

Wave operator and propagator

$$\begin{aligned}
\text{Quadratic (free) action} \\
S = & \int \int \int \left(\frac{1}{6} (2t_1 \omega_{\alpha}^{\alpha i} \omega_{, \theta}^{\theta} + 6 f^{\alpha \beta} \tau_{\alpha \beta} + 6 \omega^{\alpha \beta \chi} \sigma_{\alpha \beta \chi} - 4 t_1 \omega_{\alpha}^{\theta} \partial_{, f} f^{\alpha i} + \right. \\
& 4 t_1 \omega_{, \theta}^{\theta} \partial_{, f} f^{\alpha} - 2 t_1 \partial_{, f} f_{\theta}^{\theta} \partial_{, f} f^{\alpha} - 2 t_1 \partial_{, f} f^{\alpha i} \partial_{\theta} f_{\alpha}^{\theta} + \\
& 4 t_1 \partial_{, f} f^{\alpha} \partial_{\theta} f_{, i}^{\theta} - 6 t_1 \partial_{\alpha} f_{, \theta} \partial^{\theta} f^{\alpha i} - 3 t_1 \partial_{\alpha} f_{, \theta} \partial^{\theta} f^{\alpha i} + \\
& 3 t_1 \partial_{, i} f_{\alpha} \partial^{\theta} f^{\alpha i} + 3 t_1 \partial_{\theta} f_{\alpha} \partial^{\theta} f^{\alpha i} + 3 t_1 \partial_{\theta} f_{, i} \partial^{\theta} f^{\alpha i} + \\
& 6 t_1 \omega_{\alpha \theta i} (\omega^{\alpha i \theta} + 2 \partial^{\theta} f^{\alpha i}) + 8 r_2 \partial_{\beta} \omega_{\alpha i \theta} \partial^{\theta} \omega^{\alpha \beta i} - \\
& 4 r_2 \partial_{\beta} \omega_{\alpha \theta i} \partial^{\theta} \omega^{\alpha \beta i} + 4 r_2 \partial_{\beta} \omega_{, i \theta \alpha} \partial^{\theta} \omega^{\alpha \beta i} - \\
& 2 r_2 \partial_{, i} \omega_{\alpha \beta \theta} \partial^{\theta} \omega^{\alpha \beta i} + 2 r_2 \partial_{\theta} \omega_{\alpha \beta i} \partial^{\theta} \omega^{\alpha \beta i} - \\
& \left. 4 r_2 \partial_{\theta} \omega_{\alpha i \beta} \partial^{\theta} \omega^{\alpha \beta i} \right) [t, x, y, z] dx dy dz dt
\end{aligned}$$
$$S = \iiint \left(\frac{1}{6} (2t_1 \omega^\alpha{}_\alpha \omega^\theta{}_\theta + 6f^{\alpha\beta} \tau_{\alpha\beta} + 6\omega^{\alpha\beta\chi} \sigma_{\alpha\beta\chi} - 4t_1 \omega^\theta{}_\alpha \omega^\alpha{}_\theta \partial_\theta f^{\alpha\chi} + 4t_1 \omega^\theta{}_\omega \partial_\theta f^\alpha{}_\alpha - 2t_1 \partial_\theta f^\theta{}_\theta \partial_\theta f^\alpha{}_\alpha - 2t_1 \partial_\theta f^{\alpha\chi} \partial_\theta f^\theta{}_\alpha + 4t_1 \partial_\theta f^\alpha{}_\alpha \partial_\theta f^\theta{}_\omega - 6t_1 \partial_\omega f_{\theta\theta} \partial_\theta f^{\alpha\chi} - 3t_1 \partial_\omega f_{\theta\chi} \partial_\theta f^{\alpha\chi} + 3t_1 \partial_\theta f_{\alpha\theta} \partial_\theta f^{\alpha\chi} + 3t_1 \partial_\theta f_{\alpha\chi} \partial_\theta f^{\alpha\chi} + 3t_1 \partial_\theta f_{\alpha\theta} \partial_\theta f^\chi{}_\chi + 8r_2 \partial_\beta \omega_{\alpha\theta} \partial^\theta \omega^{\alpha\beta\chi} - 6t_1 \omega_{\alpha\theta\chi} (\omega^{\alpha\theta\chi} + 2\partial^\theta f^{\alpha\chi}) + 4r_2 \partial_\beta \omega_{\theta\alpha} \partial^\theta \omega^{\alpha\beta\chi} - 4r_2 \partial_\beta \omega_{\alpha\theta\chi} \partial^\theta \omega^{\alpha\beta\chi} + 4r_2 \partial_\theta \omega_{\alpha\beta\chi} \partial^\theta \omega^{\alpha\beta\chi} + 2r_2 \partial_\omega \omega^{\alpha\beta\chi} \partial^\theta \omega_{\alpha\beta\chi} + 2r_2 \partial_\theta \omega_{\alpha\beta\chi} \partial^\theta \omega^{\alpha\beta\chi} - 4r_2 \partial_\theta \omega_{\alpha\beta\chi} \partial^\theta \omega^{\alpha\beta\chi}) [t, x, y, z] dz dy dx dt \right)$$

0	0	$\frac{t_1}{2}$
$-\frac{ikt_1}{\sqrt{2}}$	$k^2 t_1$	0
$\frac{t_1}{2}$	$\frac{ikt_1}{\sqrt{2}}$	0

$\sigma_0^{\#1}$	0	0	0	$\frac{1}{\kappa^2 r_2 t_1}$
$\tau_0^{\#2}$	0	0	0	0
$\tau_0^{\#1}$	0	0	0	0
$\sigma_0^{\#1}$	0	0	0	0

	$\omega_0^{\#1}$	$f_0^{\#1}$	$f_0^{\#2}$	$\omega_0^{\#1}$
$\omega_0^{\#1} \uparrow$	0	0	0	0
$f_0^{\#1} \uparrow$	0	0	0	0
$f_0^{\#2} \uparrow$	0	0	0	0
$\omega_0^{\#1} \uparrow$	0	0	0	$k^2 r_2 \cdot t_1$

	$\sigma_{2^+}^{\#1} \alpha\beta$	$\tau_{2^+}^{\#1} \alpha\beta$	$\sigma_{2^-}^{\#1} \alpha\beta\chi$
$\sigma_{2^+}^{\#1} \dagger \alpha\beta$	$\frac{2}{(1+2k^2)^2 t_1}$	$-\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	0
$\tau_{2^+}^{\#1} \dagger \alpha\beta$	$\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	$\frac{4k^2}{(1+2k^2)^2 t_1}$	0
$\sigma_{2^-}^{\#1} \dagger \alpha\beta\chi$	0	0	$\frac{2}{t_1}$