

Wave operator and propagator

Source constraints/gauge generators	SO(3) irreps	Multiplicities
	$\tau_{0+}^{\#2} == 0$	1
	$\tau_{0+}^{\#1} - 2 \, i \, k \, \sigma_{0+}^{\#1} == 0$	1
	$\tau_{1-}^{\#2 \alpha} + 2 \, i \, k \, \sigma_{1-}^{\#2 \alpha} == 0$	3
	$\tau_{1-}^{\#1 \alpha} == 0$	3
	$\tau_{1+}^{\#1 \alpha \beta} + i \, k \, \sigma_{1+}^{\#2 \alpha \beta} == 0$	3
	$\tau_{2+}^{\#1 \alpha \beta} - 2 \, i \, k \, \sigma_{2+}^{\#1 \alpha \beta} == 0$	5
Total constraints:		16

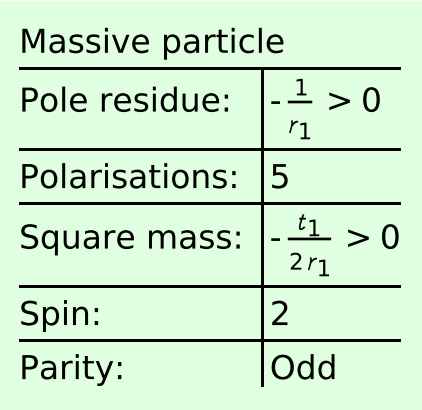
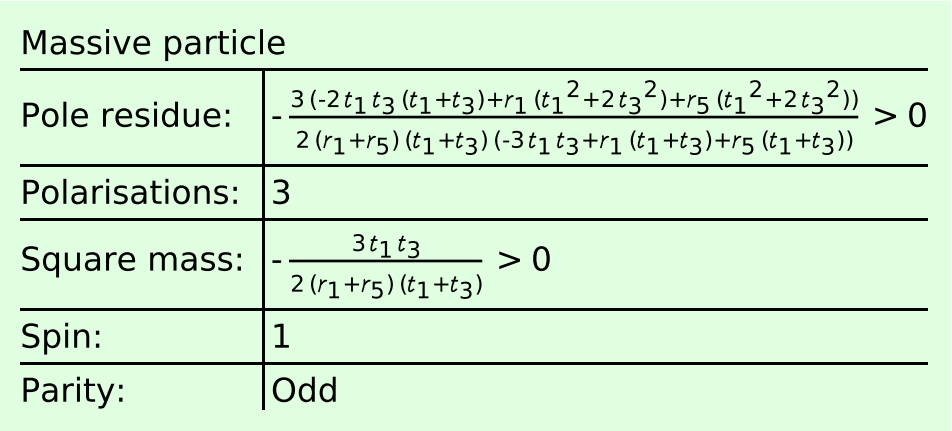
	$\sigma_{2^+}^{\#1} \alpha\beta$	$\tau_{2^+}^{\#1} \alpha\beta$	$\sigma_{2^-}^{\#1} \alpha\beta\chi$
$\sigma_{2^+}^{\#1} \dagger \alpha\beta$	$\frac{2}{(1+2k^2)^2 t_1}$	$-\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	0
$\tau_{2^+}^{\#1} \dagger \alpha\beta$	$\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	$\frac{4k^2}{(1+2k^2)^2 t_1}$	0
$\sigma_{2^-}^{\#1} \dagger \alpha\beta\chi$	0	0	$\frac{2}{2k^2 r_1 + t_1}$

	$\omega_{2^+}^{\#1} f_{2^+}^{\#1} \omega_{2^+}^{\#1}$	$\omega_{2^+}^{\#1} f_{2^+}^{\#1} \omega_{2^+}^{\#1}$	$\omega_{2^+}^{\#1} f_{2^+}^{\#1} \omega_{2^+}^{\#1}$
$\omega_{2^+}^{\#1} \dagger^{\alpha\beta}$	$\frac{t_1}{2}$	$-\frac{i k t_1}{\sqrt{2}}$	0
$f_{2^+}^{\#1} \dagger^{\alpha\beta}$	$\frac{i k t_1}{\sqrt{2}}$	$k^2 t_1$	0
$\omega_{2^+}^{\#1} \dagger^{\alpha\beta\chi}$	0	0	$k^2 r_1 + \frac{t_1}{2}$

$\omega_0^{\#1} +$	t_3	$-i\sqrt{2}kt_3$	$f_0^{\#2}$	$\omega_0^{\#1}$
$\omega_0^{\#1} +$	$i\sqrt{2}kt_3$	$2k^2t_3$	$f_0^{\#1}$	0
$f_0^{\#2} +$	0	0	$f_0^{\#1}$	0
$\omega_0^{\#1} +$	0	0	0	$-t_1$

$$\begin{aligned} S = & \int \int \int \left(\frac{1}{6} (2 \omega_{\alpha}^{\alpha i} (t_1 \omega_{, \theta}^{\theta} - 2 t_3 \omega_{, \kappa}^{\kappa}) + 6 f^{\alpha \beta} \tau_{\alpha \beta} + 6 \omega^{\alpha \beta \chi} \sigma_{\alpha \beta \chi} - \right. \\ & 4 t_1 \omega_{\alpha}^{\theta} \partial_{, f} f^{\alpha i} + 8 t_3 \omega_{\alpha}^{\kappa} \partial_{, f} f^{\alpha i} + 4 t_1 \omega_{, \theta}^{\theta} \partial_{, f} f^{\alpha} - 8 t_3 \omega_{, \kappa}^{\kappa} \partial_{, f} f^{\alpha} - \\ & 2 t_1 \partial_{, f} f^{\theta} \partial_{, f} f^{\alpha} + 4 t_3 \partial_{, f} f^{\kappa} \partial_{, f} f^{\alpha} - 2 t_1 \partial_{, f} f^{\alpha i} \partial_{\theta} f_{\alpha}^{\theta} + 4 t_1 \partial_{, f} f^{\alpha} \partial_{\theta} f_{, i}^{\theta} - \\ & 6 t_1 \partial_{\alpha} f_{, \theta} \partial^{\theta} f^{\alpha i} - 3 t_1 \partial_{\alpha} f_{\theta, i} \partial^{\theta} f^{\alpha i} + 3 t_1 \partial_{, f} \partial^{\theta} f^{\alpha i} + 3 t_1 \partial_{\theta} f_{\alpha i} \partial^{\theta} f^{\alpha i} + \\ & 3 t_1 \partial_{\theta} f_{, \alpha} \partial^{\theta} f^{\alpha i} + 6 t_1 \omega_{\alpha \theta, i} (\omega^{\alpha i \theta} + 2 \partial^{\theta} f^{\alpha i}) - 8 r_1 \partial_{\beta} \omega_{\alpha i \theta} \partial^{\theta} \omega^{\alpha \beta i} + \\ & 4 r_1 \partial_{\beta} \omega_{\alpha \theta, i} \partial^{\theta} \omega^{\alpha \beta i} - 16 r_1 \partial_{\beta} \omega_{, i \theta \alpha} \partial^{\theta} \omega^{\alpha \beta i} - 4 r_1 \partial_{, i} \omega_{\alpha \beta \theta} \partial^{\theta} \omega^{\alpha \beta i} + 4 r_1 \partial_{\theta} \omega_{\alpha \beta, i} \\ & \partial^{\theta} \omega^{\alpha \beta i} + 4 r_1 \partial_{\theta} \omega_{\alpha i \beta} \partial^{\theta} \omega^{\alpha \beta i} + 6 r_5 \partial_{, i} \omega_{\theta}^{\kappa} \partial^{\theta} \omega_{\alpha}^{\alpha i} - 6 r_5 \partial_{\theta} \omega_{\alpha}^{\kappa} \partial^{\theta} \omega_{, \kappa}^{\alpha i} + \\ & 4 t_3 \partial_{, f} f^{\alpha i} \partial_{\kappa} f_{\alpha}^{\kappa} - 8 t_3 \partial_{, f} f^{\alpha} \partial_{\alpha} f_{, i}^{\kappa} - 6 r_5 \partial_{\alpha} \omega^{\alpha i \theta} \partial_{\kappa} \omega_{, \theta}^{\kappa} + 12 r_5 \partial^{\theta} \omega_{\alpha}^{\alpha i} \partial_{\kappa} \omega_{, \theta}^{\kappa} + \\ & \left. 6 r_5 \partial_{\alpha} \omega^{\alpha i \theta} \partial_{\kappa} \omega_{\theta, i}^{\kappa} - 12 r_5 \partial^{\theta} \omega_{\alpha}^{\alpha i} \partial_{\kappa} \omega_{\theta, i}^{\kappa} \right) [t, x, y, z] dz dy dx dt \end{aligned}$$

Unitarity conditions



(No massless particles)

$$r_1 < 0 \ \&\& \ r_5 < -r_1 \ \&\& \ t_1 > 0 \ \&\& \ t_3 < -t_1 \ || \ t_3 > 0$$