an estimate of θ by plugging in the LS estimate β in the equation for θ :

$$\hat{\theta}_{\mathit{LS}} = \mathbf{c}^{\mathsf{T}} \hat{\beta} = \mathbf{c}^{\mathsf{T}} (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$$

This is a linear¹ and unbiased estimator of θ . Its mean square error can be calculated as:

$$MSE(\hat{\theta}_{LS}) = \mathbb{E}(\hat{\theta}_{LS} - \theta)^2 = Var(\hat{\theta}_{LS})$$

¹It is a linear combination of the *n* data points y_1, y_2, \ldots, y_n

Gauss-Markov theorem (Cont.)

– Suppose there is another estimate of θ , which is also linear and unbiased. The following Theorem states that $\hat{\theta}_{LS}$ is always better in the sense that its MSE is always smaller (or at least, not bigger).

Gauss-Markov Theorem

The estimator $\hat{\theta}_{LS} = \mathbf{c}^T \hat{\beta}$ is the BLUE (best linear unbiased estimator) of the parameter $\mathbf{c}^T \beta$ for any vector $\mathbf{c} \in \mathbb{R}^p$.

Proof: Please see Supplemental Material.

Maximum Likelihood Estimation

- Recall the normality assumption for the regression model:

$$y_i = \mathbf{x}_i^T \beta + \varepsilon_i \ i = 1, \dots, n, \text{ with } \varepsilon_i \sim N(0, \sigma^2)$$

- This implies that $\mathbf{y} \sim \mathbf{N_n}(\mathbf{X}\beta, \sigma^2 \mathbf{I})$.
- We can show that the likelihood function can be written as:

$$L(\beta, \sigma^2 | \mathbf{y}) \propto \frac{RSS}{n}^{-\frac{n}{2}}$$

- The value of β that maximizes the Likelihood function is the Maximum Likelihood Estimator (MLE) of β .
- This estimator is equal to the LS estimate of β .

Distribution of the Least-Squares estimates

– Recall the assumption for the linear regression model:

$$\mathbf{y} \sim \mathbf{N_n}(\mathbf{X}\boldsymbol{\beta}, \sigma^2 \mathbf{I})$$

- Any affine transformation of **y** will also have a Normal distribution².
- We can show that:

$$\begin{split} \hat{\beta} &= (\mathbf{X}^\mathsf{T} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{Y} \sim N_p(\beta, \sigma^2 (\mathbf{X}^\mathsf{T} \mathbf{X})^{-1}) \\ \hat{\mathbf{y}} &= \mathsf{H} \mathbf{y} \sim N_n (\mathbf{X} \beta, \sigma^2 \mathsf{H}) \\ \hat{\mathbf{r}} &= (\mathbf{I}_n - \mathsf{H}) \mathbf{y} \sim N_n (\mathbf{0}, \sigma^2 (\mathbf{I}_n - \mathsf{H})) \end{split}$$

²They will also have a joint Normal distribution

Distribution of the Least-Squares estimates

Indeed, for the fitted values \hat{y} and the estimated residuals $\hat{e}=r$ we can calculate the mean and covariance matrices as follows:

$$\begin{split} \mathbb{E}[\hat{\mathbf{y}}] &= \mathbf{H} \, \mathbb{E}[\mathbf{y}] = \mathbf{H} \mathbf{X} \boldsymbol{\beta} = \mathbf{X} \boldsymbol{\beta} \\ \textit{Cov}(\hat{\mathbf{y}}) &= \mathbf{H} \boldsymbol{\sigma}^2 \mathbf{H}^T = \boldsymbol{\sigma}^2 \mathbf{H} \\ \mathbb{E}[\mathbf{r}] &= (\mathbf{I_n} - \mathbf{H}) \mathbf{X} \boldsymbol{\beta} = \mathbf{0} \\ \textit{Cov}(\mathbf{r}) &= (\mathbf{I_n} - \mathbf{H}) \boldsymbol{\sigma}^2 (\mathbf{I_n} - \mathbf{H})^T = \boldsymbol{\sigma}^2 (\mathbf{I_n} - \mathbf{H}) \end{split}$$

Residuals' Properties

- Although **r** is a vector of dimension n, it always lies in a subspace of dimension (n p).
- **r** behaves like a random vector with a distribution $\mathbf{N}_{n-p}(\mathbf{0}, \sigma^2 \mathbf{I}_{n-p})$, so we have:

$$\hat{\sigma}^2 = \frac{||\mathbf{r}||^2}{n-p} \sim \sigma^2 \frac{\chi_{n-p}^2}{n-p}$$

– It can be show that \hat{y} and r are uncorrelated since they are in orthogonal spaces. Since they also have a joint normal distribution, they are independent.³

 $^{^3}$ Note that if two random variables are uncorrelated, they are not necessarily independent, unless they have a joint Normal distribution