
Graph and Dijkstra Algorithm

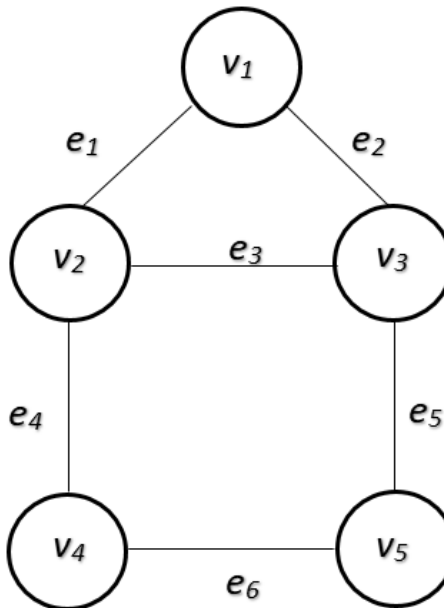
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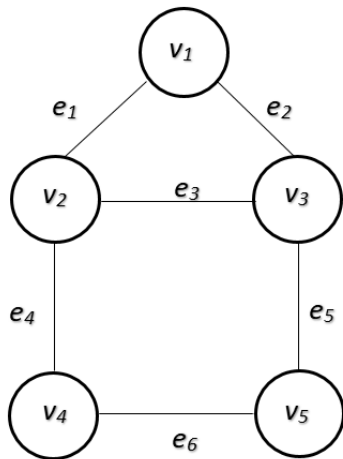
Graph

- A graph G is a data structure that consists of a set of vertices V and edges E
 - An edge e is a pair of vertices (v_i, v_j) , where $v_i, v_j \in V$
 - For example, the following picture shows a graph with 5 vertices and 6 edges



Adjacency Matrix

- If two vertices in a graph are connected by an edge, we say the vertices are adjacent
 - In our graph example, vertex v_1 has two adjacent vertices, v_2 and v_3
 - Based on this property, we can use an adjacency matrix or adjacency list to represent a graph
 - We can also use an adjacency list to represent a graph



	v_1	v_2	v_3	v_4	v_5
v_1	0	1	1	0	0
v_2	1	0	1	1	0
v_3	1	1	0	0	1
v_4	0	1	0	0	1
v_5	0	0	1	1	0

Adjacency Matrix

v_1	v_2, v_3
v_2	v_1, v_3, v_4
v_3	v_1, v_2, v_5
v_4	v_2, v_5
v_5	v_3, v_4

Adjacency List

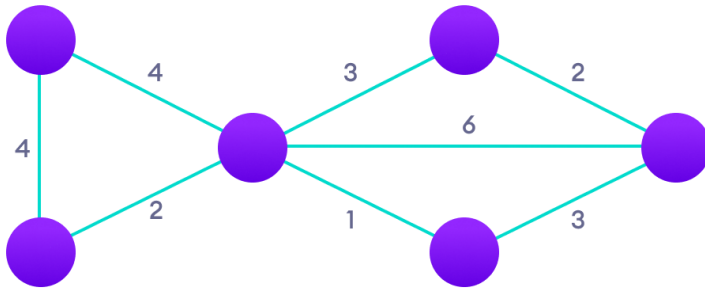
Dijkstra Algorithm for Shortest Path

- The algorithm exists in many variants
 - Dijkstra's original algorithm finds the **shortest path between two given nodes**
 - But a more common variant fixes a single node as the "source" node and finds shortest paths from the **source to all other nodes** in the graph, producing a shortest-path tree

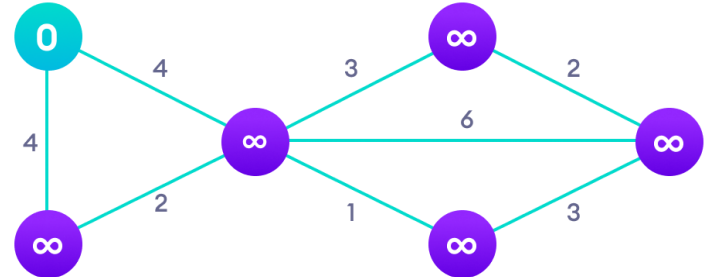
Dijkstra Algorithm (Source to All)

- ❑ 1. Mark all nodes **unvisited**
- ❑ 2. Assign to every node a tentative distance value
 - **Zero for the initial node and infinity for all other nodes**
- ❑ 3. Select an **unvisited node** that is marked with the **smallest tentative distance**
- ❑ 4. **Update the tentative distances** of all the unvisited neighbors through the selected node and mark the selected node as visited
- ❑ 5. If all the nodes have been marked visited, then stop
 - Otherwise, go back to step 3

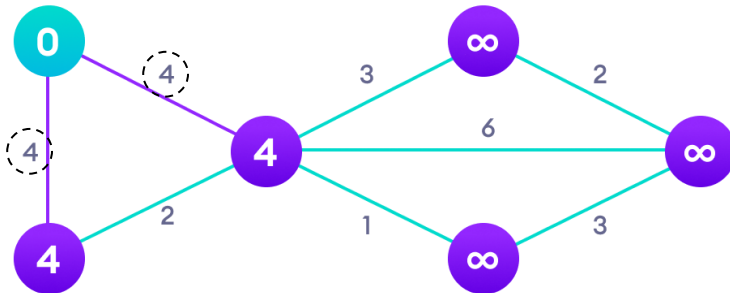
Example (1/2)



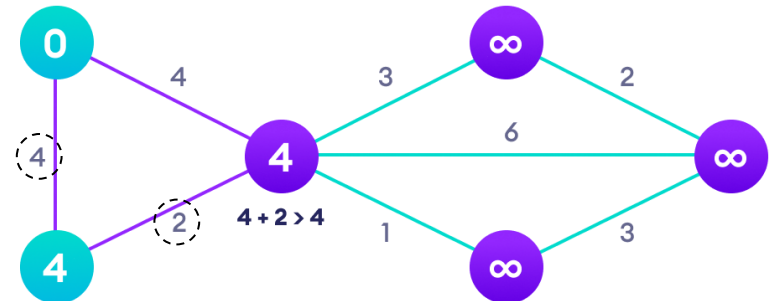
Step: 1



Step: 2

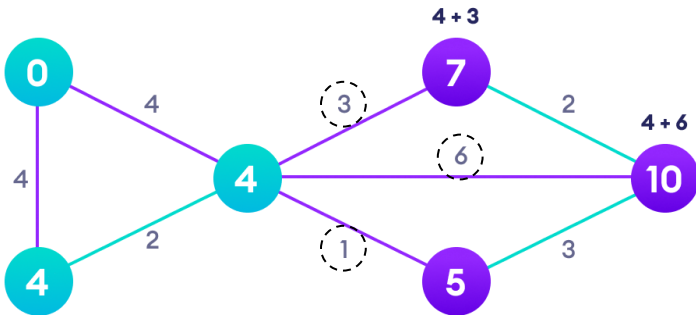


Step: 3

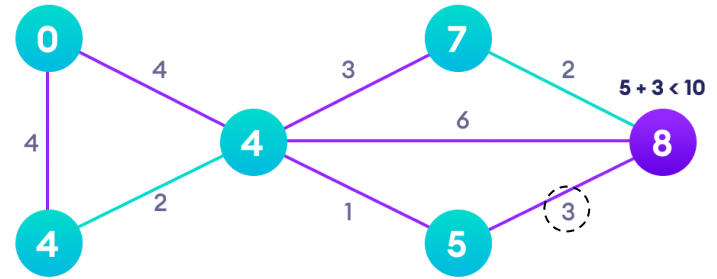


Step: 4

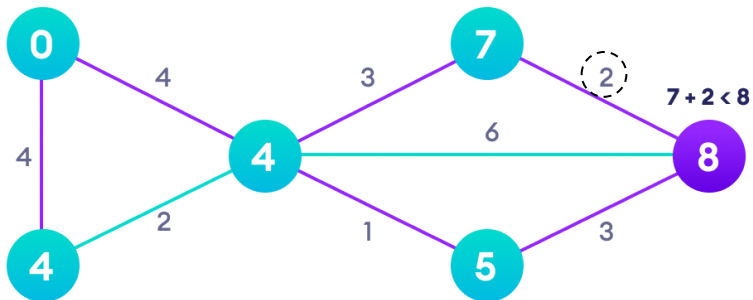
Example (2/2)



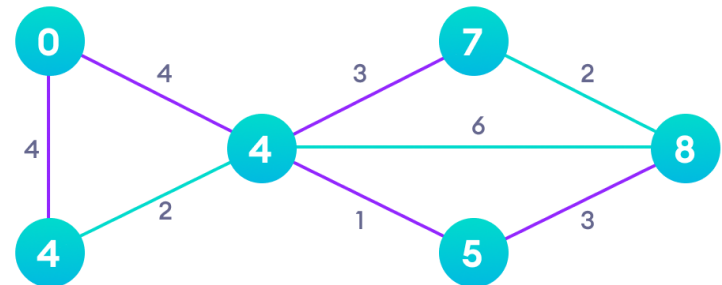
Step: 5



Step: 6



Step: 7



Step: 8



thank you!