

A Practical Guide to MEMS Inertial Sensors

Stanford PNT Symposium

Alissa M. Fitzgerald, Ph.D. | 14 November 2013



AMFITZGERALD
& ASSOCIATES

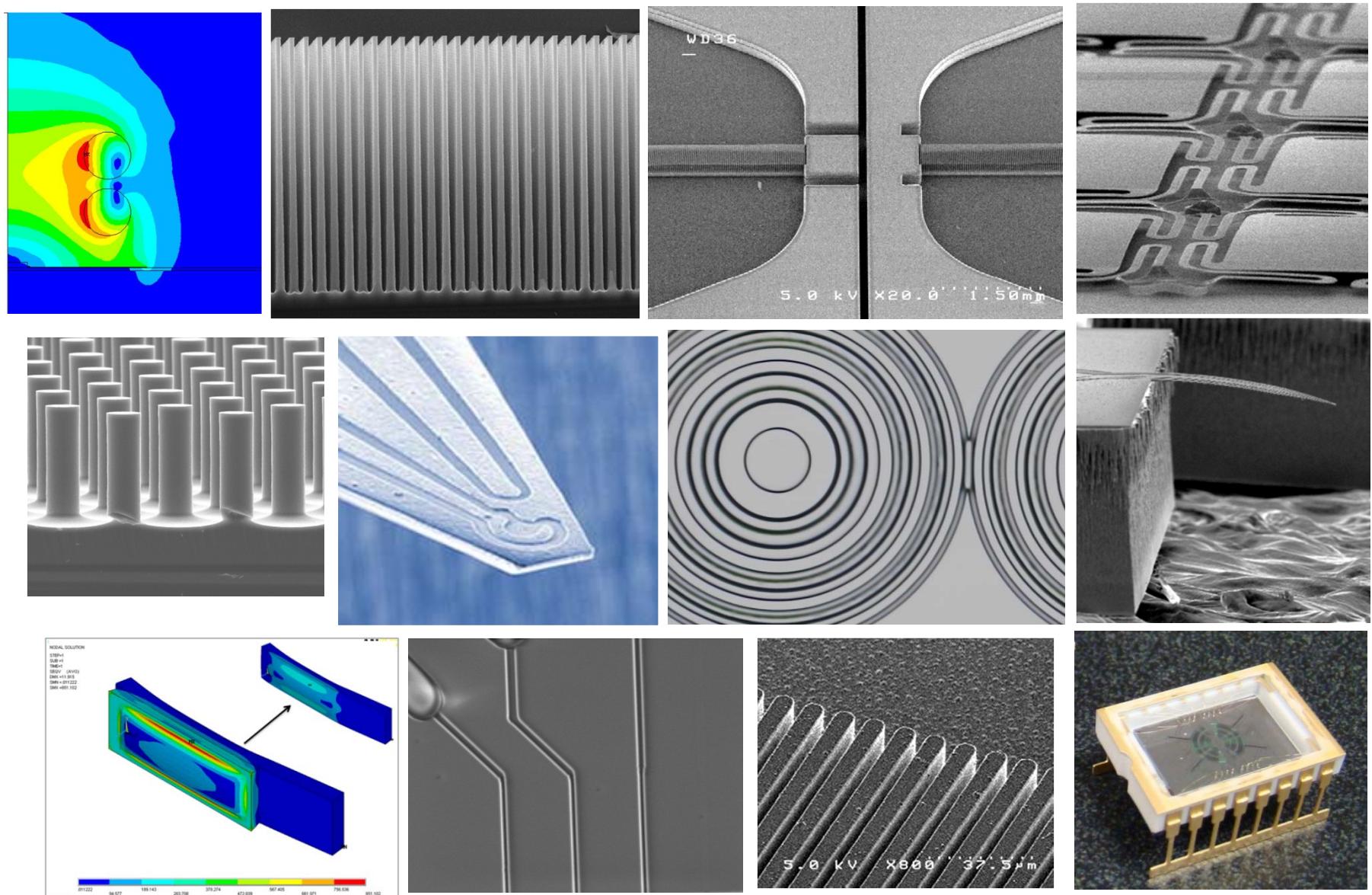


Overview

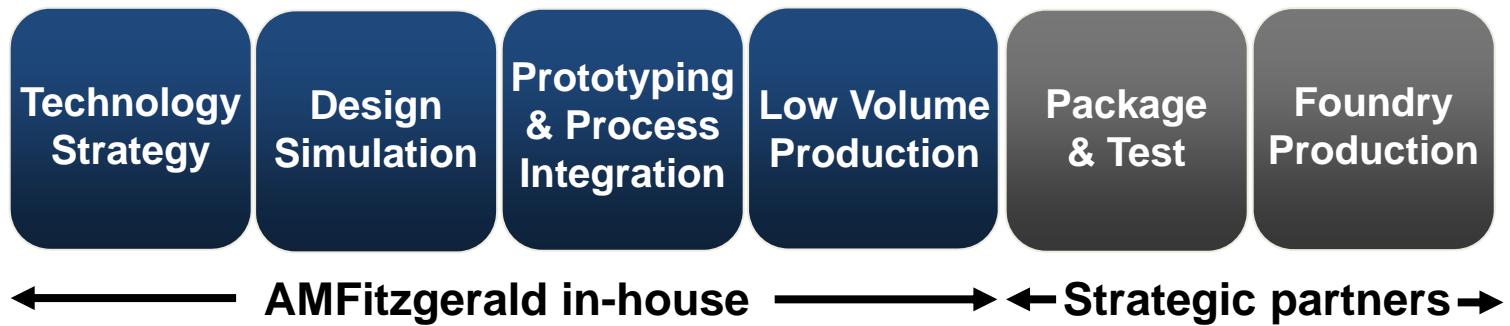
- **About AMFitzgerald**
- **How MEMS* are made**
- **MEMS inertial sensor overview**
- **Packaging**
- **6 DOF and more**
- **Appendix: Specifications for a selection of sensors**

MEMS = *Micro Electro Mechanical Systems

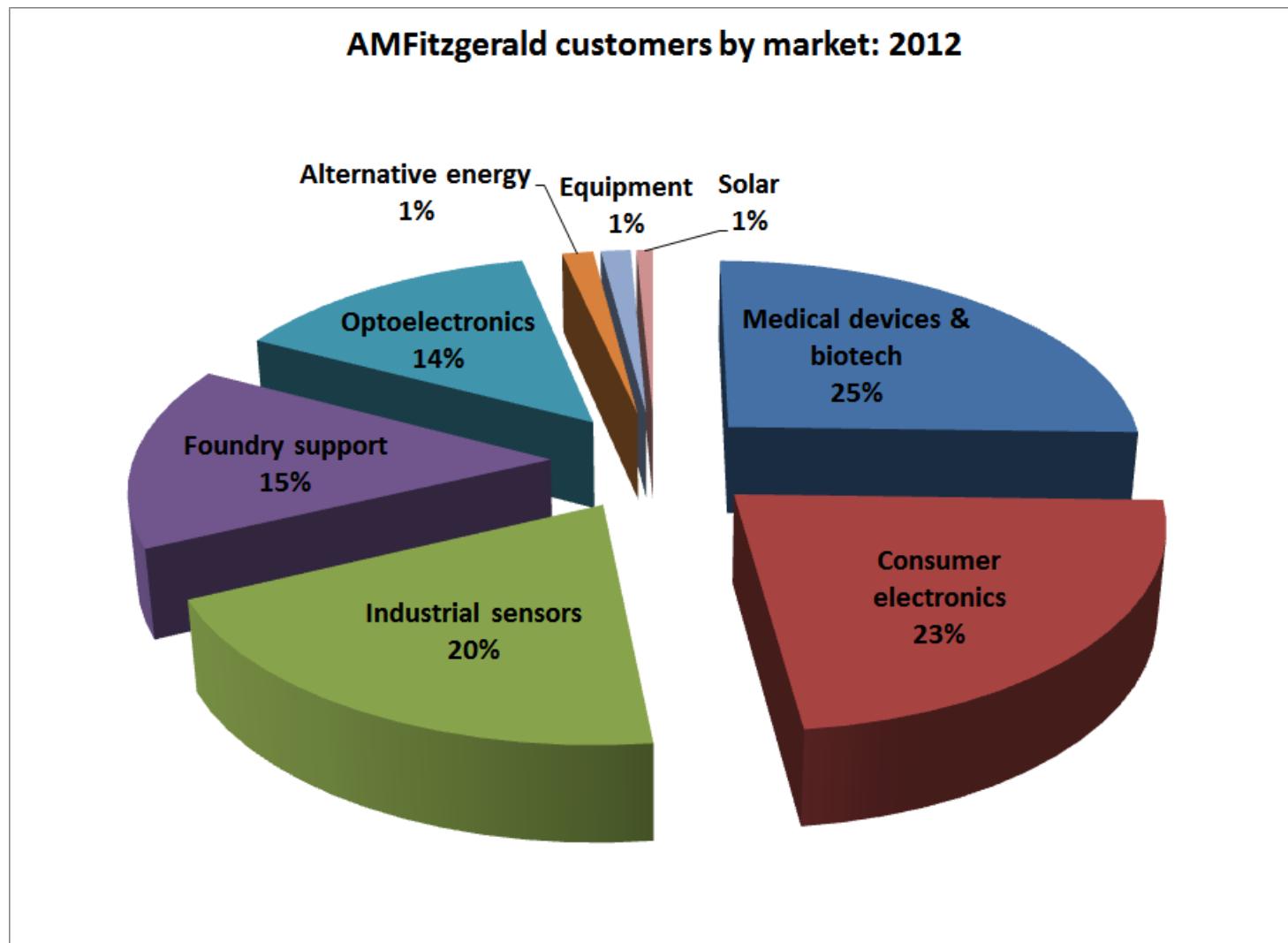
AMFitzgerald: Your Partner in MEMS Product Development



AMFitzgerald: MEMS solutions, from concept to production



Our customer base is as diverse as MEMS itself



Types of MEMS developed in 2012:

- Optical switch**
- Microfluidics**
- Microphone**
- Timing**
- Microtexture**
- Inkjet**
- Radiation**
- Motion**
- Pressure**
- Micro-mirror**
- Cantilever**
- IR imager**
- Fuel cell**
- Display**
- Chemical**

Birth of MEMS

- Evolved from semiconductor processes
- 1970's: using silicon processing to make mechanical devices, not transistors
 - Accelerometers
 - Pressure sensors
 - Inkjet nozzles
- 1982: Petersen's “Silicon as a Mechanical Material”



Popular Science, June 1984

Silicon – the purest material refined by humans

Start



Silicon dioxide

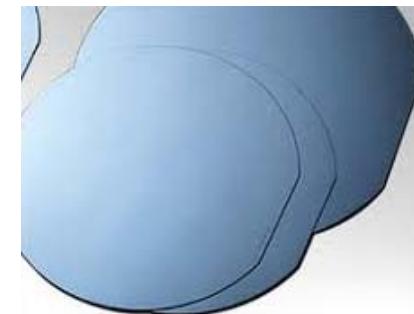


“Pulling” crystals

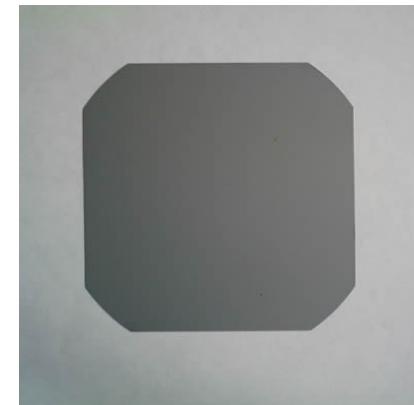


Ingot

Finish



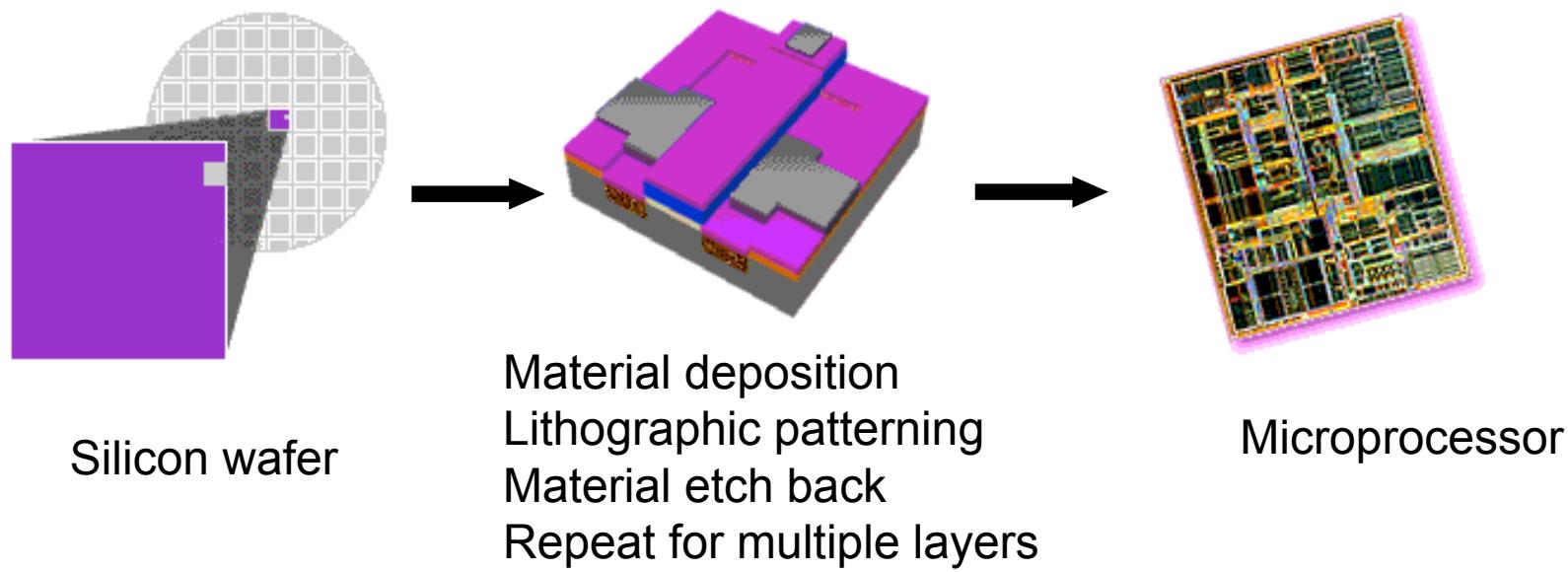
Semiconductor wafer



Solar cell wafer

Silicon process technology

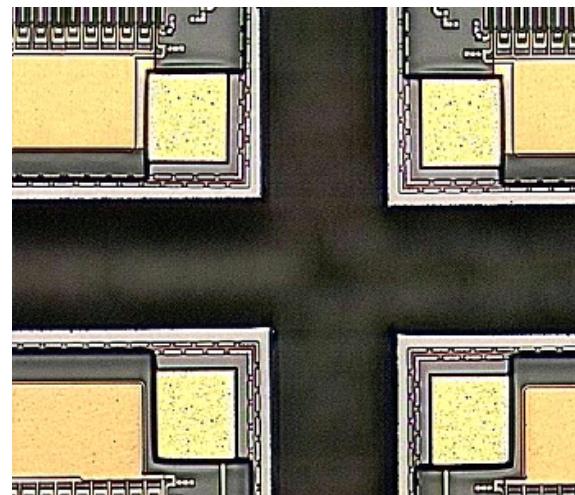
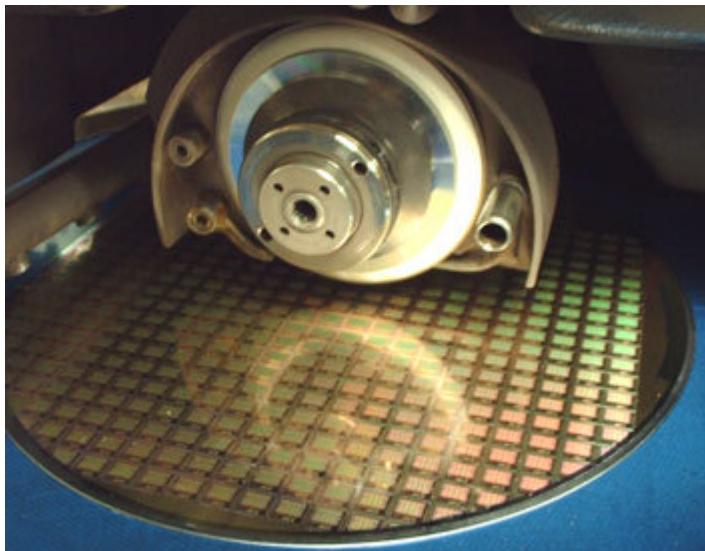
- Developed to make transistors and integrated circuits



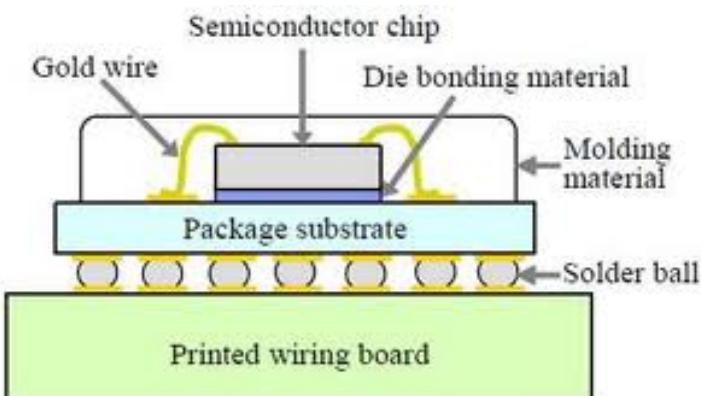
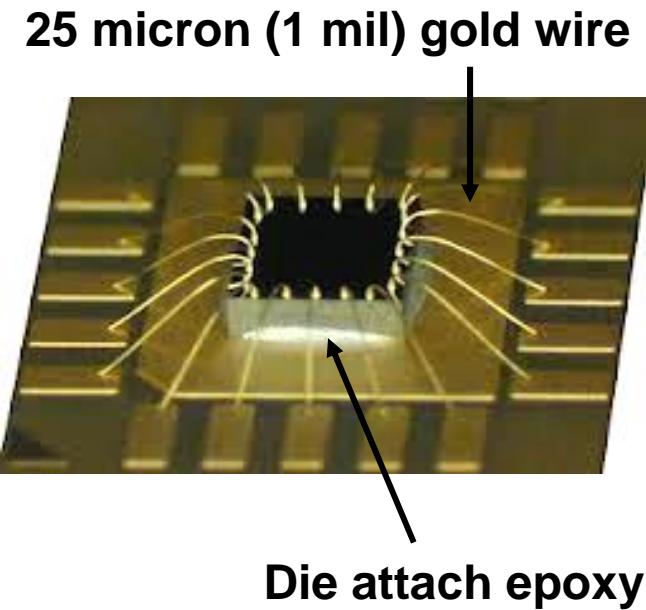
Images from: <http://www.intel.com/education/chips/index.htm>

Wafer dicing

- Similar to cutting tile

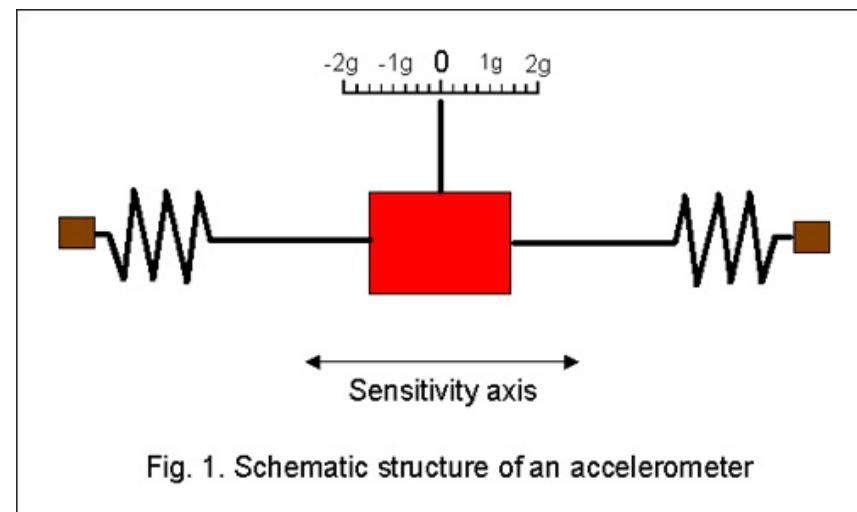


Die attach and wire-bonding



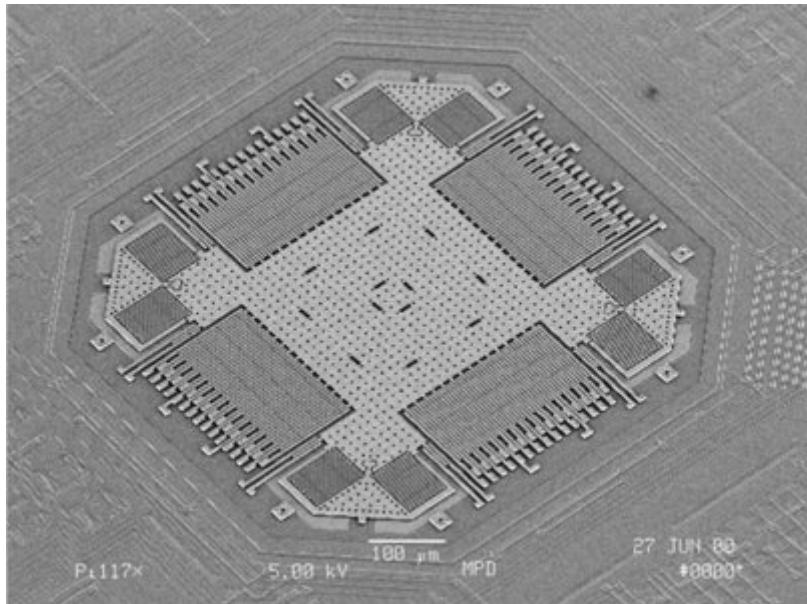
MEMS accelerometer schematic

- Displacement transduction method:
 - Capacitive
 - Piezoresistive
 - Thermal (MEMSIC)
 - Piezoelectric

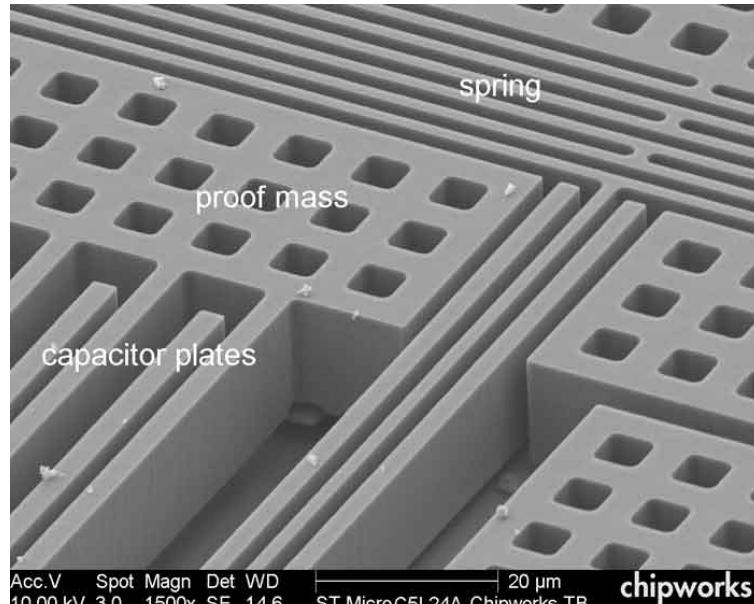


In practice: diversity of architectures

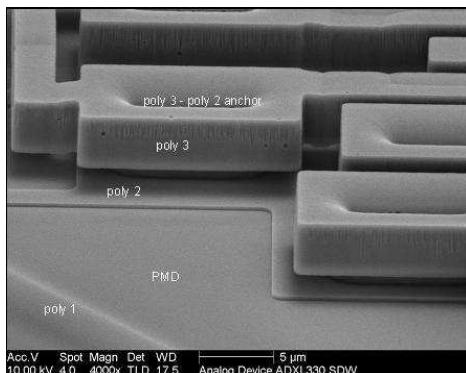
Accelerometers



ADI ADXL50

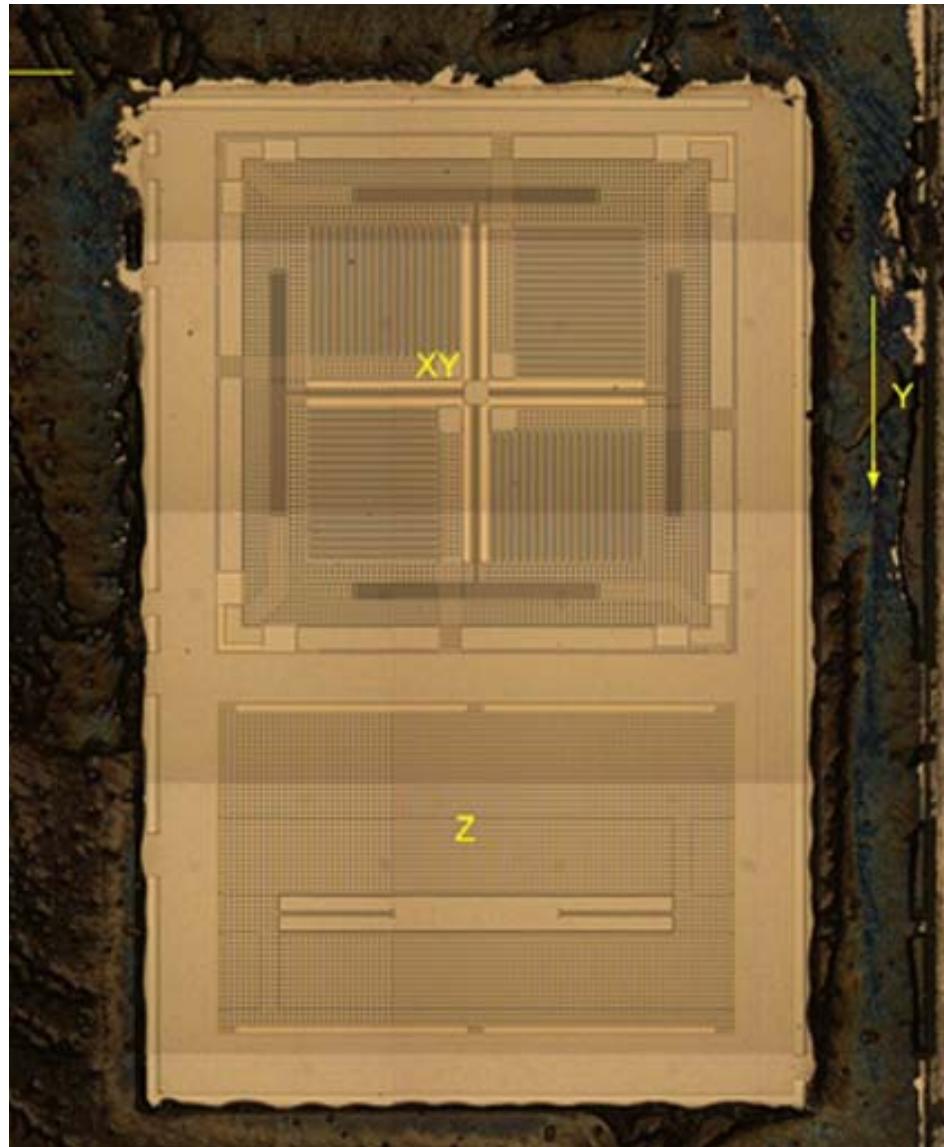


ST C5L24A



Acc.V Spot Magn Det WD 5 μm
10.00 kV 4.0 4000x TLD 17.5 Analog Device ADXL330 SDW

3-Axis accelerometer

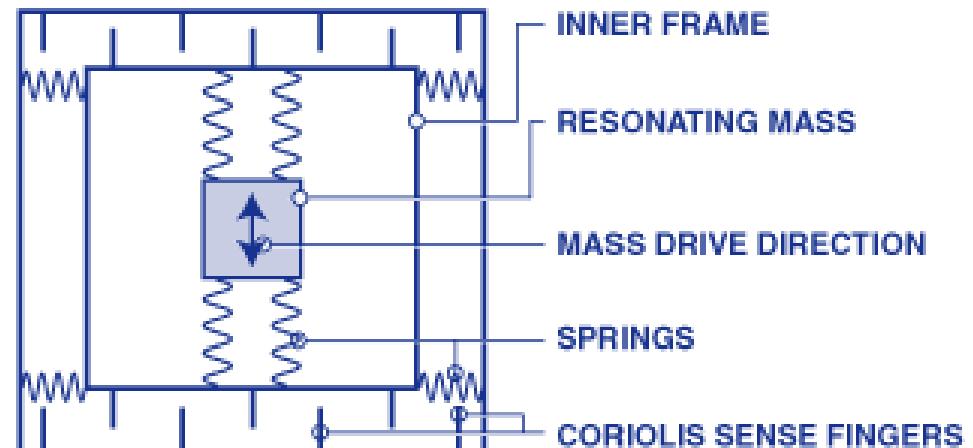
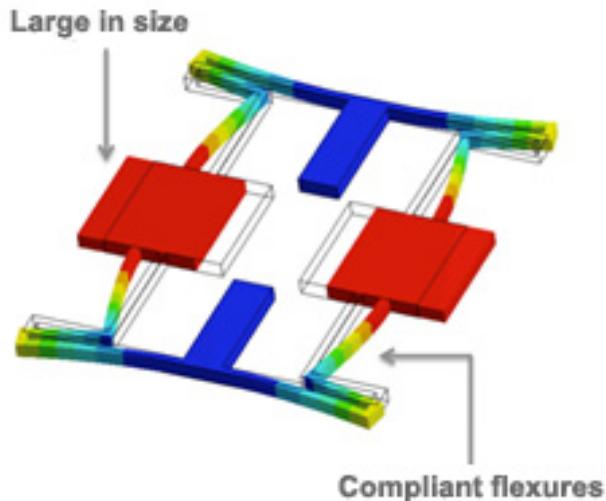


Source: ST, Chipworks
iPhone 4 Teardown

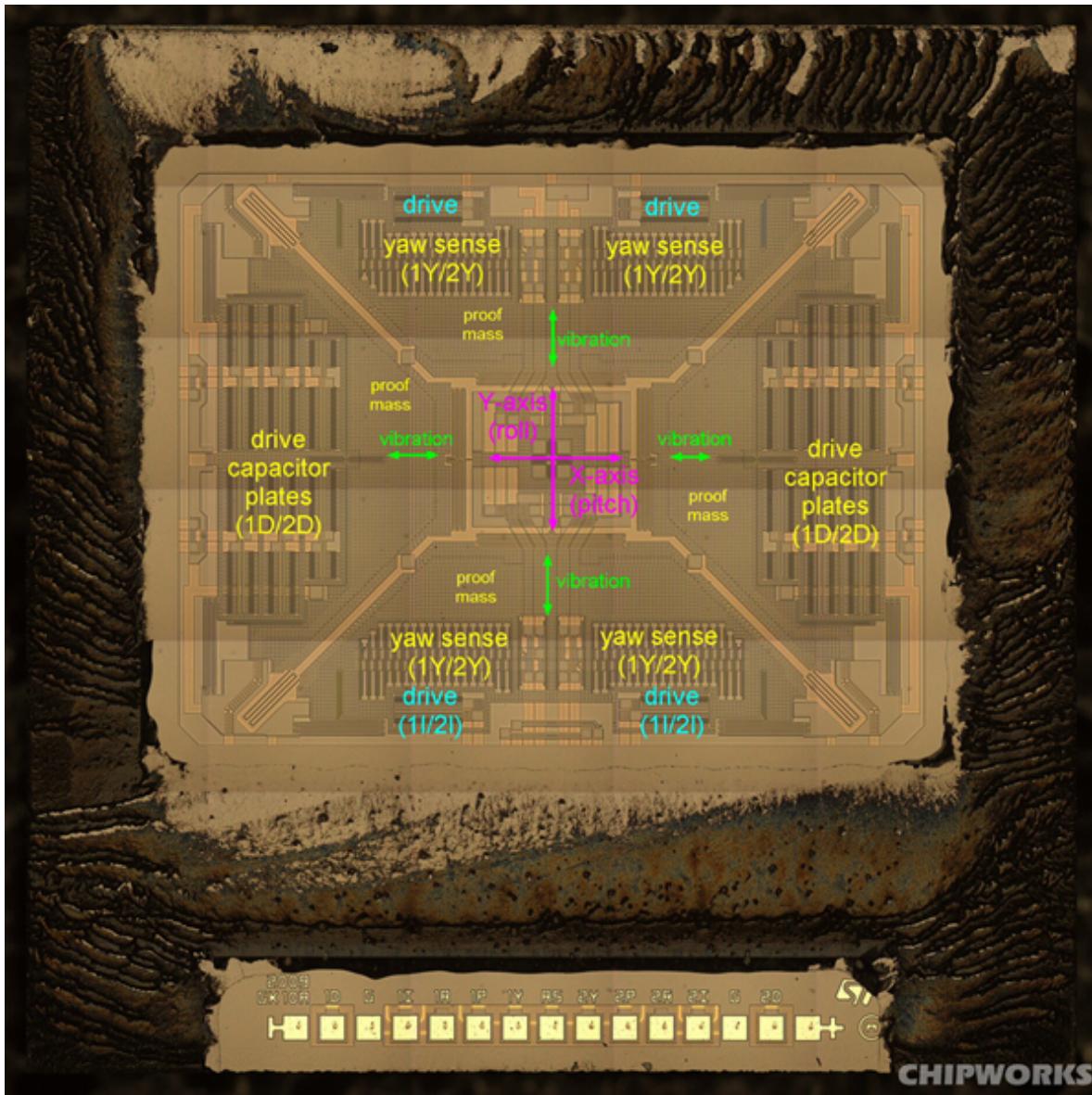
MEMS gyroscopes schematic

- Rotation of component exerts perpendicular coriolis force on resonating proof mass
- Displacement is measured capacitively

Conventional Tuning-Fork Gyros

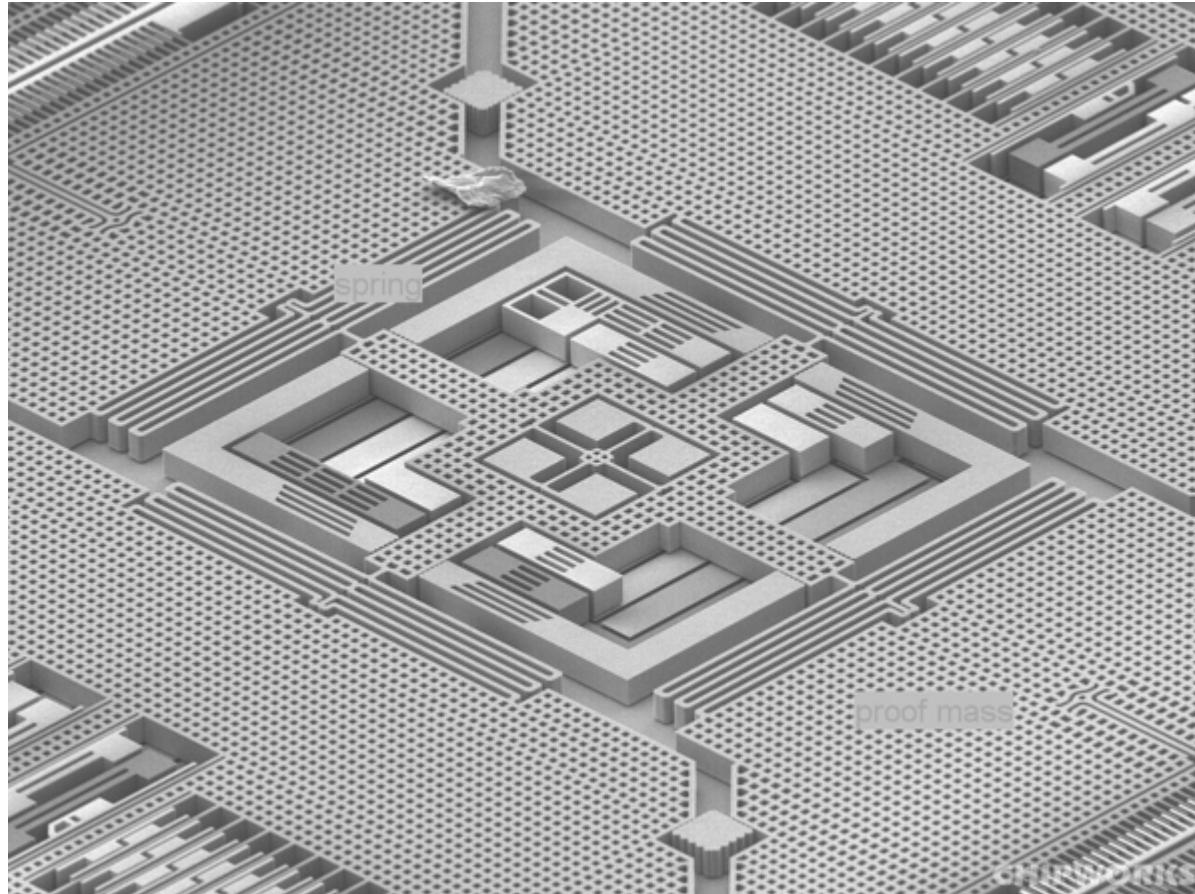


2-axis gyroscope



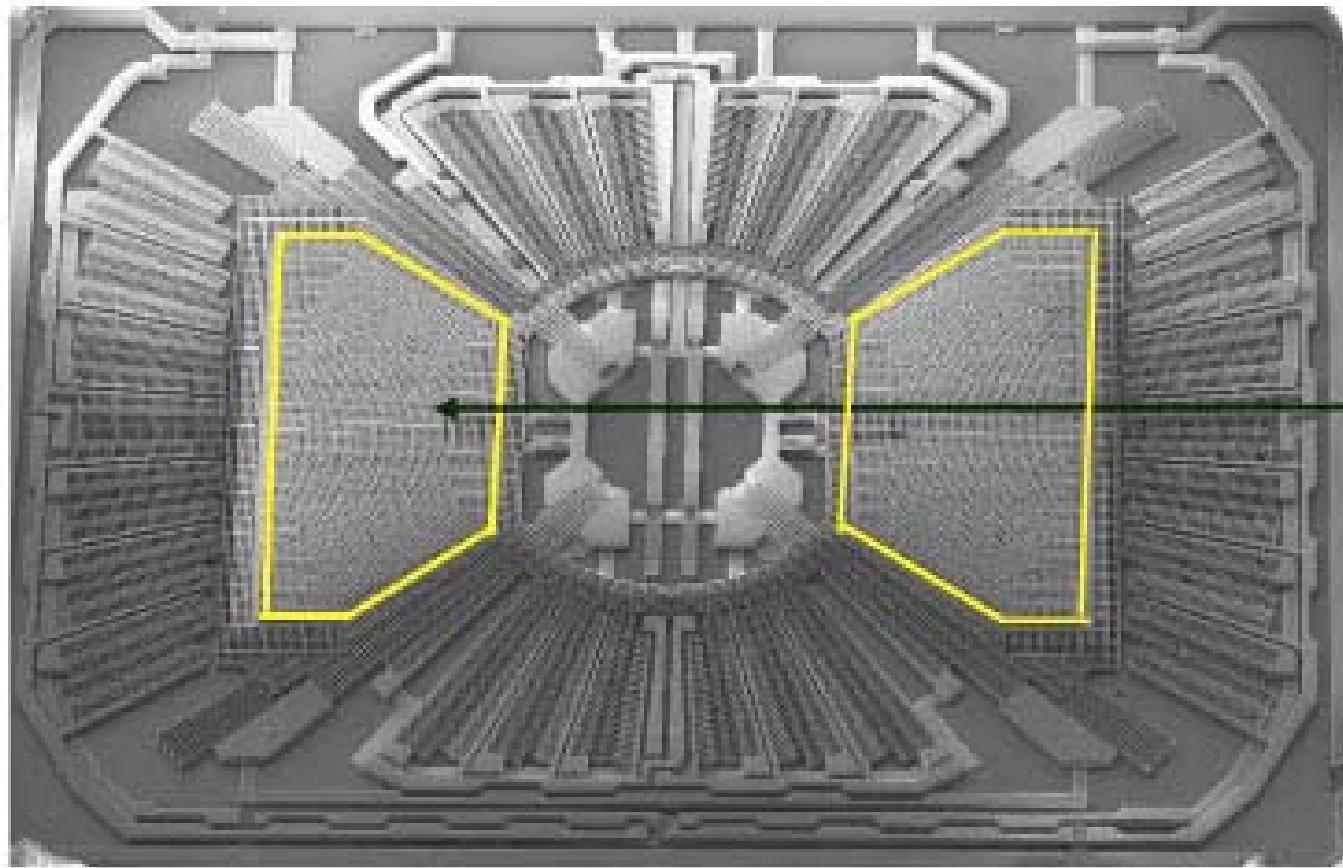
Source: ST, Chipworks
iPhone 4 Teardown

2-axis gyroscope



Source: ST, Chipworks
iPhone 4 Teardown

3-axis gyroscope: introduced 2009



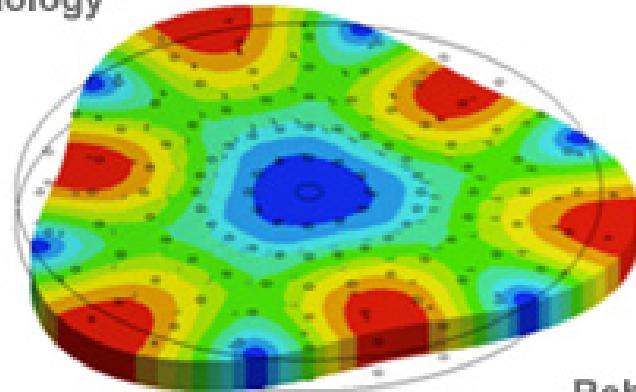
Package size: 4.4 x 7.5 x 1.1 mm

Source: ST, Chipworks

Bulk acoustic wave gyro – similar in concept to HRG

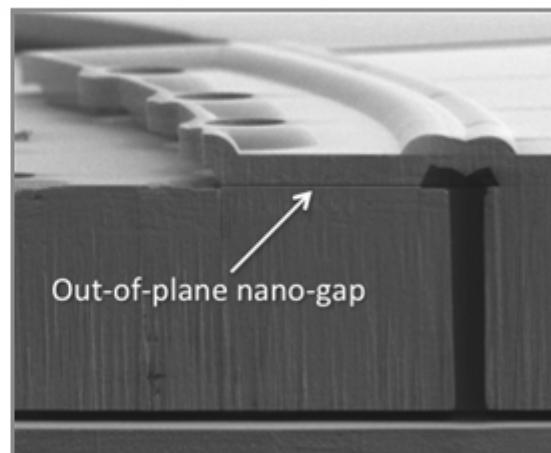
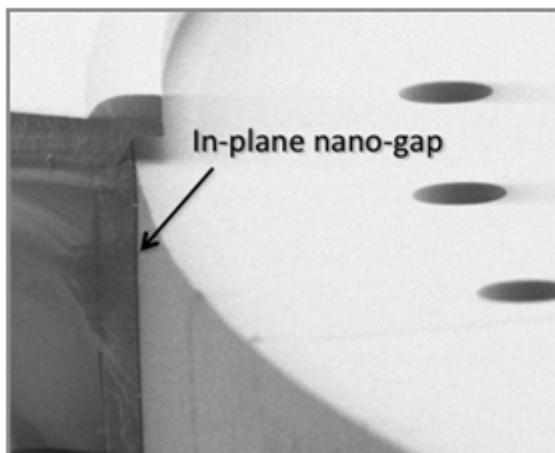
Qualtré's BAW Gyroscope

Easily scalable
technology

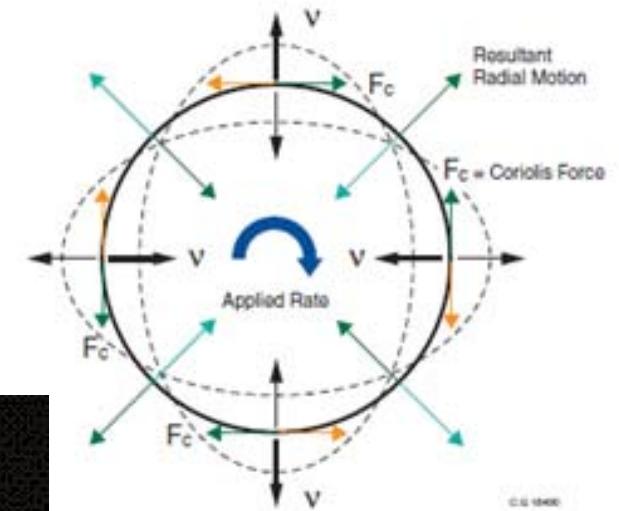
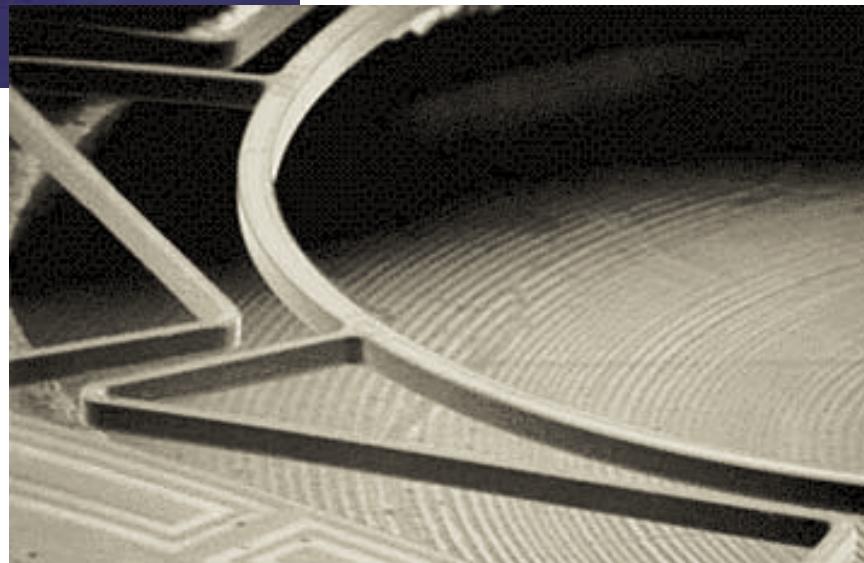
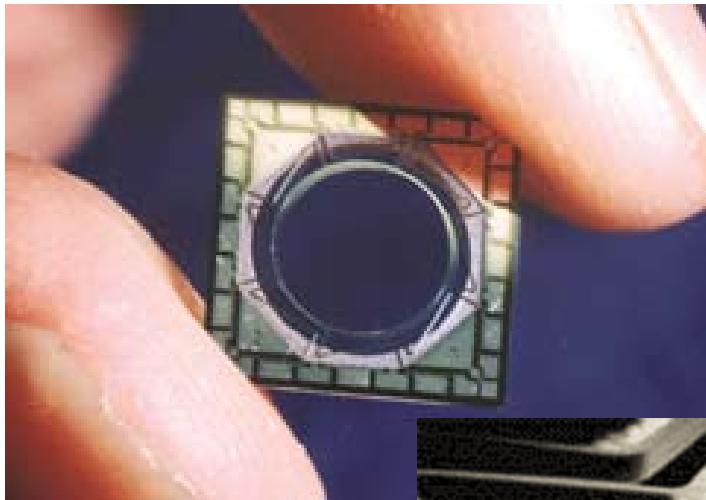


Fully symmetric
geometry

Robust
solid-state
device



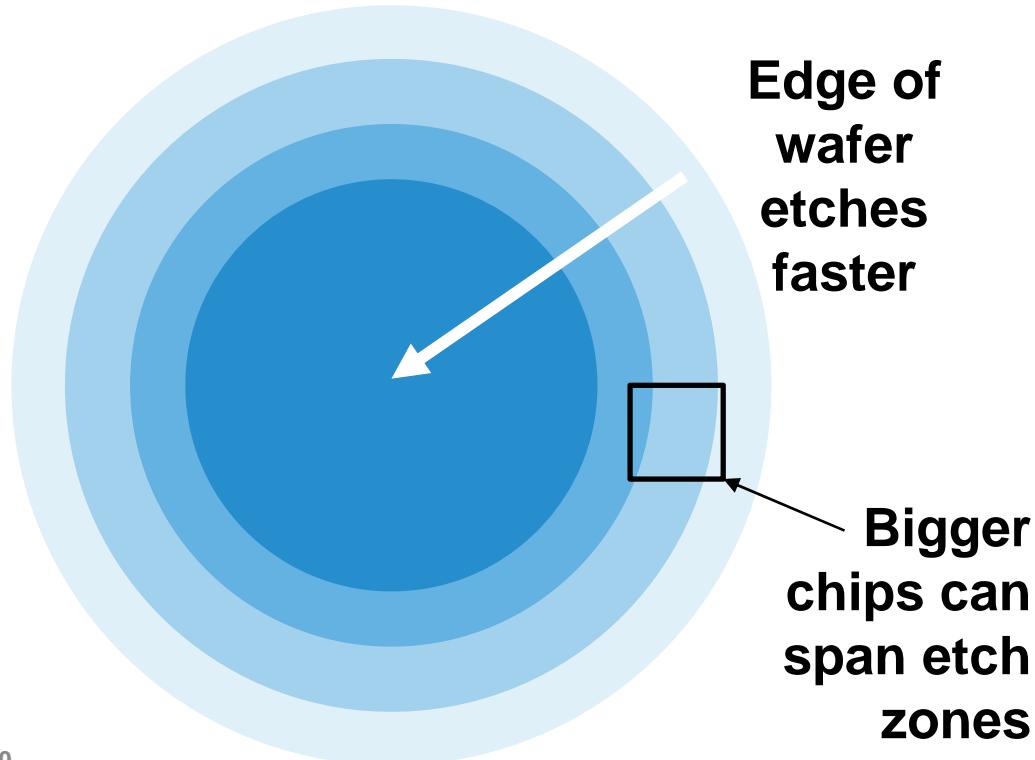
Precision single-axis with inductive drive/sense



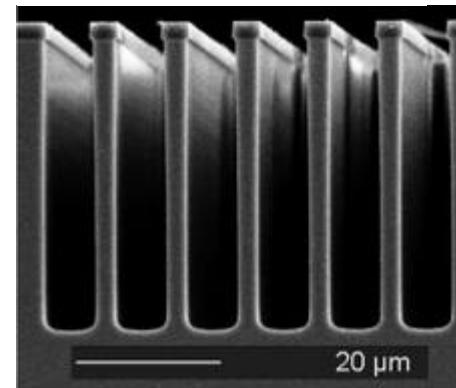
Source: Silicon Sensing Systems

Performance challenges with MEMS inertial sensors

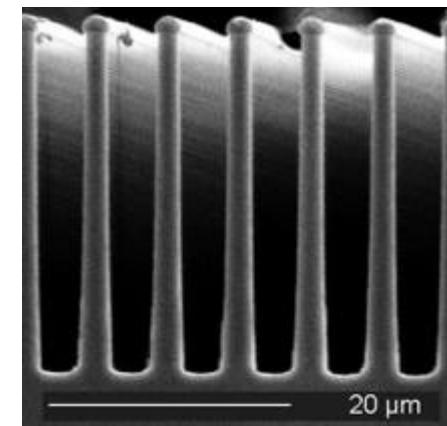
- **Silicon etch uniformity affects all devices**
 - Yield
 - Calibration
 - Performance binning



Top heavy



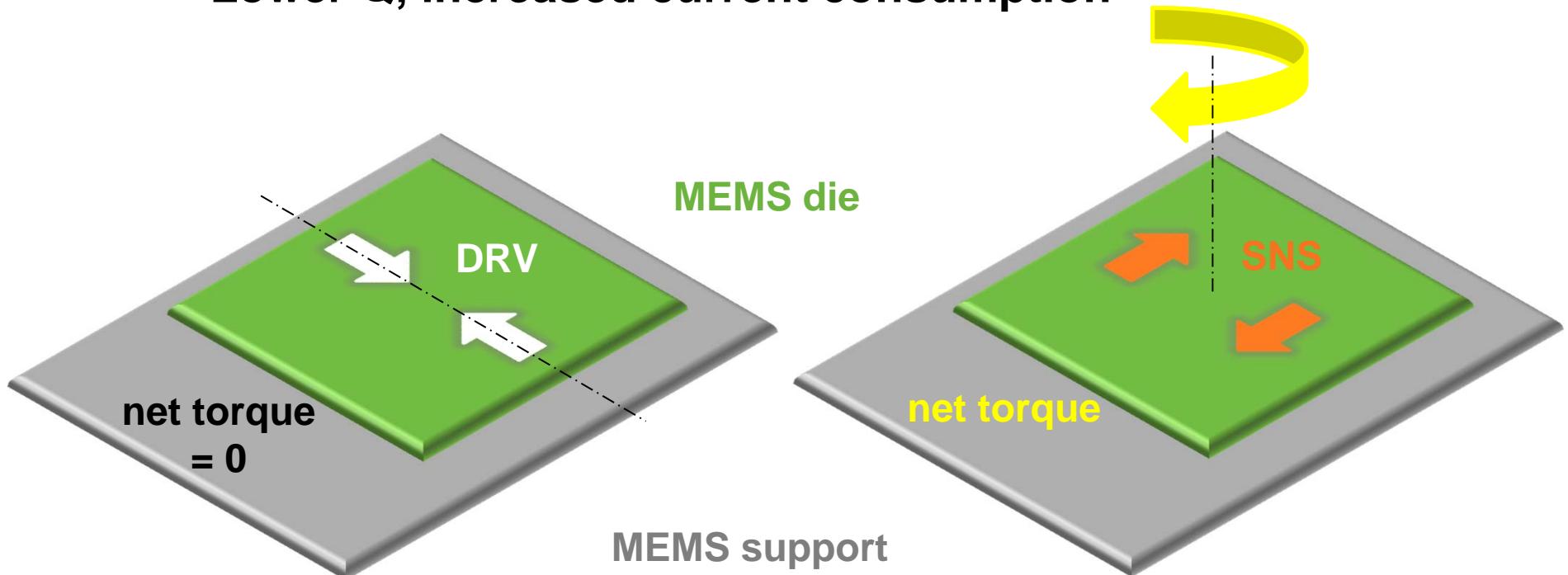
Bottom heavy



Source: Intellisense

Performance challenges with MEMS inertial sensors

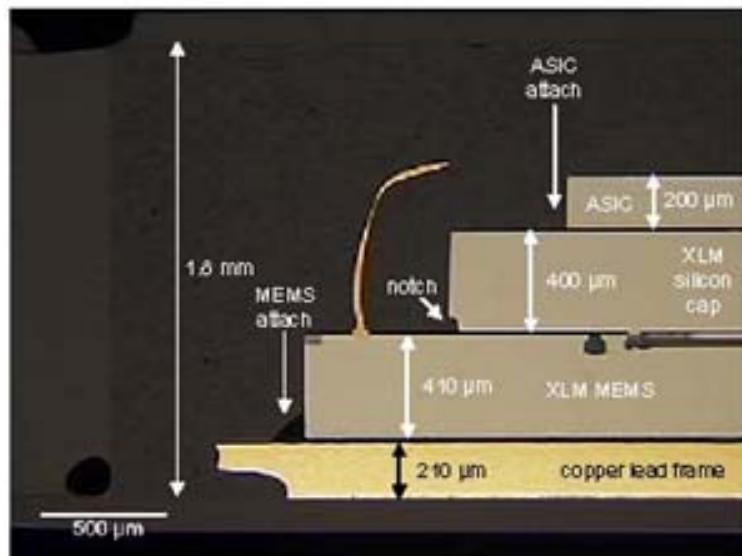
- Temperature sensitivity from CTE mismatch
- Energy dissipation through structure and package
 - Anchor design critical
 - Die attach materials
 - Lower Q, increased current consumption



Used with permission from Tronics

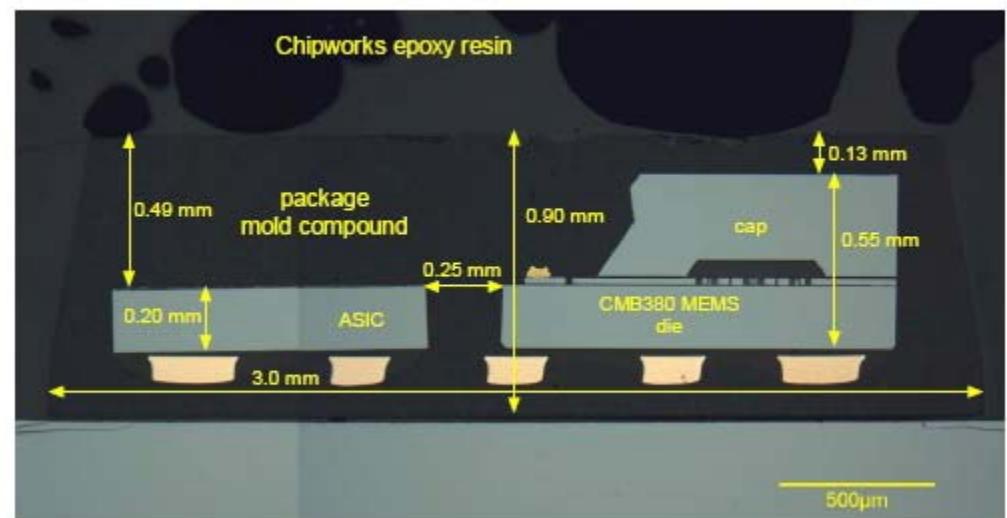
By the way, these sensors need ASICs*!

Stacked



Source: Chipworks photo of Kionix KXM52

Side-by-side



Source: Chipworks photo of Bosch SMB380

*Application-Specific Integrated Circuits

6 DOF “Combo” Sensors and more...

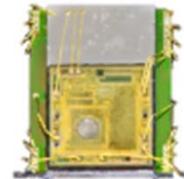
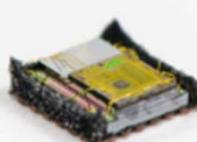
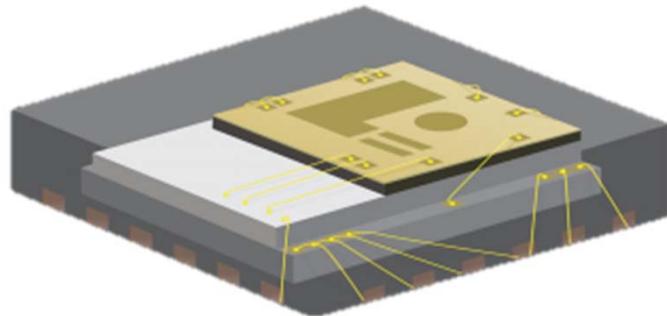
- **Combo = accel, gyro, magnetometer, altimeter, etc.**
- **The Dream: Monolithic integration**
 - Fabricate all sensors and control circuitry on same piece of silicon
 - Small form factor, lower parasitics
- **Reality today: Most are Multi-Chip Modules**
 - Gyros need vacuum, accels need partial atmosphere
 - Best strategy to fight yield problems
 - ASICs yield at 98+%
 - Accels yield at 60+%
 - Gyros yield at 25+%
 - Easier to swap out sensors and ASIC chips mid-product cycle

InvenSense vs. Competition

InvenSense

Patented Single Cavity Multi-Axis Motion Sensor Technology
enables Higher Integration and Smaller Size

InvenSense 9-Axis

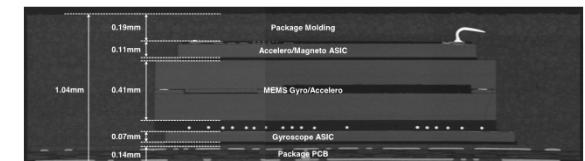
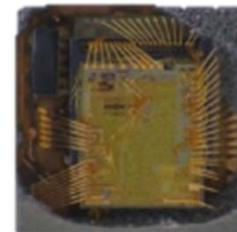
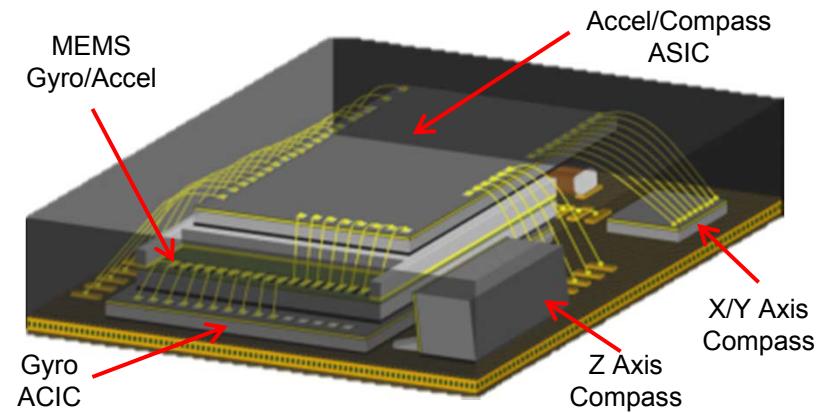


3x3x1 mm³
3 Die
<30 Wire bonds



Used with permission

Competition 9-Axis

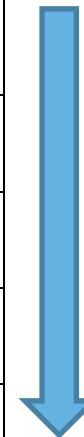


4x4x1 mm³
5 Die, including 1 vertical (Z-axis Magnet)
>55 Wire bonds

Application grade and bias stability

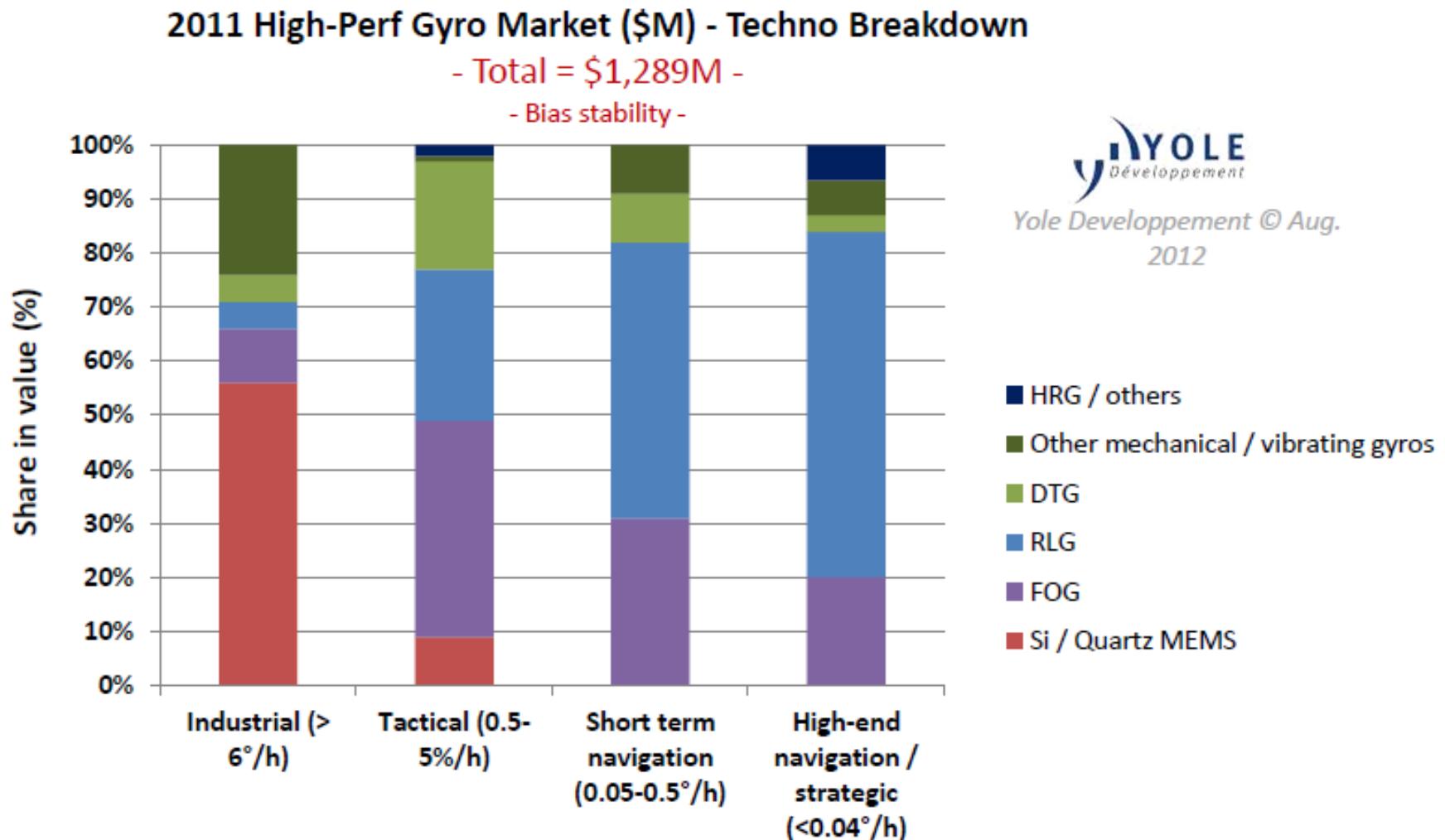
| Application grade | Bias stability | Relative accuracy (*) | Main application |
|--|-----------------------|-----------------------|-------------------------------|
| CONSUMER AND AUTOMOTIVE GYRO | | | |
| Consumer | 10 °/s | 3% | Motion interface |
| Automotive | 1 °/s | 0.3% | ESP |
| HIGH PERFORMANCE GYRO | | | |
| Low-end Tactical also called Industrial | 10°/h (Earth rate) | 10 ppm | Amunitions & rockets guidance |
| Tactical | 1°/h | 1 ppm | Platform stabilization |
| Short-term Navigation | 0.1°/h | 100 ppb | Missile navigation |
| Navigation | 0.01°/h | 10 ppb | Aeronautics navigation |
| Strategic | 0.001°/h | 1 ppb | Submarine navigation |

Range of current MEMS gyro



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MEMS is only starting to compete on tactical grade performance



YOLE
Développement
Yole Developpement © Aug.
2012

Summary

- **MEMS fabrication technology enabled low-cost, small form-factor inertial sensors**
 - Wide variety of device architectures and specifications
 - Broad adoption in consumer-grade applications in just 6 years due to low cost
- **Current sensor performance limited by current architecture and manufacturing methods**
 - Not likely to reach beyond Tactical Grade without technology shift



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Specifications

ST MEMS Gyroscopes

| Part # | Description | Fullscale | Main Features |
|---------|--|---|---|
| L3GD20H | <p>3-axis gyroscope in 3x3 LGA package.</p> <p>One single gyro for many applications:</p> <ul style="list-style-type: none"> • Navigation • Location based services • Geo-fencing, • Gaming, • Pointing devices, etc. | <ul style="list-style-type: none"> • $\pm 245\text{dps}$ • $\pm 500\text{dps}$ • 2000dps | <ul style="list-style-type: none"> • Very Low noise ($0.011 \text{ dps}/\sqrt{\text{Hz}}$) • Ultra Low Power Consumption • Embedded Power down • Embedded Sleep Mode • 16-bit Resolution • I²C/SPI interfaces • Embedded FIFO • Embedded Temp. Sensor • Wide V. Range: 2.2V to 3.6V • Low voltage compatible IOs, 1.8 V |
| L2G3IS | <p>2-axis OIS gyroscope in 3x3.5x1 LGA Package</p> <p>Applications:</p> <ul style="list-style-type: none"> • optical image stabilization • Applications requiring very high sensitivity and ultra low noise. | <ul style="list-style-type: none"> • $\pm 65\text{dps}$ • $\pm 130 \text{ dps}$ | <ul style="list-style-type: none"> • Ultra Low noise ($0.006 \text{ dps}/\sqrt{\text{Hz}}$) • Low Power Consumption • Power-down and Sleep Mode for smart power Saving • SPI digital interface • Embedded temp. sensor • Integrated low and high-pass filters with user-selectable bandwidth • Wide V. range: 2.4 V to 3.6 V • Low voltage-compatible IOs (1.8V) |



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ST MEMS Inertial Modules

| Part # | Description | Fullscales | Main Features |
|---------|---|--|--|
| LSM6DS0 | iNEMO inertial module in 3x3: <ul style="list-style-type: none">• 3-axis accelerometer• 3-axis gyroscope | Accel: $\pm 2/\pm 4/\pm 8$ g Gyro: $\pm 245/\pm 500/\pm 2000$ dps | <ul style="list-style-type: none">• Embedded Power-down• Embedded Sleep modes• SPI/I2C serial interface• Embedded Temp. Sensor• Embedded FIFOs• V. Range: 1.71 V to 3.6 V• Independent IOs supply (1.8 V)• Embedded Selftest |
| LSM9DS0 | iNEMO inertial module in 4x4 LGA Package: <ul style="list-style-type: none">• 3-axis accelerometer• 3-axis gyroscope• 3-axis magnetometer | Accel: $\pm 2/\pm 4/\pm 6/\pm 8/\pm 16$ g Mag: $\pm 2/\pm 4/\pm 8/\pm 12$ Gyro: $\pm 245/\pm 500/\pm 2000$ dps | <ul style="list-style-type: none">• SPI / I2C serial interfaces• V. Range 2.4 V to 3.6 V• 16-bit data output• Power-down / low-power mode• Programmable interrupt generators• Embedded self-test• Embedded temperature sensor• Embedded FIFO• Position and motion detection• Click/double-click recognition• Intelligent power saving for handheld devices |



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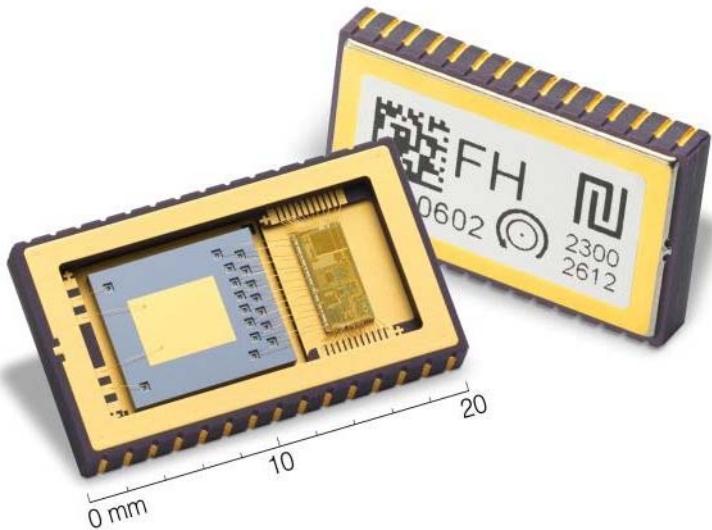
ST Compass Modules

| Part # | Description | Fullscales | Main Features |
|---------------------|--|---|---|
| LSM303C/ LSM303E | E-compass in 2x2 LGA Package <ul style="list-style-type: none">• 3-axis accelerometer• 3-axis magnetometer Applications: <ul style="list-style-type: none">• Tilt-compensated compasses• Motion-activated functions | Accel: $\pm 2/\pm 4/\pm 8$ g Mag: ± 16 Gauss | <ul style="list-style-type: none">• Ultra-compact• High-performance• SPI / I2C serial interfaces• 16-bit data output• Analog supply voltage 1.9 V to 3.6 V• Power-down mode / low-power mode• Programmable interrupt generators• Embedded temp. sensor• Embedded FIFO |



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Example of a high performance MEMS Gyro



GYPRO2300 released at
Electronica, Nov 2012

- Z-axis Angular Rate Sensor
- 300°/s input range, 100 Hz BandWidth
- 24-bit output (SPI)
- Bias Instability (Allan variance): 1°/h
- Bias variation over temp (-40/+85°C):
+/- 0.05 °/s
- Noise density: 10°/h/ $\sqrt{\text{Hz}}$
- Power consumption: 25mA under 5V
- 19.6 x 11.5 x 2.9 mm
- 2 grams