1. For this part, we have to derive an expression for I(x) (where I is a 1D ramp image) after filtering it by a zero-mean Gaussian filter with standard deviation σ . In other words, we convolve g with I, where g is the PDF associated with $N(0, \sigma^2)$ (the zero-mean Gaussian distribution). So, we get

$$J(x) = (g * I)(x)$$

$$= \int_{-\infty}^{\infty} g(y)I(x - y) dy$$

$$= \int_{-\infty}^{\infty} g(y) (c(x - y) + d) dy$$

$$= -\int_{-\infty}^{\infty} cyg(y) dy + \int_{-\infty}^{\infty} (cx + d)g(y) dy$$

$$\underbrace{\mathcal{I}_{1}}_{1}$$

In the above expression for J(x), we observe that \mathcal{I}_1 is 0 because the integrand is an odd function. Therefore, upon simplifying, we get

$$J(x) = \int_{-\infty}^{\infty} (cx + d)g(y) dy$$

$$= (cx + d) \int_{-\infty}^{\infty} g(y) dy$$

$$= cx + d$$

$$= I(x)$$
(2)

where (1) follows because c and d are constants in \mathbb{R} , and x is constant w.r.t. y, and (2) follows because the integral of a PDF over the entire space is equal to 1.

2. Note that the general definition of a bilateral filter (as can be found here, for example) does not require the intensity smoothing filter and the distance smoothing filter to be Gaussian filters. For this question, we assume that both filters are Gaussian filters, in accordance to what was taught in class and what was shown in the slides.

Let the bilateral Gaussian filter with parameters σ_s and σ_r , be denoted by $B_{\ell}(y)$ and defined as follows:

$$B_{\ell}(y) = \frac{b(y)}{W}$$

Where we define b(y) and W as

$$b(y) := \left(\frac{\exp\left(\frac{-y^2}{2\sigma_s^2}\right)}{\sqrt{2\pi}\sigma_s}\right) \left(\frac{\exp\left(\frac{-(I(x-y)-I(x))^2}{2\sigma_r^2}\right)}{\sqrt{2\pi}\sigma_r}\right)$$
(3)

$$W \coloneqq \int_{-\infty}^{\infty} b(y) \, \mathrm{d}y \tag{4}$$

Similar to the previous question, in order to find an expression for J(x), we will convolve B_{ℓ} with I to get the new image. We get

$$J(x) = (B_{\ell} * I)(x)$$

$$= \int_{-\infty}^{\infty} \frac{b(y)}{W} I(x - y) dy$$

$$= \frac{1}{W} \int_{-\infty}^{\infty} b(y) (c(x - y) + d) dy$$
(5)

Upon expanding the integral in (5), we get

$$J(x) = \frac{1}{W} \int_{-\infty}^{\infty} (cx - cy + d)b(y) \, dy$$
$$= -\frac{1}{W} \int_{-\infty}^{\infty} cyb(y) \, dy + \frac{1}{W} \int_{-\infty}^{\infty} (cx + d)b(y) \, dy$$
(6)

Observe that since I is a ramp image, I(x-y) - I(x) simplifies to -cy, so (3) simplifies to

$$b(y) = \left(\frac{\exp\left(\frac{-y^2}{2\sigma_s^2}\right)}{\sqrt{2\pi}\sigma_s}\right) \left(\frac{\exp\left(\frac{-cy^2}{2\sigma_r^2}\right)}{\sqrt{2\pi}\sigma_r}\right) = \frac{\exp\left(\frac{-y^2}{2\sigma_s^2}\right) \exp\left(\frac{-cy^2}{2\sigma_r^2}\right)}{2\pi\sigma_s\sigma_r}$$
(7)

The key thing to note is that (7) is an even function, meaning that yb(y), which is the integrand in \mathcal{I}_2 , is an odd function. Hence, $\mathcal{I}_2 = 0$, which implies that (6) can be simplified to

$$J(x) = \frac{1}{W} \int_{-\infty}^{\infty} (cx + d)b(y) \, dy$$
$$= \frac{1}{W} \int_{-\infty}^{\infty} I(x)b(y) \, dy$$
$$= I(x) \left(\frac{1}{W} \cdot \int_{-\infty}^{\infty} b(y) \, dy\right)$$
$$= I(x)$$

where the last equality is due to the definition of W (see (4)). \square We note that, in general, the above result about 1D ramp images will hold for any intensity smoothing filter $S_{\mathcal{I}}$ and any distance smoothing filter S_d , as long as both $S_{\mathcal{I}}$ and S_d are even functions.

Hence, in both cases, we get back the same image after applying the filter.