


$$r_2 < 0 \ \&\& \ t_2 > 0$$
$$r_2 < 0 \ \&\& \ t_2 > 0$$

The diagram shows two vertices (pink circles) connected by a horizontal dashed line representing a massive particle. The left vertex has two incoming lines (black) and two outgoing lines (black). The right vertex has two incoming lines (black) and two outgoing lines (black). The dashed line is labeled with $J^P = 0^-$ and k^μ with an arrow pointing from left to right.

Massive particle	
Pole residue:	$-\frac{1}{r_2} > 0$
Polarisations:	1
Square mass:	$-\frac{t_2}{r_2} > 0$
Spin:	0
Parity:	Odd

(No massless particles)

$\sigma_1^{\#1} \dagger \alpha\beta$	$\sigma_1^{\#2} \dagger \alpha\beta$	$\tau_1^{\#1} \dagger \alpha\beta$	$\sigma_1^{\#1} \dagger \alpha$	$\sigma_1^{\#2} \dagger \alpha$	$\tau_1^{\#1} \dagger \alpha$	$\tau_1^{\#2} \dagger \alpha$
$\frac{2(t_1+t_2)}{3t_1t_2}$	$\frac{\sqrt{2}(t_1-2t_2)}{3(1+k^2)t_1t_2}$	$\frac{i\sqrt{2}k(t_1-2t_2)}{3(1+k^2)t_1t_2}$	0	0	0	0
$\frac{\sqrt{2}(t_1-2t_2)}{3(1+k^2)t_1t_2}$	$\frac{t_1+4t_2}{3(1+k^2)^2t_1t_2}$	$\frac{ik(t_1+4t_2)}{3(1+k^2)^2t_1t_2}$	0	0	0	0
$-\frac{i\sqrt{2}k(t_1-2t_2)}{3(1+k^2)t_1t_2}$	$-\frac{ik(t_1+4t_2)}{3(1+k^2)^2t_1t_2}$	$\frac{k^2(t_1+4t_2)}{3(1+k^2)^2t_1t_2}$	0	0	0	0
$\sigma_1^{\#1} \dagger \alpha$	0	0	$\frac{6}{(3+4k^2)^2t_1}$	$\frac{6\sqrt{2}}{(3+4k^2)^2t_1}$	0	$\frac{12ik}{(3+4k^2)^2t_1}$
$\sigma_1^{\#2} \dagger \alpha$	0	0	$\frac{6\sqrt{2}}{(3+4k^2)^2t_1}$	$\frac{12}{(3+4k^2)^2t_1}$	0	$\frac{12i\sqrt{2}k}{(3+4k^2)^2t_1}$
$\tau_1^{\#1} \dagger \alpha$	0	0	0	0	0	0
$\tau_1^{\#2} \dagger \alpha$	0	0	$-\frac{12ik}{(3+4k^2)^2t_1}$	$-\frac{12i\sqrt{2}k}{(3+4k^2)^2t_1}$	0	$\frac{24k^2}{(3+4k^2)^2t_1}$

$\omega_{1+}^{\#1} + \alpha\beta$	$\omega_{1+}^{\#2} + \alpha\beta$	$f_{1+}^{\#1} + \alpha\beta$	$\omega_{1-}^{\#1} + \alpha$	$\omega_{1-}^{\#2} + \alpha$	$f_{1-}^{\#1} + \alpha$	$f_{1-}^{\#2} + \alpha$
$\frac{1}{6}(t_1 + 4t_2)$	$-\frac{t_1 - 2t_2}{3\sqrt{2}}$	$-\frac{i k(t_1 - 2t_2)}{3\sqrt{2}}$	0	0	0	0
$\omega_{1+}^{\#2} + \alpha\beta$	$-\frac{t_1 - 2t_2}{3\sqrt{2}}$	$\frac{1}{3} i k(t_1 + t_2)$	0	0	0	0
$f_{1+}^{\#1} + \alpha\beta$	$-\frac{i k(t_1 - 2t_2)}{3\sqrt{2}}$	$\frac{1}{3} k^2(t_1 + t_2)$	0	0	0	0
$\omega_{1-}^{\#1} + \alpha$	0	0	$\frac{t_1}{6}$	$\frac{t_1}{3\sqrt{2}}$	0	$\frac{i k t_1}{3}$
$\omega_{1-}^{\#2} + \alpha$	0	0	$\frac{t_1}{3\sqrt{2}}$	$\frac{t_1}{3}$	0	$\frac{1}{3} i \sqrt{2} k t_1$
$f_{1-}^{\#1} + \alpha$	0	0	0	0	0	0
$f_{1-}^{\#2} + \alpha$	0	0	$-\frac{1}{3} i k t_1$	$-\frac{1}{3} i \sqrt{2} k t_1$	0	$\frac{2k^2 t_1}{3}$

Source constraints	
SO(3) irreps	#
$\tau_{0+}^{\#2} == 0$	1
$\tau_{0+}^{\#1} == 0$	1
$\tau_{1-}^{\#2\alpha} + 2\,i\,k\,\sigma_{1-}^{\#1\alpha} == 0$	3
$\tau_{1-}^{\#1\alpha} == 0$	3
$\sigma_{1-}^{\#1\alpha} == \sigma_{1-}^{\#2\alpha}$	3
$\tau_{1+}^{\#1\alpha\beta} + i\,k\,\sigma_{1+}^{\#2\alpha\beta} == 0$	3
$\tau_{2+}^{\#1\alpha\beta} - 2\,i\,k\,\sigma_{2+}^{\#1\alpha\beta} == 0$	5
Total #:	19

	$\sigma_0^{\#1}$	$\tau_0^{\#1}$	$\tau_0^{\#2}$	$\sigma_0^{\#1}$
$\sigma_0^{\#1} \dagger$	$\frac{1}{6k^2 r_3}$	0	0	0
$\tau_0^{\#1} \dagger$	0	0	0	0
$\tau_0^{\#2} \dagger$	0	0	0	0
$\sigma_0^{\#1} \dagger$	0	0	0	$\frac{1}{k^2 r_2 + t_2}$

$\omega_2^{\#1} + \alpha\beta$	$\frac{t_1}{2}$	$-\frac{ikt_1}{\sqrt{2}}$	0	$\omega_2^{\#1} \alpha\beta X$
$f_2^{\#1} + \alpha\beta$	$\frac{ikt_1}{\sqrt{2}}$	$k^2 t_1$	0	
$\omega_2^{\#1} + \alpha\beta X$	0	0	$\frac{t_1}{2}$	

$\omega_0^{\#1} \uparrow$	$6k^2r_3$	$\omega_0^{\#1} \uparrow$	$f_0^{\#1} \uparrow$	$f_0^{\#1} \uparrow$	$\omega_0^{\#1}$
$\omega_0^{\#1} \uparrow$		0	0	0	0
$f_0^{\#1} \uparrow$	0	0	0	0	0
$f_0^{\#2} \uparrow$	0	0	0	0	0
$\omega_0^{\#1} \uparrow$	0	0	0	0	$k^2r_2 + t_2$

$\sigma_2^{\#1} \dagger \alpha\beta$	$\frac{2}{(1+2k^2)^2 t_1}$	$-\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	$\sigma_2^{\#1} \alpha\beta\chi$
$\tau_2^{\#1} \dagger \alpha\beta$	$\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	$\frac{4k^2}{(1+2k^2)^2 t_1}$	0
$\sigma_2^{\#1} \dagger \alpha\beta\chi$	0	0	$\frac{2}{t_1}$

$\frac{2}{(1+2k^2)^2 t_1}$	$-\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	0
$\frac{2i\sqrt{2}k}{(1+2k^2)^2 t_1}$	$\frac{4k^2}{(1+2k^2)^2 t_1}$	0
0	0	$\frac{2}{t_1}$