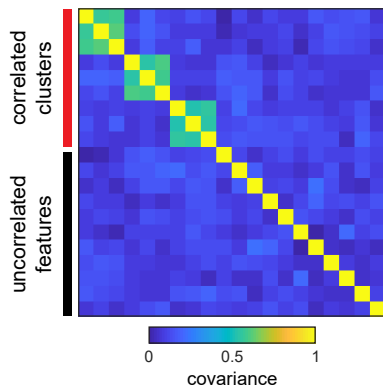


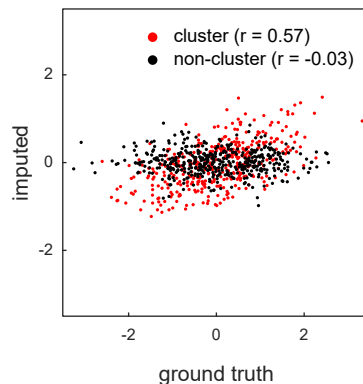
A

covariance matrix

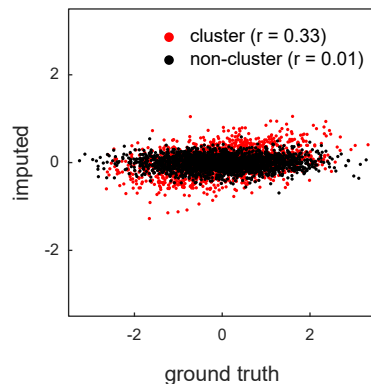


B

fraction missing = 0.10

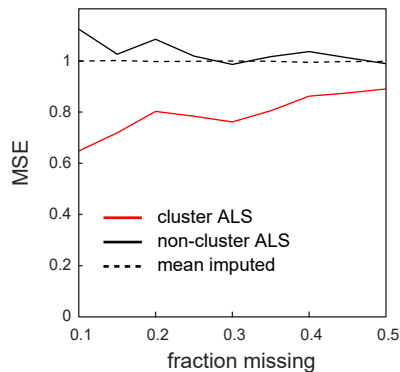


fraction missing = 0.50



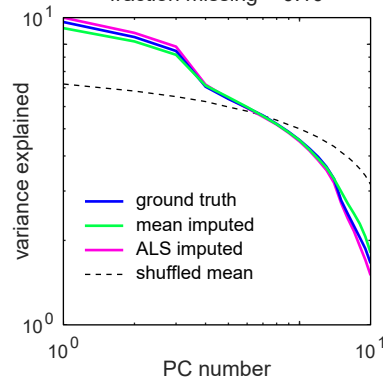
C

imputation error



D

fraction missing = 0.10



fraction missing = 0.50

