

F Henry PhysA Waves Probs ①

$$7) \lambda^2 = -\frac{g}{L} \sin \lambda = -\sin \lambda$$

$$x = \theta \quad \therefore \dot{x} = \dot{\theta}$$

$$\therefore \dot{x} = \sin \theta$$

$$8a) s = x$$

$$u = 0$$

$$v = \dot{x}$$

$$a = g$$

$$t = t$$

$$x = \frac{1}{2} g t^2 \text{ ① for free mass}$$

$$x = v t \text{ ② for wave speed}$$

$$\textcircled{1} x = \frac{1}{2} g \times \frac{x^2}{v^2}$$

$$M v^2 = \frac{T}{\rho} = \frac{T L}{m}$$

$$T = m g$$

$$x^2 = \frac{m^2 g^2 L^2}{m^2} = g^2 L^2$$

$$\cancel{x = \frac{1}{2} g x^2} = \cancel{\frac{x^2}{2 g L^2}} = \cancel{x (2 g L^2)} = 0$$

$$\cancel{M x = 0} \text{ or } \boxed{x = 2 g L^2}$$

$$\therefore v^2 = \frac{m g L}{m} = g L \quad \therefore x = \frac{\frac{1}{2} g x^2}{g L} = \frac{x^2}{2 L}$$

$$x = 0 \text{ or } \boxed{x = 2 L} \text{ — ? longer than string}$$

$$b) T = \cancel{m g} g(m+M) \text{ and calculate } x = L$$

but makes wrong earlier so can't do

$$x \left(\frac{g(m+M)L}{m} \right) = \frac{1}{2} g x^2$$

$$x = 0 \text{ or } x = \frac{2 L(m+M)}{m}$$

$$x = L \therefore m = 2m + 2M$$

$$\boxed{M = -\frac{m}{2}}$$

wrong earlier on so can't work

$$9a) m \text{ of string} = \pi \times \left(\frac{0.5 \times 10^{-3}}{2}\right)^2 \times 700 \times 10^{-3} \times 7800$$

$$= 1.07 \times 10^{-3} \text{ kg}$$

$$\frac{m}{L} = 1.53 \times 10^{-3} \text{ kg m}^{-1} = \rho$$

$$f_1 = \frac{v}{2L} = \frac{\sqrt{\frac{T}{\rho}}}{2L}$$

$$\therefore \rho(2Lf_1)^2 = T = 205 \text{ N}$$

$$\text{stress at this tuning} = \frac{T}{A} = \frac{T}{\pi \left(\frac{0.5 \times 10^{-3}}{2}\right)^2} = 1.04 \times 10^9 \text{ Nm}^{-2}$$

piano tuning could be dangerous as could yield or snap if tuned to higher frequencies than material can handle. (high Tension string snaps could be dangerous)

$$b) 261.6 \text{ Hz? } 200 \times 10^9 = \frac{1.04 \times 10^9}{\text{strain}}$$

$$f) \text{ strain} = 5.2 \times 10^{-3}$$

$$\therefore \Delta x = 3.63 \times 10^{-3} \text{ m}$$

$$T = k \Delta x$$

$$\therefore k = 5.63 \times 10^4$$

assuming SHM in string acting as spring

$$\omega^2 = \frac{k}{m} \therefore \omega = \sqrt{\frac{k}{m}} = 7250 \text{ rad s}^{-1}$$

$$f = 1150 \text{ s}^{-1}$$

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9c) $T = k \times \text{strain} \times L$ strain = ϵ

$$T = k \epsilon L$$

$$k = \frac{T}{\epsilon L}$$

$$v \cdot f_L = \frac{1}{2\pi} \sqrt{\frac{T}{\epsilon m}}$$

$$f_T = \frac{1}{2L} \sqrt{\frac{TL}{m}} = \frac{1}{2} \sqrt{\frac{T}{mL}}$$

$$\frac{f_T}{f_L} = \frac{\frac{1}{2} \sqrt{\frac{T}{mL}}}{\frac{1}{2\pi} \sqrt{\frac{T}{\epsilon mL}}} = \frac{1}{\frac{1}{\pi} \times \frac{1}{\sqrt{\epsilon}}} = \pi \sqrt{\epsilon}$$

~~$\frac{f_T}{f_L} > 1$~~ If $\frac{f_T}{f_L} > 1$ then transverse waves will be faster than compression waves

$$\therefore \pi \sqrt{\epsilon} > 1$$

$$\epsilon > \frac{1}{\pi^2}$$

$$\epsilon > 0.10 \quad \therefore \text{strain} > 10\%$$

as it breaks usually if more than 1-2% this means transverse almost always slower than compression.

10a) $\Psi_{y,1} = a \sin \theta \cos(kz - \omega t + \phi_0)$

$\Psi_{y,2} = b \cos(kz - \omega t + \frac{\pi}{2})$ is this right hand?

~~$\Psi_{y,3} = A_x = 2A_y$~~
 ~~$\Psi_{y,3} = \frac{\Psi_{x,3} \cos \phi}{2} - \frac{\sqrt{4A_y^2 - \Psi_{x,3}^2}}{2} \sin \phi$~~
 $\Psi_{y,3} = \frac{c}{2} \cos(kz - \omega t - \phi)$

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$$10b) \Psi_{x,1} + \Psi_{x,2} = a \cos \theta (\cos(kz - \omega t) \cos \phi_0 - \sin(kz - \omega t) \sin \phi_0) + b \cos(kz - \omega t)$$

$$= \cos(kz - \omega t) (a \cos \theta \cos \phi_0 + b) - a \cos \theta \sin \phi_0 \sin(kz - \omega t)$$

~~compare coefficients to~~ $\Psi_{x,3}$

$$a \cos \theta \cos \phi_0 + b = c \quad (1) \quad a \cos \theta \sin \phi_0 = 0 \quad (2)$$

$$\Psi_{y,1} + \Psi_{y,2} = a \sin \theta (\cos(kz - \omega t) \cos \phi_0 - \sin(kz - \omega t) \sin \phi_0)$$

$$+ b (\cos(kz - \omega t) \cos \frac{\pi}{2} - \sin(kz - \omega t) \sin \frac{\pi}{2})$$

~~compare coefficients to $\Psi_{y,3}$~~

$$= a \sin \theta \cos \phi_0 \cos(kz - \omega t) - \sin(kz - \omega t) (a \sin \theta \sin \phi_0 + b)$$

compare coefficients to $\Psi_{y,3}$

$$\Psi_{y,3} = \frac{c}{2} (\cos(kz - \omega t) \cos \phi + \sin(kz - \omega t) \sin \phi)$$

$$\frac{c}{2} \cos \phi = a \sin \theta \cos \phi_0 \quad (3) \quad -\frac{c}{2} \sin \phi = a \sin \theta \sin \phi_0 + b \quad (4)$$

this is true if ①, ②, ③, ④ all hold

$$\frac{c^2}{4} = a^2 \sin^2 \theta \cos^2 \phi_0 + a^2 \sin^2 \theta \sin^2 \phi_0 + 2ab \sin \theta \sin \phi_0 + b^2$$

$$\frac{c^2}{4} = a^2 \sin^2 \theta + b^2 + 2ab \sin \theta \sin \phi_0$$

From ② $\cos \theta = 0$ or $\sin \phi_0 = 0$ ~~sub ② into ③~~

$$P = -T \frac{\partial \Psi}{\partial z} \times \frac{\partial \Psi}{\partial t}$$

$$1) \quad Z = \frac{F}{u}$$

$$P = Fu = Z \left(\frac{\partial \Psi}{\partial t} \right)^2$$

$$P(t) = Z C = A + Bi$$

$$\frac{\partial \Psi}{\partial t} = \Psi = R(A + Bi)(e^{i(\omega t - kz)})$$

$$= A \cos(\omega t - kz) - B \sin(\omega t - kz)$$

$$\frac{\partial \Psi}{\partial t} = -\omega A \sin(\omega t - kz) - \omega B \cos(\omega t - kz)$$

$$\left(\frac{\partial \Psi}{\partial t} \right)^2 = (-\omega)^2 (A^2 \sin^2(\omega t - kz) + B^2 \cos^2(\omega t - kz) + 2AB \sin(\omega t - kz) \cos(\omega t - kz))$$

$$\therefore \langle P \rangle = Z \times \omega^2 \left(\frac{1}{2} A^2 + \frac{1}{2} B^2 + 0 \right)$$

$$= Z \times \omega^2 \left(\frac{1}{2} \right) (|C|^2)$$

$$= \frac{1}{2} Z \omega^2 (|C|)^2$$

If Z is complex
and with same frequency
as sinusoidal wave

$$Z = Z_0 e^{i\omega t}$$

Means ^{Real} Impedance value changes
with wave phase (blocks power
more at certain phases of the wave)

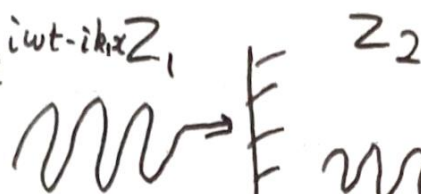
$$\langle P \rangle = \frac{1}{4} Z_0 \omega^2 (|C|)^2 ?$$

F Henry Phys A Wave Probs (4)

$$12) v = \sqrt{\frac{T}{\mu}} \quad \frac{\partial \Psi}{\partial t} = u_v$$

at $x=0$ ~~$\Psi_1 = A_1 e^{i\omega t - ik_1 x}$~~

$$\Psi_1 = A_1 e^{i\omega t - ik_1 x}$$



$$A_1 + B_1 = A_2 \quad (1)$$

$$\Psi_2 = B_1 e^{i\omega t + ik_1 x}$$

$$\Psi_3 = A_2 e^{i\omega t - ik_2 x}$$

$$T(-ik_1)A_1 + T(ik_1)B_1 = T(ik_2)A_2 - \alpha A_2$$

$$TA_2(-ik_2)$$

$$R_1 = \frac{\omega}{v_1} \quad R_2 = \frac{\omega}{v_2}$$

$$-\frac{T}{v_1} \omega A_1 + \frac{T}{v_1} \omega B_1 = -\frac{T}{v_2} \omega A_2 + \alpha i$$

$$-TA_1 - T\left(\frac{\partial \Psi_1}{\partial t}\right) - T\left(\frac{\partial \Psi_2}{\partial t}\right) = -T\left(\frac{\partial \Psi_3}{\partial t}\right) - \alpha\left(\frac{\partial \Psi_3}{\partial t}\right)$$

$x=0$

$$T(-k_1)A_1 + T(k_1)B_1 = T(k_2)A_2 - \alpha(-k_2)A_2$$

$$R_1 = \frac{\omega}{v_1} \quad R_2 = \frac{\omega}{v_2}$$

$$\therefore -\frac{T}{v_1} A_1 + \frac{T}{v_1} B_1 = -\frac{T}{v_2} A_2 - \frac{\alpha}{v_2} A_2$$

$$\left(\frac{T}{v_1} = Z_1\right) \left(\frac{T}{v_2} = Z_2\right)$$

$$\therefore -Z_1 A_1 + Z_1 B_1 = -Z_2 A_2 - \frac{Z_2 \alpha}{T} A_2$$

$$Z_1(A_1 - B_1) = Z_2 A_2 \left(1 + \frac{\alpha}{T}\right) \quad (2)$$

Sub (1) into (2) $Z_1(A_1 - B_1) = Z_2 \left(1 + \frac{\alpha}{T}\right) (A_1 + B_1)$

$$A_1(Z_1 - Z_2(1 + \frac{\alpha}{T})) = B_1(Z_2(1 + \frac{\alpha}{T}) + Z_1)$$

$$\frac{B_1}{A_1} = \frac{Z_1 - Z_2(1 + \frac{\alpha}{T})}{Z_1 + Z_2(1 + \frac{\alpha}{T})} = r$$

12) done wrong α should be a scale factor of Z_2

~~is important!~~ If α is large then would be node
If α is small then would be antinode

can't do rest as maths is wrong

7) $\ddot{\theta} = -\sin \theta$

$$x = \dot{\theta} \quad \& \quad \dot{x} = \ddot{\theta} = -\sin \theta$$

$$\begin{pmatrix} \dot{\theta} \\ \dot{x} \end{pmatrix} = \begin{pmatrix} x \\ -\sin \theta \end{pmatrix}$$

$$\dot{\vec{y}} = \vec{F}$$

$$\frac{\vec{y}_{t+1} - \vec{y}_t}{\Delta t} = \vec{F} \Rightarrow \vec{y}_{t+1} = \vec{y}_t + \Delta t \cdot \vec{F}$$

$$\vec{y} = \begin{pmatrix} \theta \\ x \end{pmatrix} = \begin{pmatrix} \theta \\ \dot{\theta} \end{pmatrix}$$