

view\_frames Result

Recorded at time: 1615321897.122

os\_sensor

Broadcaster: /os\_cloud\_node

Average rate: 10000.000 Hz

Most recent transform: 0.000 ( 1615321897.122 sec old)

Buffer length: 0.000 sec

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Average rate: 10000.000 Hz

Most recent transform: 0.000 ( 1615321897.122 sec old)

Buffer length: 0.000 sec

os\_imu

os\_lidar