Pose error object₁ with varying Training Data Split 160 - 10^{1} 140 -Pose error (in degrees) 120 100 - 10^{0} 80 -60 40 -20 - 10^{-1} 0 0.1 0.2 0.3 0.4 0.6 0.7 8.0 0.9 0.5 Training Data Split