

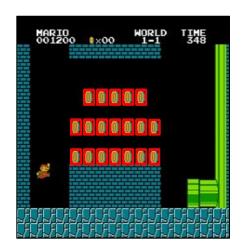
Image Recognition

# COMPUTER VISIONS

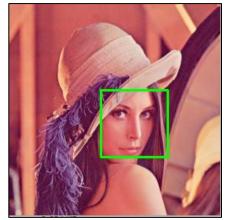
**01416500**Course Code

Overview

1. Template Matching



2. Face Detection



**Asst. Prof. Dr. Anakkapon Saenthon**King Mongkut's Institute of Technology Ladkrabang



What is template matching?

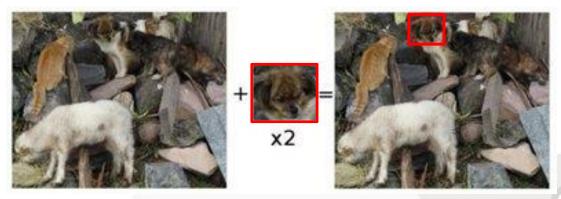
Template matching is a technique for finding areas of an image that match (are similar) to a template image (patch).

We need **two** primary components:

- Source image (I): The image in which we expect to find a match to the template image
- II. Template image (T): The patch image which will be compared to the template image



## Our goal is to detect the highest matching area:



By **sliding**, we mean moving the patch one pixel at a time (left to right, up to down).

To identify the **matching area**, we have to **compare** the template image against the source image by sliding it:

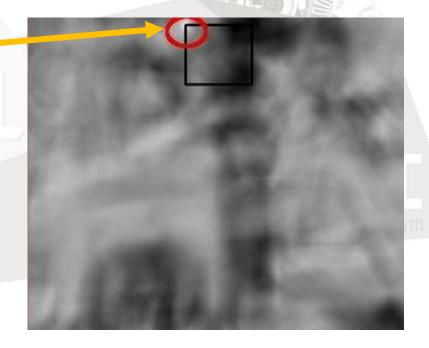




- Several comparison methods are implemented in OpenCV,
- It returns a <u>grayscale image</u>, where each pixel denotes how much does the neighborhood of that pixel match with template.

Some location maximum result

For each location of T over I, you store the metric in the result matrix (R). Each location (x,y) in R contains the match metric:





Which are the matching methods available in OpenCV

1. method=CV\_TM\_SQDIFF

$$R(x,y) = \sum_{x',y'} (T(x',y') - I(x + x',y + y'))^2$$
 (Min)

2. method=CV\_TM\_SQDIFF\_NORMED

$$R(x,y) = \frac{\sum_{x',y'} (T(x',y') - I(x+x',y+y'))^2}{\sqrt{\sum_{x',y'} T(x',y')^2 \cdot \sum_{x',y'} I(x+x',y+y')^2}}$$
 (Min)

3. method=CV\_TM\_CCORR

$$R(x,y) = \sum_{x',y'} (T(x',y') \cdot I(x+x',y+y')) \text{ (Max)}$$



4. method=CV\_TM\_CCORR\_NORMED

$$R(x,y) = \frac{\sum_{x',y'} (T(x',y') \cdot I(x+x',y+y'))}{\sqrt{\sum_{x',y'} T(x',y')^2 \cdot \sum_{x',y'} I(x+x',y+y')^2}}$$
 (Max)

5. method=CV\_TM\_CCOEFF

$$R(x,y) = \sum_{x',y'} (T'(x',y') \cdot I(x+x',y+y'))$$
 (Max)

where

$$\begin{array}{l} T'(x',y') = T(x',y') - 1/(w \cdot h) \cdot \sum_{x'',y''} T(x'',y'') \\ I'(x+x',y+y') = I(x+x',y+y') - 1/(w \cdot h) \cdot \sum_{x'',y''} I(x+x'',y+y'') \end{array}$$

6. method=CV\_TM\_CCOEFF\_NORMED

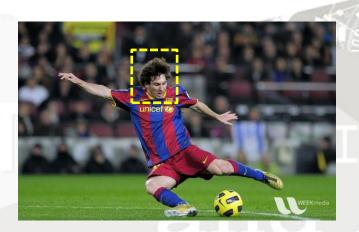
$$R(x,y) = \frac{\sum_{x',y'} (T'(x',y') \cdot I'(x+x',y+y'))}{\sqrt{\sum_{x',y'} T'(x',y')^2 \cdot \sum_{x',y'} I'(x+x',y+y')^2}} \quad \text{(Max)}$$



Here, as an example, we will search for Messi's face in his photo.

So if created a template as below:





We will try all the comparison methods so that we can see how their results look like:



OpenCV function:

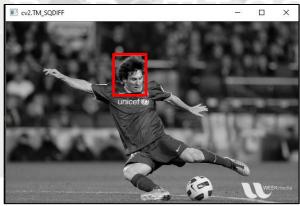
# cv2.matchTemplate()

```
import cv2
import numpy as np
from matplotlib import pyplot as plt
img = cv2.imread('dataset/messi.jpg',0)
template = cv2.imread('dataset/template.jpg',0)
w= template.shape[1]
h= template.shape[0]
method = cv2.TM_SQDIFF
res = cv2.matchTemplate(img,template,method)
min val, max val, min loc, max loc = cv2.minMaxLoc(res)
top_left = min_loc
bottom_right = (top_left[0] + w, top_left[1] + h)
cv2.rectangle(img,top_left, bottom_right, 255, 2)
# cv2.imshow("Gray",res)
cv2.imshow("cv2.TM_SQDIFF",img)
cv2.waitKey()
cv2.destroyAllWindows()
```

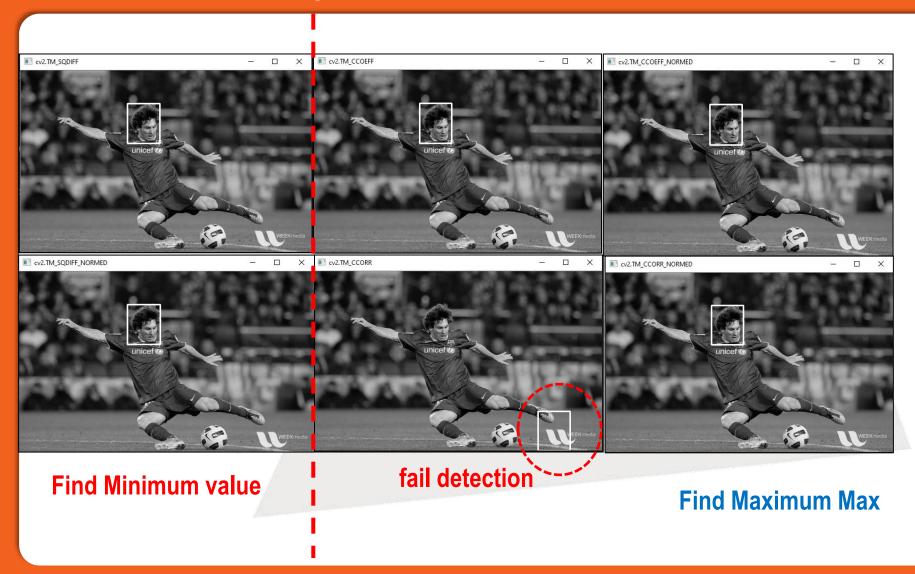


#### Template image











# Quiz 1 (15 min)

Let you show the location of coins in "mario.png" and template image "mario\_coin.png" (free to select template matching method)



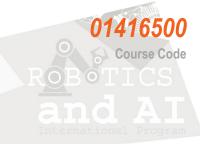
Output image



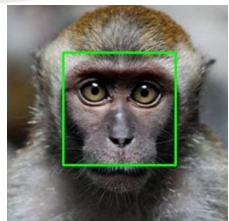


Image Recognition

# COMPUTER VISIONS







**Face Detection** 



#### What is "Face Detection"?

Face detection is a type of application classified under "**computer vision**" technology. It is the process in which algorithms are developed and trained to properly locate faces or objects (in object detection, a related system), in images.

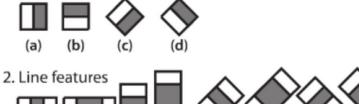
Face detection uses *classifiers*, which are algorithms that detects what is either a face(1) or not a face(0) in an image. Classifiers have been trained to detect faces using thousands to millions of images in order to get more accuracy.

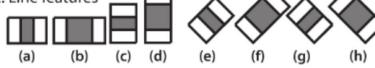


# **Understanding Haar Cascades**

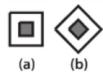
A sequence of rescaled "**square-shaped**" functions which together form a wavelet family or basis.







3. Center-surround features

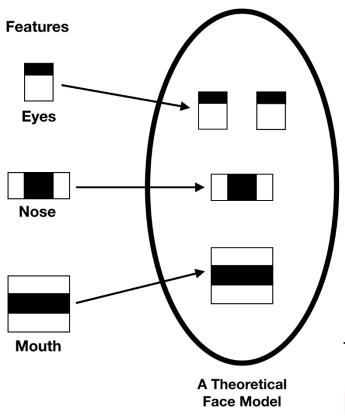


**Face Detection** determines the locations and sizes of human faces in arbitrary (digital) images.

In **Face Recognition**, the use of Face Detection comes first to determine and isolate a face before it can be recognized.



#### **Feature Extraction**

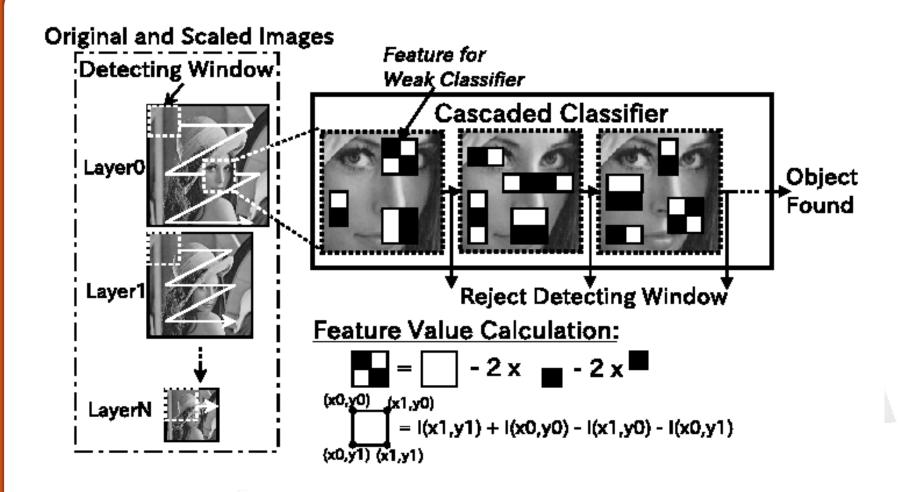


Haar Cascades use machine learning techniques in which a function is trained from a lot of positive and negative images.

This process in the algorithm is feature extraction.

The training data used in this project is an XML file called:

haarcascade\_frontalface\_default.xml



Ref: A low-power Adaboost-based object detection processor using Haar-like features



This contains code parameters that are the most important to consider.

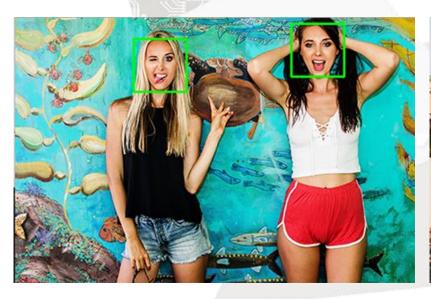
**scaleFactor:** The value indicates how much the image size is reduced at each image scale. A lower value uses a **smaller step for downscaling**. This allows the algorithm to detect the face. It has a value of x.y, where x and y are arbitrary values, you can set.

minNeighbors: This parameter specifies how many "neighbors" each candidate rectangle should have. A higher value results in less detections but it detects higher quality in an image.

minSize: The minimum object size. By default it is (30,30). The smaller the face in the image, it is best to adjust the minSize value lower.

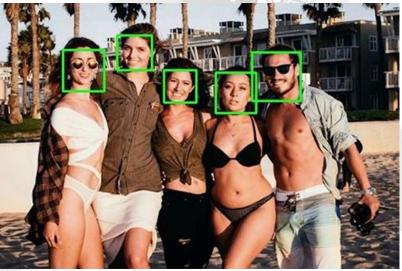
Parameters:

scaleFactor=1.4, minNeighbors=1, minSize=(10,10),



Parameters:

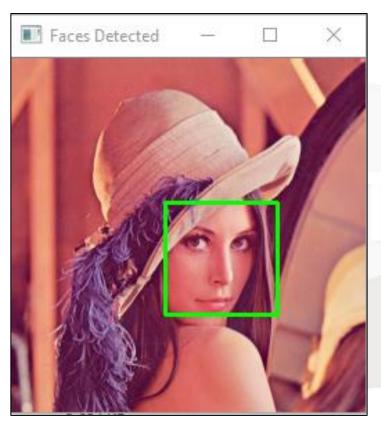
scaleFactor=1.6, minNeighbors=2, minSize=(20,20),



Ref: https://becominghuman.ai/face-detection-using-opencv-with-haar-cascade-classifiers-941dbb25177



#### Running OpenCV



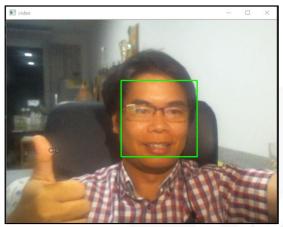
#### OpenCV function:

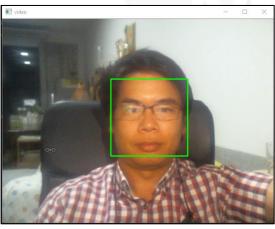
# faceCascade.detectMultiScale()

```
import cv2
cascPath = "dataset/haarcascade_frontalface_default.xml"
faceCascade = cv2.CascadeClassifier(cascPath)
image = cv2.imread("dataset/lena_color_256.tif")
gray = cv2.cvtColor(image, cv2.COLOR BGR2GRAY)
faces = faceCascade.detectMultiScale(
    gray,
    scaleFactor=1.1,
    minNeighbors=5,
    minSize=(1,1),
    flags = cv2.CASCADE_SCALE_IMAGE
print("Detected {0} faces!".format(len(faces)))
for (x, y, w, h) in faces:
    cv2.rectangle(image, (x, y), (x+w, y+h), (0, 255, 0), 2)
cv2.imshow("Faces Detected", image)
cv2.waitKey(0)
```



#### This example for video capture

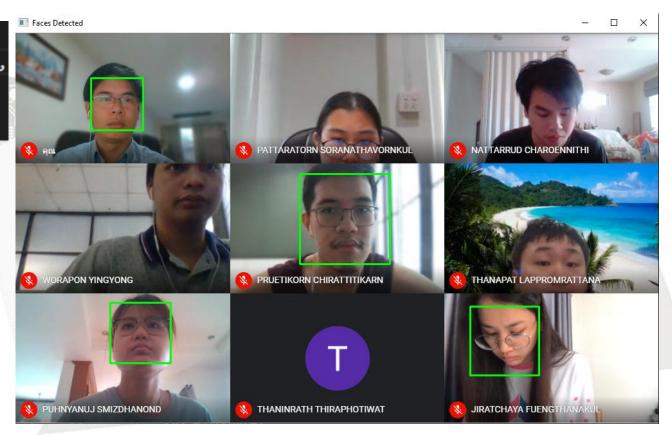




```
import numpy as np
import cv2
faceCascade = cv2.CascadeClassifier(
    'dataset/haarcascade frontalface default.xml')
cap = cv2.VideoCapture(0)
cap.set(3,640) # set Width
cap.set(4,480) # set Height
while True:
   ret, img = cap.read()
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
   faces = faceCascade.detectMultiScale(
        gray,
        scaleFactor=1.2,
        minNeighbors=5,
        minSize=(20, 20)
    for (x,y,w,h) in faces:
        cv2.rectangle(img,(x,y),(x+w,y+h),(0,255,0),2)
        roi_gray = gray[y:y+h, x:x+w]
        roi_color = img[y:y+h, x:x+w]
    cv2.imshow('video',img)
    k = cv2.waitKey(30) & 0xff
   if k == 27: # press 'ESC' to quit
        break
cap.release()
cv2.destroyAllWindows()
```



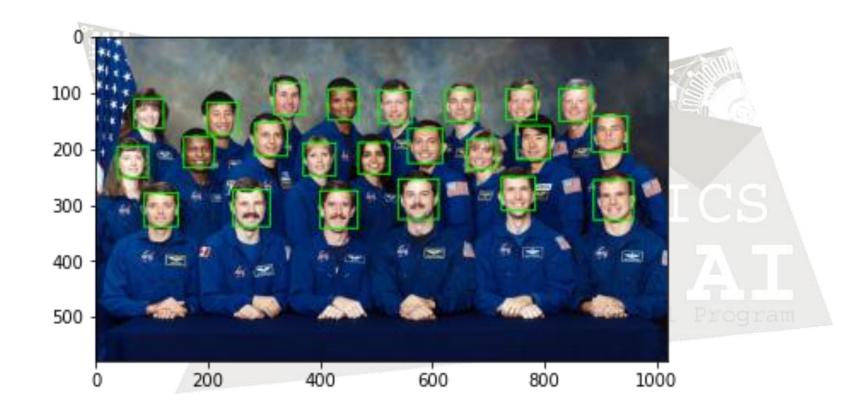
gray,
scaleFactor=1.2,
minNeighbors=6,
minSize=(20,20)





# Quiz 2 (15 min)

# Find all face in "NASA.jpg" image



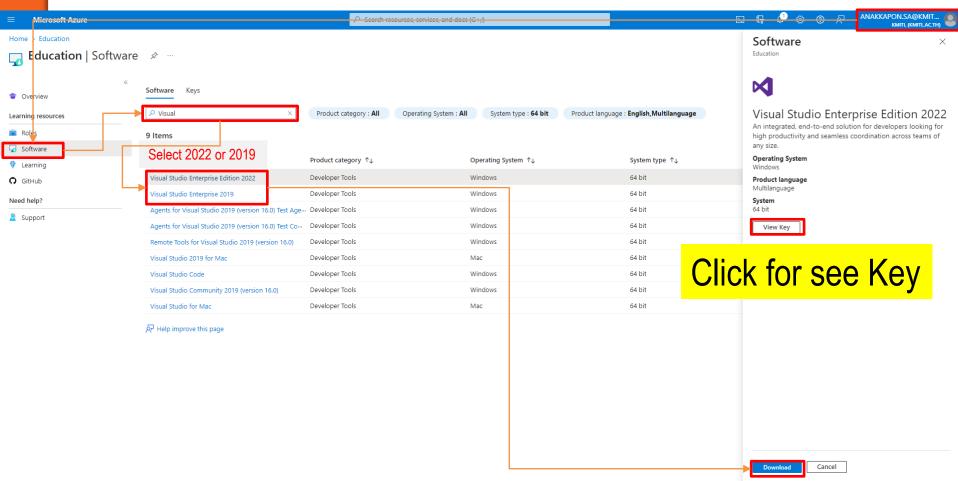


## Next class

#### Download Visual Studio C# .NET

https://azureforeducation.microsoft.com/devtools

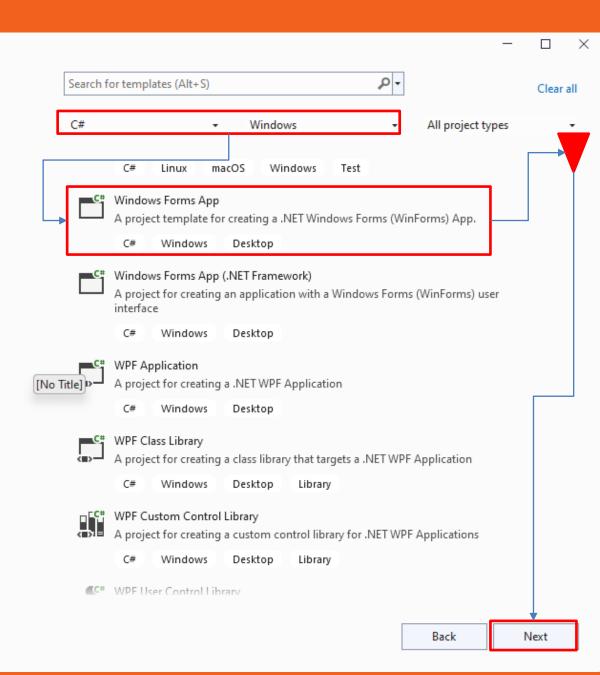
#### KMITL account login



#### Create a new project

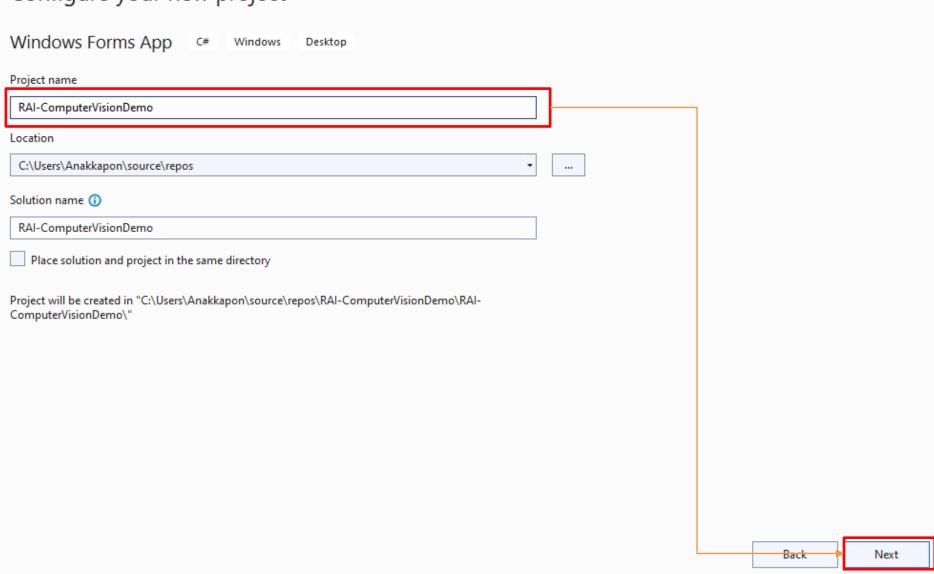
#### Recent project templates

A list of your recently accessed templates will be displayed here.





#### Configure your new project





# Assignment#9.3

- 1. Preparation software of Visual Studio .NET C# (version 2019 or 2022)
- 2. Capture Visual Studio .NET C# screen
- 3. Submitting an image file to MS-TEAM

