



**Michigan
Technological
University**

MEEM 4707: Autonomous system

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Lab - 2

By

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Problem 1

Following are incorrect ROS commands. Rearrange command keywords in the correct order:

1. package_name node_file.py rosrun
roslaunch package_name node_file.py
2. launch_file.launch roslaunch package_name
roslaunch package_name launch_file.launch

Problem 2

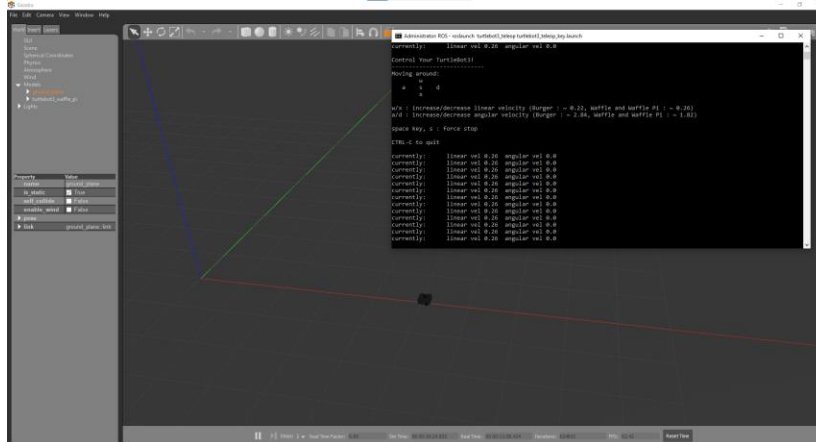
What is the difference between rosrunch and roslaunch commands?

Rosrun, a command from the rosbash module, is used for running programs from the shell (BASH). Roslaunch, however, is used to launch one or more ROS nodes.

1. Write the command to run a python node named: "test_node.py" present in a ROS package named: "test_package"
roslaunch test_package test_node.py
2. Write the command to run a launch file named: "test.launch" present in a ROS package named: "test_package"
roslaunch test_package test.launch

Problem 3

1. Move the robots using teleop command and capture the motion (You may use snipping tools. Do not take a photo of screen with a phone.)



2. Write the maximum speed of the turtlebot.
Note: The robot can be moved by pressing the keys only if the corresponding window terminal running the teleop command is active
Max linear velocity: 0.26