

$$T(x, t)$$

$$\dot{q}_x - \dot{q}_{x+dx} + \dot{\bar{E}}_y = \dot{E}_{st} \quad !$$

$$\dot{q}_{x+dx} = \dot{q}_x + \frac{d\dot{q}_x}{dx} dx + \dots$$

$$-\frac{d\dot{q}_x}{dx} dx + \dot{\bar{E}}_y = \dot{E}_{st}$$

$$-\frac{\partial}{\partial x} \left(-K A \frac{dT}{dx} \right) dx + \dot{q} \cancel{A dx} = \frac{\partial}{\partial t} \left(\rho A \cancel{dx} C_p T \right)$$

$$\div (A dx)$$

$$\frac{\partial}{\partial x} \left(K \frac{\partial T}{\partial x} \right) + \dot{q} = \frac{\partial}{\partial t} (\rho C_p T) \quad \underbrace{\left(\frac{K}{\rho C_p} \right)}_{\alpha} \frac{\partial^2 T}{\partial x^2} + \frac{\dot{q}}{\rho C_p} = \frac{\partial T}{\partial t}$$

- Estacionario $\frac{\partial}{\partial t} = 0$

- prop. cts K, ρ, C_p

- sin generación $\dot{q} = 0$

$$K \frac{d^2 T}{dx^2} = 0$$

$$\frac{d^2 T}{dx^2} = 0$$

$$d \left(\frac{dT}{dx} \right) = 0 \quad dx$$

$$\int \frac{d^2 T}{dx^2} dx = 0$$

$$\frac{dT}{dx} + C_1 = 0 \Rightarrow$$

$$\frac{dT}{dx} = -C_1$$

$$\dot{q}_x = -KA \frac{dT}{dx} = cte$$

$$q_x = -KA(-c_1)$$

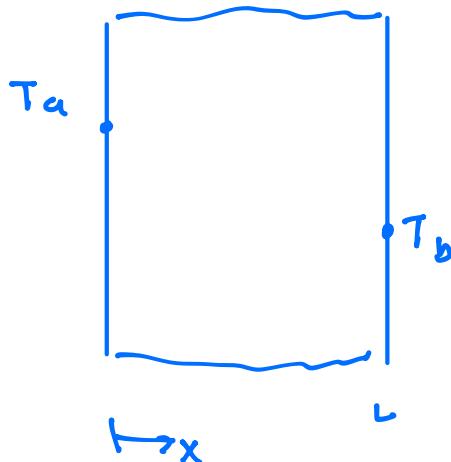
$$q_x = KA C_1$$

$$C_1 = \frac{q_x}{KA}$$

$$\int \left(\frac{dT}{dx} + c_1 \right) dx = \int q dx$$

$$T + c_1 x + c_2 = 0 \Rightarrow T = -c_1 x - c_2$$

$$T = -\frac{q_x}{KA} - c_2$$



$$x=0 \quad T(0)=T_a$$

$$x=L \quad T(L)=T_b$$

$$T_a + c_1(0) + c_2 = 0$$

$$T_b + c_1(L) + c_2 = 0$$

$$c_1 = \frac{T_b - T_a}{L} \quad c_2 = -T_a$$

$$\left\{ \begin{array}{l} T(x) = \frac{T_b - T_a}{L} x + T_a \\ q(x) = KA \left(\frac{T_a - T_b}{L} \right) \end{array} \right.$$

$$K \frac{d^2T}{dx^2} + \dot{q} = 0$$

$$\frac{d^2T}{dx^2} = -\frac{\dot{q}}{K}$$

$$\int d\left(\frac{dT}{dx}\right) = \int -\frac{\dot{q}}{K} dx$$

$$\frac{dT}{dx} = -\frac{\dot{q}}{K} x + C_1$$

$$dT = \left(-\frac{\dot{q}}{K} x + C_1 \right) dx$$

$$T = -\frac{\dot{q}}{2K} x^2 + C_1 x + C_2$$

$$g_x = -KA \frac{dT}{dx} = -KA \left(-\frac{\dot{q}}{K} x + C_1 \right)$$

$$T_a = C_2$$

$$T_b = -\frac{\dot{q}}{2k} \quad \downarrow^2 + C_1 L + C_2$$

$$T(x) = -\frac{\dot{q}}{2k} x^2 + \left(\frac{L^2 q - 2T_a k + 2T_b k}{2Lk} \right) x + T_a$$

$$\dot{q}(x) = -KA \frac{dT}{Jx} = KA \left(-\frac{\dot{q}}{k} x + \left(\frac{L^2 q - 2T_a k + 2T_b k}{2Lk} \right) \right)$$