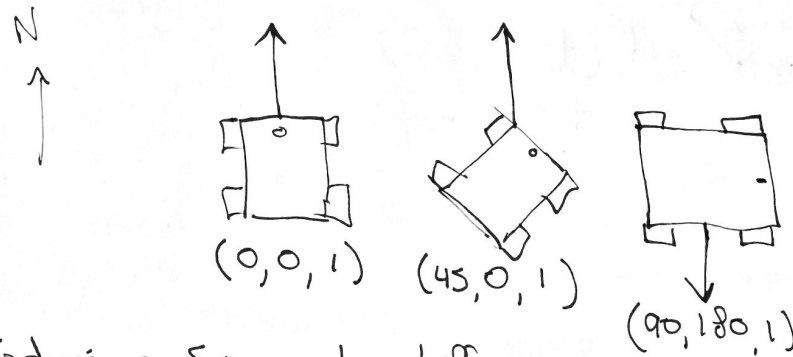


Auto Plan 12/8

- Goals:
- Driving in straight line. \rightarrow Using IMU
 - Double check turning. Is IMU 180 or 360?
 - Absolute orientation (from init)

Long term: master drive function:

name(double angle, double direction, double speed)



- Today:
- Some auto stuff
 - \hookrightarrow To carousel + park (ignore arm for now)
 - Test new drive function
 - Make sure code is competition ready
 - \hookrightarrow Doesn't throw errors
 - \hookrightarrow Make class names sensible