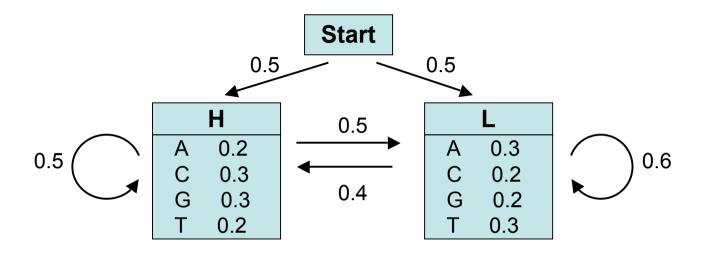


Let's consider the following simple HMM. This model is composed of 2 states, **H** (high GC content) and **L** (low GC content). We can for example consider that state H characterizes coding DNA while L characterizes a non-coding DNA.

The model can then be used to predict the region of coding DNA from a given sequence.

**Sources**: For the theory, see Durbin *et al* (1998);

For the example, see Borodovsky & Ekisheva (2006), pp 80-81



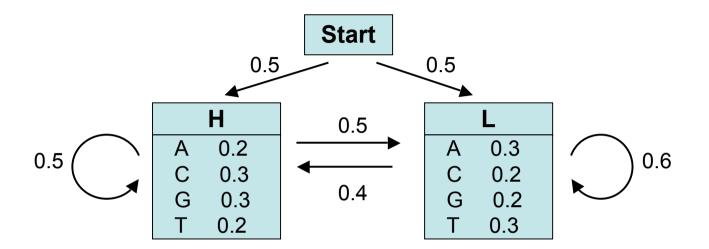
### Consider the sequence S= **GGCACTGAA**

There are several paths through the hidden states (H and L) that lead to the given sequence.

Example: P = LLHHHHLLL

The probability of the HMM to produce sequence S through the path P is:

$$p = p_L(0) * p_L(G) * p_{LL} * p_L(G) * p_{LH} * p_H(C) * ...$$
  
= 0.5 \* 0.2 \* 0.6 \* 0.2 \* 0.4 \* 0.3 \* ...  
= ...

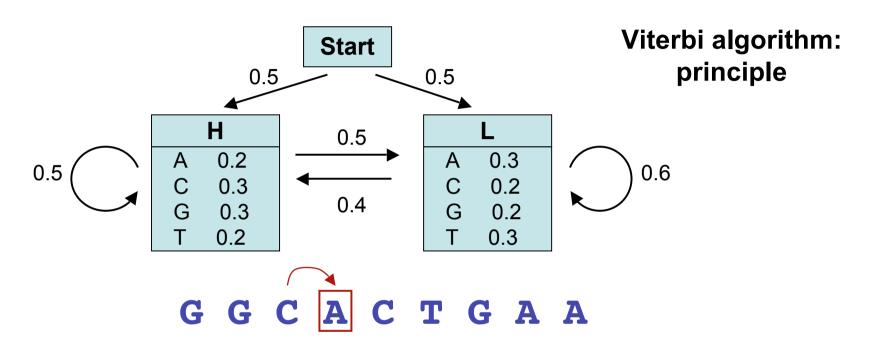


#### **GGCACTGAA**

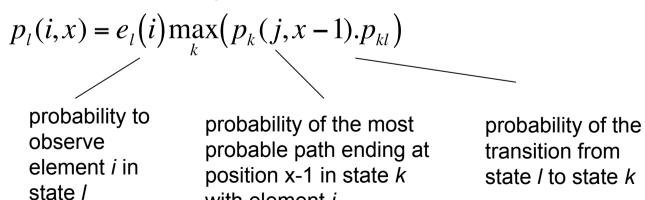
There are several paths through the hidden states (H and L) that lead to the given sequence, but they do not have the same probability.

The **Viterbi algorithm** is a dynamical programming algorithm that allows us to compute the most probable path. Its principle is similar to the DP programs used to align 2 sequences (i.e. Needleman-Wunsch)

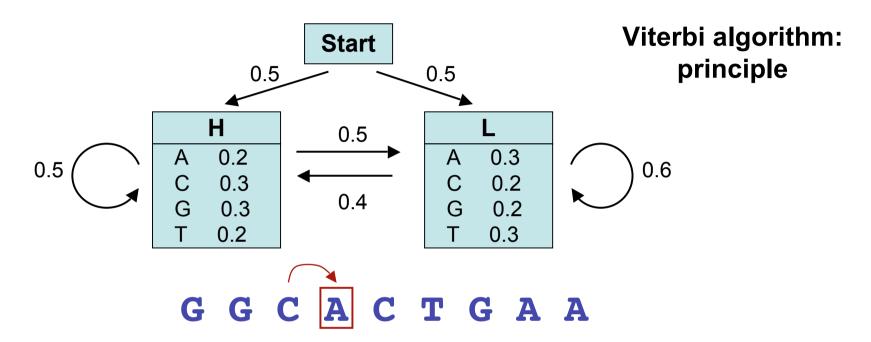
Source: Borodovsky & Ekisheva, 2006



The probability of the most probable path ending in state **k** with observation "i" is



with element *j* 



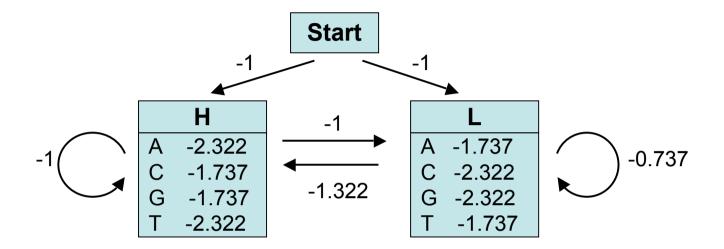
The probability of the most probable path ending in state **k** with observation "i" is

$$p_l(i,x) = e_l(i) \max_{k} (p_k(j,x-1).p_{kl})$$

In our example, the probability of the most probable path ending in state **H** with observation "A" at the 4th position is:

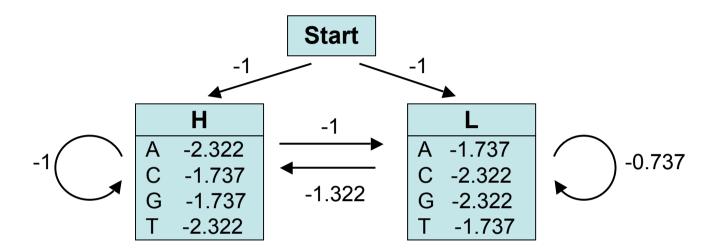
$$p_H(A,4) = e_H(A) \max(p_L(C,3)p_{LH}, p_H(C,3)p_{HH})$$

We can thus compute recursively (from the first to the last element of our sequence) the probability of the most probable path.



**Remark**: for the calculations, it is convenient to use the log of the probabilities (rather than the probabilities themselves). Indeed, this allows us to compute *sums* instead of *products*, which is more efficient and accurate.

We used here  $log_2(p)$ .



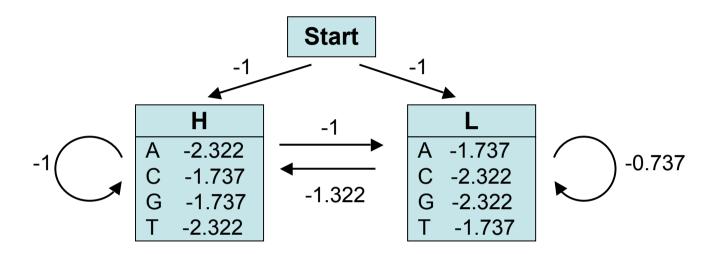
#### **GGCACTGAA**

Probability (in log<sub>2</sub>) that **G** at the first position was emitted by state **H** 

$$p_H(G,1) = -1 -1.737 = -2.737$$

Probability (in log<sub>2</sub>) that **G** at the first position was emitted by state **L** 

$$p_L(G,1) = -1 -2.322 = -3.322$$



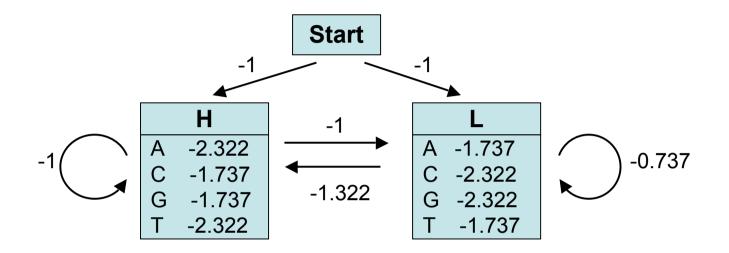
### **GGCACTGAA**

Probability (in log<sub>2</sub>) that **G** at the 2nd position was emitted by state **H** 

$$p_H(G,2) = -1.737 + max (p_H(G,1)+p_{HH}, p_L(G,1)+p_{LH})$$
  
= -1.737 + max (-2.737 -1 , -3.322 -1.322)  
= -5.474 (obtained from  $p_H(G,1)$ )

Probability (in log<sub>2</sub>) that **G** at the 2nd position was emitted by state **L** 

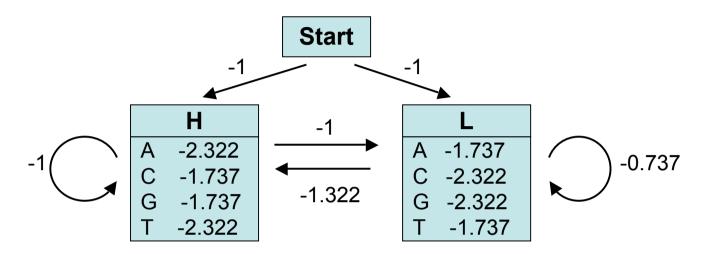
$$p_L(G,2) = -2.322 + max (p_H(G,1)+p_{HL}, p_L(G,1)+p_{LL})$$
  
= -2.322 + max (-2.737 -1.322 , -3.322 -0.737)  
= -6.059 (obtained from  $p_H(G,1)$ )



#### **GGCACTGAA**

	G	G	С	Α	С	Т	G	Α	Α
Н	-2.73	<b>→</b> -5.47 <b>→</b>	-8.21	-11.53	-14.01				-25.65
L	-3.32	-6.06	-8.79	-10.94	►-14.01 <b>-</b>	<b></b> -	<b>-</b>	<b>-</b>	<b>→</b> -24.49

We then compute iteratively the probabilities  $p_H(i,x)$  and  $p_L(i,x)$  that nucleotide i at position x was emitted by state H or L, respectively. The highest probability obtained for the nucleotide at the last position is the probability of the most probable path. This path can be retrieved by back-tracking.



### **GGCACTGAA**

### back-tracking

(= finding the path which corresponds to the highest probability, -24.49)

	G	G	С	Α	С	Т	G	Α	Α
Н	-2.73	-5.47	-8.21	-11.53	-14.01				-25.65
L	-3.32	-6.06	-8.79	-10.94	-14.01 -		<b>-</b>	<b>-</b>	-24.49

The most probable path is: **HHHLLLLL** 

Its probability is  $2^{-24.49} = 4.25E-8$ (remember that we used  $log_2(p)$ )

#### Remarks

The **Viterbi algorithm** is used to compute the most probable path (as well as its probability). It requires knowledge of the parameters of the HMM model and a particular output sequence and it finds the state sequence that is most likely to have generated that output sequence. It works by finding a maximum over all possible state sequences.

In sequence analysis, this method can be used for example to predict coding vs non-coding sequences.

In fact there are often many state sequences that can produce the same particular output sequence, but with different probabilities. It is possible to calculate the probability for the HMM model to generate that output sequence by doing the summation over all possible state sequences. This also can be done efficiently using the **Forward algorithm**, which is also a dynamical programming algorithm.

In sequence analysis, this method can be used for example to predict the probability that a particular DNA region match the HMM motif (i.e. was emitted by the HMM model).

#### Remarks

To create a HMM model (i.e. find the most likely set of state transition and output probabilities of each state), we need a set of (related/aligned) sequences.

No tractable algorithm is known for solving this problem exactly, but a local maximum likelihood can be derived efficiently using the **Baum-Welch** algorithm or the **Baldi-Chauvin algorithm**. The Baum-Welch algorithm is an example of a forward-backward algorithm, and is a special case of the Expectation-maximization algorithm.

For more details: see Durbin et al (1998)