

Seminar 4

Special relativity

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What is special relativity?

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What is special relativity?

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- This regime tends to **break** classical laws of physics:
 - **quantum mechanics** → **quantum field theory**
 - **classical mechanics** → **relativistic mechanics**
- Three space dimensions and one time dimension are **aspects** of a connected whole known as **spacetime**



Special vs general relativity

- What is the difference between **special** and **general** relativity?



Special vs general relativity

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- **General relativity** is needed when there is enough **mass**, **energy**, **momentum** or **stress** (or when the **densities** of these are high enough) that there is some **gravity** involved



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- What does that mean about the **shape** of spacetime?



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- What does that mean about the **shape** of spacetime?
 - **Special relativity** → **flat spacetime**



Special vs general relativity

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- **General relativity** is needed when there is enough **mass**, **energy**, **momentum** or **stress** (or when the **densities** of these are high enough) that there is some **gravity** involved
- What does that mean about the **shape** of spacetime?
 - **Special relativity** → **flat spacetime**
 - **General relativity** → **curved spacetime**



Special vs general relativity

- The **three** dimensional space we all live in is known as **Euclidean** space



Special vs general relativity

- The **three** dimensional space we all live in is known as **Euclidean** space
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 - We can **rotate** the space



Special vs general relativity

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- **Euclidean** space has some properties you are all very **familiar** with, but which we need to describe **mathematically** in order to compare with **non-Euclidean** space (i.e. **four** dimensional spacetime):
 - We can **rotate** the space
 - We can define **distances** which don't change when we **rotate** the space



We want everything simple...

- We will only deal with **two** dimensions at a time, otherwise everything will become very complicated!



Euclidean rotations

- Start with **two** ordinary space dimensions and coordinates x and y , what is a **vector** which describes a **position** in that space?



Euclidean rotations

- Start with **two** ordinary space dimensions and coordinates x and y , what is a **vector** which describes a **position** in that space?
- Should have:

$$\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix}$$



Euclidean rotations

- Now we need to introduce **matrices**!



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Euclidean rotations

- Now we need to introduce **matrices**!
- Just a **table** of numbers:

$$\mathbf{R} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$



Euclidean rotations

- Now we **multiply** a **vector** by a **matrix**!



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Euclidean rotations

- Now we **multiply** a **vector** by a **matrix**!
- Here is the **rule** for doing this:

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$



Euclidean rotations

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- **WRITE THIS DOWN, YOU WILL NEED IT**



Euclidean rotations

- **Over to you:** find x' and y' if:

$$\mathbf{R} = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



Euclidean rotations

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- Emre: $\theta = 10^\circ$, Mason: $\theta = 360^\circ$, Ali Goktug: $\theta = 45^\circ$, Claudia: $\theta = 70^\circ$, Federico: $\theta = 180^\circ$, Beltran: $\theta = 270^\circ$



Euclidean rotations

- **Still over to you:** Now find $\sqrt{x'^2 + y'^2}$ for these new vectors!



Euclidean rotations

- We should have found the following **exciting** things:



Euclidean rotations

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 - The matrix **R** just **rotates** the position in space through the **angle**



Euclidean rotations

- We should have found the following **exciting** things:
 - The matrix **R** just **rotates** the position in space through the **angle**
 - This leaves the **distance** from the origin **unchanged**



Euclidean rotations

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Euclidean rotations

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 - **Rotations** are done with **trigonometric** functions $\sin(\theta)$ and $\cos(\theta)$



Euclidean rotations

- So we can say this about **Euclidean** space:
 - **Rotations** are done with **trigonometric** functions $\sin(\theta)$ and $\cos(\theta)$
 - **Distances** are done like this: $\sqrt{x^2 + y^2 + z^2}$



Galilean rotations

- This was rather **boring** actually, it gets more interesting if we have one **space** dimension and one **time** dimension



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- Let's say **space** is just given by x , what would be a good coordinate for time?



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- It would be nice if we could set up this **two** dimensional space with coordinates which have the same **units**
- Let's say **space** is just given by x , what would be a good coordinate for time?
- So our new **position vector** is:

$$\mathbf{x} = \begin{bmatrix} ct \\ x \end{bmatrix}$$



Galilean rotations

- We've just started to put together the idea of **spacetime**!



Galilean rotations

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- Some important points:
 - In **space** positions are usually known as **points**
 - In **spacetime** the positions are known as **events**



Galilean rotations

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- Some important points:
 - In **space** positions are usually known as **points**
 - In **spacetime** the positions are known as **events**
- Why?



Galilean rotations

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- What is our x at general t ?



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- At $t = 0$, we were at $x = 0$
- What is our x at general t ?
- What is our t at general t (trick question!)?



Galilean rotations

- With this in mind, how will we measure t' and x' of some **event**:

$$\mathbf{x} = \begin{bmatrix} ct \\ x \end{bmatrix}$$



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Galilean rotations

- With this in mind, how will we measure t' and x' of some **event**:

$$\mathbf{x} = \begin{bmatrix} ct \\ x \end{bmatrix}$$

- Just using common sense, we should end up with these very simple formulae:

$$\begin{aligned} t' &= t, \\ x' &= x - vt \end{aligned}$$



Galilean rotations

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- Does anyone **disagree**?



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- Does anyone **disagree**?
- These formulae are **completely and utterly wrong**, but nobody noticed until 1905!



Galilean rotations

- Note that I used the word **transformations** for $t \rightarrow t'$ and $x \rightarrow x'$, but **rotations** for $x \rightarrow x'$ and $y \rightarrow y'$



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- That is because the idea of **rotating space** makes **perfect sense**, but **rotating space and time** sounds like **nonsense**...



Galilean rotations

- Note that I used the word **transformations** for $t \rightarrow t'$ and $x \rightarrow x'$, but **rotations** for $x \rightarrow x'$ and $y \rightarrow y'$
- That is because the idea of **rotating space** makes **perfect sense**, but **rotating space and time** sounds like **nonsense**...
- Let's do it anyway!



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Lorentz rotations

- **Over to you again:** find t' and x' if:

$$\mathbf{R} = \begin{bmatrix} \frac{1}{\sqrt{1-v^2/c^2}} & \frac{-v/c}{\sqrt{1-v^2/c^2}} \\ \frac{-v/c}{\sqrt{1-v^2/c^2}} & \frac{1}{\sqrt{1-v^2/c^2}} \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} ct \\ x \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



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- Emre: $v = c$, Mason: $v = 2c$, Ali Goktug: $v = 0$, Claudia: $v = 0.5c$, Federico: $v = 0.2c$, Beltran: $v = 0.1c$



Lorentz rotations

- **Next task:** find $\sqrt{c^2t'^2 - x'^2}$ for your vectors!



Lorentz rotations

- Now find this:

$$\left(\frac{1}{\sqrt{1 - v^2/c^2}} \right)^2 - \left(\frac{-v/c}{\sqrt{1 - v^2/c^2}} \right)^2$$



Lorentz rotations

- **Now find this:**

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- **Finally who can remember what this is for any ψ :**

$$\cosh(\psi)^2 - \sinh(\psi)^2$$



Lorentz rotations

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- Claudia: ψ is another Greek letter pronounced 'psi' ;)



Lorentz rotations

- So it turns out we can just write that horrible matrix in a simple form:

$$\mathbf{R} = \begin{bmatrix} \frac{1}{\sqrt{1-v^2/c^2}} & \frac{-v/c}{\sqrt{1-v^2/c^2}} \\ \frac{-v/c}{\sqrt{1-v^2/c^2}} & \frac{1}{\sqrt{1-v^2/c^2}} \end{bmatrix} = \begin{bmatrix} \cosh(\psi) & \sinh(\psi) \\ \sinh(\psi) & \cosh(\psi) \end{bmatrix} = \mathbf{\Lambda}$$



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- Claudia: Λ is uppercase Greek letter 'lambda', lowercase is λ ;)



Lorentz rotations

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Lorentz rotations

- So unlike last time, the things we get now should actually be interesting:
 - When we move, space and time **rotate**, but instead of **trigonometric** rotations with $\sin(\theta)$ and $\cos(\theta)$ for some angle θ we have **hyperbolic** rotations with **hyperbolic** functions $\sinh(\psi)$ and $\cosh(\psi)$ – don't bother with what ψ actually is, there is a formula for it in terms of v/c (Mason, find $\psi(v/c)$)



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 - The **distance** in spacetime is just $\sqrt{c^2t^2 - x^2 - y^2 - z^2}$



Lorentz rotations

- Some long words:



Lorentz rotations

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 - **Distance** in spacetime is known as the **interval** – in the same sense that the **point** is known as an **event**



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 - **Minkowskian spacetime** is flat, but has a **negative metric signature** – tomorrow (Seminar 5) we will look at general relativity, in which the metric signature is the same, but because there is **gravity** the spacetime is **curved**



Lorentz rotations

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 - **Minkowskian spacetime** is flat, but has a **negative metric signature** – tomorrow (Seminar 5) we will look at general relativity, in which the metric signature is the same, but because there is **gravity** the spacetime is **curved**
 - You might want to look up some of these terms, but we don't have time (or the mathematical development) to go into them



Lorentz rotations

- Note to self: find some Lorentz transformations on Youtube



Lorentz rotations

- But I didn't go into why any of this **hyperbolic/Lorentz** rotation stuff is true. . .



Lorentz rotations

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- In fact, we were happy with the simpler Galilean transformations before weren't we?



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Lorentz rotations

- But I didn't go into why any of this **hyperbolic/Lorentz** rotation stuff is true...
- In fact, we were happy with the simpler Galilean transformations before weren't we?
- Go back to t and x (i.e. **two dimensional case**) – what if the **event** was a photon being **emitted** in the past at $t < 0$ and some position x , and detected by us ($v = 0$) at the **origin** of spacetime ($t_0 = 0$ and $x_0 = 0$) **Find the interval for the photon:**

$$\sqrt{c^2 t^2 - x^2}$$



Lorentz rotations

- We should find:

$$\sqrt{c^2t^2 - x^2} = 0$$



Lorentz rotations

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Lorentz rotations

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- This relies on the photon moving at c , right?
- And even if we start moving at v we just spent ages proving that the **interval** of the photon's motion remains **unchanged**:

$$\sqrt{c^2 t'^2 - x'^2} = 0$$



Lorentz rotations

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- So when we are moving at v , **what is the speed of the photon?**



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- This relies on the photon moving at c , right?
- And even if we start moving at v we just spent ages proving that the **interval** of the photon's motion remains **unchanged**:

$$\sqrt{c^2 t'^2 - x'^2} = 0$$

- So when we are moving at v , **what is the speed of the photon?**
- So all this **hyperbolic** rotation stuff just ensures that **the speed of light is the same, no matter how fast you are moving**



Lorentz rotations

- Finally, we **Lorentz** rotations:

$$ct' = \frac{ct}{\sqrt{1 - v^2/c^2}} - \frac{vx/c}{\sqrt{1 - v^2/c^2}},$$
$$x' = \frac{x}{\sqrt{1 - v^2/c^2}} - \frac{vt}{\sqrt{1 - v^2/c^2}},$$



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- And **Galilean** transformations:

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- And **Galilean** transformations:

$$t' = t,$$
$$x' = x - vt,$$

- Explain why **Galilean** transformations are okay so long as $v \ll c$



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Lorentz rotations

- We also have **relativistic** momentum:

$$p = \frac{mv}{\sqrt{1 - v^2/c^2}}$$



Lorentz rotations

- We also have **relativistic** momentum:

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- And **non-relativistic** momentum:

$$p = mv$$



Lorentz rotations

- We also have **relativistic** momentum:

$$p = \frac{mv}{\sqrt{1 - v^2/c^2}}$$

- And **non-relativistic** momentum:

$$p = mv$$

- Explain why they agree at $v \ll c$



Lorentz rotations

- Finally we have **relativistic** energy:

$$\mathcal{E} = \frac{mc^2}{\sqrt{1 - v^2/c^2}}$$



Lorentz rotations

- Finally we have **relativistic** energy:

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- What happens at $v \ll c$?



Lorentz rotations

- Finally we have **relativistic** energy:

$$\mathcal{E} = \frac{mc^2}{\sqrt{1 - v^2/c^2}}$$

- What happens at $v \ll c$?**
- Should have **non-relativistic** energy:

$$\mathcal{E} = mc^2 + \frac{1}{2}mv^2$$



Lorentz rotations

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Lorentz rotations

- Should have **non-relativistic** energy:

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- What happens if the particle is standing still?

$$\mathcal{E} = mc^2$$



Lorentz rotations

- Should have **non-relativistic** energy:

$$\mathcal{E} = mc^2 + \frac{1}{2}mv^2$$

- What happens if the particle is standing still?

$$\mathcal{E} = mc^2$$

- **The end.**



Astrophysical phenomena

""einstein".jpg



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