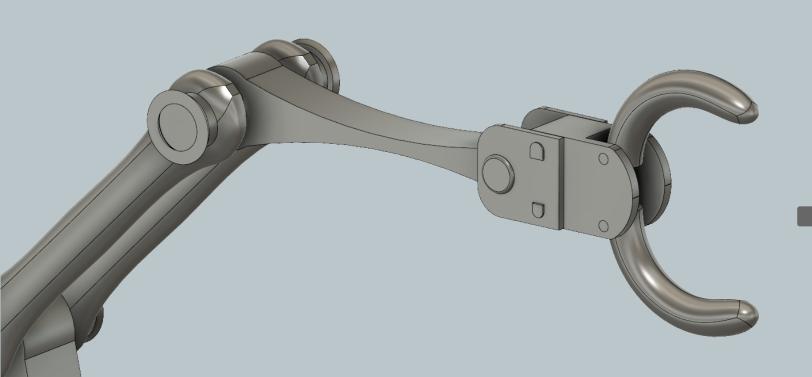


ROBOT ARM PROJECT

For Smart Methodes Copmany

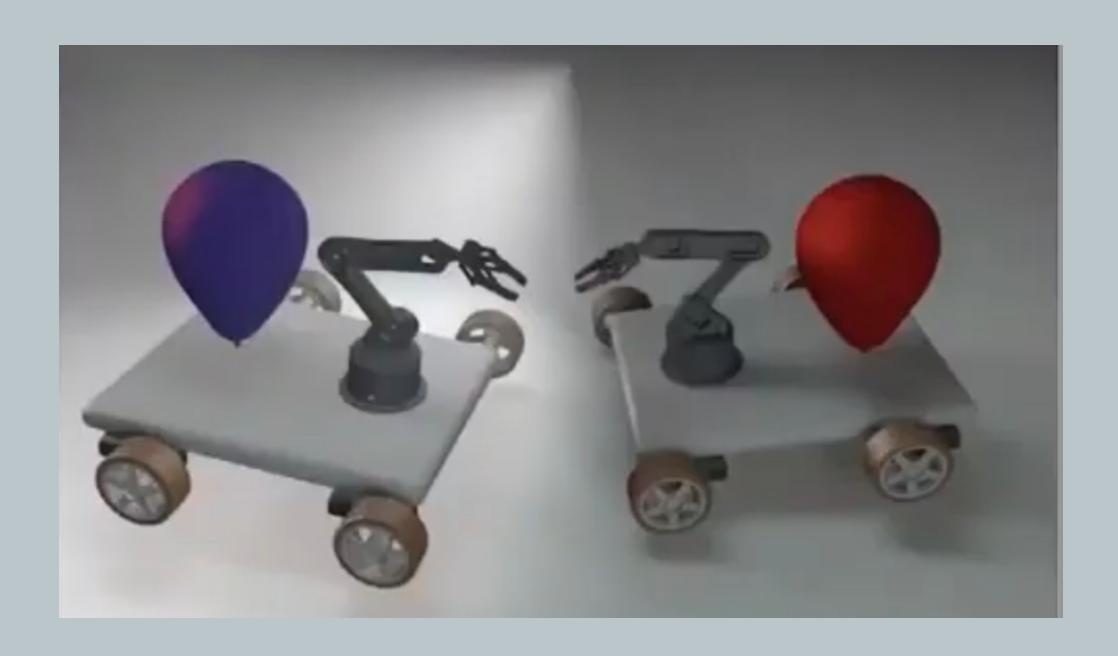


Prepared by: Wesam Al-jurish

PROJECTIDEA

Designe a Robotic Arm and programmed it to participate in the Robotic Arms competition.

The competition is starts by putting two Robotic Arms in the ring with a balloon behind each one, then they try to destroy the balloon of the other Arm.



GROUP ORGANIZATIONAL STRUCTURE

INDUSTRIAL AND SYSTEM ENGINEERING DEPARTMENT (Group Leader)

ELECTRONICS AND POWER DEPARTMENT

INTERNET OF THINGS DEPARTMENT

MECHANICAL DEPARTMENT ROBOTICS AND AI DEPARTMENT

PROJECTPLAN

- 1.Planning for the project by gathering all the team members and discussing the mechanism of the project.
- 2.Divide tasks between team members and define deadline to complete the project's tasks
- 3.Choose all the required electrical (electric circuits) and mechanical (materials) parts
- → 4.Starts the mental visualization of structure, the drawing and way of implementation it on real-life.
- → 5.Start printing the robot parts, design convenient electric circuits, develop the web page controller and combine robot with AI to make it smarter

DISTRIBUTION OF TASKS

MECHANICAL DEPARTMENT	Design robot parts	Assembly parts	3d printing
ELECTRONICS DEPARTMENT	Building electrical circuits	Programming electrical circuits	Test the motores
IOT DEPARTMENT	Design UI to control Robot	Create Database for the robotic control system	Connect Database with UI and test it
ROBOTICS(AI) DEPARTMENT	Use ROS system to simulate the robot movement	Control the movement of the robot	Design vision system for robot

Group management

and organization

Coordination between

members

Leading and

supervising the

process

INDUSTRIAL

DEPARTMENT

TIMELINE

	Mon	Tues	Wed	Thurs	Fri
MECHANICAL DEPARTMENT	Design ro	bot parts	Assembly parts	3d pri	nting
ELECTRONICS DEPARTMENT	Daniam g erecti rear		Progra electrica	mming I circuits	Test the motores
IOT DEPARTMENT	Design UI to control Robot		Create Database for the robotic control system	Connect Database with UI and test it	
ROBOTICS(AI) DEPARTMENT	Use ROS system to simulate the robot movement	Control the of the		Design visi	

PRODUCTION LINE

Modeling	
Package —	—— In an airtight box and the arms fixed with pieces of cork.
Software —	