

$$X = \begin{bmatrix} x_0 & x_1 & x_2 \\ x_0 & x_1 & x_2 \\ x_0 & x_1 & x_2 \end{bmatrix}$$

$$Y = \begin{bmatrix} y_0 & y_1 & y_2 \\ y_0 & y_1 & y_2 \\ y_0 & y_1 & y_2 \end{bmatrix}$$

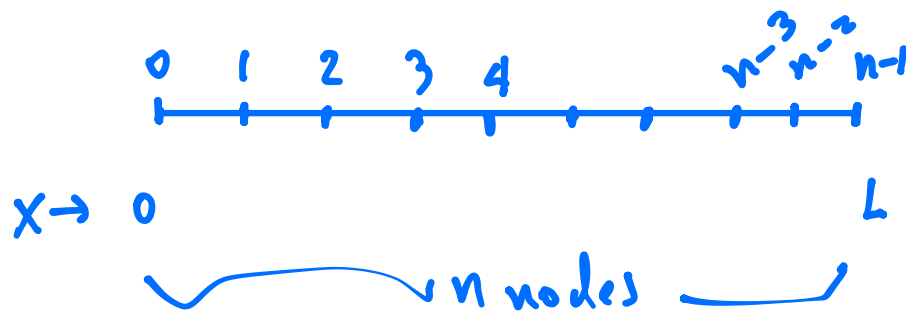
$(x_0, y_0)$   $(x_0, y_1)$   $(x_0, y_2)$   
 $(x_1, y_0)$   $(x_1, y_1)$   $(x_1, y_2)$

$$\frac{d^2 T}{dx^2} = -f(x)$$

Finite differences  
F-D

$$x=0 \quad T(0) = T_a$$

$$x=L \quad T(L) = T_b$$



$$\Delta x = \frac{L}{n-1}$$

$$\left. \frac{dT}{dx} \right|_x \approx \frac{T(x+\Delta x) - T(x)}{\Delta x} = \frac{dT}{dx} \Big|_{\Delta x \rightarrow 0} \rightarrow f'$$

$T_{i+1}$                    $T_i$

$$\left. \frac{dT}{dx} \right|_x \approx \frac{T(x) - T(x-\Delta x)}{\Delta x}$$

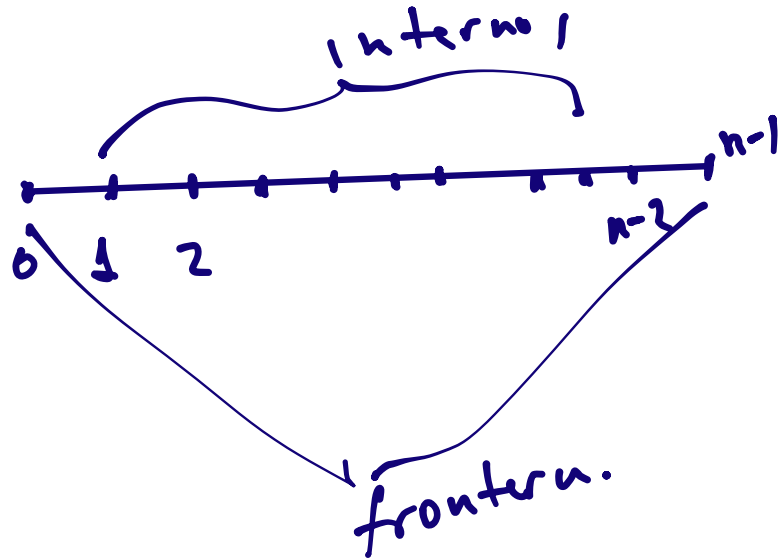
$T_i$                    $T_{i-1}$

$$\left. \frac{dT}{dx} \right|_x \approx \frac{T(x+\Delta x) - T(x-\Delta x)}{2\Delta x}$$

$T_{i+1}$                    $T_{i-1}$

$$\left. \frac{d^2 T}{dx^2} \right|_x \approx \frac{T^{T_{i+1}}(x+\Delta x) - 2T^T_i(x) + T^{T_{i-1}}(x-\Delta x)}{\Delta x^2}$$

$$\left. \frac{d^2 T}{dx^2} \right|_i = -f(x_i)$$



$$\left\{ \begin{array}{l} \frac{T_{i+1} - 2T_i + T_{i-1}}{\Delta x^2} = -f(x_i) \quad i = 1, 2, 3, \dots, n-2 \end{array} \right.$$

$$\left\{ \begin{array}{l} T_0 = T_u \\ T_{n-1} = T_b \end{array} \right. \quad i=1 \quad \frac{T_2 - 2T_1 + T_0}{\Delta x^2} = -f(x_1)$$

$$\checkmark \quad i=2 \quad \frac{T_3 - 2T_2 + T_1}{\Delta x^2} = -f(x_2)$$

$$i=3 \quad \frac{T_4 - 2T_3 + T_2}{\Delta x^2} = -f(x_3)$$

⋮

$$T_0 = T_a$$

$$T_{n-1} = T_b$$

$$\begin{matrix}
 0 \\
 1 \\
 2 \\
 \vdots \\
 n-1
 \end{matrix}
 \begin{bmatrix}
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 \frac{1}{\Delta x^2} & \frac{-2}{\Delta x^2} & \frac{1}{\Delta x^2} & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & \frac{1}{\Delta x^2} & \frac{-2}{\Delta x^2} & \frac{1}{\Delta x^2} & 0 & 0 & 0 & 0 & 0 \\
 \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1
 \end{bmatrix}
 \begin{bmatrix}
 T_0 \\
 T_1 \\
 \vdots \\
 T_{n-1}
 \end{bmatrix}
 =
 \begin{bmatrix}
 T_a \\
 -f(x_1) \\
 -f(x_2) \\
 \vdots \\
 T_b
 \end{bmatrix}$$

$$\begin{matrix}
 [A] \\
 n \times n
 \end{matrix}
 \{T\} = \{B\}$$