

Meta-Learning as Prediction Map Approximation

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Collaborators



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Requeima



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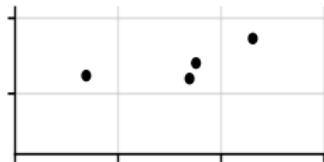
Anna
Vaughan



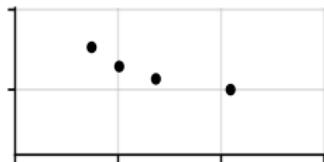
Yann
Dubois



Rich
Turner

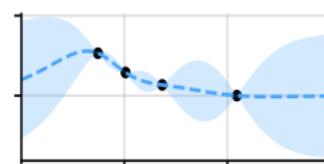
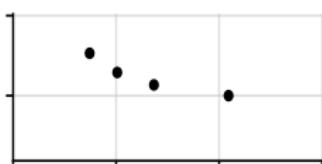
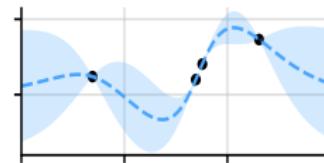
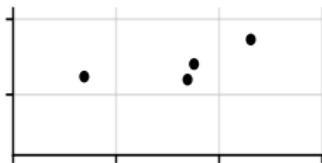


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Meta-Learning and Neural Processes

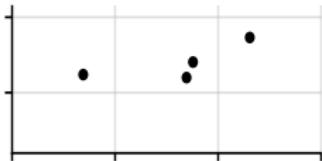
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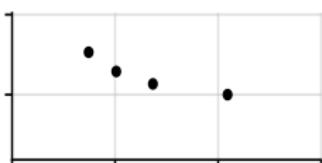
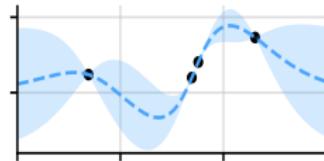
π : data sets \mathcal{D}

\rightarrow

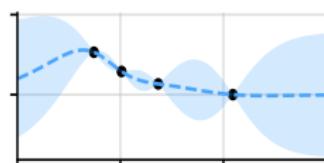
predictions \mathcal{P}



$\pi \rightarrow$



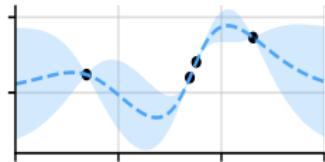
$\pi \rightarrow$



$\pi : \text{data sets } \mathcal{D} \rightarrow \text{predictions } \mathcal{P}$



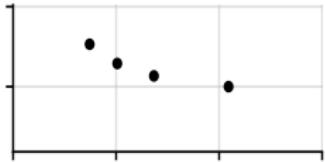
$\pi \rightarrow$



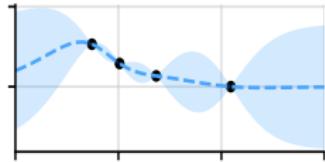
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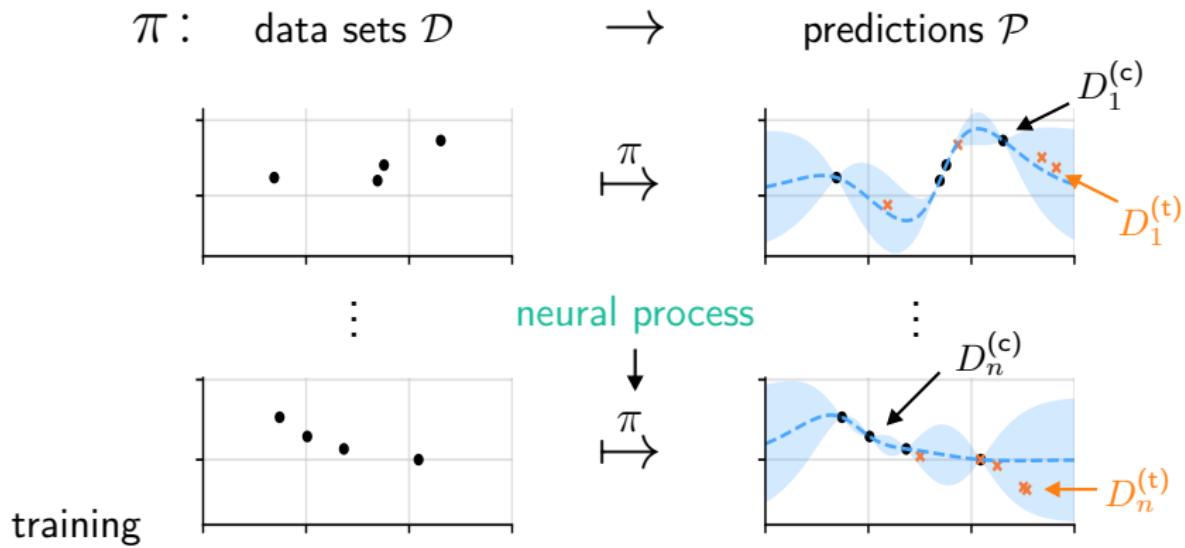
neural process

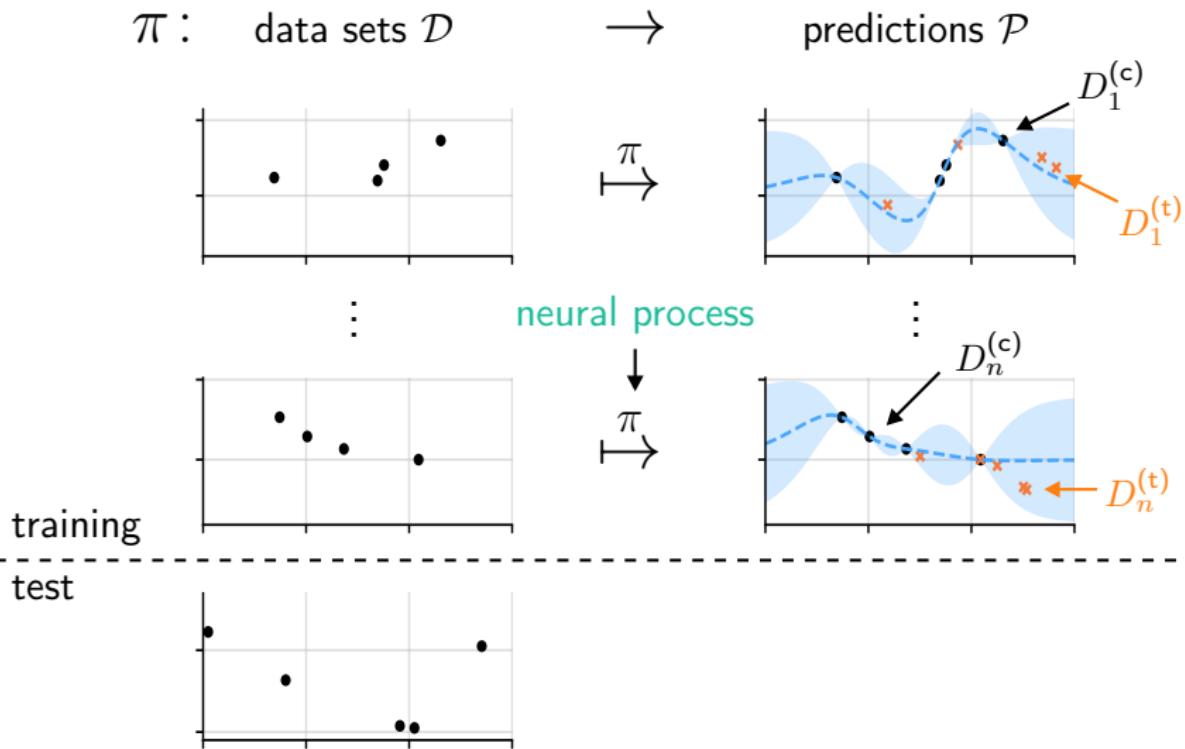
:



\downarrow
 $\pi \rightarrow$

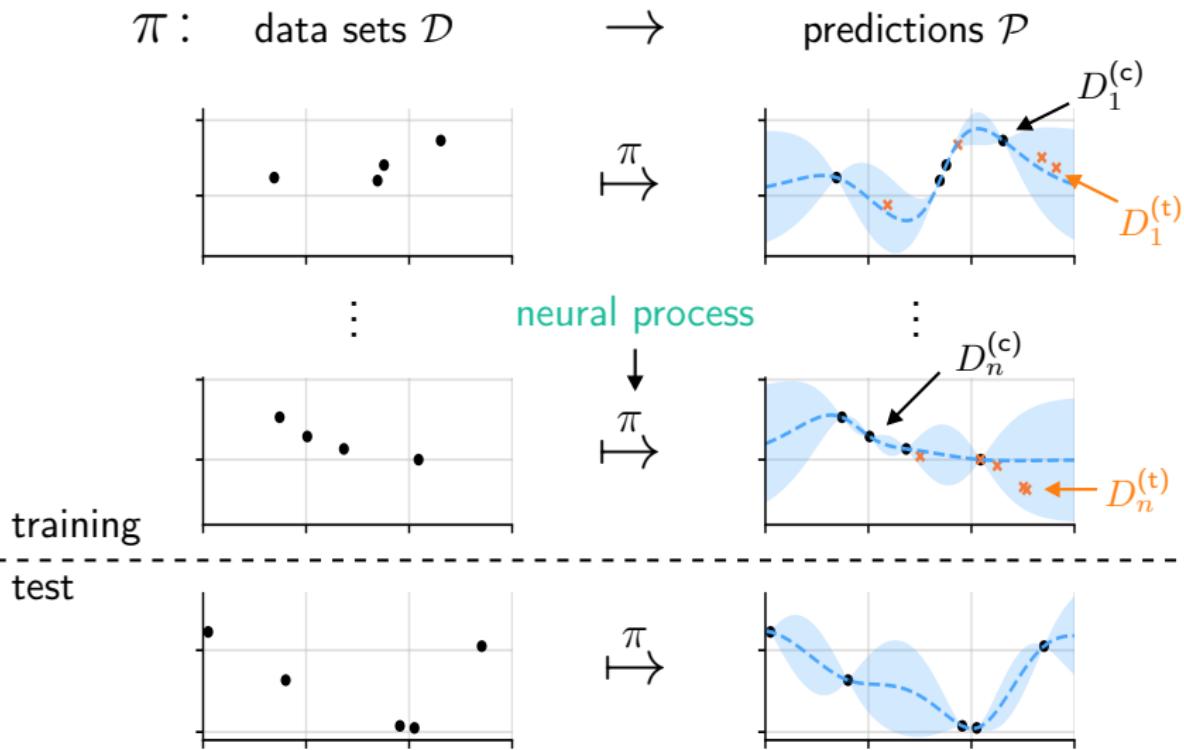






Meta-Learning and Neural Processes

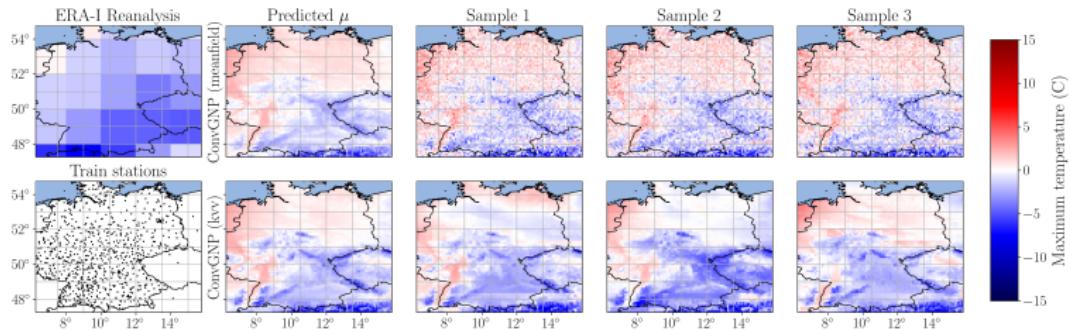
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Applications of Neural Processes

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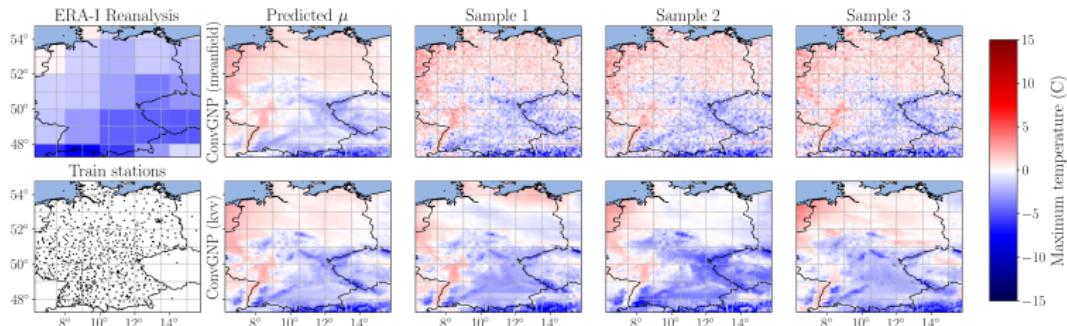
- Climate model downscaling (Markou et al., 2022):



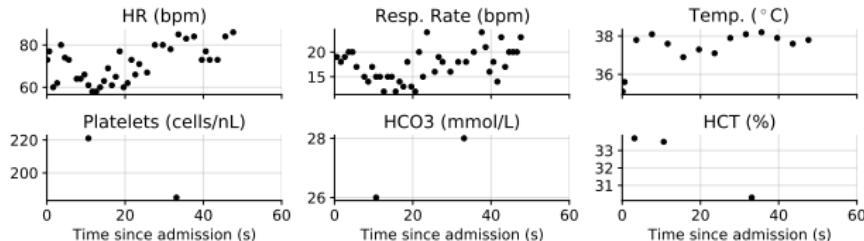
Applications of Neural Processes

2/11

- Climate model downscaling (Markou et al., 2022):



- ICU monitoring (Silva et al., 2012; Shysheya, 2020):



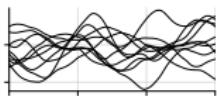
Today: Prediction Map Approximation

3/11

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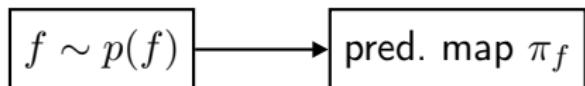
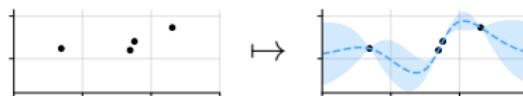
$$f \sim p(f)$$



Today: Prediction Map Approximation

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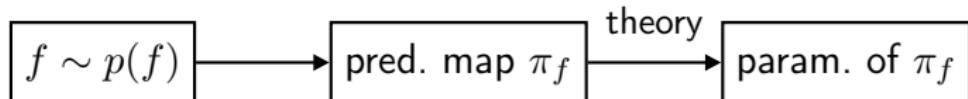
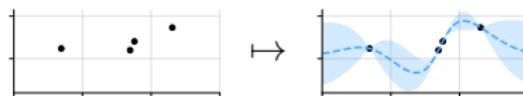
$$D \quad \mapsto \quad \pi_f \quad p(f | D)$$



Today: Prediction Map Approximation

3/11

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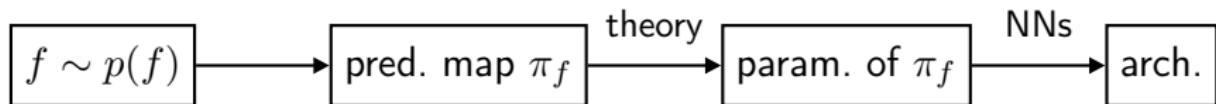
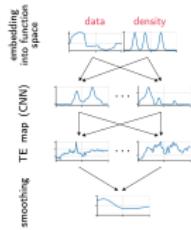
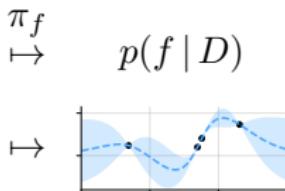
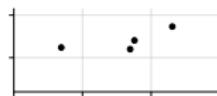


$$m(D) = \rho \left(\sum_{(x,y) \in D} \phi(x, y) \right)$$

Today: Prediction Map Approximation

3/11

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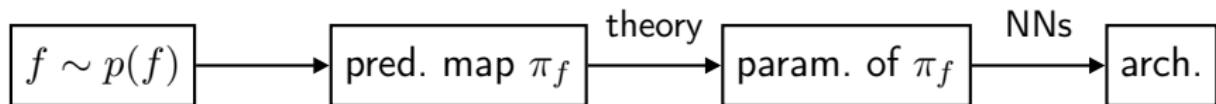
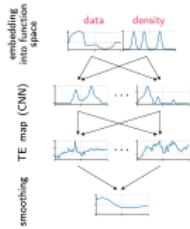


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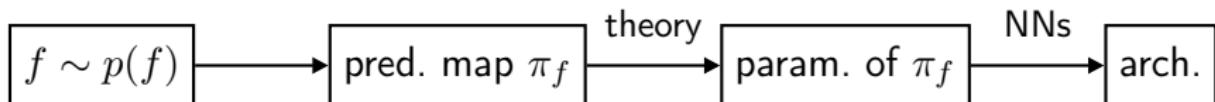
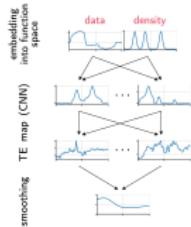
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3/11

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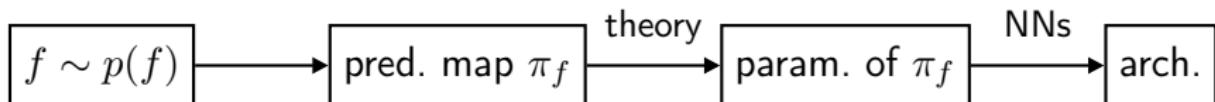
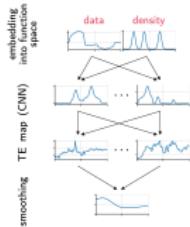
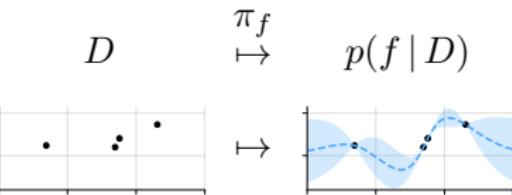


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- ✓ Architectures with universal approximation properties
- ✓ Properties of $f \Rightarrow$ symmetries of $\pi_f \Rightarrow$ param. efficient archs!

Prediction Map Approximation

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$$\tilde{\pi}(D) = \pi_{\text{MM}}(D) := \mathcal{GP}(m_{f|D}, k_{f|D}).$$

- Practical objective:

$$\tilde{\pi} \in \arg \min_{\pi \in \mathcal{Q}} \mathcal{L}(\pi),$$

$$\mathcal{L}(\pi) = \mathbb{E}_{p(D)p(\mathbf{x})} \text{KL}(P_{\mathbf{x}}\pi_f(D), P_{\mathbf{x}}\pi(D))$$

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- Setting \mathcal{Q} to

$$\mathcal{M}_{\mathcal{G}} = \{\pi: \mathcal{D} \rightarrow \mathcal{P}_{\mathcal{G}} : \pi \text{ continuous}\},$$

minimiser exists, is unique, and coincides with original problem!

- For now, consider $\mathcal{Q}_{G, MF} = \{\pi: \mathcal{D} \rightarrow \mathcal{P}_{G, MF}\}$.

GPs without correlations,
↓ i.e. $k(x, x') = 0$ if $x \neq x'$

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- Separately parametrise **mean map** and **variance map**:

$$m: \mathcal{D} \rightarrow C(\mathbb{R}, \mathbb{R}), \quad \sigma^2: \mathcal{D} \rightarrow C(\mathbb{R}, (0, \infty)).$$

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Thm (Zaheer et al., 2017; Wagstaff et al., 2019). A continuous function $f: \mathcal{D}_{\leq M} \rightarrow Z$ has the form of a deep set:

$$f(D) = \rho\left(\sum_{(x,y) \in D} \phi(x, y)\right)$$

where $\phi: \mathbb{R}^2 \rightarrow \mathbb{R}^M$ and $\rho: \mathbb{R}^M \rightarrow Z$ are continuous.

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- Conditional neural process (Garnelo et al., 2018):

$$\mathcal{L} + \mathcal{Q}_{G, MF} + \text{deep sets for } \pi = \text{CNP}$$

Consistency of Prediction Map Approximation

The Problem

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$$\mathcal{L}_n(\pi) = -\frac{1}{N} \sum_{n=1}^N \log q(D_n^{(t)} | D_n^{(c)})$$

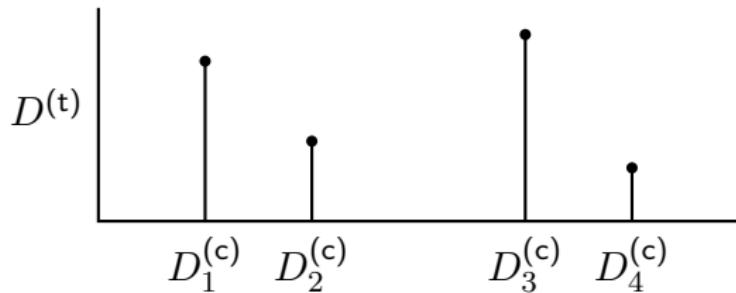
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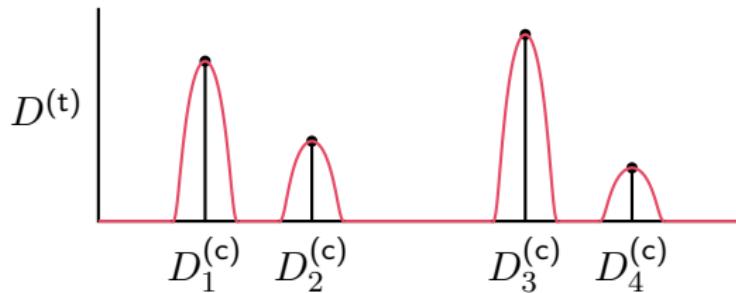
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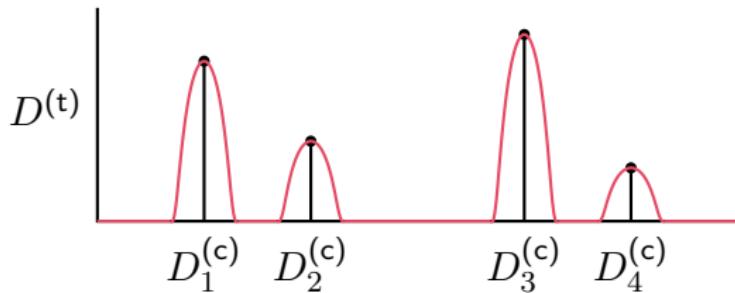
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$$\mathcal{L}_n(\pi) = -\frac{1}{N} \sum_{n=1}^N \log q(D_n^{(t)} | D_n^{(c)}) \approx \frac{1}{N} \sum_{n=1}^N (D_n^{(t)} - f(D_n^{(c)}))^2$$

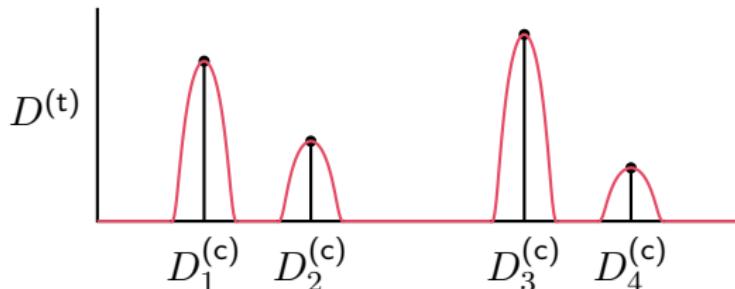
The Problem

7/11



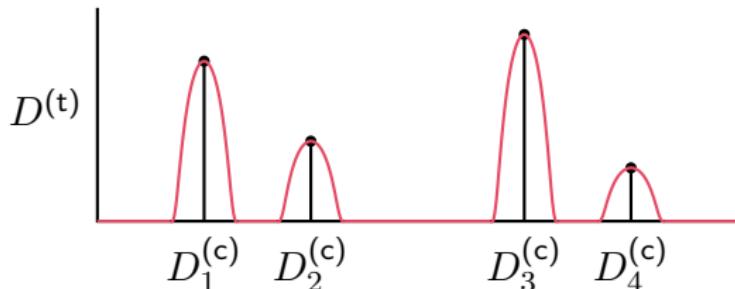
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⇒ Cannot optimise $\mathcal{L}_n(\pi)$ over $\pi \in \mathcal{M}_G$: **overfitting!**



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⇒ Cannot optimise $\mathcal{L}_n(\pi)$ over $\pi \in \mathcal{M}_G$: **overfitting!**

- **Practice:** tune NN capacity using black magic.
- Will show that we can reasonably restrict to **compact** $\mathcal{Q} \subset \mathcal{M}_G$.

Let $\mathcal{D} \subseteq \bigcup_{n=0}^{\infty} (\mathcal{X} \times \mathbb{R})^n$ be a collection of data sets of interest.

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Assumptions:

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- There exist $p \geq 2$, $q > 1$, $c > 0$, and $r > 0$ such that

$$\mathbb{E}[|f(x) - f(y)|^p] \leq c|x - y|^q \quad \text{whenever } |x - y| < r.$$

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- Observations under Gaussian noise with $\sigma^2 \in [\underline{\sigma}^2, \bar{\sigma}^2]$.

- Identify every $\pi \in \mathcal{M}_G$ with

$$m: \mathcal{X} \times \mathcal{D} \rightarrow \mathbb{R}, \quad k: \mathcal{X} \times \mathcal{X} \times \mathcal{D} \rightarrow \mathbb{R}, \quad \sigma^2 \in [\underline{\sigma}^2, \bar{\sigma}^2].$$

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- Then exist $L^*: [0, \infty)^2 \rightarrow [0, \infty)$ and $M^* > 0$ such that

$$\pi_{\text{MM}} \in \left\{ \pi \in \mathcal{M}_G \left| \begin{array}{l} |m(x_1, D_1) - m(x_2, D_2)| \leq L^*(|x_1 - x_2|, \|D_1 - D_2\|) \\ |k(x_1, D_1) - k(x_2, D_2)| \leq L^*(|x_1 - x_2|, \|D_1 - D_2\|) \\ \|m\|_\infty, \|k\|_\infty \leq M^* \end{array} \right. \right\}.$$

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- Call this collection \mathcal{Q}^* . Define a metric on \mathcal{Q}^* :

$$d(\pi_1, \pi_2) = \|m_1 - m_2\|_\infty + \|k_1 - k_2\|_\infty + |\sigma_1^2 - \sigma_2^2|.$$

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- Arzelà–Ascoli theorem: (\mathcal{Q}^*, d) is compact.

Thm. Let

$$\pi_n \in \arg \min_{\pi \in \mathcal{Q}^*} \mathcal{L}_n(\pi), \quad \mathcal{L}_n(\pi) = -\frac{1}{N} \sum_{n=1}^N \log q(D_n^{(t)} | D_n^{(c)}).$$

Then, almost surely, $\pi_n(D) \rightarrow \pi_{\text{MM}}(D)$ for all $D \in \mathcal{D}$.

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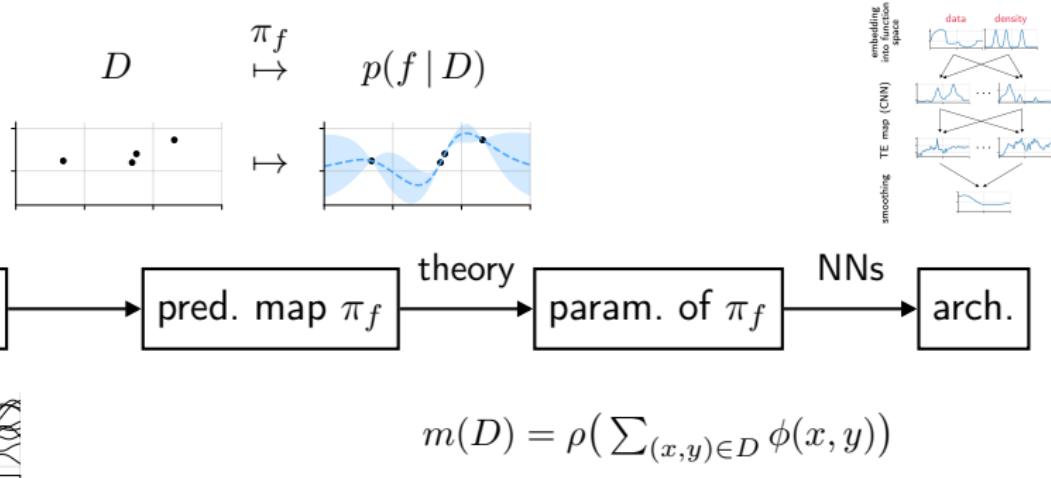
Pending questions:

- $\mathcal{Q}_{\text{NN}} = \{(m_\theta, k_\theta, \sigma^2) : \theta \in \mathbb{R}^P\}$?
- **How much data:** finite-sample bounds / rates of convergence?

Wrapping Up

Prediction Map Approximation

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- ✓ Theoretical framework
- ✓ Architectures with universal approximation properties
- ✓ Properties of $f \Rightarrow$ symmetries of $\pi_f \Rightarrow$ param. efficient archs!

These slides: <https://wesselb.github.io/pdf/cbl-predmap.pdf>

Appendix

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