

# WESLEY YEE

Robotics Graduate Student - University of Pennsylvania

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in wesley-yee

🌐 wesleyyee.com

## EDUCATION

### Robotics M.S.E.

University of Pennsylvania

📅 Aug 2020 - Present ● GPA: 3.70

### B.S. Mechanical Engineering

Rice University

📅 Aug 2014 - May 2018 ● GPA: 3.50

## SKILLS

Java	<div><div></div></div>
SQL	<div><div></div></div>
Python	<div><div></div></div>
Matlab	<div><div></div></div>
C++	<div><div></div></div>
ROS	<div><div></div></div>
Fusion 360	<div><div></div></div>
AWS	<div><div></div></div>

## RELEVANT COURSEWORK

Intro. to Robotics

Distributed Systems

Computer Graphics

Algorithms and Computation

Fundamentals of Control Systems

Intro. to Engineering Design

## AWARDS

### World Congress of Biomechanics

2018 finalist in international undergraduate design competition

### President's Honor Roll

Spring 2017

## WORK EXPERIENCE

### Software Consultant

Quorum Software

📅 August 2018 - May 2020 ● Houston, TX

- Developed, implemented and tested project implementations for 120+ hour web-based ERP systems in C# and SQL for data management needs of natural gas pipeline clients
- Performed mapping of target to source data sets, created conversion scripts, and executed migration of measurement and billing data collected from 1.2 million customers accumulated over 10+ years

### Teaching Assistant

University of Pennsylvania

📅 January 2021 - Present ● Philadelphia, PA

- Grade course material and hold weekly office hours for CIS 455/555 (Distributed Systems), which is consistently rated as one of most difficult courses at Penn

## PROJECTS

### Distributed Search Engine

- Worked on team of four to build a Google-inspired distributed search engine completely hosted on AWS
- Independently constructed the web crawler capable of downloading 160,000+ pages/hour using Spark Java web framework

### Controller for 6-DOF Robotic Manipulator

- Implemented an RRT\* and artificial potential field path planning algorithm with obstacle avoidance in MATLAB and ROS
- Utilized forward, inverse, and velocity kinematics to pick up blocks from dynamic turnstile during in-class competition

### Robotic Horse for Rehabilitative Therapy

- Worked on team of six to build a programmable device used to simulate movement of a horse for hippotherapy patients
- Utilized Stewart Platform concept to enable 6-DOF movement and a low-cost, open-source design