

A Tale of Two Tasks: Data Control and Modeling

Wayne D. Gray

Beyond OpenData Sharing: Making Sense of Massive Data Sets

(Isn't that what MacSHAPA was really about???)

Beyond Open Data Sharing

- High bandwidth data collection with well formatted records, easy to reuse documentation, and ability to address new questions after the data is collected
- Tools that will aggregate sampled data to form meaningful units at different levels of analysis
- Visualizing and exploring data in terms of sequence, co-occurrence, and other patterns
- Newell's Dream: Automated or semi-automated protocol analyses, which enable theory-based parsing of log files to form runnable cognitive models



Then & Now

- MacSHAPA
 - MacSHAPA (1995's) - Submarine Commanders: managing complexity of verbal and action protocols
 - MacSHAPA Cognitive Metrics Profiling
- Action Protocol Tracer
 - Finite state grammars for pattern recognition in action protocol data
- SANLab
 - SANLab - tool for Stochastic Analytic Network modeling +++
 - Newell's Dream: Automating production of cognitive models from behaviorial/action protocol analysis



Experience with MacSHAPA

- Submariners (\approx 1995 to 2000)
- Tool for examining output of computational cognitive modeling

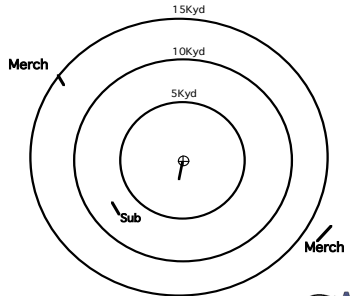
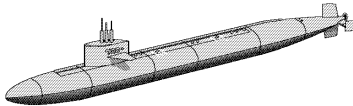
Project Nemo, or, Subgoaling Submariners

A Joint University–Naval
University
Hum

Collaboration
Ph.D.
ition

≈ 1996

...schenbaum, Ph.D.
Warfare Center Division
Newport, RI



Seven Phased Approach

- Phase 1: Data Collection using simulation (at NUWC) -->**COMPLETED**<--
- Phase 2: Encoding protocols from Phase 1 -->**COMPLETED**<--
- Phase 3: Development of scaled simulation (scaled world) -->**COMPLETED**<--
- Phase 4: Development of preliminary computational cognitive models ****CURRENT****
- Phase 5: Data Collection using scaled world ****CURRENT****
- Phase 6: Analysis of data and refinement of models
- Phase 7: Modifications of suite of models and scaled world as deliverables

≈ 1996



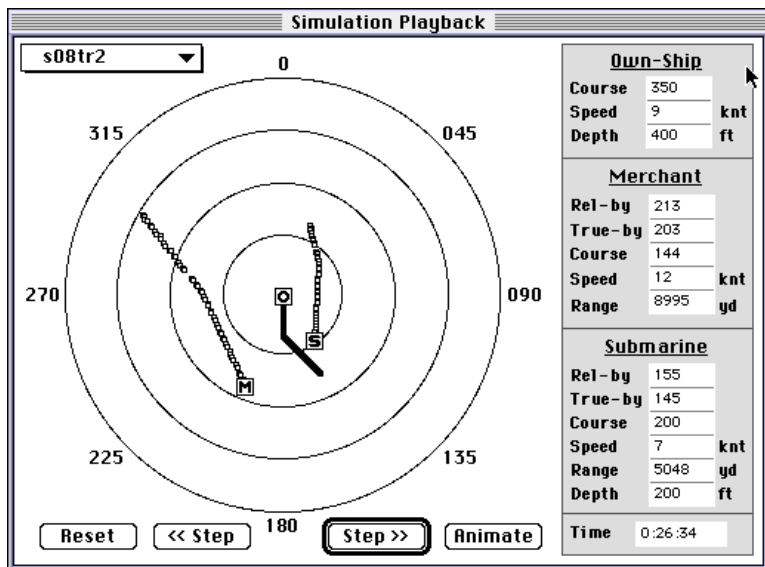
Table 2: Segment Shown in Table 1 Following Resegmentation and Encoding of Goals by the Experimenters

Time	L1	L2	L3	Operator	Info-Source	Ship	Attribute	Value	Duration
62.428		DETECT-SUB							
63.98				DISPLAY-NAV	SONAR-NB-TOWED				
66.82				QUERY	NBT-WATERFALL				
				RECEIVE	NBT-WATERFALL	SUB	ON-SONAR	NO	4.221
		POP							
		LOCALIZE-MERC							
		SET-TRACKER							
67.02				SET-TRACKER	SONAR-NB-TOWED	MERC			
68.201				RECEIVE	NBT-WATERFALL	MERC	ON-SONAR	YES	4.221
68.201				RECEIVE	NBT-WATERFALL	MERC	BEARING	BEAM	4.221
68.201				RECEIVE	NBT-WATERFALL	MERC	TRACKING	YES	4.221
		POP							
		DETERMINE-CONICAL-ANGLE							
70.063				QUERY	NBT-CONICAL-ANGLE-FIELD	MERC	CONICAL-ANGLE		
70.724				RECEIVE	NBT-CONICAL-ANGLE-FIELD	MERC	CONICAL-ANGLE	82.15	0.661
		POP							
		DETERMINE-BY							
71.111				QUERY	NBT-BEARING-FIELD	MERC	BEARING		
72.088				RECEIVE	NBT-BEARING-FIELD	MERC	BEARING	152_OR_314	0.977
		POP							
		DETERMINE-SNR							
72.393				QUERY	NBT-SNR-FIELD	MERC	SNR		
72.987				RECEIVE	NBT-SNR-FIELD	MERC	SNR	6.63	0.594
		POP							
		EVALUATE-ARRAY-STATUS							
74.635				QUERY	NBT-ARRAY-STATUS-FIELD	OS	ARRAY		
75.601				RECEIVE	NBT-ARRAY-STATUS-FIELD	OS	ARRAY	STABLE	0.966
		POP							

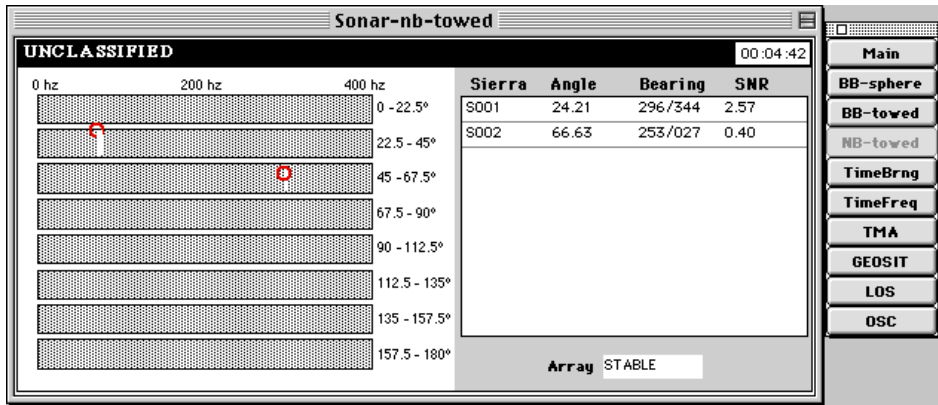
Note: The headings are the same as in Table 1 with the addition of three fields for goals and subgoals: levels 1 (L1), 2 (L2), and 3 (L3). No L3 goals are encoded in this segment.

Downloaded from 129.100.100.100 on September 16, 2011

Phase 2: Tool Development -- To facilitate Encoding of Data we developed a Tool to playback the files collected at NUWC



Phase 3: NED



One of Ned's 10 displays that AOs use for situation assessment. In data-collection mode, all AO interactions with Ned are recorded and time stamped at 60hz (16.67 msec); along with the current state of the simulation (truth!)

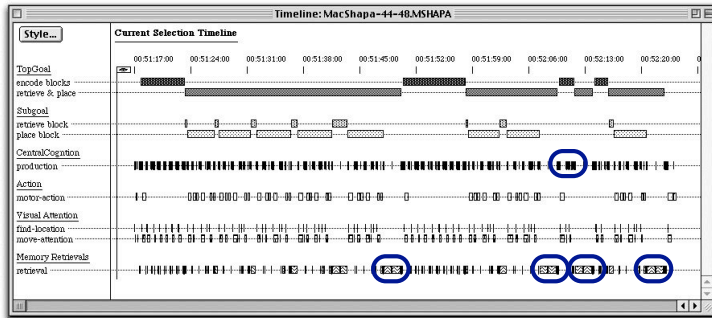
Experience with MacSHAPA

- Submariners (\approx 1995 to 2000)
- **Tool for examining output of computational cognitive modeling**



Visualizing the Output of a Process Model (ACT-R)

- ? We were asking whether we could use this approach to develop a predictions of cognitive workload by identifying tasks or subtasks where the resource demands are excessive
- Especially places where the using the system (i.e., the structure of the interactive system) consumes resources required for doing the task



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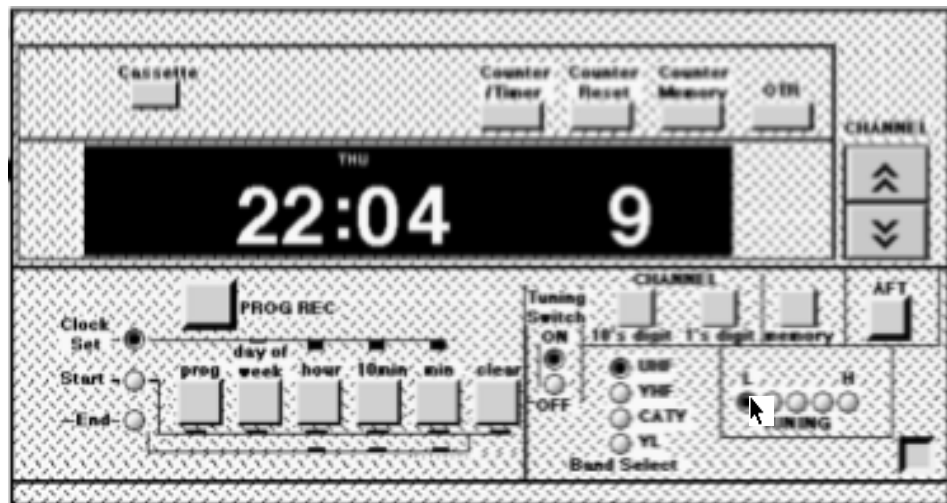
Our Focus was on Discrete Action Protocols

- E.g. Mouse clicks, key presses collected by a computer system
- Characteristics:
 - A large volume of protocols can be easily collected
 - High temporal resolution (e.g. 16.67 msec)
 - Constrained and easy to interpret (compared to verbal protocols)
 - Easy to aggregate across subjects

But, approach could be applied to any data process data that could be encoded in SHAPA spreadsheets

Action protocol analysis

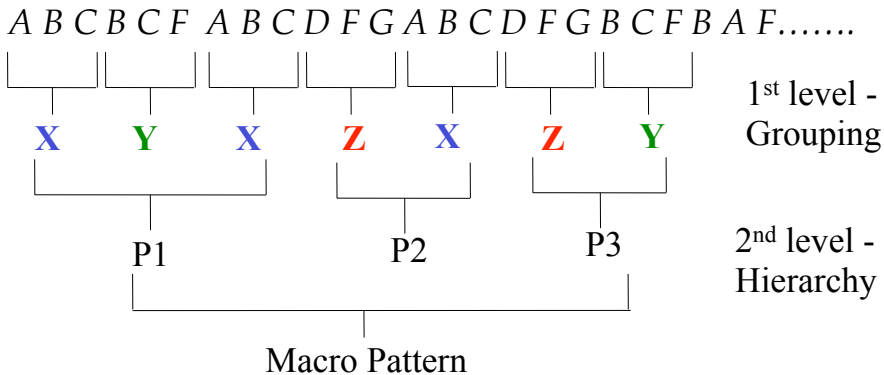
- Two approaches to do the analysis:
 - Exploratory: searching for possible patterns in the protocols
 - Confirmatory: Looking for evidence supporting the researcher's theory
 - Both approaches require some kind of pattern matching to patterns generated by the researcher
- Automatic (or semi-automatic) protocol analyzer
 - Reduce effort
 - Increase objectivity



CURTIME	WINDOW	BUTTON	REC-MODE	PR	CLOCK	PROGNUM	CHANNEL	DOV	WEEK?	POWER?	KP-HOUR	KP-10MIN	KP-MIN
141802	SHOW-INFO-WIN	Start Trial	CLICKON	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
141802	VCR-WINDOW	Start Trial	CLOCKSET-MODE	OFF	15 00	NONE	NIL	NIL	NIL	NIL	15	0	0
141865	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
141924	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
142047	VCR-WINDOW	START-RADIO-BUT	START-MODE	OFF	E EE	1	15 WED	NIL	ON	E	E	E	E
142097	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 WED	NIL	ON		15	0	0
142202	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 THU	NIL	ON		15	0	0
142213	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 FRI	NIL	ON		15	0	0
142230	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 SAT	NIL	ON		15	0	0
142241	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 SUN	NIL	ON		15	0	0
142271	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 MON	NIL	ON		15	0	0
142307	VCR-WINDOW	DAY-OF-WEEK	START-MODE	OFF	15 00	1	15 TUE	NIL	ON		15	0	0
142453	VCR-WINDOW	HOUR	START-MODE	OFF	16 00	1	15 TUE	NIL	ON		16	0	0
142483	VCR-WINDOW	HOUR	START-MODE	OFF	17 00	1	15 TUE	NIL	ON		17	0	0
142512	VCR-WINDOW	HOUR	START-MODE	OFF	18 00	1	15 TUE	NIL	ON		18	0	0
142529	VCR-WINDOW	HOUR	START-MODE	OFF	19 00	1	15 TUE	NIL	ON		19	0	0
142550	VCR-WINDOW	HOUR	START-MODE	OFF	20 00	1	15 TUE	NIL	ON		20	0	0
142579	VCR-WINDOW	HOUR	START-MODE	OFF	21 00	1	15 TUE	NIL	ON		21	0	0
142621	VCR-WINDOW	HOUR	START-MODE	OFF	22 00	1	15 TUE	NIL	ON		22	0	0
142650	VCR-WINDOW	HOUR	START-MODE	OFF	23 00	1	15 TUE	NIL	ON		23	0	0
142730	VCR-WINDOW	10MIN	START-MODE	OFF	23 10	1	15 TUE	NIL	ON		23	1	0
142824	VCR-WINDOW	10MIN	START-MODE	OFF	23 20	1	15 TUE	NIL	ON		23	2	0
142853	VCR-WINDOW	10MIN	START-MODE	OFF	23 30	1	15 TUE	NIL	ON		23	3	0
142909	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
142980	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	14 TUE	NIL	ON		23	3	0
142993	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	13 TUE	NIL	ON		23	3	0
143066	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	12 TUE	NIL	ON		23	3	0
143076	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	11 TUE	NIL	ON		23	3	0
143084	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	10 TUE	NIL	ON		23	3	0
143092	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	9 TUE	NIL	ON		23	3	0
143099	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	8 TUE	NIL	ON		23	3	0
143111	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	7 TUE	NIL	ON		23	3	0
143132	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	6 TUE	NIL	ON		23	3	0
143141	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	5 TUE	NIL	ON		23	3	0
143150	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	4 TUE	NIL	ON		23	3	0
143178	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	3 TUE	NIL	ON		23	3	0
143194	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	2 TUE	NIL	ON		23	3	0
143220	CCL:VCR-WINDOW	CH-DOWN	START-MODE	OFF	23 30	1	1 TUE	NIL	ON		23	3	0
143255	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
143324	VCR-WINDOW	END-RADIO-BUT	END-MODE	OFF	E EE	1	15 NIL	NIL	ON	E	E	E	E
143343	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
143371	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
143556	VCR-WINDOW	HOUR	END-MODE	OFF	23 30	1	1 NIL	NIL	ON		23	3	0
143707	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
143755	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
143836	VCR-WINDOW	CS-RADIO-BUT	CLOCKSET-MODE	OFF	15 00	NONE	15 WED	NIL	ON		15	0	0
143902	VCR-WINDOW	PROGREC	CLOCKSET-MODE	ON	15 00	NONE	NIL WED	NIL	ON		15	0	0
143943	VCR-WINDOW	NIL	VCR-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
144008	SHOW-INFO-WIN	Stop Trial	CLICKON	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
144008	ERROR-TRIAL	RESET	SHOW-ET	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL
144028	SHOW-INFO-WIN	NIL	SW-LEAVE	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL	NIL

Finding patterns in data

- A sequential stream of discrete action protocol



Structure of ACT-PRO

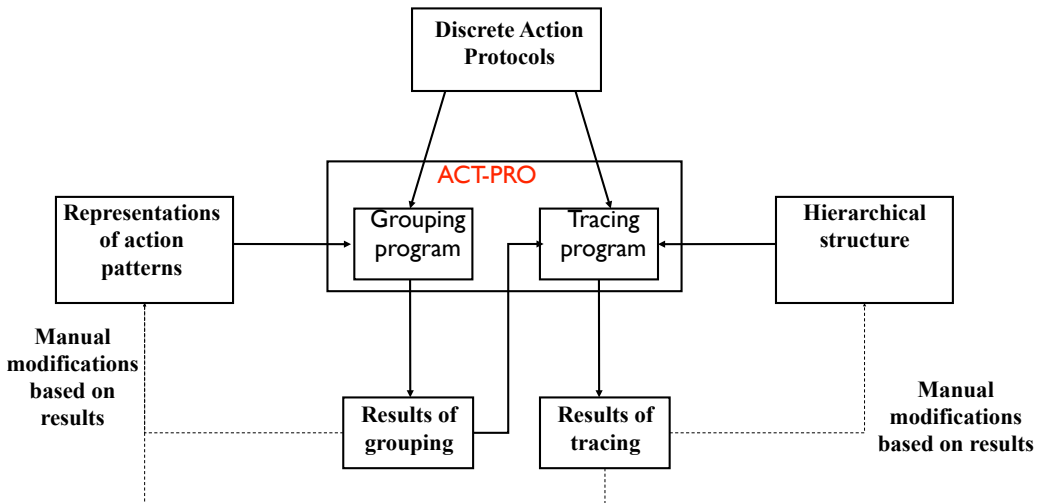


Table 2
Grammar That Captures Variations of the Action Sequence
Formed by Pressing the Buttons Channel, Up-Arrow,
Down-Arrow, and Enter

SET-CHANNEL: [Object1][Object2][Object3]	(1)
[Object1] → <i>channel</i>	(2)
[Object2] → <i>up-arrow</i>	(3)
[Object2] → <i>down-arrow</i>	(4)
[Object2] → <i>up-arrow</i> [Object2]	(5)
[Object2] → <i>down-arrow</i> [Object2]	(6)
[Object2] → <i>enter</i> [Object2]	(7)
[Object3] → <i>enter</i>	(8)

Table 3
An Example of the Trace and Validation Results of
Using the Hierarchical Goal Structure of Figure 1

Trace	Validation results
Push goal: PROGRAM-SHOW	Push goal match
Push goal: SET-START-TIME	Push goal match
Push goal: SET-START-HOUR	Push goal match
Action: <i>start-hour</i>	
Action: <i>start-hour</i>	
Pop goal: SET-START-HOUR	Pop goal match
Push goal: SET-START-10MIN	Push goal match
Action: <i>start-10min</i>	
Pop goal: SET-START-10MIN	Pop goal match
Pop goal: SET-START-TIME	Pop goal mismatch
Push goal: SET-CHANNEL	Push goal match
Action: <i>channel</i>	
Pop goal: SET-CHANNEL	Pop goal match
Push goal: SET-START-TIME	Push goal match
Push goal: SET-START-MIN	Push goal match
Action: <i>start-min</i>	
...	

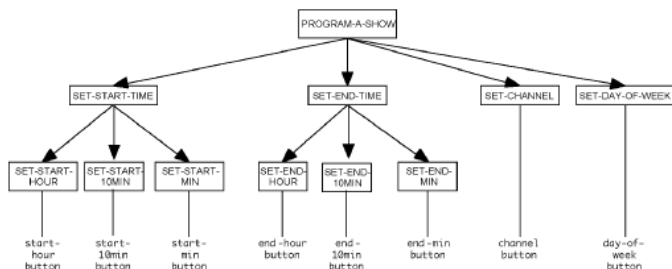
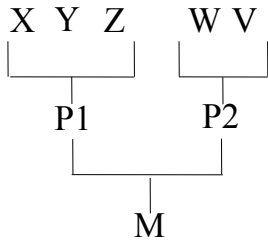
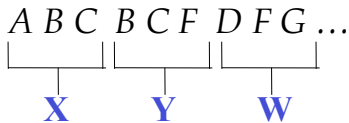


Figure 1. The simplified task-relevant hierarchical goal structure of a VCR interface (Gray, 2000; Gray & Fu, 2000).

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Using the Hierarchical Goal Structure of Figure 1

Trace	Validation results
Push goal: PROGRAM-SHOW	Push goal match
Push goal: SET-START-TIME	Push goal match
Push goal: SET-START-HOUR	Push goal match
Action: <i>start-hour</i>	
Action: <i>start-hour</i>	
Pop goal: SET-START-HOUR	Pop goal match
Push goal: SET-START-10MIN	Push goal match
Action: <i>start-10min</i>	
Pop goal: SET-START-10MIN	Pop goal match
Pop goal: SET-START-TIME	Pop goal mismatch
Push goal: SET-CHANNEL	Push goal match
Action: <i>channel</i>	
Pop goal: SET-CHANNEL	Pop goal match
Push goal: SET-START-TIME	Push goal match
Push goal: SET-START-MIN	Push goal match
Action: <i>start-min</i>	
...	

Output Trace and Goodness-of-fit



Trace

Push M
 Push P1
 Push X
 Actions: A B C
 Pop X
 Push Y
 Actions: B C F
 Pop Y
 Pop P1
 Push P2
 Push W
 Actions: D F G
 Pop W
 ⋮

Validation Results

Push match
 Push match
 Push match

 Pop match
 Push match

 Pop match
 Pop mismatch
 Push match
 Push match

 Pop match

W
P2
M

Results

- 64 subjects, 1,228 trials, 51,232 actions
 - 8 grammars were constructed for each interface, each representing a structural pattern (a strategy)
 - Worst-fitting trial: 81.1%; best-fitting trial: 100% Average: 95.1% of the actions were captured by the grammars
 - By inspecting the results, we found change of strategies in different interfaces
-
- Two different hierarchies were used in the two interfaces
 - We also found differences in the higher-level patterns in the two interfaces
 - 15,245 higher-level patterns are parsed
 - 464 (3%) of the patterns were identified as mismatches between the data and the hierarchy



AT:ST Ratio – Analysis Time to Sequence Time

- Pre-Action Protocol Tracer
 - Gray (2000) estimated as 100:1
 - Analyzed data from 9 Ss, \approx 72 trials
- With the Action Protocol Tracer
 - For the 3 data sets described in the Fu 2001 the building of grammars, on average, took the researchers 2–3 h, and the average running time was about 1 h.
 - 1:10

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- SANLab-CM
 - SANLab - tool for Stochastic Analytic Network Cognitive Modeling
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- An extension of the tools used by Gray & John (1993) and Gray & Boehm-Davis (2000) & other studies
- Schweickert in numerous studies

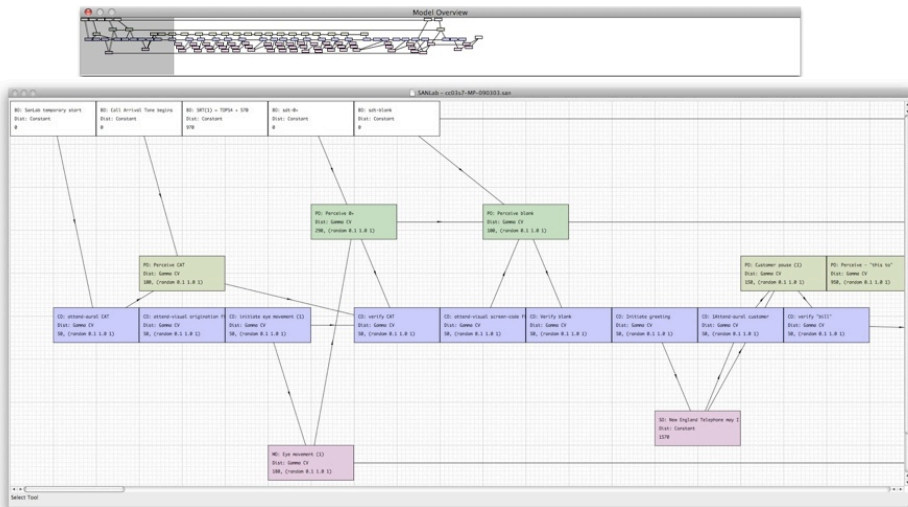
Schweickert, R., Fisher, D. L., & Proctor, R. W. (2003). Steps toward building mathematical and computer models from cognitive task analyses. *Human Factors*, 45(1), 77–103.

Schweickert, R. (1978). A critical path generalization of the additive factor method: Analysis of a Stroop task. *Journal of Mathematical Psychology*, 18(2), 105–139.

Gray, W. D., & Boehm-Davis, D. A. (2000). Milliseconds Matter: An introduction to microstrategies and to their use in describing and predicting interactive behavior. *Journal of Experimental Psychology: Applied*, 6(4), 322–335.

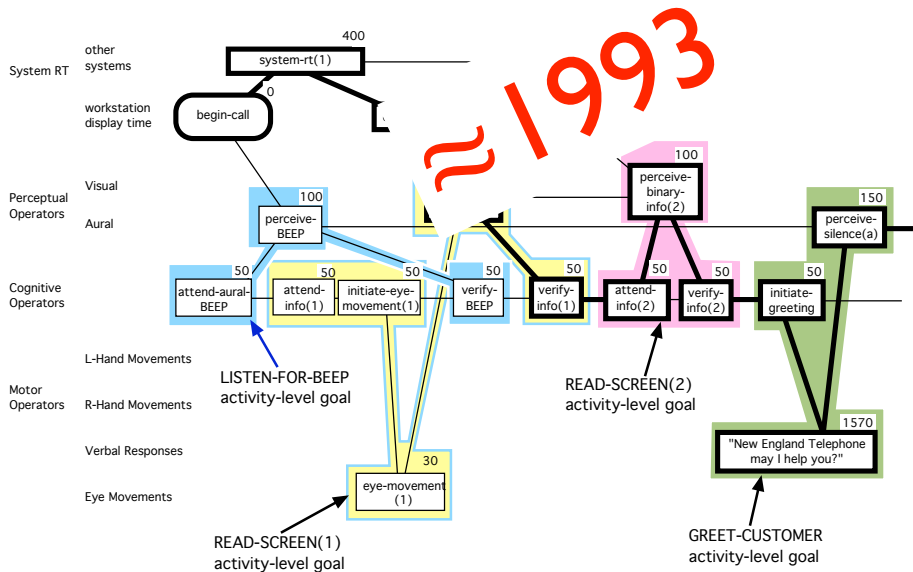
Gray, W. D., John, B. E., & Atwood, M. E. (1993). Project Ernestine: Validating a GOMS analysis for predicting and explaining real-world performance. *Human-Computer Interaction*, 8(3), 237–309.

Model Window and Model Overview Window



Telephone Operator Workstation

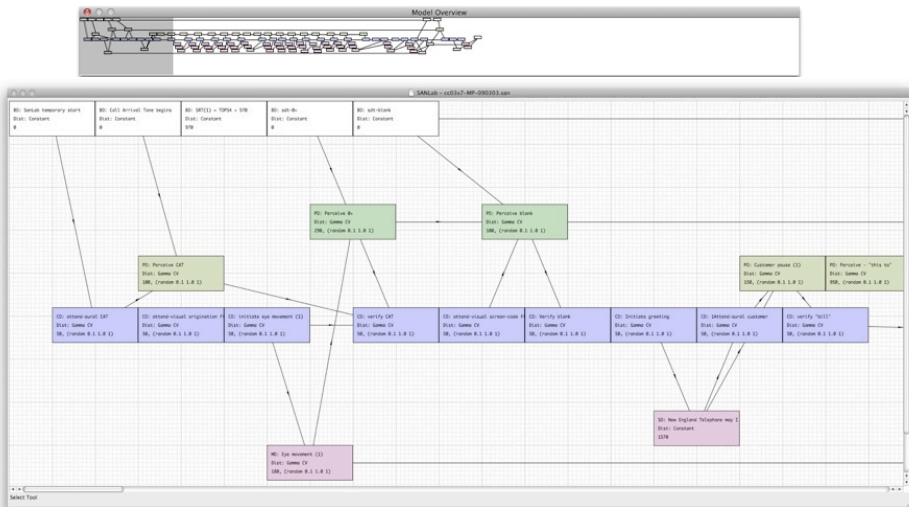
CPM-GOMS Level



SANLab-CM

- Stochastic Activity Network Laboratory for Cognitive Modeling
- Idea inspiring SANLab-CM
 - Cognitive, perceptual, and motor processes are inherently variable
 - This variability may result in changes in workload even when load conditions are constant
- Hence, SANLab-CM is a tool for analyzing and predicting variability with and without extra workload

Model Window and Model Overview Window

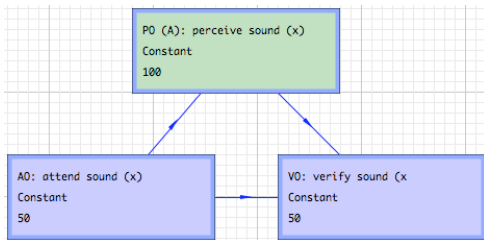


Example 1: Constructing a very simple CPM-GOMS model in SANLab

- Parts
- Interleaving
- Stochasticity
- Comparison of very simple models

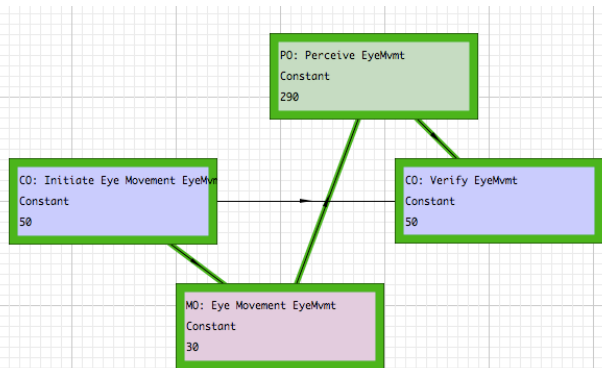
Building a Preliminary CPM-GOMS Model

CPM-GOMS Templates



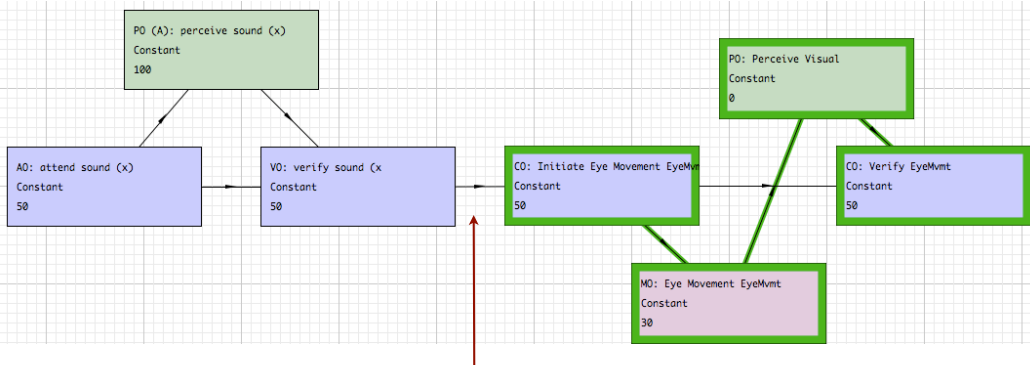
Perceive Simple Sound

Perceive Visual Information
With Eye Movement



Building a Preliminary CPM-GOMS Model

Cut & Paste & String Together

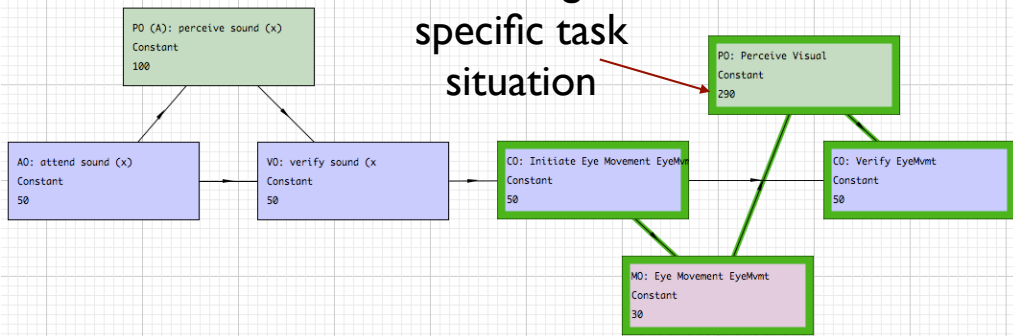


Inserted dependency line

Building a Preliminary CPM-GOMS Model

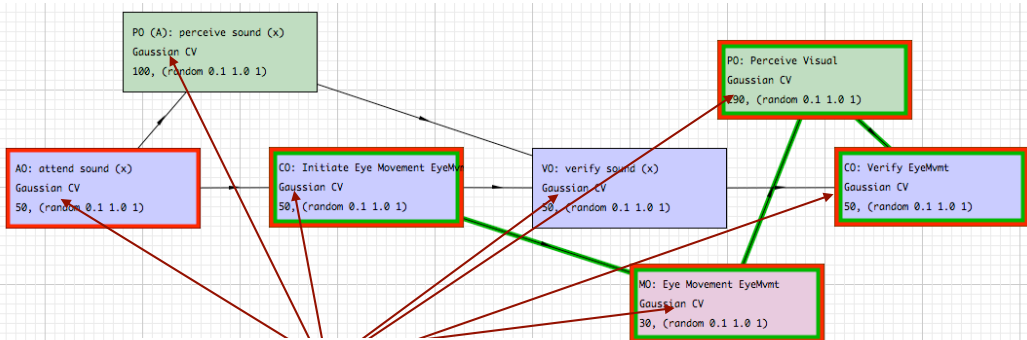
Insert Operator Durations

Inserted
duration
according to
specific task
situation



Building a Preliminary CPM-GOMS Model

Interleave Operators + Stochastic Operation Times



Gaussian Distribution
(randomly sampled on each
model run)

Building a Preliminary CPM-GOMS

Interleave Operators + Stochastic C

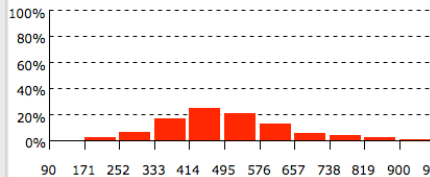
PO (A): perceive sound (x)
Gaussian CV
100, (random 0.1 1.0 1)

A0: attend sound (x)
Gaussian CV
50, (random 0.1 1.0 1)

C0: Initiate Eye Movement EyeMvt
Gaussian CV
50, (random 0.1 1.0 1)

VO: verify s
Gaussian CV
50, (random 0.1 1.0 1)

MO: Eye Movement EyeMvt
Gaussian CV
30, (random 0.1 1.0 1)



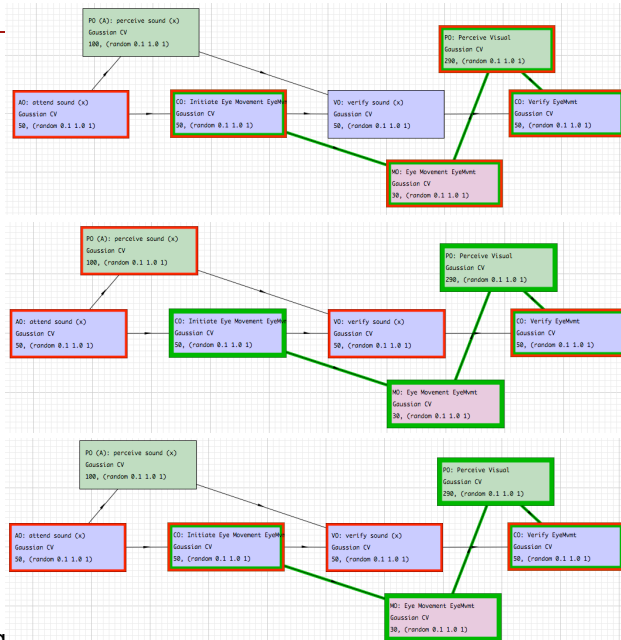
X-min = 90 X-max = 1320 Bin size = 81

Path statistics:

%	Mean	StDev	Min	Max	CPI	Path
100.00	490.42	165.40	146.51	1257.04	NIL	< Overall >
89.80	510.86	159.37	148.40	1257.04	0	attend sound (x)
9.40	317.30	92.47	146.51	578.41	1	attend sound (x)
.80	230.23	38.07	152.93	279.70	2	attend sound (x)

Three critical paths!
Different mean times!

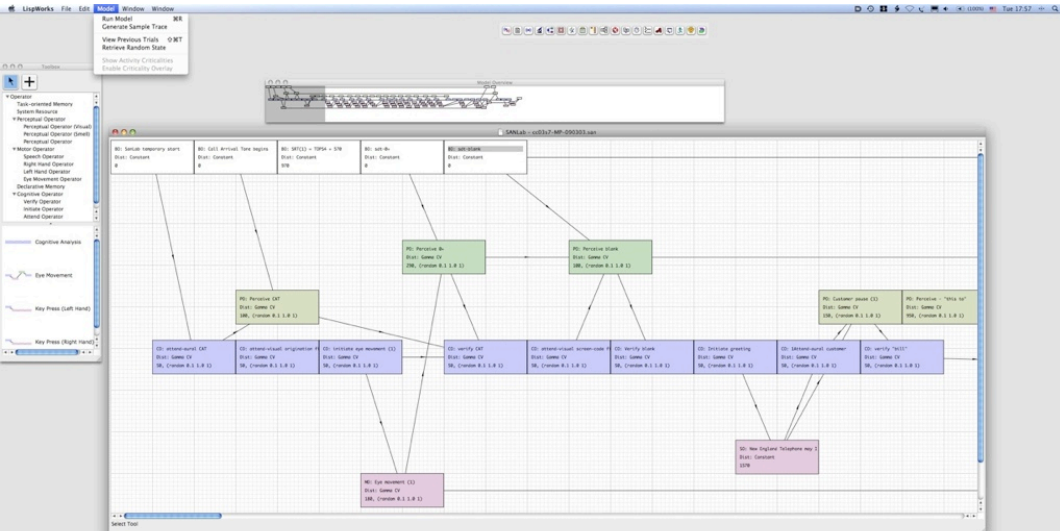
Three Critical Paths



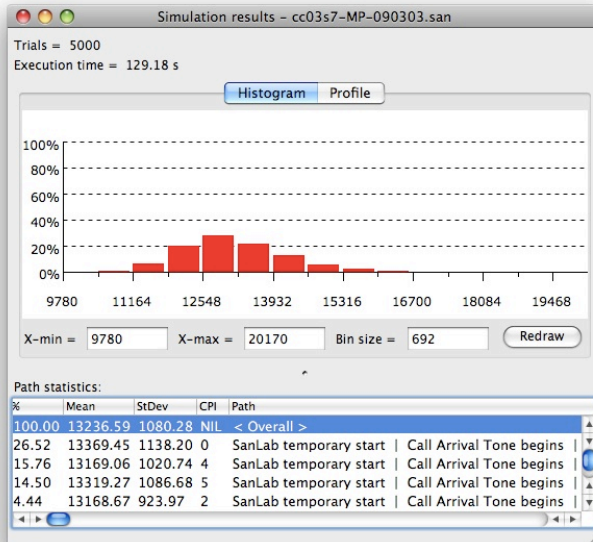
Very Simple Model: Summary

Interleaving	Fixed/ Stochastic	Critical Path	Predicted Times
No Interleaving	Fixed	One	620 ms
Interleaving	Fixed	One	470 ms
Interleaving	Stochastic	Average	490 ms
Interleaving	Stochastic	90%	511 ms
Interleaving	Stochastic	9%	317 ms
Interleaving	Stochastic	1%	230 ms

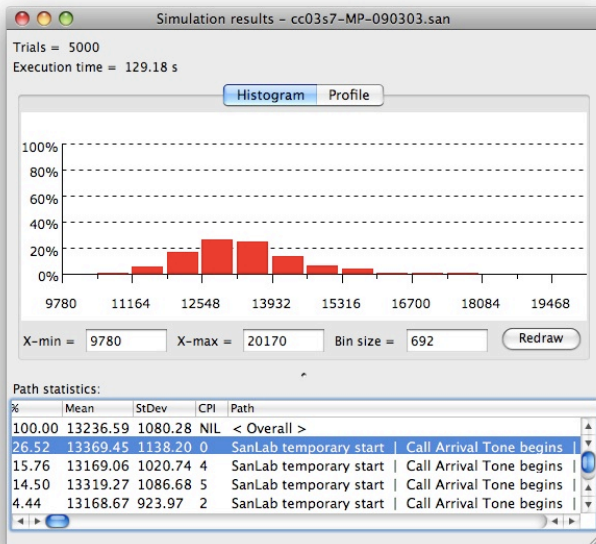
Running a Model 5,000 Times



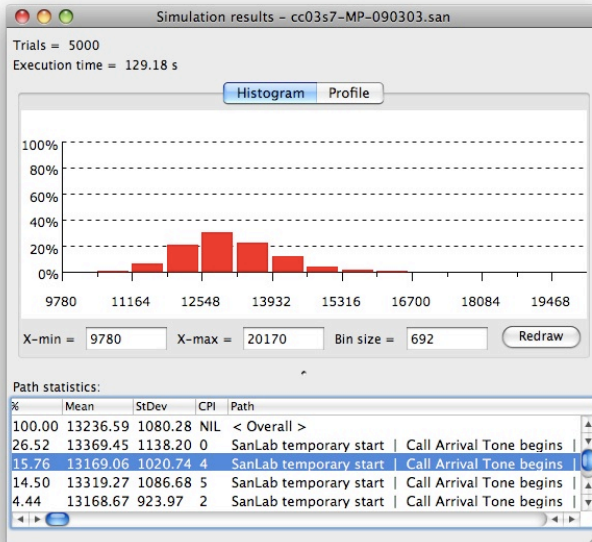
Histogram: Runtime Distribution of 5000 model runs – min ≈ 10 s, max ≈ 16 s



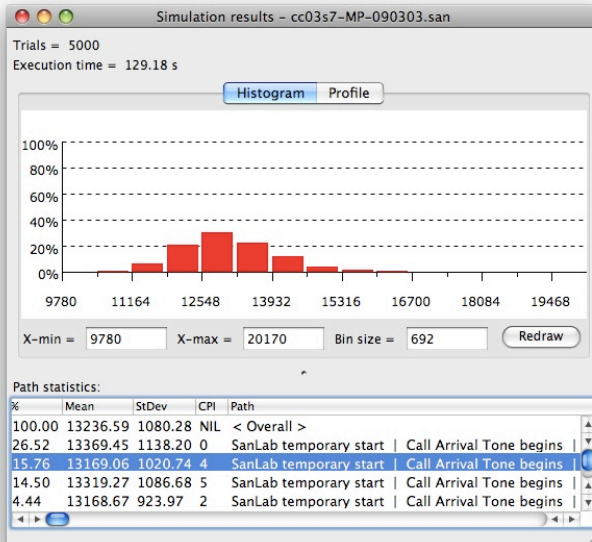
Most Frequent Critical Path Accounts for 27% of Runs



2nd Most Frequent Critical Path Accounts of 16% of Runs



2nd Most Frequent Critical Path Accounts of 16% of Runs



Demonstration of predicting the distribution of time taken by a skilled pilot to perform a routine task in the cockpit using CogTool and SANLab-CM

Bonnie E. John
Carnegie Mellon University
30 August 2011

Newell's Dream

- CogTool to SANLab is an important but limited step
- How about the ability to go from log files of people performing tasks directly to modeling?
- Newell's dream of an automatic protocol analyzer

Newell's Dream

- SANLab+
 - Requires cognitive architectures that encompass
 - Control of cognition
 - Cognition
 - Perception
 - Action
 - Ability to swap out architectural assumptions
 - For example, ACT-R, Soar, EPIC
 - Initial data sets will be taken from people performing three different paradigms

Newell's Dream

- SANLab+
 - Initial data sets will be taken from people performing three different paradigms
 - PRP – psychological refractory period
 - Behaviorally this is a very simple response time paradigm
 - NavBack – a dual-task paradigm
 - Continuous motor movement
 - Eye movements
 - Working memory maintenance
 - DMAP – Decision Making Argus Prime
 - Complex visual search and decision making task

Then & Now

- MacSHAPA
 - MacSHAPA (1995's) - Submarine Commanders: managing complexity of verbal and action protocols
 - MacSHAPA Cognitive Metrics Profiling
- Action Protocol Tracer
 - Finite state grammars for pattern recognition in action protocol data
- SANLab
 - SANLab - tool for Stochastic Analytic Network modeling +++
 - Automating production of cognitive models from behavioral/ action protocol analysis

The image features four brass gears of varying sizes interlocked on a solid blue background. The largest gear is at the top left, with three smaller gears meshing with it. A fourth gear is at the bottom right. The gears have a polished, metallic finish with visible teeth and central hubs. The text "Thank You!" is superimposed in the upper-middle area.

Thank You!