NEURAL NETWORKS HOMEWORK 3

Self-Organizing Maps

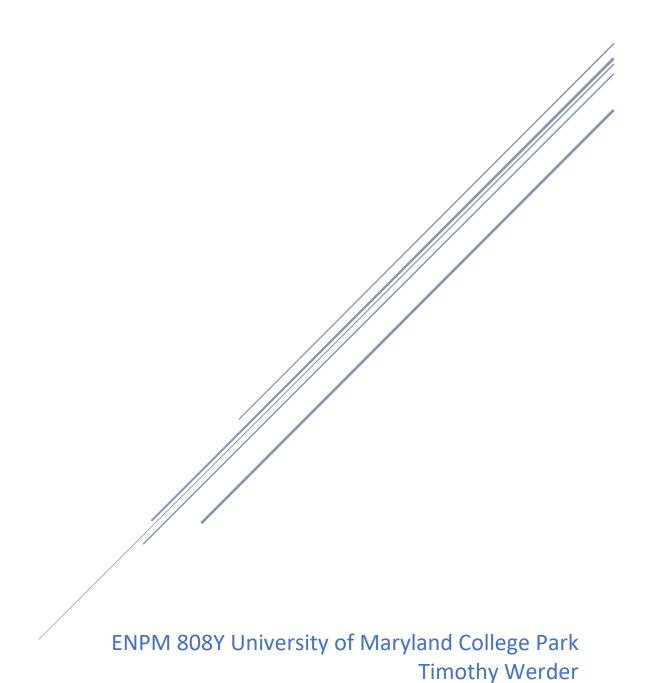


Table of Contents

| SOM Design | 2 |
|-------------------------------------|----|
| Problem 1: Traveling Salesman | 3 |
| Results | 3 |
| Hyperparameters | 6 |
| Discussion | 6 |
| Problem 2: Characteristic Mapping | 7 |
| Results | 7 |
| Hyperparameters | 9 |
| Discussion | 9 |
| Problem 3: Internal Polygon mapping | 10 |
| Results | 10 |
| Hyperparameters | 11 |
| Discussion | 11 |
| Key takeaways | 11 |

SOM Design

For my Neural network I designed a simple SOM that was modified and adapted for each problem. I began by initializing the net based on the input size multiplied by a modifier (pivot). The algorithm then randomly selects an input data and performs the Euclidian distance operation between the net and the selected values and returns the minimum coordinates and Euclidian mapping (Activation).

$$E\Delta = \sqrt{(q1-p1)^2 + (q2-p2)^2}$$

The algorithm then performs a nearest neighbors' operation using the minimum coordinates resulting in a local gaussian distribution.

$$d\Delta = min|shape-q1, q2|$$

$$Bij = e^{\frac{d\Delta^2}{2(\sigma^2)}}$$

The local gaussian distribution is then multiplied by the learning rate and the difference between the selected values and the network (Deactivation). The learning rate and the n value (neighboring sigma) are then diminished. The SOM training operation exits once the number of runs has completed or the learning rate or number of neighbors have diminished below a threshold.

Problem 1: Traveling Salesman

Results

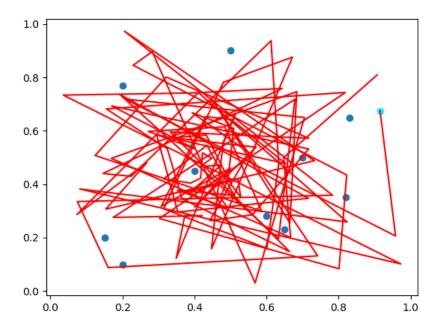


Figure 1: TSP Epoch=1

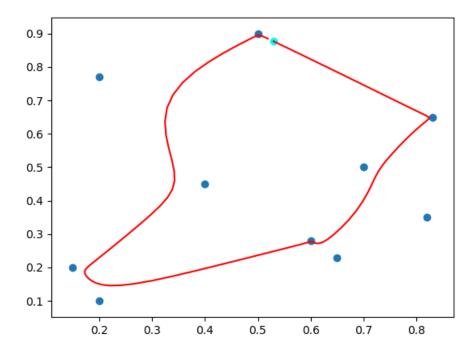


Figure 2: TSP Epoch=50

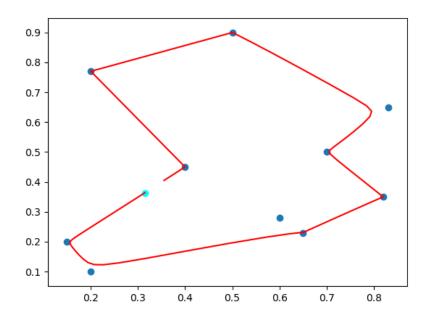


Figure 3: TSP Epoch=150

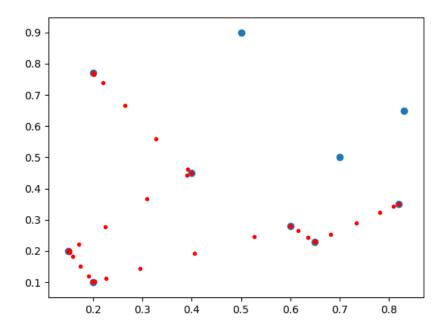


Figure 4: TSP Final Animated

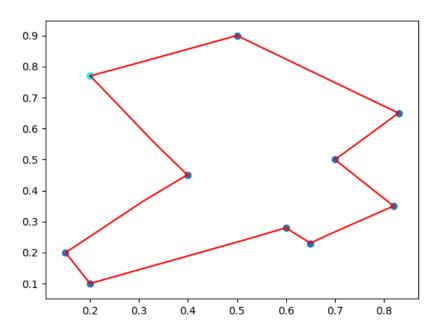


Figure 5: TSP Final Epoch=458

Hyperparameters

| Learning Rate= 0.8 | Neurons: | Sigma: | Layering: |
|----------------------|----------|--------|---------------------|
| | 100 | 6 | |
| Time to Train: 0.78s | Epochs: | N: | Euclidean, Gaussian |
| | 458 | 10 | |

Discussion

The TSP problem is a relatively easy problem of ordering distances. For most algorithms this constitutes checking a point to all neighbors and ordering the minimum distances from start to finish. With SOMs we roughly do the same procedure, with the difference being the gaussian distribution across a network that distributes the distances and eventually culminates in a pathing formed by a linear interpretation of the network. Overall my algorithm performs very well within a short learning period.

Problem 2: Characteristic Mapping Results

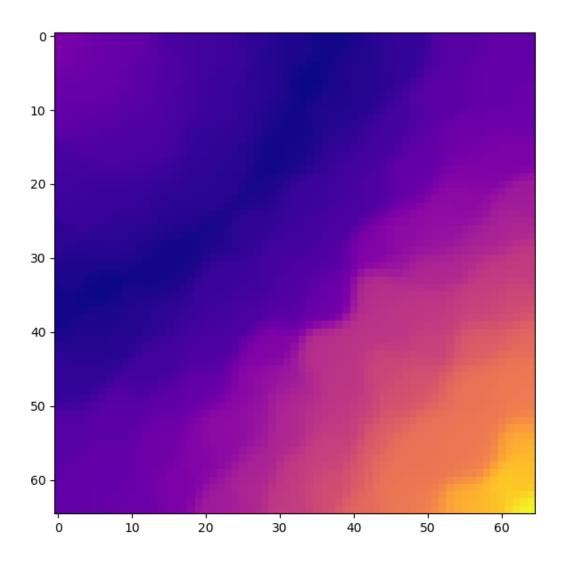


Figure 6: Euclidean gradient mapping

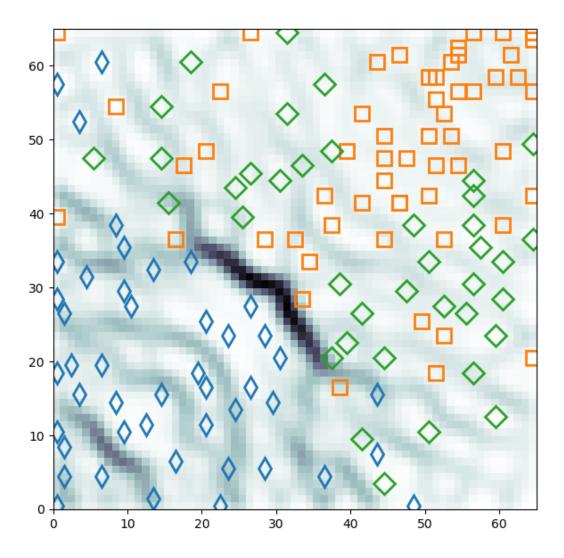


Figure 7: Cluster Mapping

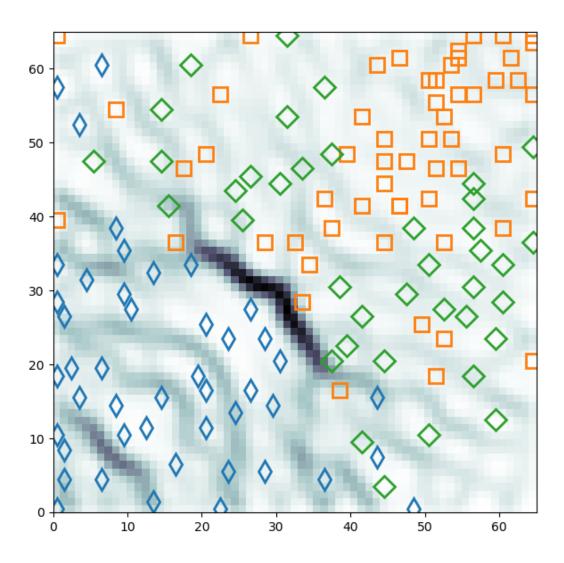


Figure 8: Cluster Mapping Segmentation

Hyperparameters

| Learning Rate= 0.7 | Neurons: | Sigma: | Layering: |
|----------------------|----------|--------|------------------------|
| | 65 | 7 | |
| | 03 | / | |
| Time to Train: 3.23s | Epochs: | N: | Euclidean, Gaussian 2D |
| | 4172 | 5 | |

Discussion

The 2D mapping of clusters of data from a multi-dimensional space to a 2D Kohen map is one of the bigger advantages of SOMs. In this problem 13 aspects of data were classified into three classes, these

classes are represented by the different colored shapes. For this I shuffled the data and trained. The data was then run against the activation function and plotted along the map after transposing the map and determining the distance map. Overall my algorithm computes a fairly good cluster in a short amount of time. It would have been better if there was more data to split into a train and test segment so that testing could show a better approximation of the map.

Problem 3: Internal Polygon mapping Results

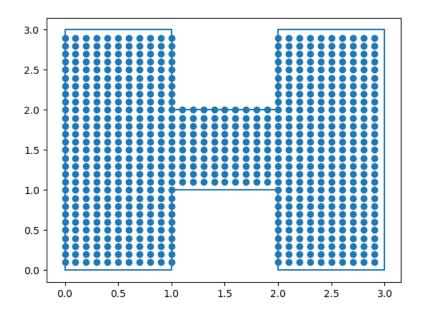


Figure 9: Internal area polygon point representation

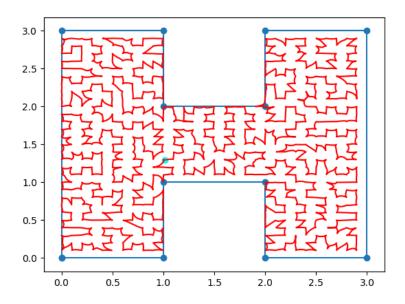


Figure 10: Internal mapping of Polygon

Hyperparameters

| Learning Rate= 0.8 | Neurons: | Sigma: | Layering: |
|-----------------------|----------|--------|---------------------|
| | 9786 | 6 | |
| Time to Train: 17.44s | Epochs: | N: | Euclidean, Gaussian |
| | 9184 | 14 | |

Discussion

Similar to the TSP problem the SOM attempts to map out a region. For this to work an additional aspect of data preparation must be made, a distribution of points internal to the polygon. This is done by creating a mask against the polygon and selecting only points internal to the walls. This requires that a larger number of neurons be used to accurately map out each of the points and a higher sigma value to get a finer gaussian distribution. Overall my algorithm performs well with the occasional external mapping to complete the route and does this within a short period of time given the number of neurons and neighbors needing to be accounted for.

Key takeaways

This project helped me understand the power of SOMs. They are very powerful and very lightweight ways to do self-organizing based on large or limited quantities of data. Overall, my code worked well, but given more time it could be adapted such that it could act more as a library to be called for any dimension rather than tuning the internal parameters for each problem but I am overall happy with the results.