Evaluation of a Multimodal Interface for 3D Terrain Visualization

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Abstract

This paper describes an evaluation of various interfaces for visual navigation of a whole Earth 3D terrain model. A mouse driven interface, a speech interface, a gesture interface, and a multimodal speech and gesture interface were used to navigate to targets placed at various points on the Earth. Novel speech and/or gesture interfaces are candidates for use in future mobile or ubiquitous applications. This study measured each participant's recall of target identity, order, and location as a measure of cognitive load. Timing information as well as a variety of subjective measures including discomfort and user preferences were taken. While the familiar and mature mouse interface scored best by most measures, the speech interface also performed well. The gesture and multimodal interface suffered from weaknesses in the gesture modality. Weaknesses in the speech and multimodal modalities are identifed and areas for improvement are discussed.

Keywords: Multimodal interaction, evaluation, navigation, speech recognition, gesture recognition, virtual reality, mobile visualization, GIS.

1 Introduction

We believe that 3D visualizations will be among the mobile computing applications of the near future. Interaction with such mobile visualizations will be challenging. Users may be standing, moving, encumbered, or away from desktop surfaces. In any of these cases, tradition mouse and keyboard interfaces will be unavailable or unusable. Furthermore, the users may be attending to other tasks, spreading their cognitive resources thinly. We are investigating and characterizing candidate interfaces that could be used in mobile visualization. The interface must be unencumbering, expressive, and have low cognitive load.

In this paper, we evaluate a multimodal interface that might eventually be used in mobile visualization. This interface may be used with a visualization running on a wearable computer. The interface might also be used in an environment augmented with computers and displays. In this instance, the user might interact with the visualization while standing at a distance from any display or keyboard, or attending to another task. Since we are doing an initial evaluation on a prototyping environment, we have eschewed making the system entirely mobile so that we can concentrate on the interface elements. However, the user does have freedom to be away from the display and enjoys some freedom of movement.

We are interested in mobile visualization and its interfaces because increasing compactness and increasing computing power is becoming available in wearable and other mobile systems. In addition, wireless networking and geo-located services (using GPS and other devices) allows mobile systems to access potentially unlimited resources and inform that access with awareness of a user's location and context. Yet the ever smaller footprint of these devices and the fact that they will be carried and used everywhere makes the type of interface a critical issue. Without considering this issue, users may be faced with the prospect of having ever increasing resources at hand with less and less efficient ways of getting to them.

It is worthwhile to characterize and understand the inherent qualities of a speech and/or hand gesture interface rather than rejecting them in comparisons to more familiar and established interfaces. For many ubiquitous or mobile applications, these new interfaces may be the interfaces of choice because they best fit the environment and usage needs of the user. As mentioned earlier, in these applications, one may not have a mouse, keyboard, tracked 3D interaction device, or other wired device available. One may not have a desktop surface on which to operate. Furthermore, the user might stand apart from the display and computer or might be moving around. The user might also have her hands occupied either all or part of the time. Finally a speech and gesture interface with the appropriate affordances may not demand the attention or have the cognitive load of a traditional interface, which can be a key issue in many mobile visualization applications. For these and other reasons it is worthwhile to study the hand gesture and speech multimodal interface in their own right to understand their characteristics. The issue is then whether these interfaces perform effectively and accurately for its tasks, and if they do not, what characteristics need to be improved.

This paper builds on previous work[6], which provides a more detailed description of the interface architecture and implementation. The basic modes of interaction are hand gestures, captured by a camera worn on a user's chest, and speech recognition. These modes were used both separately and together for 3D navigation. This paper focuses on the formal evaluation of an initial multimodal interface in the context of a geospatial visualization system. This is the type of system that will be used in many location-aware applications. The extended navigation properties of the system provide a rich environment for testing the multimodal interface. In addition, a variety of other interface paradigms have been used with this system.

2 Related Work

There has been keen interest in multimodal control interfaces for a long period of time. Early work like Bolt's "Put That There" has been followed by a large number of systems and studies. Some related work in multimodal interfaces and visualization is discussed below.

MSVT, the Multimodal Scientific Visualization Tool[4] is a semi-immersive visualization environment for exploring scientific

data such as fluid flow simulations. The interface is composed of a pair of electro-magnetically tracked pinch gloves and voice recognition. Voice recognition provides over 20 commands and the gloves provide a variety of navigation, manipulation, and picking techniques. Visualization tools such as streamlines, rakes, and color planes are available. In our work we track hands without gloves, which encourages a more natural and unencumbered interaction. Furthermore, our visualization is a global terrain visualization with an extended range of scale, requiring richer navigation techniques.

Sharma et al.[10] describe another multimodal testbed composed of a virtual environment called MDScope and a graphical front-end called VMD. This system allows structural biologists to simulate the interaction of biomolecular structures. Interaction is through a simple command language composed of spoken actions executed with objects and parameters composed of both speech and gesture. The voice recognition system spots words from a continuous stream of speech while video streams from two fixed cameras are processed to yield 3D finger pointing and simple hand gestures. Our system uses a body mounted camera, so user mobility is enhanced.

BattleView[9] is a virtual reality battlefield application for supporting planning and decision making developed by the National Center for Supercomputing Applications. Much like the MD-Scope/VMD application, 3D pointing and simple hand gestures form the gesture part of the multimodal interface. IBM ViaVoice forms the speech recognition system. A multimodal integration module combines the recognizer streams. A state diagram describes the command language that allows users to navigate as well as select and manipulate virtual objects. Stereoscopic displays such as workbenches and single rear projected screens are supported. Again, a fixed single camera mounted on the display is used for gesture recognition, as opposed to a body mounted camera.

Quickset is a 2D map application with a rich pen and speech interface developed at the Oregon Graduate Institute of Science and Technology[2]. Users can create and manipulate virtual entities on the map for a variety of applications, including medical informatics, military simulation and training, 3D terrain visualization, and disaster management. Quickset uses a 3 tier hierarchical recognition technique called Members-Teams-Committee. Member recognizers report results to one or more team leaders which apply various weighting schemes. These team leaders report to a committee which weights the results and provides a ranked list of multimedia interpretations. Each of these components is implemented as an agent that discover other components through a facilitator service. This allows a flexible and error robust system.

Quickset has also been adapted to Dragon[5], a battlefield visualization tool developed at the Naval Research Laboratory[3]. Features of the VR system include "digital ink" that is deposited on the 3D terrain surface by raycasting. This ink plays the same role as pen strokes in 2D Quickset applications. Also, a 3D speech and 3D gesture vocabulary is integrated with the now available 3D information. An example would be the query "How high is this hill (3D gesture)?" Our multimodal interface is based on speech and hand gesture, rather than speech and pen stroke as in Quickset. Pen gestures require some reference or interaction with the display surface. With a body mounted camera, users can be distant from the display and still interact.

3 Method

This study explored four interfaces for navigation in a 3D visualization. These interfaces included a mouse interface, a speech interface, a hand gesture interface, and a multimodal speech and gesture interface. This study also attempted to determine the impact of each interface on cognitive load as well as take subjective measures such as discomfort, user preference.
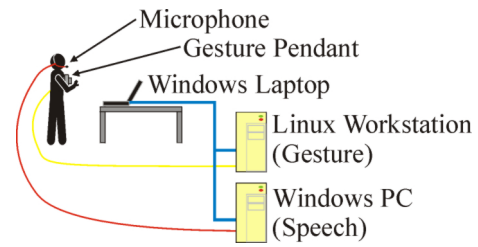

Figure 1: System Architecture

3.1 Participants

Twenty-four students were recruited from an undergraduate computer game design course. The participants were male, and most had experience with 3D graphics in gaming or 3D design applications. Some had used commercially available speech recognition in the form of PC applications or telephone information applications. A small number had used applications with hand or arm gesture recognition. While not representative of the population in general, this group should be adaptable to new interfaces.

3.2 Apparatus

The apparatus used in this experiment consisted of a Pentium III 800MHz laptop running the VGIS visualization application. A Linux workstation ran vision algorithms for the gesture recognition interface and sent packets with the results over a network to the laptop. A Windows NT system ran a speech recognition interface and also sent the results over a network to the laptop. A diagram of the system is in Figure 1.

3.2.1 VGIS

VGIS[7] is a 3D global geospatial visualization system that displays phototextures of the Earth's surface overlaid on 3D elevation data. Three dimensional models of buildings are also included for some urban areas. Recently, we have also included real-time 3D weather visualization in the VGIS framework. A hierarchical data organization allows the display of appropriate levels of detail and real time navigation of multiple gigabyte data sets.

VGIS supports a variety of 3D stereoscopic displays and interface devices such as mice, spaceballs, and Polhemus trackers. VGIS also supports a variety of navigation modes such as a downward-looking orbital mode, a helicopter-like fly mode, and a ground following walk mode. A variety of configuration options and navigation commands are available.

In this experiment, we used simplified navigation interfaces to minimize the complexity, training, and time involved in this evaluation. The interface was limited to the downward looking orbital mode. This navigation mode was further simplified by restricting roll, pitch, and yaw. Users could pan horizontally or vertically, and zoom in and out.

3.2.2 Mouse Interface

The simplified mouse interface uses a three-button mouse. Clicking the left button and dragging allows the user to pan horizontally and vertically. Pressing the middle button zooms in and pressing the right button zooms out. An additional zoom characteristic was that the mouse position determined the center of the zoom in and zoom out motions. This allows users to pan a small amount while zooming, allowing fine adjustments of their trajectories.

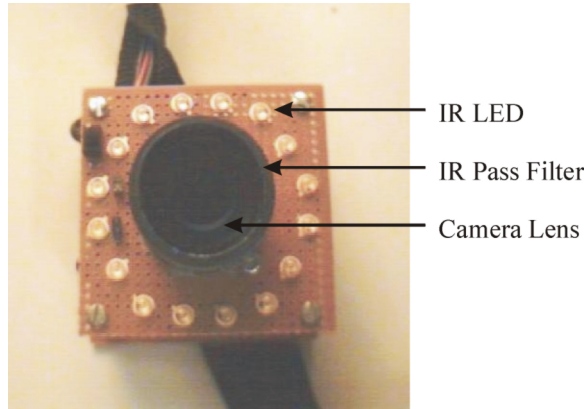| Movement Commands |
| --- |
| Move {In, Out, Forwards, Backwards} |
| Move {Left, Right, Up, Down} |
| Move {Higher, Lower} |
| *Speed Commands* |
| Slower, Faster, Stop |
| *Discrete Movement Commands* |
| Jump {Forwards, Backwards} |
| Jump {Left, Right, Up, Down} |
| Jump {Higher, Lower} |

Table 1: A Sample of Recognized Speech Commands

Figure 2: Gesture Pendant

3.2.3 Speech Interface

The speech interface uses Microsoft's Speech API for recognition. No user training is needed, but some users with certain US regional dialects or non-US accents experience more recognition difficulties. Fortunately, synonyms are available for commands that often cause difficulty.

The speech interface provides three classes of commands (Table 1). There are movement commands that start the user moving in a particular direction. For example, the user can "Move left" or "Move right" to pan horizontally. "Move up" and "Move down" are used to pan vertically. A second movement command stops the previous motion and begins a new motion. This constraint was added when we found in pilot tests that combining movements proved more difficult for users to control. The speed control commands, "Faster", "Slower", and "Stop", allow the user to modify speed once a movement command has been given. The final class of commands, the discrete movement commands, "Jump left", "Jump up", "Jump down", are much like the movement commands, except the user moves in small jumps with no control of speed.

3.2.4 Gesture Interface

The gesture interface uses the Gesture Pendant[11]. It consists of a small, black and white, NTSC video camera that is worn on the user's chest (Figure 2). Since bare human skin is very reflective to infrared light, regardless of skin tone, an array of infrared emitting LED's is used to illuminate the camera's field of view. An infrared filter over the camera's lens prevents other light sources from interfering with segmentation of the user's hand. The limited range of the LED's prevents objects beyond a few feet from being seen by the camera.

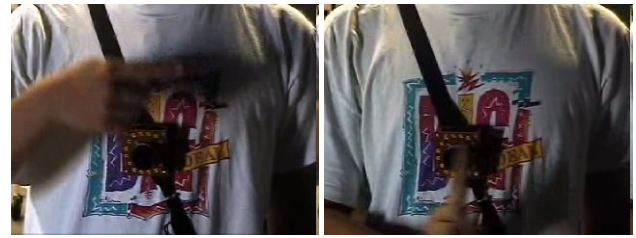Sweeping a vertical finger in a horizontal direction allows hori-

Figure 3: Moving the right index finger up and down causes vertical panning. Moving a vertical index finger left and right causes horizontal panning.

Figure 4: Moving the left index finger up and down causes zooming. An open palm stops movement.

zontal panning. Sweeping a horizontal finger from the right hand up and down allows vertical panning. Sweeping a horizontal finger from the left hand up and down allows the user to zoom in and zoom out. A flat palm facing the chest stops any motion. As in the speech interface, a second movement command stops the previous motion and begins a new motion.

3.2.5 Multimodal Interface

The multimodal interface uses both speech commands and gestures. The speech component is basically the same as the speech interface; however, the gesture component is different. For example, the user first gives a speech command such as "Move left", which causes the motion in the left direction. The gesture component segments the user's finger tip and detects x and y motion of the finger tip. By moving the finger tip left and right, the user can speed, slow, or even slightly reverse the motion. Zooming and vertical panning are controlled by vertical displacement of a horizontal finger tip. Two additional speech commands were also added to provide additional alternative commands for a few functions. "Horizontal" allows the horizontal finger tip displacement to determine both the direction and speed of horizontal panning and "Vertical" allows vertical finger tip displacement to control the same for vertical panning.

3.3 Design

The experiment compared the effect of a single variable (interface type) on a variety of objective and subjective measures. This was a within subjects design, so each participant used each interface type. Each participant experienced the interfaces in different orders.

A single interface task consisted of navigating to four different targets. These targets were each associated with a unique symbol. This task was repeated, with different target symbols and locations, for each of the four interfaces. There were two objective measures taken. The time needed to reach each target was measured. Also, participants were given a memory test to determine if they remembered the symbols they saw, what order they saw them, and where
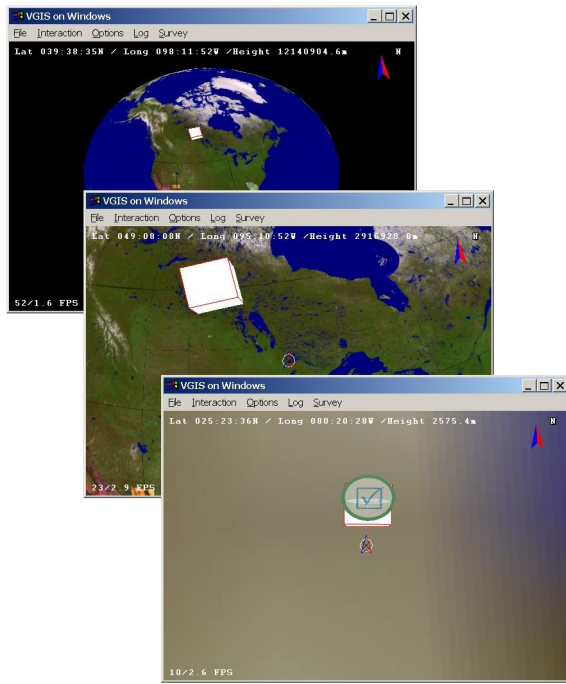
Figure 5: Sequence of Images from an Experimental Task

Figure 6: Average Target Time in Seconds for Each Interface

Figure 7: Average Number of Correctly Recalled Positions for Each Interface

the symbols were located. This was a measure to determine the cognitive load of the interface. One widely used result of cognitive psychology shows that there are severe limitations on working memory capacity[8] and when individuals are forced to use working memory or other cognitive resources, information is lost or displaced[1]. The cognitive load of a particular interface should be reflected in the how much an individual can remember while using the interface.

After each interface task, participants were asked to rate ten specific interface characteristics on a five point disagree-agree response scale. They were also asked to write open-ended comments on aspects of the interface that were helpful and aspects that were problems.

At the end of the experiment, after experiencing each interface, participants were given the same ten interface characteristics and asked to order the interfaces by how well they expressed each characteristic. They were again asked to write open-ended comments on what was helpful or problematic for each interface. They were also asked to comment on how each interface might be improved.

4   Procedure

Each of the twenty-four participants was given a consent form to read and sign. A questionnaire was given to each user to collect basic demographic information and assess their experience with computers, 3D graphics, speech recognition, and gesture interfaces. Participants were then shown a set of thirty symbols and asked to assign each a simple one word name. This allowed participants to become familiar with the set of symbols they would see during the task.

Participants were given several minutes to become familiar with each interface before starting the task. For interfaces involving speech recognition, they read the command list to ensure that they were familiar with all commands and the speech recognition process was working properly. They were allowed to try all commands and also practice navigation by finding and zooming in on Lake
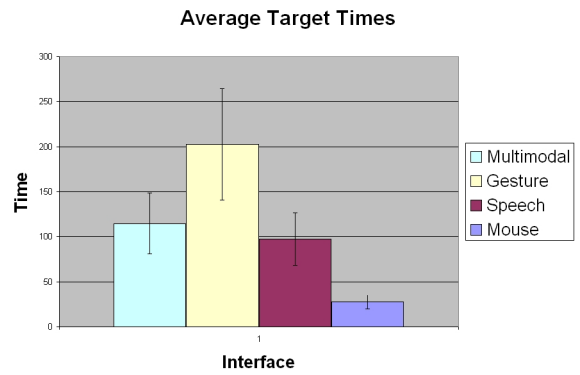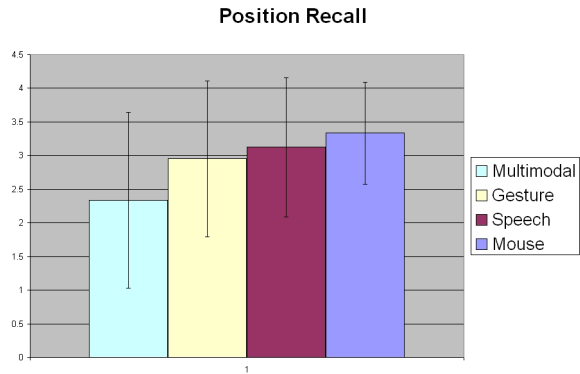
Okeechobee in Florida.

Participants were informed of the nature of the interface task and told to pay attention to symbols, location, and order of presentation. Participants began in a stationary position about twelve thousand kilometers above North America (see Figure 5). When an interface task began, a white cube appeared at a location in North America. As participants navigated closer and zoomed in, the white cube began to shrink. Eventually, the cube revealed a disc with a symbol. When the participant came to within about 4 kilometers, a chime sounded, signaling that the user had come close enough and should zoom out to find the next target. After four targets, a different chime sounded, signifying the end of the task. Participants were then given the memory recall test and after that, the post-task questionnaire. After all four tasks, the final post-experiment questionnaire was given.

5   Results

A oneway ANOVA and Tukey post hoc analysis of the objective results shows significant differences in average target time ($p = 0.001$). The average target times of all of the interfaces were significantly different with the exception of the speech interface and multimodal interface. The mouse interface is significantly faster than the others. All these results are illustrated in Figure 6.

The statistical analysis also shows a significant difference in recall of the target locations ($p = 0.013$). The mouse interface
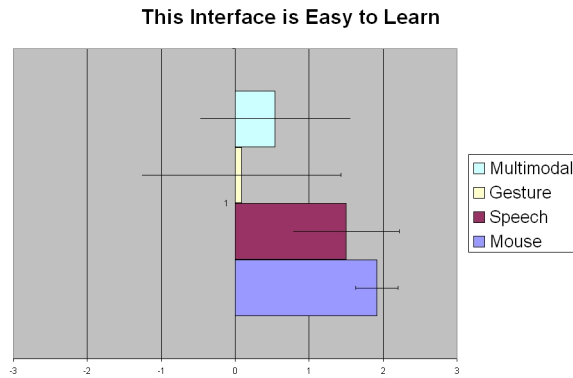
Figure 8: Response to Ease of Learning of Each Interface

Figure 9: Response to Ease of Use of Each Interface

and multimodal interface were significantly different. However, the other interfaces had no significant differences. Furthermore, no significant differences among the interfaces were found at the ($p < 0.05$) level for symbol recall or order recall.

Participants were also questioned about ten interface characteristics on post-task and post-experiment questionnaires. The results were consistent although the post-task questions were on a five point disagree-agree scale and the post-experiment questions asked respondents to rank the interfaces. The mapping of the responses were as follows (-2 Disagree, -1 Agree, 0 Indifferent, 1 Agree, 2 Strongly Agree). An ANOVA and Tukey post hoc analysis was performed to determine if the mean responses significantly differed between interfaces.

5.1 Ease of Learning

For the ease of learning characteristic (Figure 8), the interfaces fell into two groups. The participants felt that multimodal and gesture interfaces were not as easy to learn as speech and mouse. No significant differences were found between multimodal and gesture nor were there differences between speech and mouse.

5.2 Ease of Use

Participants' responses for the ease of use question were significantly different for each interface. The ranking of the interfaces from easiest to hardest was mouse, speech, multimodal, and gesture (Figure 9).

5.3 Errors

The speech and mouse interfaces were not significantly different in the participants' responses about error (Figure 10). However, the speech and mouse interfaces were better than the multimodal interface which was also better than the gesture interface.

5.4 Speed

The participants' responses concerning the speed of the interfaces (Figure 11) perfectly reflected the objective measurements of average task time. The speech and multimodal interfaces were not statistically different. The mouse interface was felt to be fast and the gesture interface was felt to be slow.
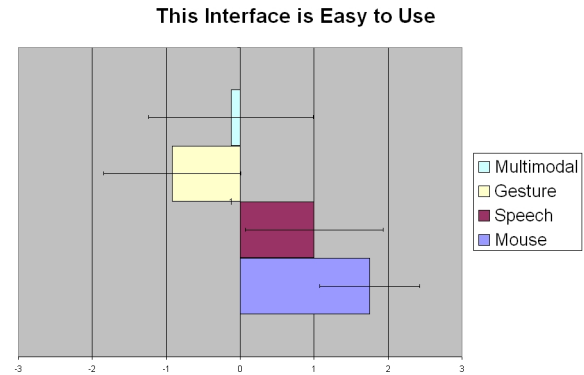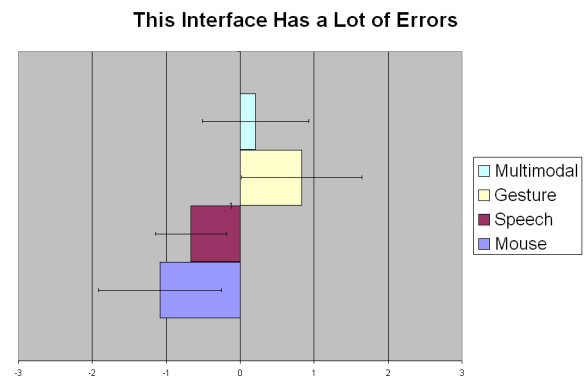

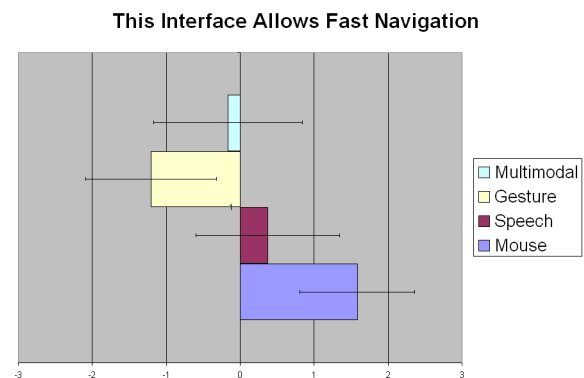Figure 10: Response to Error Rate of Each Interface

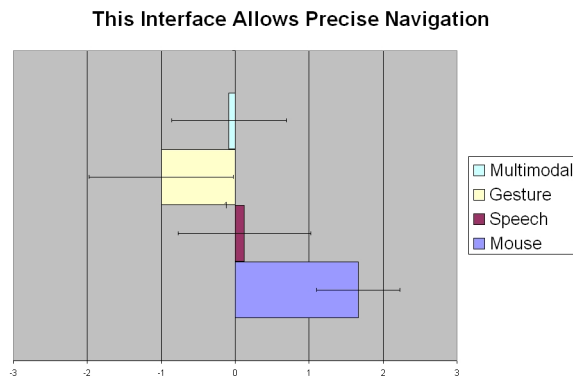Figure 11: Response to Speed of Each Interface

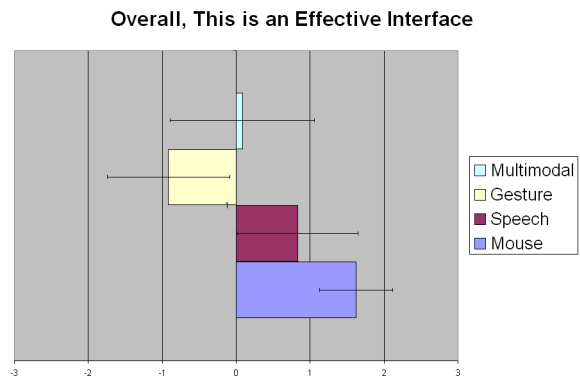Figure 12: Response to Precision of Each Interface
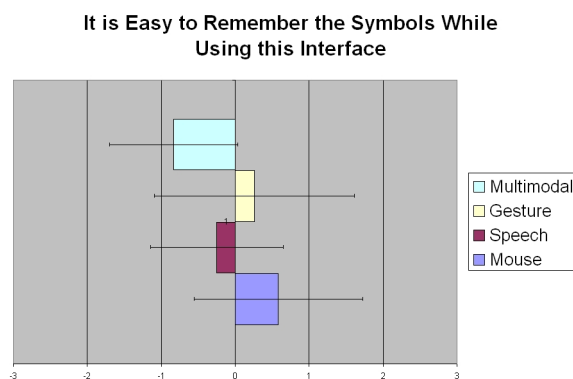

Figure 14: Response to Effectiveness of Each Interface

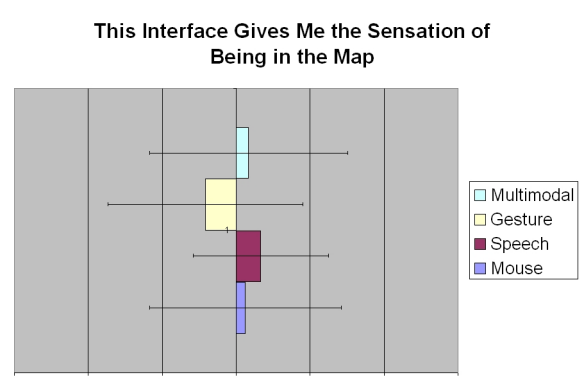
Figure 13: Response to Cognitive Load of Each Interface

Figure 15: Response to Presence of Each Interface

5.5 Precision

The participants' evaluation of the precision of the interfaces paralleled their evaluation of the speed (Figure 12). Again, the speech and multimodal interfaces were not statistically different. The mouse interface was felt to be most precise and the gesture interface imprecise.

5.6 Cognitive Load

The multimodal interface was considered to provide the most interference of remembering the symbols (Figure 13). The mouse was evaluated as providing the least. This was also reflected in the location recall analysis. The gesture and speech interfaces did not significantly differ.

5.7 Effectiveness

Users strongly felt that the mouse interface was effective. Their responses for each of the interfaces were significantly different (Figure 14). The second highest support was for the speech interface followed by the multimodal interface and the gesture interface.

5.8 Presence

The participants were asked whether "This interface gives me the sensation of being in the map, i.e. I am present and part of the

virtual environment." This was an attempt to determine if any of the interfaces improved the sense of presence in the visualization. However, there were no significant differences in opinion between the interfaces (Figure 15). The environment did not seem to become more immersive with any of the interfaces. It is also possible that the question was confusing to the respondents.

5.9 Comfort

The most comfortable interface appears to be the mouse interface followed by the speech interface. The multimodal and gesture interfaces appear to be the least comfortable to use. User responses distinguished all but the multimodal and gesture interfaces; they appear to be equally uncomfortable (Figure 16).

5.10 Desirability

After using and considering the characteristics of the interface, the participants were asked if they would like that interface on their own computers. The mouse was rated significantly higher than the other interfaces. The speech interface was second, but still still significantly higher than the gesture and multimodal interfaces. The difference between attitudes towards the gesture and multimodal interfaces were not significantly different (Figure 17).

This Interface is Comfortable to Use

Figure 16: Response to Comfort of Each Interface

I Would Like to Have This Interface on My Own Computer

Figure 17: Response to Desirability of Each Interface

6   Conclusion

The familiarity of the mouse interface was one reason why the participants favored that interface. A few users were able to complete the navigation with the mouse so fast, they commented that it was difficult for them to recall targets. However, this concern was not widespread and was not reflected in the objective recall measures.

Overall, the speech interface was well regarded. The recognition lag in the speech interface was a source of difficulty for participants. Participants occasionally had to repeat commands and give some commands early to anticipate for lag. Precision was somewhat difficult, but users could adjust.

The gesture interface seemed to be the most difficult interface for the users. Errors in the recognition were a large source of problems. Precise movement was very difficult. Furthermore, some participants found it even uncomfortable to point a forefinger upward and move it left and right. Some wanted to use a thumb or point the forefinger down.

Since performing the task with gesture interface took far more time than any of the other interfaces, and since participants were only expected to spend about an hour on the experiment, several participants did not complete the task for the gesture interface. However, this did not seem to greatly affect the results of this study.

The mouse and speech interfaces seem to rank highest by most measures. Of course, these interfaces are based on the most mature technologies. A few observations about the relatively low performance of the multimodal interface should be made.

While it is not surprising that the gesture interface was slowest and the mouse interface was the fastest, it is interesting to note that the speech and multimodal interfaces were not significantly different in speed. It was hoped that the additional expressiveness of the multimodal interface would have some benefit in speed. From the subjective results, it is apparent that the participants did not feel that the multimodal interface was more precise or faster than the speech interface. The addition of the gesture component did not improve performance. Furthermore, it hurt performance in some aspects. The multimodal interface was ranked most like the gesture interface in some subjective measures and indistinguishable from the gesture interface in ease of use, comfort, and desirability. The performance of the gesture component was certainly limited by the resolution of the video camera and the performance of the finger tip segmentation. A more robust and faster segmentation algorithm could significantly affect these results.

For our objective of use in a ubiquitous or mobile visualization environment, where a mouse may not be available or handy, the results indicate that speech can be effective, at least for the extended navigation task presented. The results indicate that better gesture recognition is an important factor here and further work is needed to improve recognition. Furthermore, there may be different or more complicated tasks where the increased expressiveness of a multimodal interface would pay off. Different gestures should also be tried for improved comfort, ease of use, and precision.

7   Future Work

Future work would be to address the problems and limitations of the gesture interface. Both hardware and software enhancements are possible. Recognition might improve if the Gesture Pendant could capture and process 3D data. This could be accomplished through a stereo camera pair. Depth information could be used to better segment the nearby hand silhouette from more distant infrared light sources and reflections off highly reflective objects. Depth information would also allow gestures along the Z axis and allow better differentiation of the wrist and finger tips. An alternative approach would be to use a single camera and a visible laser projected into a grid pattern. Measuring deformations in this structured light would
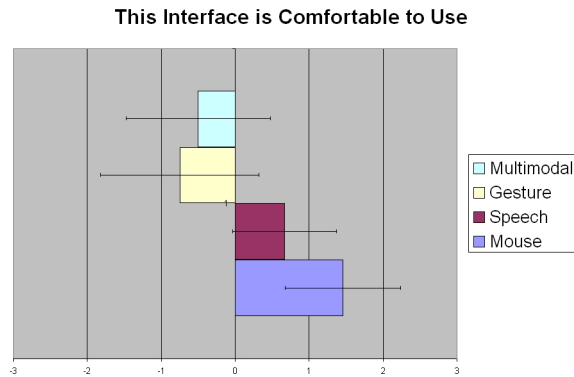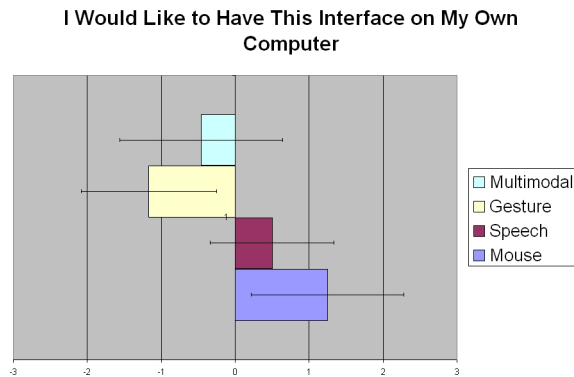
allow 3D imaging of the hand. This would have the additional benefit of visibly illuminating the camera's field of view so users would know when their hand was visible to the camera. Also, this configuration could allow outdoor gesture use. While sunlight's broad spectrum and intensity overwhelms the current Gesture Pendant's infrared illumination, the visible laser may be intense and narrow band enough for outdoor use. We are currently designing a structured light device.

Another line of work would investigate multimodal interfaces using speech and a mouse or other pointer input device. These devices would be less susceptible to recognition errors. We are planning a user study to investigate speech and two handed input through IBM trackpoint devices mounted on rings or gloves. We feel that this interface might be very expressive, yet non-intrusive and non-encumbering enough for use in the mobile or wearable contexts we are investigating.

8 Acknowledgements

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