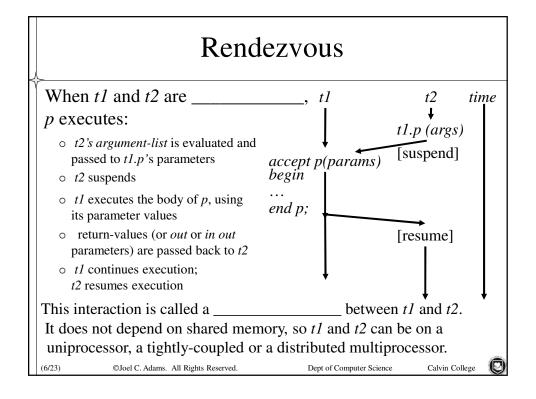


An Ada Task ... has 3 characteristics: • its own _____ of control; • its own _____; and _____ (aka entry procedures) Entry procedures are self-synchronizing subprograms that another task can invoke for task-to-task communication. If task t1 has an entry procedure p, then another task t2 can execute: *t1.p(argument-list);* In order for *p* to execute, *t1* must execute: accept p (parameter-list); - If t1 executes accept p and t2 has not called p, _____ - If t2 calls p and t1 has not done accept p, _____ ©Joel C. Adams. All Rights Reserved. Dept of Computer Science Calvin College



Ada Array Processing

```
How can we rewrite what's below to complete more quickly?
 procedure sumArray is
   N: constant integer := 1000000;
    type RealArray is array(1..N) of float;
    anArray: RealArray;
    function sum(a: RealArray; first, last: integer)
                 return float is
      result: float := 0.0;
   begin
      for i in first..last loop
        result := result + a(i);
      end loop;
     return result;
    end sum;
    -- code to fill anArray with values omitted
   put( sum(anArray, 1, N) );
 end sumArray;
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```

Divide-And-Conquer via Tasks

```
procedure parallelSumArray is
  -- declarations of N, RealArray, anArray, Sum() as before ...
   task type ArraySliceAdder
      entry SumSlice(Start: in Integer; Stop: in Integer);
      entry GetSum(Result: out float);
   end ArraySliceAdder;
   task body ArraySliceAdder is
      i, j: Integer; Answer: Float;
   begin
    accept SumSlice(Start: in Integer; Stop: in Integer) do
      i:= Start; j:= Stop;
                                             -- get inputs
    end SumSlice;
    Answer := Sum(anArray, i, j);
                                             -- do the work
    accept GetSum(Result: out float) do
      Result := Answer;
                                             -- report outcome
    end GetSum;
   end ArraySliceAdder;
  -- continued on next slide...
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```

Divide-And-Conquer via Tasks (ii)

```
-- continued from previous slide ...
   firstHalfSum, secondHalfSum: Integer;
                                -- T1, T2 start & wait on accept
   T1, T2 : ArraySliceAdder;
  begin
     -- code to fill anArray with values omitted
    T1.SumSlice(1, N/2);
                                   -- start T1 on 1st half
     T2.SumSlice(N/2 + 1, N);
                                   -- start T2 on 2nd half
     T1.GetSum(firstHalfSum); -- get 1st half sum from T1
     T2.GetSum( secondHalfSum ); -- get 2nd half sum from T2
     put(firstHalfSum + secondHalfSum); -- we're done!
  end parallelSumArray;
Using two tasks T1 and T2, this parallelSumArray version requires
 roughly 1/2 the time required by sumArray (on a multiprocessor).
Using three tasks, the time will be roughly 1/3 the time of sumArray.
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```

Producer-Consumer in Ada

To give the producer and consumer separate threads, we can define the behavior of one in the 'main' procedure:

and the behavior of the other in a separate task:

We can then build a Monitorstyle *Buffer task* with *put()* and *get()* as (auto-synchronizing) entry procedures...

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```
procedure ProducerConsumer is
  buf: Buffer;
  it: Item;
```

```
task consumer;
task body consumer is
  it: Item;
begin
  loop
   buf.get(it);
   -- consume Item it
  end loop;
end consumer;
```

```
begin -- producer task
loop
    -- produce an Item in it
    buf.put(it);
end loop;
end ProducerConsumer;
```

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Capacity-1 Buffer

task type BoundedBuffer1 is A single-value buffer is entry get(it: out Item); easy to build using an entry put(it: in Item); end BoundedBuffer1; Ada task body BoundedBuffer1 is As a *task-type*, variables of myBuffer: Item; begin this type (e.g., buf) will automatically have their accept put(it: in Item) do myBuffer := it; own thread of execution. end put; The body of the task is a accept get(it: out Item) do loop that accepts calls to it := myBuffer; end get; put() and get() in strict end loop; alternation. end BoundedBuffer1;

This causes *buf* to alternate between being empty and nonempty.

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Capacity-N Buffer

An N-value buffer is a bit more work:

We can accept any call to *get()* so long as we are not empty, and any call to *put()* so long as we are not full.

Ada provides the *select-when* statement to ____

______, and perform it if and only if a given condition is *true*

```
-- task declaration is as before ...
task body BoundedBuffer is
```

N: constant integer := 1024;
 package Buf is new Queue(N, Items);
begin

loop

```
select
  when not Buf.isFull =>
    accept put(it: in Item) do
    Buf.append(it);
  end put;
  or when not Buf.isEmpty =>
    accept get(it: out Item) do
    it := Buf.first;
    Buf.delete;
  end get;
  end select;
and loop:
```

end loop;
end BoundedBuffer;

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MPI ...

... is the _____

... is an industry-standard library for distributed-memory parallel computing in C, C++, Fortran, with 3rd party bindings for Java, Python, R, ...

... was designed by a large consortium in 1994:

- •12 companies: Cray, IBM, Intel, ...
- •11 national labs: ANL, LANL, LLNL, ORNL, Sandia, ...
- representatives from 16 universities
- ... has "built in" support for many parallel design patterns
- ... continues to evolve (MPI 2.0 in 1997; 3.0 in 2012; ...)

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Typical MPI Program Structure

The 6 MPI Basic Functions

- MPI_Init(&argc, &argv);
 - Set up MPI_COMM_WORLD, a "communicator"

 (The set of processes that make up the distr. computation)
- MPI_Comm_size(MPI_COMM_WORLD, &numProcesses);
 - How many of us processes are there to attack the problem?
- MPI_Comm_rank (MPI_COMM_WORLD, &id);
 - -Which of the *n* processes am I?

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The 6 MPI Basic Functions (Ct'd)

- - Send the item(s) at *sendAddress* to *destinationRank*
- 5. MPI_Recv(receiveBuffer, bufferSize, itemType, senderID, tag, communicator, status);
 - Receive up to bufferSize items from senderRank
- 6. MPI_Finalize();
 - Shut down distributed computation

These 6 commands are all you need to do useful work!

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Other Useful Functions

- Broadcast bufferSize items from senderID to everyone in comm

- Use *combineOp* to combine the distributed items at *sendAddress* into *receiveBuffer* at *destinationRank*

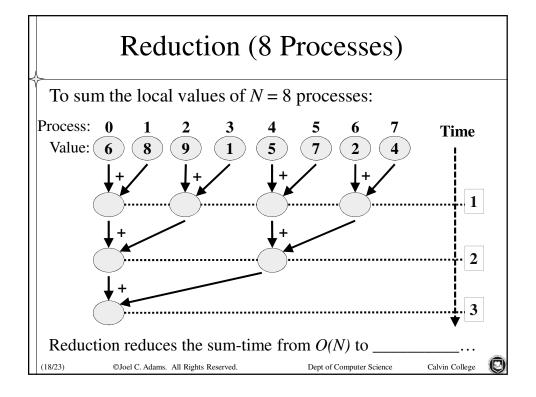
These (and many other) commands provide simple but efficient *collective communication*...

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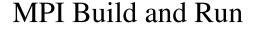
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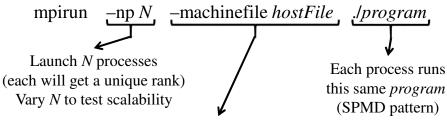
A Very Simple MPI Program

```
#include <iostream>
 #include <mpi.h>
 using namespace std;
 int main(int argc, char** argv) {
   int id = -1, n = -1;
     MPI_Init(&argc, &argv);
MPI_Comm_size(MPI_COMM_WORLD, &n);
     MPI_Comm_rank(MPI_COMM_WORLD, &id);
     int startValue = id+1;
     int square = startValue * startValue;
     int sumSquares = 0;
     MPI_Finalize();
     return 0;
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```



To build an MPI C++ *program* from the command line: mpiCC *program.cpp* –o *program*

To run an MPI program from the command line:



Launch those *N* processes on the computers listed in *hostFile* (optional ...)

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Testing sumSquares

```
$ mpirun -np 1 ./sumSquares
The sum of the squares from 1 to 1 is 1

$ mpirun -np 2 ./sumSquares
The sum of the squares from 1 to 2 is 5

$ mpirun -np 3 ./sumSquares
The sum of the squares from 1 to 3 is 14

$ mpirun -np 4 ./sumSquares
The sum of the squares from 1 to 4 is 30

$ mpirun -np 128 ./sumSquares
The sum of the squares from 1 to 128 is 707264

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```

Summary

		•					
• Con	ncurrent computations co in Smalltalk, MI in C/C++, C#, .		la				
•On a	a shared-memory multipi	cocessor:					
–Th	-The was the first synchronization primitive						
0	Java provides a Semaphore class	for synchronizing process	ses				
	and	separate a semapl	nore's mutual-				
exe	clusion usage (locks) from its	s synchronization usa	ge (c.v.s)				
	are higher-leve	el, self-synchronizing	objects				
0	Java classes have an associated (s	simplified) monitor					
•On a	a distributed system:						
-Aa	da tasks provide self-synchro	nizing					
$-E_{i}$	rlang, Scala, MPI support	betw	een processes				
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Summary (ii)									
Comparing Monitors and Tasks/Threads (and Coroutines):									
		Has Its Own Thread		Has Its Own Exc	as Its Own Execution State				
	Monitor								
	Task/Thread								
	Coroutine								
A coroutine (Simula, Lua) is two or more procedures that share a single thread, each exercising mutual control over the other:		procedure A; begin do something resume B; do something resume B; do something end A;		procedure B; begin do something resume A; do something resume A; end B;					
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